

ioLogik E2200 Series User's Manual

Version 7.1, August 2021

www.moxa.com/product



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ioLogik E2200 Series User's Manual

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Introduction

The ioLogik E2200 series is a standalone Smart Ethernet remote I/O device that can connect sensors and on/off switches for automation applications over Ethernet and IP-based networks.

The following topics are covered in this chapter:

❑ **Product Key Features and Highlights**

❑ **Package Checklist**

❑ **Product Model Information**

❑ **Product Selection Guide**

❑ **Product Specifications**

- Common Specifications
- ioLogik E2210 Specifications
- ioLogik E2212 Specifications
- ioLogik E2214 Specifications
- ioLogik E2240 Specifications
- ioLogik E2242 Specifications
- ioLogik E2260 Specifications
- ioLogik E2262 Specifications

❑ **Physical Dimensions**

- Without LCM
- With LCM

❑ **Hardware Reference**

- Panel Guide
- Pin Assignments
- LED Indicators

Product Key Features and Highlights

1. Front-end intelligence that supports 24 Click&Go rules
2. Active Messaging with real-time stamp, including SNMP Trap with I/O status, TCP, and e-mail.
3. Supports SNMPv1/v2c/v3 protocol
4. I/O peer-to-peer function
5. Built-in web console
6. PC utility: auto detection of installed modules
7. MXIO programming library for Windows, WinCE VB/VC.NET, and Linux C APIs
8. -40 to 75°C operating temperature range (T models)

Package Checklist

The ioLogik E2200 Series is shipped with the following items:

- ioLogik E22xx Smart Ethernet remote I/O device x1
- Quick installation guide (printed)
- Warranty card

NOTE: Notify your sales representative if any of the above items are missing or damaged.

Product Model Information

| Model | Description |
|-----------------|---|
| ioLogik E2210 | Ethernet Remote IO with 12 DIs, 8 DOs, -10 to 60°C operating temperature |
| ioLogik E2212 | Ethernet Remote IO with 8 DIs, 8 DOs, 4DIOs, -10 to 60°C operating temperature |
| ioLogik E2214 | Ethernet Remote IO with 6 DIs, 6 relays, -10 to 60°C operating temperature |
| ioLogik E2240 | Ethernet Remote IO with 8 AIs, 2 AOs, -10 to 60°C operating temperature |
| ioLogik E2242 | Ethernet Remote IO with 4 AIs, 12 DIOs, -10 to 60°C operating temperature |
| ioLogik E2260 | Ethernet Remote IO with 6 RTDs, 4 DOs, -10 to 60°C operating temperature |
| ioLogik E2262 | Ethernet Remote IO with 8 TCs, 4 DOs, -10 to 60°C operating temperature |
| ioLogik E2210-T | Ethernet Remote IO with 12 DIs, 8 DOs, -40 to 75°C operating temperature |
| ioLogik E2212-T | Ethernet Remote IO with 8 DIs, 8 DOs, 4 DIOs, -40 to 75°C operating temperature |
| ioLogik E2214-T | Ethernet Remote IO with 6 DIs, 6 Relays, -40 to 75°C operating temperature |
| ioLogik E2240-T | Ethernet Remote IO with 8 AIs, 2 AOs, -40 to 75°C operating temperature |
| ioLogik E2242-T | Ethernet Remote IO with 4 AIs, 12 DIOs, -40 to 75°C operating temperature |
| ioLogik E2260-T | Ethernet Remote IO with 6 RTDs, 4 DOs, -40 to 75°C operating temperature |
| ioLogik E2262-T | Ethernet Remote IO with 8 TCs, 4 DOs, -40 to 75°C operating temperature |

Product Selection Guide

The operating temperature for standard models is -10 to 60°C.

The operating temperature for wide temperature models is -40 to 75°C

| | Digital Inputs | Selectable DIO | Digital Outputs | Relay Outputs | Analog Inputs | Analog Outputs | RTD Inputs | TC Inputs |
|------------------------------|----------------------|----------------|-----------------|---------------|---------------|----------------|------------|-----------|
| E2200 Series | Common Specification | | | | | | | |
| E2210 | 12 | | 8 | | | | | |
| E2212 | 8 | 4 | 8 | | | | | |
| E2214 | 6 | | | 6 | | | | |
| E2240 | | | | | 8 | 2 | | |
| E2242 | | 12 | | | 4 | | | |
| E2260 | | | 4 | | | | 6 | |
| E2262 | | | 4 | | | | | 8 |

Product Specifications

Common Specifications

LAN

Ethernet: 1 x 10/100 Mbps, RJ45

Protection: 1.5 kV magnetic isolation

Protocols: Modbus/TCP, TCP/IP, UDP, DHCP, Bootp, SNMP, HTTP, CGI, SNTP, SMTP

Serial Communication

Interface: RS-485-2w: Data+, Data-, GND (3-contact terminal block)

Serial Line Protection: 15 kV ESD for all signals

Serial Communication Parameters

Parity: None

Data Bits: 8

Stop Bits: 1

Flow Control: None

Baudrate: 1200 to 115200 bps

Protocol: Modbus/RTU

Power Requirements

Power Input: 24 VDC nominal, 12 to 36 VDC

Physical Characteristics

Wiring: I/O cable max. 14 AWG

Dimensions: 115 x 79 x 45.6 mm (4.53 x 3.11 x 1.80 in)

Weight: under 250 g

Mounting: DIN-rail or wall

Environmental Limits

Operating Temperature:

- Standard Models: -10 to 60°C (14 to 140°F)
- Wide Temp. Models: -40 to 75°C (-40 to 167°F)

Storage Temperature: -40 to 85°C (-40 to 185°F)

Ambient Relative Humidity: 5 to 95% (non-condensing)

Altitude: Up to 2000 m

Note: Please contact Moxa if you require products guaranteed to function properly at higher altitudes.

Standards and Certifications

Safety: UL 508

EMI:

EN 61000-3-2; EN 61000-3-3; EN 61000-6-4;

FCC Part 15, Subpart B, Class A

EMS:

EN 61000-4-2, EN 61000-4-3, EN 61000-4-4,

EN 61000-4-5, EN 61000-4-6, EN 61000-4-8,

EN 61000-4-11, EN 61000-6-2

Shock: IEC 60068-2-27

Freefall: IEC 60068-2-32

Vibration: IEC 60068-2-6

Green Product: RoHS, CRoHS, WEEE

Note: Please check Moxa's website for the most up-to-date certification status.

Warranty

Warranty Period: 5 years (excluding ioLogik E2214*)

***Because of the limited lifetime of power relays, products that use that component are covered by a 2-year warranty.**

Details: See www.moxa.com/warranty

ioLogik E2210 Specifications

Inputs and Outputs

Digital Inputs: 12 channels

Digital Outputs: 8 channels

Isolation: 3K VDC or 2K Vrms

Digital Input

Sensor Type: Wet Contact (NPN), Dry Contact

I/O Mode: DI or Event Counter

Dry Contact:

- On: short to GND
- Off: open

Wet Contact (DI to GND):

- On: 0 to 3 VDC
- Off: 10 to 30 VDC

Common Type: 12 points per COM

Counter Frequency: 900 Hz

Digital Filtering Time Interval: Software selectable

Digital Output

Type: Sink

I/O Mode: DO or Pulse Output

Pulse Output Frequency: 1 kHz

Over-voltage Protection: 45 VDC

Over-current Protection: 2.6 A (4 channels @ 650 mA)

Over-temperature Shutdown: 175°C (min.)

Current Rating: 200 mA per channel

Power Requirements

Power Consumption: 203 mA @ 24 VDC

MTBF (mean time between failure)

Time: 213,673 hrs

Database: Telcordia (Bellcore)

ioLogik E2212 Specifications

Inputs and Outputs

Digital Inputs: 8 channels

Digital Outputs: 8 channels

Configurable DIOs: 4 channels

Isolation: 3k VDC or 2k Vrms

Digital Input

Sensor Type: Wet Contact (NPN or PNP) and Dry Contact

I/O Mode: DI or Event Counter

Dry Contact:

- On: short to GND
- Off: open

Wet Contact (DI to GND):

- On: 0 to 3 VDC
- OFF: 10 to 30 VDC

Common Type: 6 points per COM

Counter Frequency: 900 Hz

Digital Filtering Time Interval: Software Configurable

Digital Output

Type: Sink

I/O Mode: DO or Pulse Output

Pulse Output Frequency: 1 kHz

Over-Voltage Protection: 45 VDC

Over-Current Protection: 2.6 A (4 channels @ 650 mA)

Over-Temperature Shutdown: 175°C (min.)

DIO Output Leakage Current: 4.0 mA @ 24 VDC

Current Rating: 200 mA per channel

Power Requirements

Input Voltage: 12 to 36 VDC

Input Current: 136 mA @ 24 VDC

MTBF (mean time between failures)

Time: 217,722 hrs

Standard: Telcordia SR332

ioLogik E2214 Specifications

Inputs and Outputs

Digital Inputs: 6 channels

Relay Outputs: 6 channels

Isolation: 3K VDC or 2K Vrms

Digital Input

Sensor Type: Wet Contact (NPN or PNP) and Dry Contact

I/O Mode: DI or Event Counter

Dry Contact:

- On: short to GND
- Off: open

Wet Contact(DI to GND):

- On: 0 to 3 VDC
- Off: 10 to 30 VDC

Common Type: 3 points per COM

Counter Frequency: 900 Hz, power off storage

Digital Filtering Time Interval: Software selectable

Relay Output

Type: Form A (N.O.) power relay

Contact Current Rating:

- Inductive Load: 2 A @ 30 VDC, 250 VAC, 110 VAC
- Resistive Load: 5 A @ 30 VDC, 250 VAC, 110 VAC

Minimum permitted load: 1 A @ 5 VDC

Initial Insulation Resistance: 1000 M ohms (min.) @ 500 VDC

Mechanical endurance: 1,000,000 operations

Electrical endurance: 100,000 operations @ 5 A resistive load

Contact Resistance: 100 m ohms (max.)

Pulse Output: 0.3 Hz at rated load

Power Requirements

Power Consumption: 170 mA @ 24 VDC

MTBF (mean time between failure)

Time: 307,239 hrs

Database: Telcordia (Bellcore)

ioLogik E2240 Specifications

Inputs and Outputs

Analog Inputs: 8 channels

Analog Outputs: 2 channels

Analog Input

Type: Differential input

Resolution: 16 bits

I/O Mode: Voltage / Current

Input Range: ± 150 mV, ± 500 mV, ± 5 V, ± 10 V, 0 to 20 mA, 4 to 20 mA

Accuracy:

$\pm 0.1\%$ FSR @ 25°C

$\pm 0.3\%$ FSR @ -10 and 60°C

$\pm 0.5\%$ FSR @ -40 and 75°C

Sampling Rate:

All channels:

- 10 samples/sec for voltage
- 6 samples/sec for current

Per channel:

- 1.25 samples/sec for voltage
- 0.75 samples/sec for current

Single channel:

- 1.25 samples/sec for voltage
- 0.75 samples/sec for current

Input Impedance: 900K ohms (min.)

Built-in Resistor for Current Input: 120 ohms

Isolation: 3K VDC or 2K Vrms

Analog Output

Resolution: 12 bits

Output Range: 0 to 10 V, 4 to 20 mA

Drive Voltage: 15 VDC for current output

Accuracy:

$\pm 0.1\%$ FSR @ 25°C,

$\pm 0.3\%$ FSR @ -10 and 60°C,

$\pm 0.5\%$ FSR @ -40 and 75°C

Load Resistor: Less than 250 ohms

Power Requirements

Power Consumption: 198 mA @ 24 VDC

MTBF (mean time between failure)

Time: 155,941 hrs

Database: Telcordia (Bellcore)

ioLogik E2242 Specifications

Inputs and Outputs

Configurable DIOs (by software): 12 channels

Analog Inputs: 4 channels

Isolation: 3k VDC or 2k Vrms

Digital Input

Sensor Type: Wet Contact (NPN or PNP) and Dry Contact

I/O Mode: DI or Event Counter

Dry Contact:

- On: short to GND
- Off: Open

Wet Contact (DI to GND):

- On: 0 to 3 VDC
- Off: 10 to 30 VDC

Common Type: 6 points per COM

Isolation: 3k VDC or 2k Vrms

Counter Frequency: 900 Hz

Digital Filtering Time Interval: Software selectable

Digital Output

Type: Sink

I/O Mode: DO or Pulse Output

Pulse Output Frequency: 1 kHz

Over-Voltage Protection: 45 VDC

Over-Current Protection: 2.6 A (4 channels @ 650 mA)

Over-Temperature Shutdown: 175°C (min.)

DIO Output Leakage Current: 4.0 mA @ 24 VDC

Current Rating: 200 mA per channel

Analog Input

Type: Differential input

Resolution: 16 bits

I/O Mode: Voltage / Current (software selectable)

Input Range: ±150 mV, 0 to 150 mV, ±500 mV, 0 to 500 mV, ±5 V, 0 to 5 V, ±10 V, 0 to 10 V, 0 to 20 mA, 4 to 20 mA

Accuracy:

±0.1% FSR @ 25°C

±0.3% FSR @ -10 and 60°C

±0.5% FSR @ -40 and 75°C

Sampling Rate:

All channels: 32 samples/sec

Per channel: 8 samples/sec

Single channel: 100 samples/sec

Input Impedance: 200 kilo-ohms ohms (min.)

Built-in Resistor for Current Input: 120 ohms

Power Requirements

Input Voltage: 12 to 36 VDC

Input Current: 178 mA @ 24 VDC

MTBF (mean time between failures)

Time: 204,391 hrs

Standard: Telcordia SR332

ioLogik E2260 Specifications

Inputs and Outputs

RTD Inputs: 6 channels

Digital Outputs: 4 channels

Isolation: 3K VDC or 2K Vrms

RTD Inputs

Input Type: PT50, PT100, PT200, PT500, PT1000; JPT100, JPT200, JPT500, JPT1000; NI100, NI120, NI200, NI500, NI1000; Resistance of 310, 620, 1250, and 2200 ohms

Sampling Rate: 12 samples/sec (all channels)

Resolution: 0.1°C or 0.1 ohm

Accuracy:

±0.1% FSR @ 25°C

±0.3% FSR @ -10 and 60°C

±0.5% FSR @ -40 and 75°C

Input Impedance: 625K ohms

Digital Output

Type: Sink

I/O Mode: DO or Pulse Output

Pulse Output Frequency: 100 Hz

Over-voltage Protection: 45 VDC

Over-current Protection: 2.6 A (4 channels @ 650 mA)

Over-temperature Shutdown: 175°C

Current Rating: 200 mA per channel

Power Requirements

Power Consumption: 95 mA @ 24 VDC

MTBF (mean time between failure)

Time: 327,282 hrs

Database: Telcordia (Bellcore)

ioLogik E2262 Specifications

Inputs and Outputs

Thermocouple Inputs: 8 channels

Digital Outputs: 4 channels

Thermocouple Input

Sensor Type: J (0 to 750°C), K (-200 to 1250°C), T (-200 to 350°C), E (-200 to 900°C), R (-50 to 1600°C), S (-50 to 1760°C), B (600 to 1700°C), N (-200 to 1300°C)

Millivolt Type:

- Mode: ± 78.126 mV, ± 39.062 mV, ± 19.532 mV
- Fault and over-voltage protection: -35 to +35 VDC (power off); -25 to +30 VDC (power on)

Sampling Rate: 12 samples/sec (all channels)

Resolution: 16 bits

Millivolt Accuracy:

$\pm 0.1\%$ FSR @ 25°C

$\pm 0.3\%$ FSR @ -10 and 60°C

$\pm 0.5\%$ FSR @ -40 and 75°C

TC Accuracy:

Types J, T, E, S, B: $\pm 5^\circ\text{C}$

Types K, R, N: $\pm 8^\circ\text{C}$

CJC Sensor Accuracy:

$\pm 0.5^\circ\text{C}$ @ 25°C

$\pm 1.5^\circ\text{C}$ @ -40 and 75°C

Input Impedance: 1 M ohms

Digital Output

Type: Sink

I/O Mode: DO or Pulse Output

Pulse Output Frequency: 100 Hz

Over-voltage Protection: 45 VDC

Over-current Protection: 2.6 A (4 channels @ 650 mA)

Over-temperature Shutdown: 175°C

Current Rating: 200 mA per channel

Isolation: 3K VDC or 2K Vrms

Power Requirements

Power Consumption: 160 mA @ 24 VDC

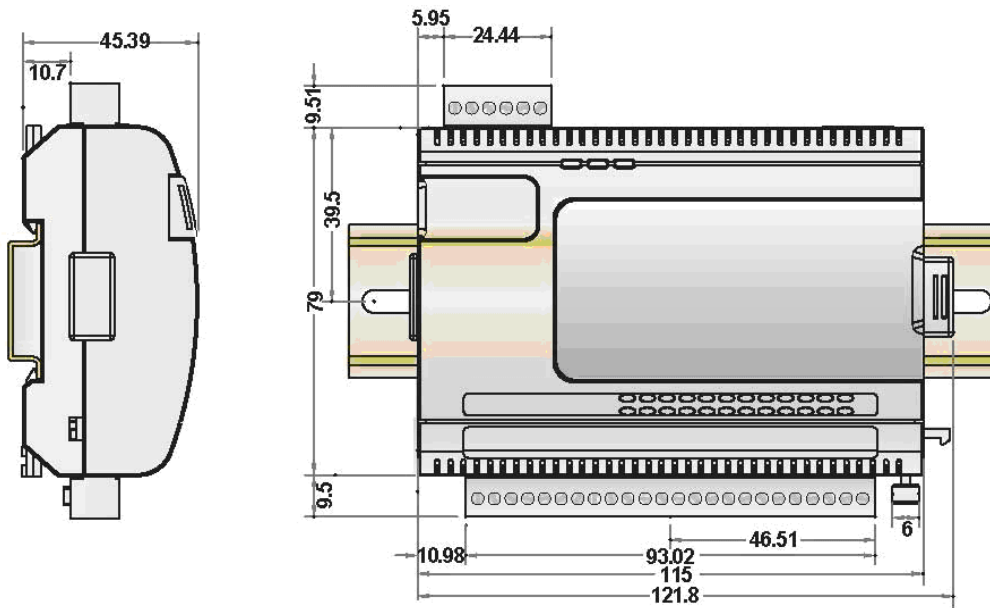
MTBF (mean time between failure)

Time: 341,063 hrs

Database: Telcordia (Bellcore)

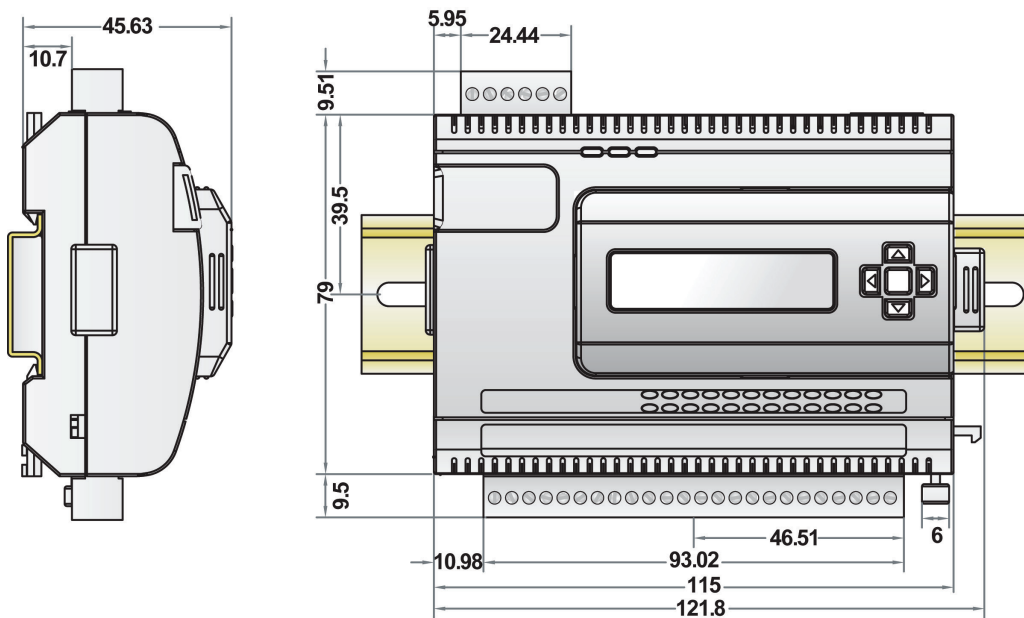
Physical Dimensions

Without LCM



Unit = mm

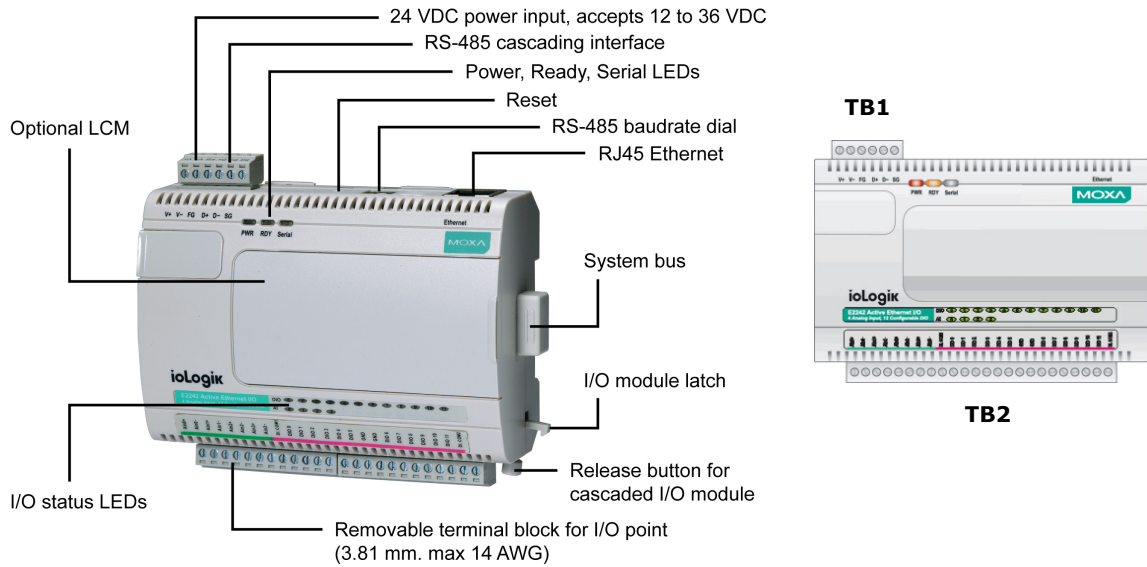
With LCM



Unit = mm

Hardware Reference

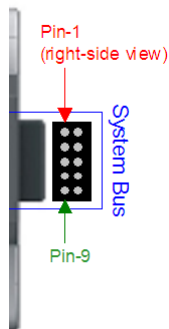
Panel Guide



NOTE The RESET button restarts the device and resets all settings to factory defaults. Use a pointed object such as a straightened paper clip to hold the RESET button down for 5 sec. The RDY LED will turn red as you are holding the RESET button down. The factory defaults will be loaded once the RDY LED turns green again. At this point you can release the RESET button.

Pin Assignments

System Bus



| | | | | | |
|---------------|----|----|----|----|----|
| Pin | 1 | 2 | 3 | 4 | 5 |
| Signal | V+ | V- | V+ | V- | NC |

| | | | | | |
|---------------|----|-------|------|-------|-----|
| Pin | 6 | 7 | 8 | 9 | 10 |
| Signal | NC | Data+ | SYNC | Data- | GND |

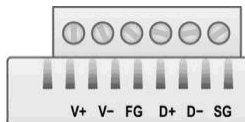
Ethernet Port



| | | | | |
|---------------|------|------|------|-----|
| Pin | 1 | 2 | 3 | 4 |
| Signal | TXD+ | TXD- | RXD+ | --- |

| | | | | |
|---------------|-----|------|-----|-----|
| Pin | 5 | 6 | 7 | 8 |
| Signal | --- | RXD- | --- | --- |

TB1 (Power Input & RS-485 Connector)



| Pin | 1 | 2 | 3 | 4 | 5 | 6 |
|--------|----|----|----|----|----|----|
| Signal | V+ | V- | FG | D+ | D- | SG |

(V+: 12 to 36 VDC)

TB2 (Input and Output Terminal)

Refer to the **Appendix F**.

LED Indicators

| LED | Light | Description |
|----------|--------------------|--|
| PWR | Off | System power off |
| | Red | System power on |
| RDY | Off | System not ready |
| | Green | System ready |
| | Red | System error |
| | Green Blinking | Click & Go running |
| | Green/Red Blinking | System in Safe mode |
| Serial | Off | Serial port not connected |
| | Red | Serial port connected |
| | Blinking | Data sending and receiving |
| Ethernet | Off | Ethernet port not connected |
| | Amber | 10 Mbps connected |
| | Green | 100 Mbps connected |
| | Blinking | Data sending and receiving |
| DI | Off | DI status off |
| | Green | DI status on |
| DO | Off | DO status off |
| | Red | DO status on |
| DIO | Off | DI or DO status off |
| | Green | DI mode and status on |
| | Amber | DO mode and status on |
| AI | Off | AI channel disabled Transmitter not connected when 4-20 mA mode |
| | Green | AI channel enabled |
| RTD | Green | RTD status on |
| | Red | RTD transmitter not connected |
| TC | Green | TC status on |
| | Red | TC transmitter not connected |
| DO Power | Off | External power off or not connected |
| | Red | External power on |

Initial Setup

This chapter describes how to install the ioLogik E2200 series.

The following topics are covered in this chapter:

- ❑ **Hardware Installation**
 - Connecting the Power
 - Grounding the Unit
- ❑ **Software Installation**
- ❑ **Restore Factory Defaults**
- ❑ **Connecting to ioAdmin via Ethernet**
 - Configuring the Host Computer's IP Address
 - Activating ioAdmin and Connecting to the ioLogik
 - Adding More I/O Channels
 - Setting the RS-485 Baudrate
- ❑ **I/O Wiring Diagrams**
- ❑ **Using ioAdmin to Import/Export Configurations**

Hardware Installation

Connecting the Power

Connect the 12 to 36 VDC power line to the ioLogik's terminal block (TB1). If power is properly supplied, the power LED will glow a solid red color.



ATTENTION

Determine the maximum possible current for each power wire and common wire. Observe all electrical codes dictating the maximum current allowable for each wire size. If the current exceeds the maximum rating, the wiring could overheat, causing serious damage to your equipment. For safety reasons, we recommend an average cable size of 22 AWG. However, depending on the current load, you may want to adjust your cable size (the maximum wire size for power connectors is 2 mm).

Grounding the Unit

The ioLogik is equipped with two grounding points, one on the wall mount socket and the other on the DIN-Rail mount. Both grounding points are connected to the same conducting pathway. Connect the ground pin if earth ground is available.

Software Installation

ioAdmin is a Windows utility provided for the configuration and management of ioLogik E2200 products and connected I/O devices. ioAdmin can be used to monitor and configure ioLogik E2200 products from anywhere on the network. Some settings may also be configured by **web console**.

ioAdmin can be downloaded from Moxa's website.

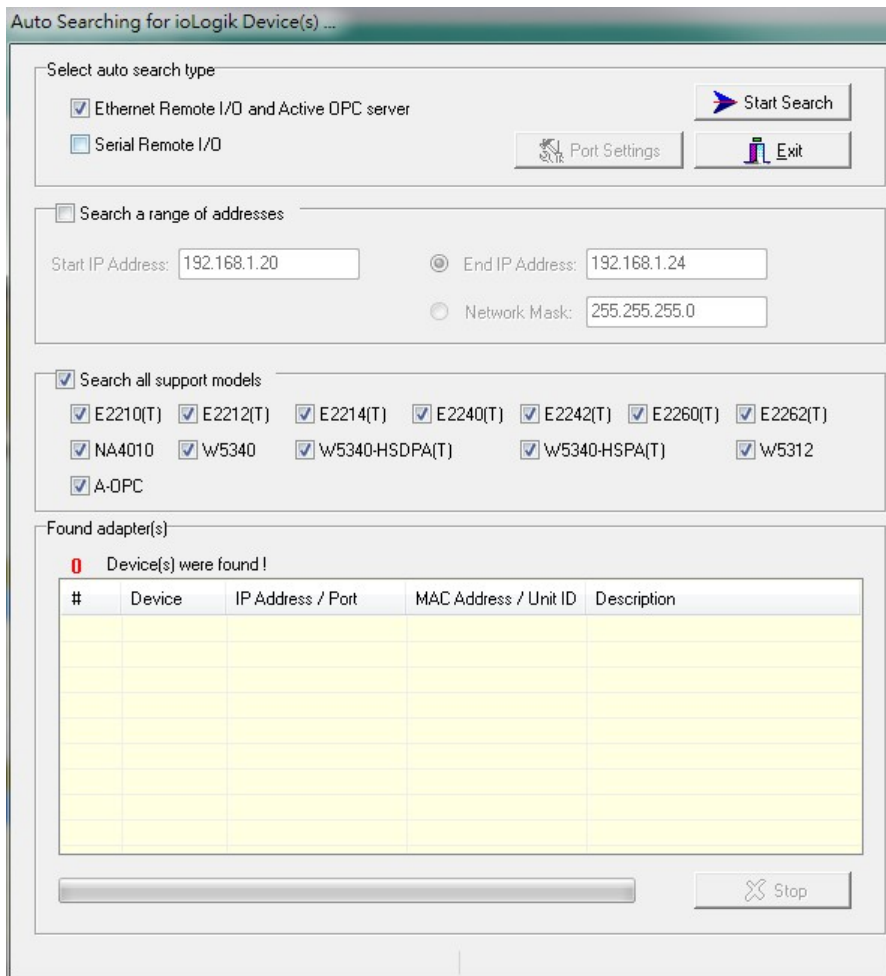
1. Installing ioAdmin from website:

- a. First click on the following link to access the website's search utility:
<http://www.moxa.com/support/search.aspx?type=soft>
- b. When the web page opens, enter the model name of your product in the search box.
- c. Click the model name and navigate to the product page, and then click on Utilities, located in the box titled Software.
- d. Download and then unzip the file. Run **SETUP.EXE** from that location.

The installation program will guide you through the installation process and install the software.

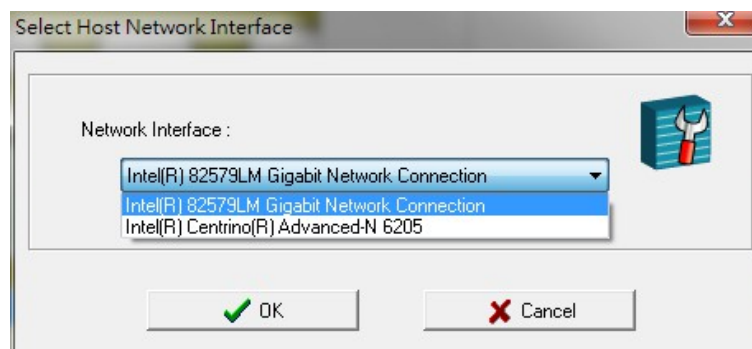
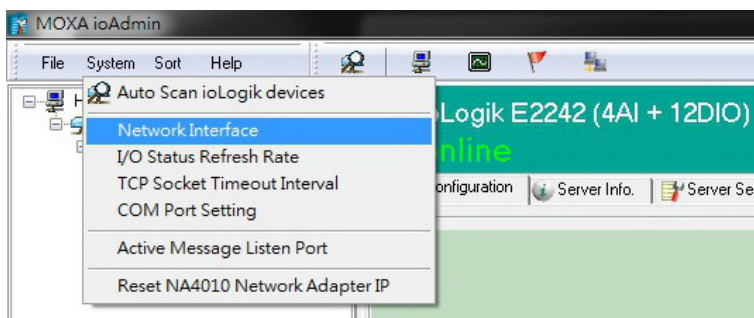
2. Open ioAdmin: After installation is finished, run ioAdmin from the Windows Start menu: **Start → Program Files → MOXA → IO Server → Utility → ioAdmin.**

3. **Search the network for ioLogik:** When ioAdmin is started, it will automatically run the auto search program. You **can also find** the program on the menu bar; select **System → Auto Scan Active ioLogik devices**. A **dialog window will appear**. Click **Start Search** to begin searching for your unit.



NOTE The best approach to setting up a previously configured ioLogik is to reset it to the factory default using the RESET button (see **Chapter 1**). You can then use the ioAdmin utility to configure the ioLogik.

NOTE If the host computer has multiple network interfaces, be sure to select the correct interface before searching.



Restore Factory Defaults

There are three ways to restore the ioLogik to factory default settings.

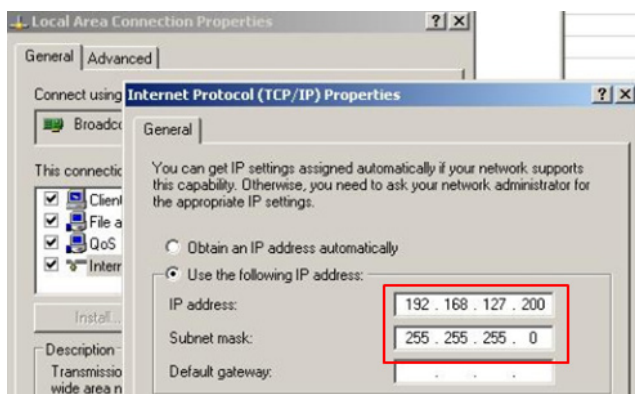
1. Hold the RESET button for 5 seconds.
2. Right-click on the specific ioLogik in the ioAdmin utility and select **Reset to Default**.
3. Select **Load Factory Default** from the web console.

Connecting to ioAdmin via Ethernet

Configuring the Host Computer's IP Address

1. For initial configuration, it is strongly recommended to use a direct connection between the ioLogik E2200 device's RJ45 Ethernet console port and the host computer, rather than remotely over the network. Connect the ioLogik to the host PC with an Ethernet cable.
2. Set the host PC's IP address to **192.168.127.xxx** (where **xxx** can be any number from 001 to 253). In Windows, you can adjust this setting under **Control Panel → Network and Internet**. The default ioLogik device settings are:

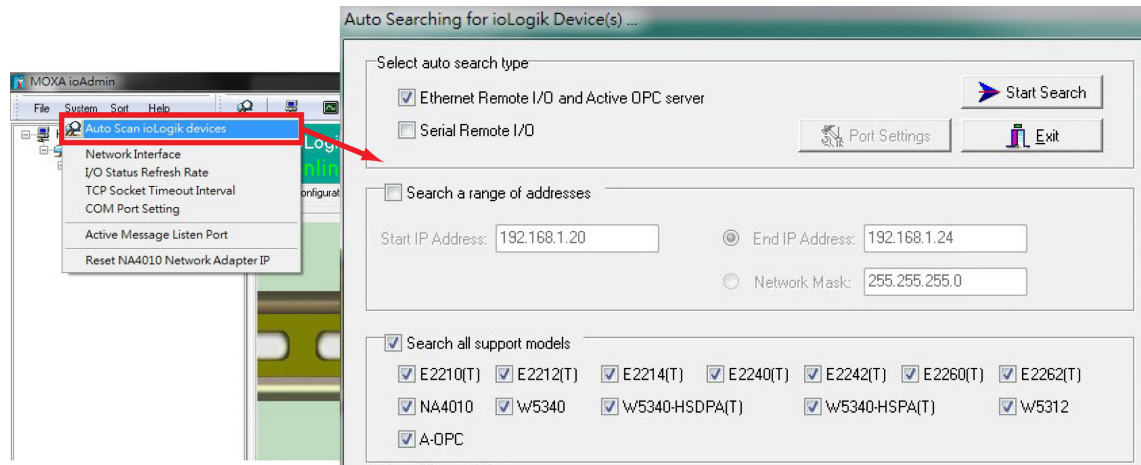
| Default IP Address | Default Netmask | Default Gateway |
|--------------------|-----------------|-----------------|
| 192.168.127.254 | 255.255.255.0 | None |



Example IP address: 192.168.127.200

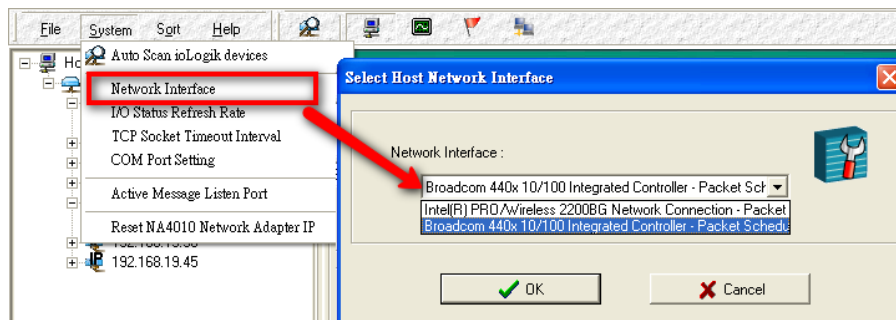
Activating ioAdmin and Connecting to the ioLogik

1. **Open ioAdmin:** Click **Start** → **Program Files** → **MOXA** → **IO Server** → **Utility** → **ioAdmin**.
2. **Search the network for the ioLogik:** When ioAdmin is started, it will automatically run the auto search program. You may also click **System** → **Auto Scan ioLogik device** on the menu bar. A dialog window will appear. Click **Start Search** to begin searching for your unit. Once the ioLogik has been detected, modify the settings as needed for your network environment, and then restart the device.

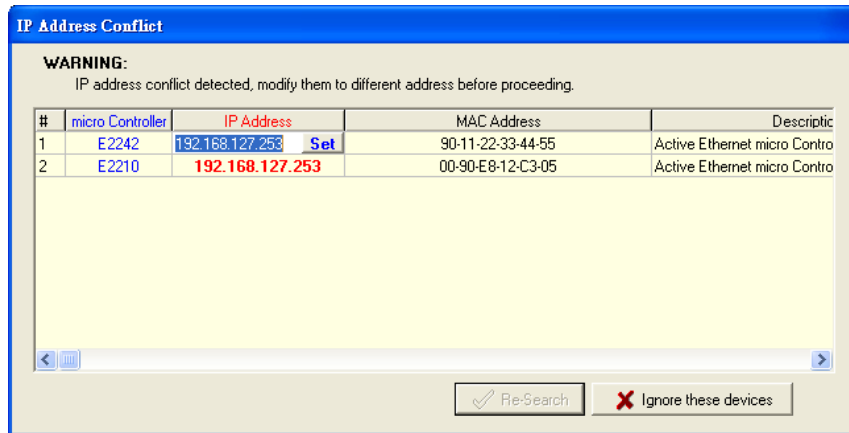


NOTE When setting up a previously configured ioLogik, first restore it to factory default settings by using the RESET button (see **Chapter 1** for details). Then use the ioAdmin utility to configure the ioLogik device.

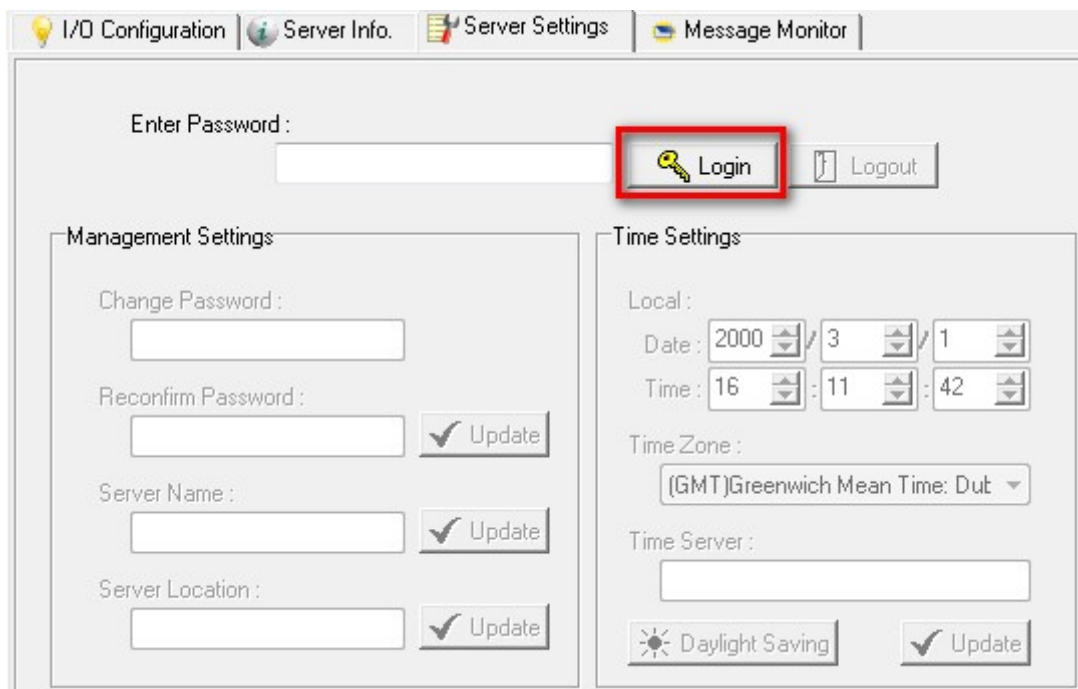
3. If the host computer supports multiple network interfaces, be sure to select the correct interface before searching the network.



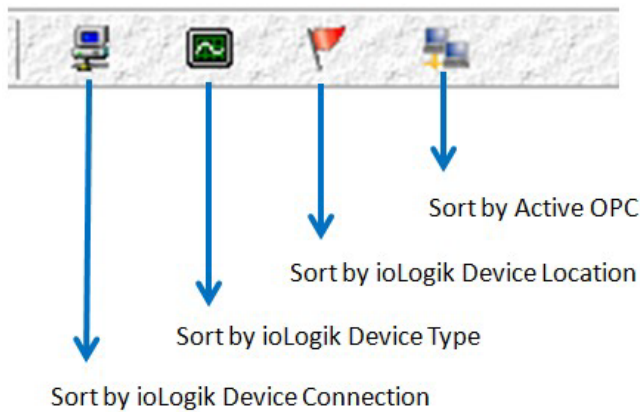
NOTE If multiple ioLogik devices with the same default IP address are installed on the same network, assign a different IP address to each device to avoid IP conflicts. ioAdmin automatically detects IP address conflicts for each device so you can modify conflicting IP addresses in the **IP Address** column, as shown below. Click the **Set** button to reboot the corresponding device with its new IP address, and then click the **Re-Search** button to refresh the list of IP address conflicts detected by ioAdmin.



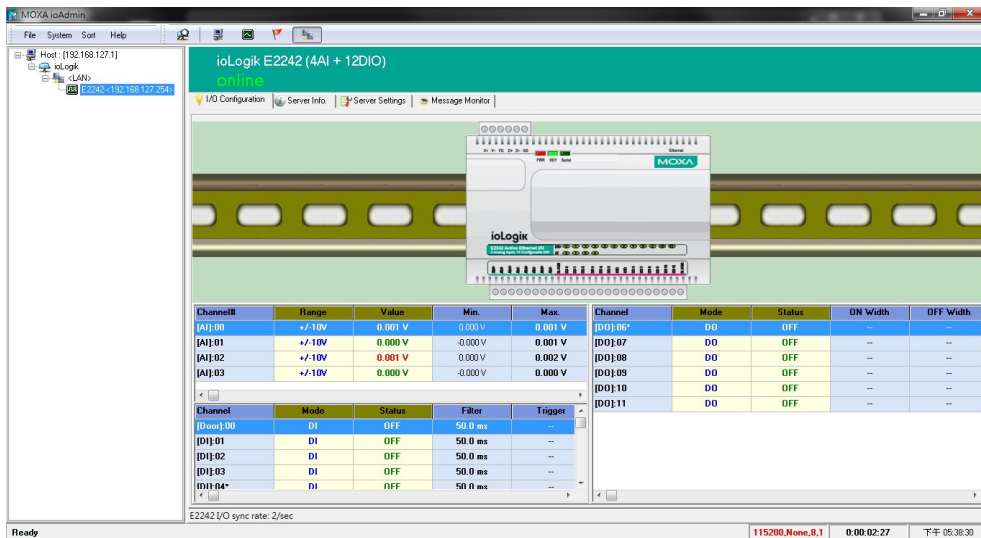
4. **Log in as administrator:** For full access to all configuration options, log in as an administrator from the **Server Settings** panel. This is required whenever you start ioAdmin, or boot up or restart the ioLogik. When you install the ioLogik for the first time, the password will be blank. Simply click **Login** to log in. If a password has already been set, hold down the reset button to clear the password and load factory defaults.



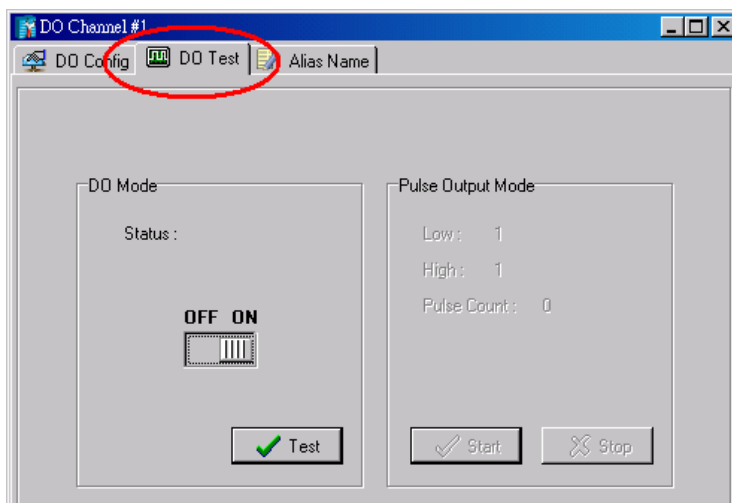
- Monitoring and Testing I/O statuses:** Once your unit has been detected by ioAdmin, you can view the status of all connected I/O modules and devices on the ioAdmin main screen.



NOTE ioAdmin supports four viewing options for the navigation panel. If you select **Sort by Active OPC Server**, the ioLogik will appear in the Active OPC Server group. Simultaneously, the same devices will be shown under the **<LAN>** group if the host computer is connected to the ioLogik’s Ethernet port instead of remotely over the network.



You can test each DO channel by opening the channel’s configuration window and selecting the **Test** tab.



After clicking the **Test** tab, you can see how a channel's status affects or is affected by the attached device. For DO channels, you can set the ON/OFF status or START/STOP pulse output. For DI channels, you can monitor the attached devices' ON/OFF status, or monitor the counter.

You can now use ioAdmin to set up or configure your ioLogik E2200. For additional information on using ioAdmin, see **Chapter 3**.

Adding More I/O Channels

A cost-effective way to add more I/O channels to your ioLogik is to attach an appropriate ioLogik R2140 (Phased Out). The 2 ioLogiks can be snapped together using the RS-485 system bus connector.



ATTENTION

Multiple ioLogik E2200/R2140 units can be snapped together as part of the same RS-485 network. But when connecting the power, be sure to use the following steps in the order below:

1. Remove the cover from the male system bus connector on the first ioLogik's right side panel
2. Remove the cover from the female system bus connector on the second ioLogik's left side panel
3. Insert the first ioLogik's male system bus connector into the second ioLogik's female system bus connector
4. Replace the covers on the exposed system bus connectors
5. Turn on the system power



ATTENTION

A total of 31 additional ioLogik R2140 products can be attached to one ioLogik E2200. The best space-saving arrangement is to use the TB1 terminal block for the cascaded RS-485 connections, instead of using the system bus.



ATTENTION

All I/O channels of the ioLogik E2200+R2140 system can be polled by a remote host PC, but Click&Go logic can only be used with the ioLogik E2200 series. Currently, Click&Go local control logic is not supported by the ioLogik R2140 series.



ATTENTION

When using the RS-485 cascading interface or system bus to add more I/O channels or to connect to RS-485 Modbus devices, the ioLogik E2200 should always have an RS-485 Unit ID of 1. The Unit ID of the attached ioLogik R2140 or other devices should always be 2 or more, with an upper limit of 99. Although the ioLogik E2200 series supports Unit IDs up to 247 for Modbus devices, the highest Unit ID on the ioLogik R2140 is 99.

Setting the RS-485 Baudrate

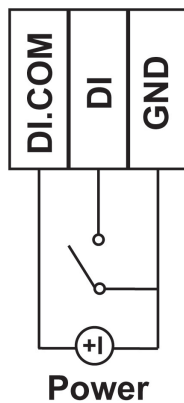
The RS-485 port on the ioLogik E2200 series is reserved for connecting to another RS-485 I/O device. The RS-485 port can run Modbus/RTU or I/O command sets. The baudrate is set by a physical dial on the top of the ioLogik. The default settings are: baudrate = 115200; parity check = N; data bits = 8; and stop bit = 1.

| | | |
|--|---|---|
| | Baudrate for RS-485 (parameters are N, 8, 1) | Dial setting and corresponding baudrate: |
| | | 0:115200 1:57600 2:38400 3:19200 4:9600 5:4800 6:2400 7:1200 |

Remember to restart the ioLogik after making any changes to the RS-485 baudrate.

I/O Wiring Diagrams

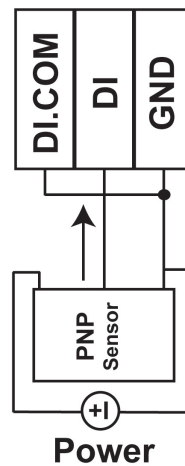
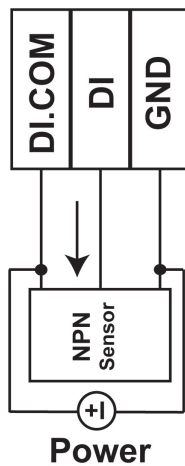
DI Dry Contact



DI Wet Contact

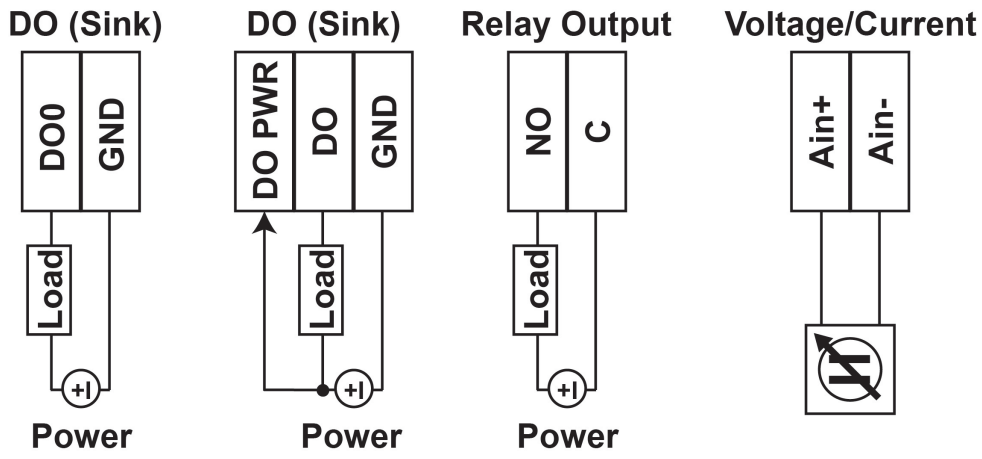
Source

Sink

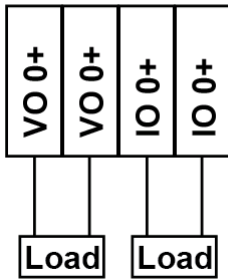


| Contact Type | Power Source Requirement |
|--------------------|---|
| Dry Contact | A dry Contact does not need to be connected to a power source to function properly.* |
| Wet Contact | A wet Contact must be connected to a power source to function properly. |

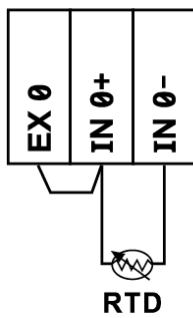
**Note: Some users connect dry contacts to a power source for added stability. Depending on your application, you can decide whether or not to connect your dry contacts to power sources.*



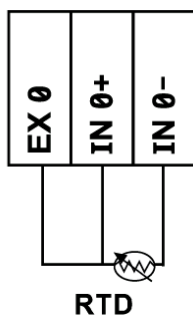
0-10V 4-20 mA



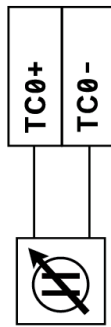
2-Wire RTD



3-Wire RTD

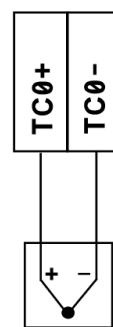


Voltage



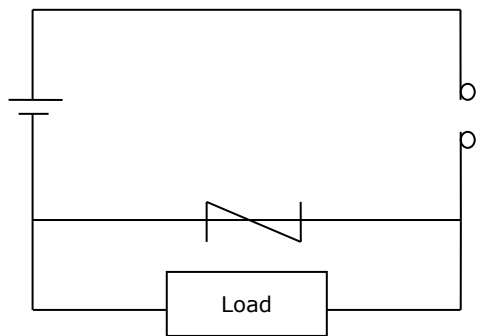
+/- 78.126mV
+/- 39.062mV
+/- 19.532mV

Thermocouple



J-type sensor
K-type sensor
T-type sensor
E-type sensor
R-type sensor
S-type sensor
B-type sensor
N-type sensor

NOTE It is strongly recommended to have a contact protection circuit for the relay output. A varistor can serve as a contact protection circuit where the parallel circuit connects with the load.



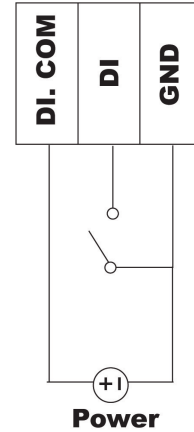
NOTE A "load" in a circuit schematic is a component or portion of the circuit that consumes electric power. For the diagrams shown in this document, "load" refers to the devices or systems connected to the remote I/O unit.



ATTENTION—Dry Contacts

When connecting an I/O device to the ioLogik's dry contacts, connect DI.COM to the power of the external sensor to avoid affecting other channels. The DI.COM input power should be between 12 to 36 VDC.

DI Dry Contact



ATTENTION—DIO Channels

Sensor types are grouped, with DIO-0 to DIO-5 forming one group and DIO-6- to DIO-11 forming another group. If an NPN sensor is connected to DI-0, then only NPN sensors can be connected to the other DI channels in the group (i.e., DIO-4 and DIO-5). Likewise, if a PNP sensor is connected to DIO-6, then only PNP sensors can be connected to the other DI channels in the group (i.e., DIO-10 and DIO-11).



ATTENTION—TC Channels

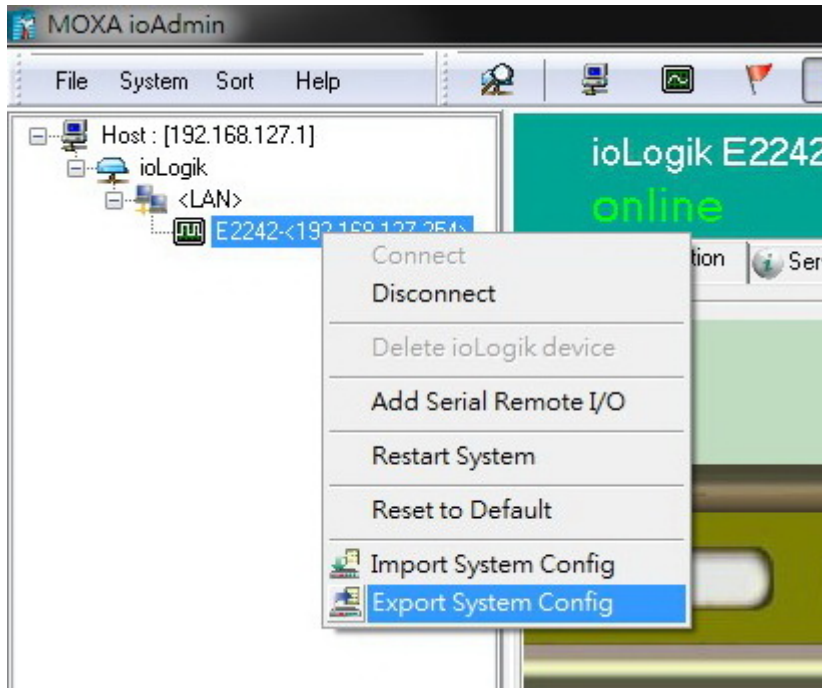
When extending the wiring distance of a TC sensor, use the corresponding TC-type extension wire to ensure the correct temperature reading.

Using ioAdmin to Import/Export Configurations

To import or export a system configuration right click on the I/O model name and then selection **Import System Config** or **Export System Config**. You must be logged in as an administrator to use this command.

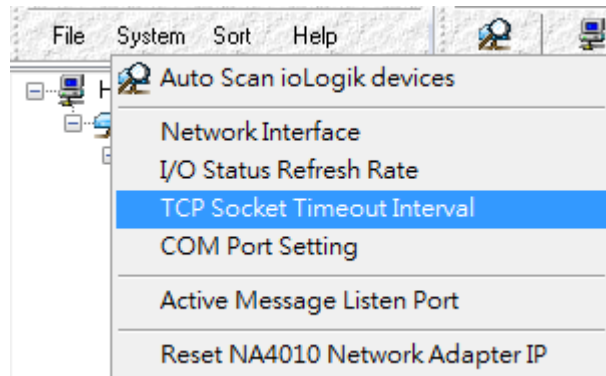
Export System Config

Select this command to export the selected ioLogik's configuration to a text file. We recommend using this method to back up your configuration after you have finished configuring the ioLogik for your application.



ATTENTION

Since there are major functional differences between firmware versions, exporting the configuration file requires a longer processing time. **Adjust the TCP Socket Timeout Interval to 30 seconds** when using ioAdmin 3.10 or above, especially if earlier versions of ioAdmin have been installed and then removed.



Import System Config

Select this command to load a configuration for the selected ioLogik from a configuration text file. The new configuration will not take effect until the ioLogik has been restarted. This command can be used to restore a configuration after loading the factory defaults, or to duplicate a configuration to multiple ioLogik units.

Using ioAdmin

In this chapter, we explain how to use ioAdmin to configure your ioLogik product.

The following topics are covered in this chapter:

- ❑ **System Requirements**

- ❑ **Features of ioAdmin**

- ❑ **ioAdmin Overview**

- Main Screen Overview
- Title
- Menu Bar
- Quick Links
- Navigation Panel
- Main Window
- Sync Rate Status
- Status Bar
- ioAdmin Administrator Functions
- I/O Configuration Tab (Administrator)
- Server Settings Tab (Administrator)
- Network Tab
- Firmware Update Tab
- Watchdog Tab
- Click&Go Logic Tab
- Active Tags Tab
- SNMP Settings Tab
- Message Monitor Panel (General)

- ❑ **Server Context Menu**

- ❑ **Using ioEventLog**

- Installing ioEventLog
- Basic Functions
- Configuration
- Checking Connected Devices
- Opening Log Files
- Clearing the Log

System Requirements

The ioLogik E2200 series device can be managed and configured by Ethernet with the **ioAdmin** Windows utility. ioAdmin's graphical user interface provides easy access to all status information and settings. ioAdmin can also be used to configure Click&Go rules to handle front-end events.

| Hardware Requirements | |
|-----------------------|--|
| CPU | Intel Pentium (Pentium 4 and above) |
| RAM | 512 MB (1024 MB recommended) |
| Network Interface | 10/100Mb Ethernet |
| Software Requirements | |
| Operating System | Microsoft Windows 2000, XP or later |
| Editor(Not necessary) | Microsoft Office 2003 (Access 2003) or later |

Features of ioAdmin

Remote management

Use ioAdmin to perform the following task over an Ethernet network:

- Search and configure multiple ioLogiks
- Monitor and control I/O statuses
- Use active message monitoring
- Configure Click&Go local control logic
- Upgrade the firmware
- Restart the ioLogik
- Restore factory default settings

On-line Wiring Guide

For added convenience, a wiring guide is available inside the ioAdmin utility to save time when troubleshooting or expanding a network.

Configuration File

ioAdmin helps you save all ioLogik configurations as a file. The file is viewable in text format and can be used as a:

- Record or backup of your configuration
- Template for configuring other ioLogik units
- Quick reference guide for configuring Modbus drivers in a SCADA system

The file includes the following information:

- File name, date, and time
- Model information
- System configuration
- I/O Modbus address

Device Management List

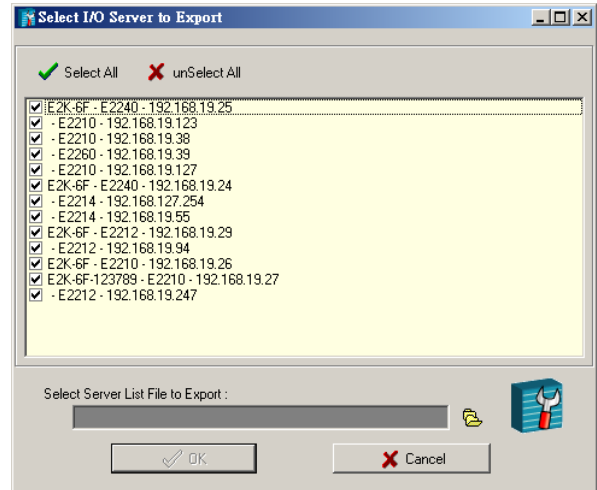
ioAdmin can import and export a list of ioLogik devices that are being managed. This file can make it easier to manage all devices on the network, and includes the following information:

- Device name
- Module
- IP address
- Unit ID

Server Management List

ioAdmin can import and export a list of ioLogik units that are being managed. This file can make it easier to manage all devices on the network, and includes the following information:

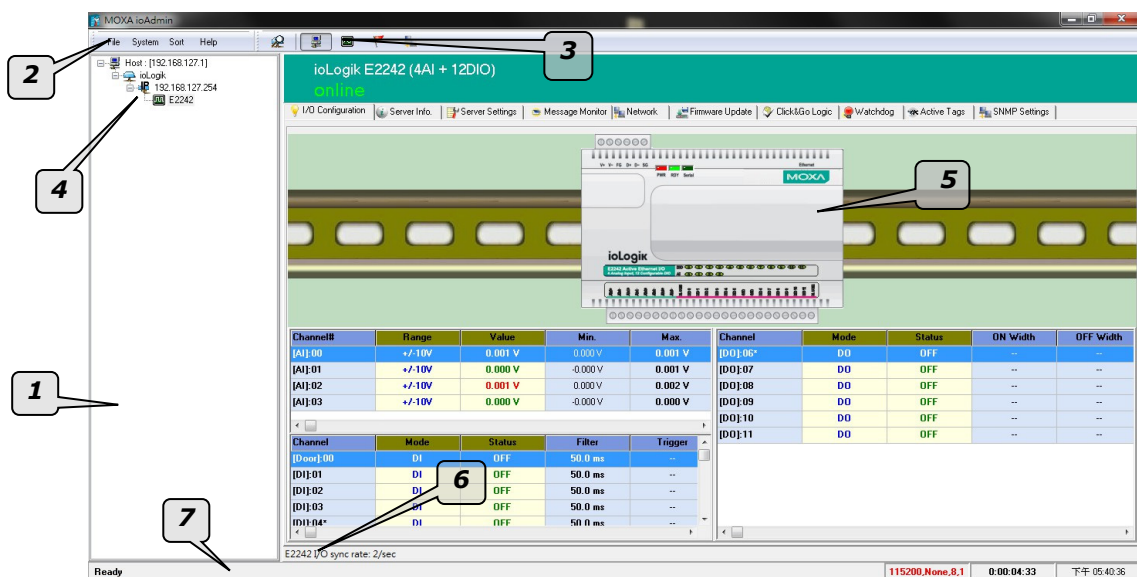
- Server name
- Module
- IP address
- Unit ID



ioAdmin Overview

Main Screen Overview

The main screen of the ioAdmin utility defaults to the **I/O Configuration** tab, which displays a figure of your ioLogik device with the status of each of its I/O channels. The other tabs on the main screen take you to server and network settings, and further functions are available when you log on to the ioLogik. Note that configuration options are not available unless you log on as an administrator.



| ioAdmin Main Screen | |
|---------------------|-----------------------------------|
| 1. | Title |
| 2. | Menu bar |
| 3. | Quick link |
| 4. | Navigation panel |
| 5. | Main window |
| 6. | Sync. rate status |
| 7. | Status bar |

Title

The **Title** shows you which program is opened. In this case, it indicates that Moxa ioAdmin is running.

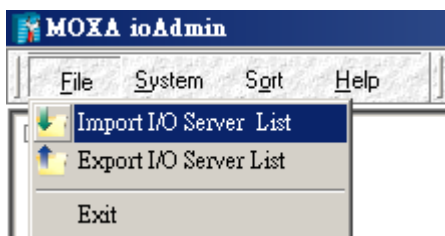
Menu Bar

The Menu bar has four items:

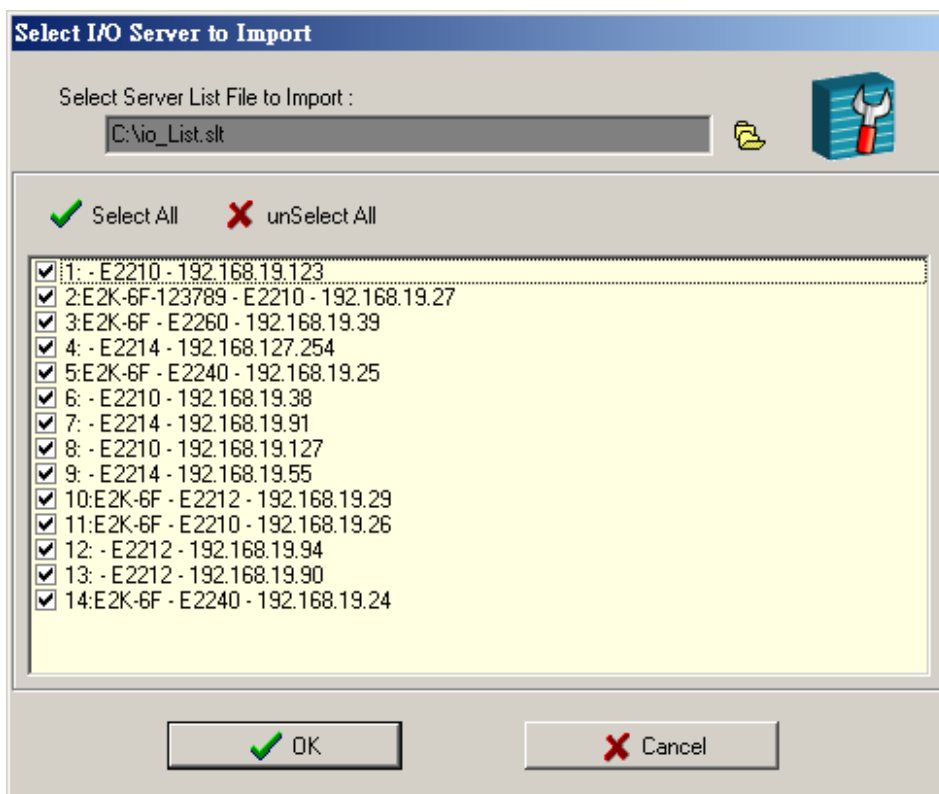
1. [File](#)
2. [System](#)
3. [Sort](#)
4. [Help](#)

File

From the **File** menu, you can export the list of ioLogiks currently displayed in the navigation panel. You can also import a list into ioAdmin.



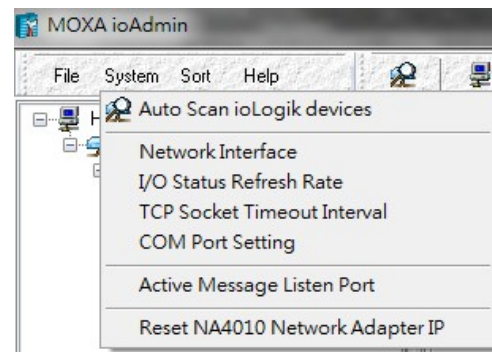
When importing/exporting a device list, you will be prompted to select which ioLogik on the list needs to be imported or exported. When a popup window appears, click the "folder" icon to select/key-in the file name to save/import a specific file.



The file will have an .SLT extension and can be opened as a text file. The server list will provide the basic information for each server, such as **Device Name**, **Model**, **IP address**, and **Unit ID**.

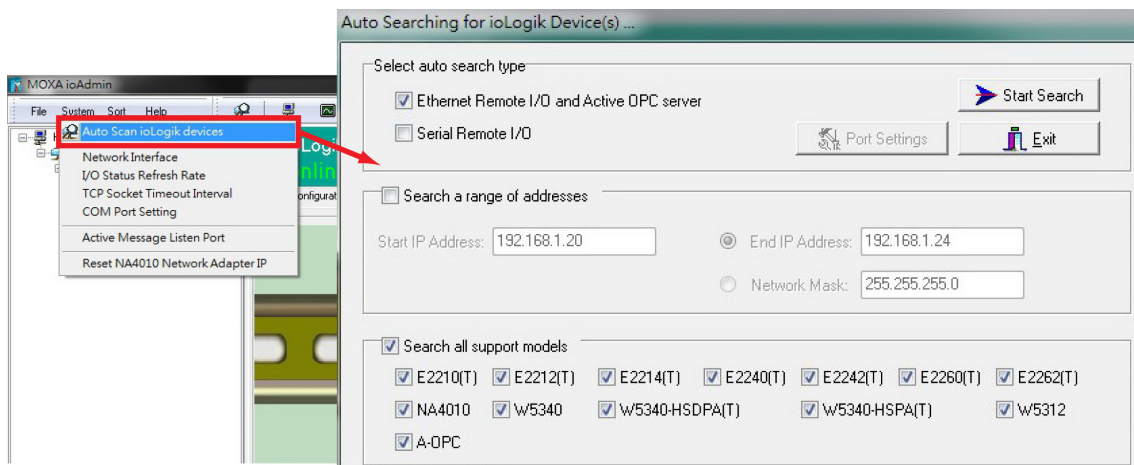
System

Several operations can be accessed from the **System** menu.



Auto Scan ioLogik Devices

The **Auto Scan ioLogik Devices** function searches for ioLogiks on the network automatically. When connecting for the first time, or when recovering from a network disconnection, you can use this command to find any ioLogik that is connected to the physical network.



You can search for ioLogik devices by type, IP address range, or model name. Click **Start Search** to start searching and the search results will be shown at the bottom of the window.

Select auto search type

Search for an ioLogik device by whether it is an **Smart Ethernet Remote I/O Device** or **RS-232/485 remote I/O**.

Search a range of addresses

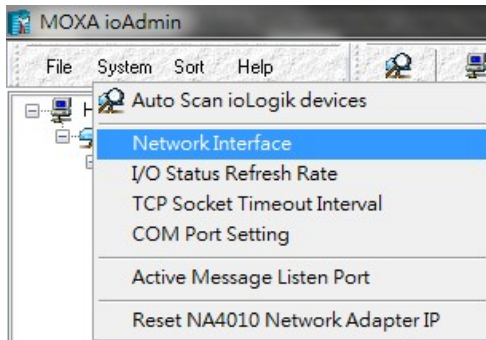
Search for ioLogik devices within a range of IP address addresses by defining a starting IP address and an ending IP address, or by using the netmask.

Search all support models

Select the specific model number(s) of the ioLogik devices you wish to search for.

Network Interface

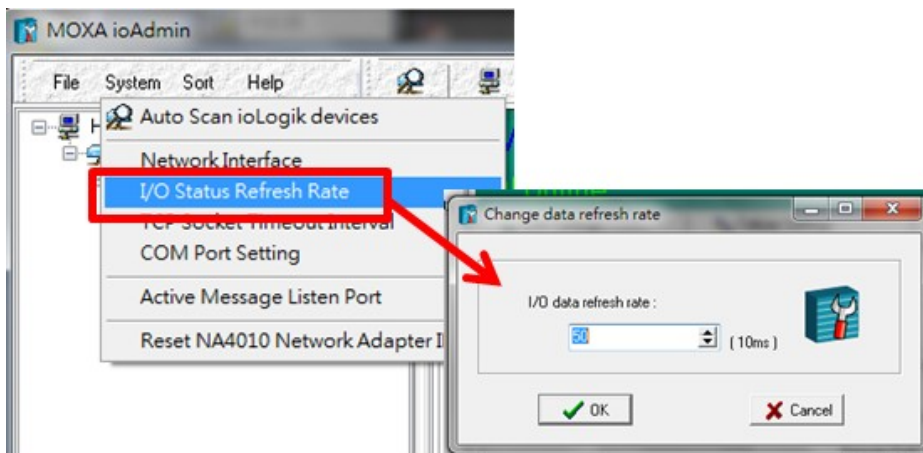
Network Interface allows you to select a network interface to use (if the PC has multiple network adaptors installed). The default network interface will be the same as the Windows setting. Make sure the interface is correct when connecting to the ioLogik device; otherwise, no devices will be found.



I/O Status Refresh Rate

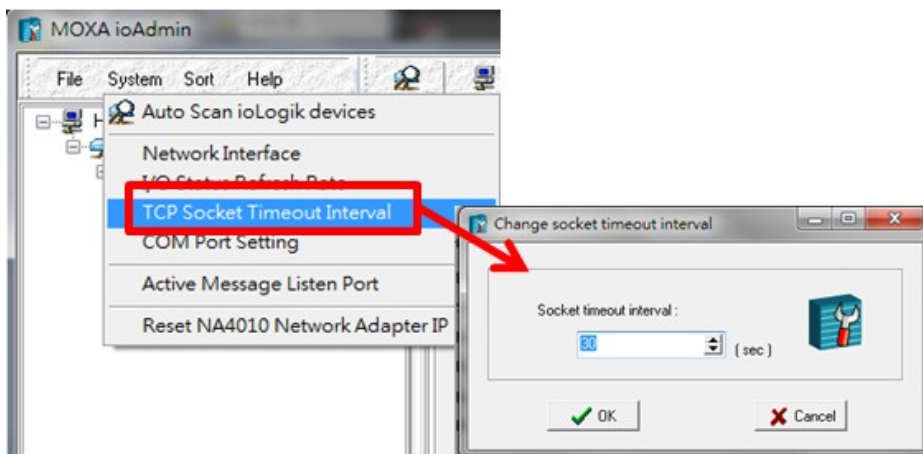
This operation is used to adjust how often the ioLogik is polled for device status by the ioAdmin utility. The current rate is displayed on the status bar at the bottom of the window.

Note: The higher sync rates result in higher loads on the network.



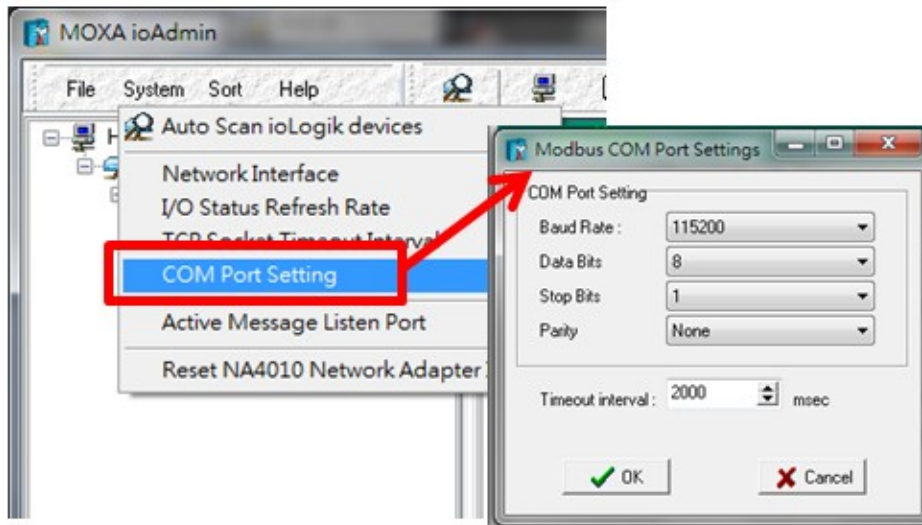
TCP Socket Timeout Interval

This operation allows you to select the preferred timeout value for TCP socket communication. When the ioLogik's E2200 connection to the server exceeds a specified time period the device will automatically release its modbus/TCP connection to the server, to free up the port for the next connection (default: 30 seconds).



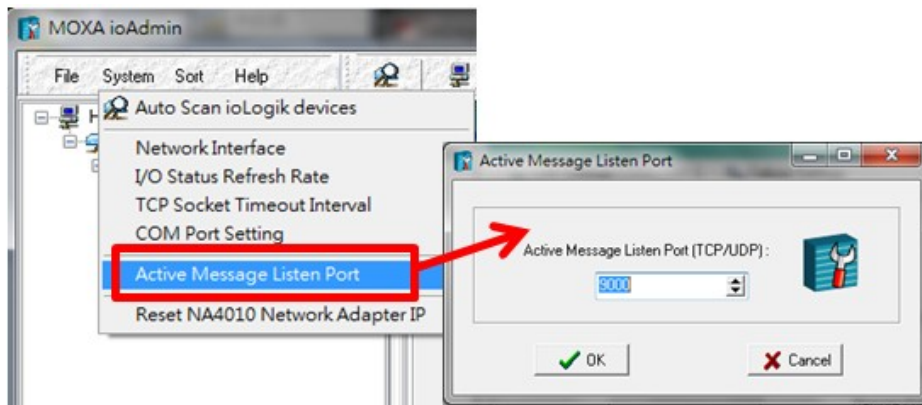
COM Port Setting

This operation is used to set the default parameters for the ioAdmin utility to establish a Modbus connection, such as baudrate, data bits, and timeout interval. For most applications, this will involve connecting to ioLogik R-series devices.



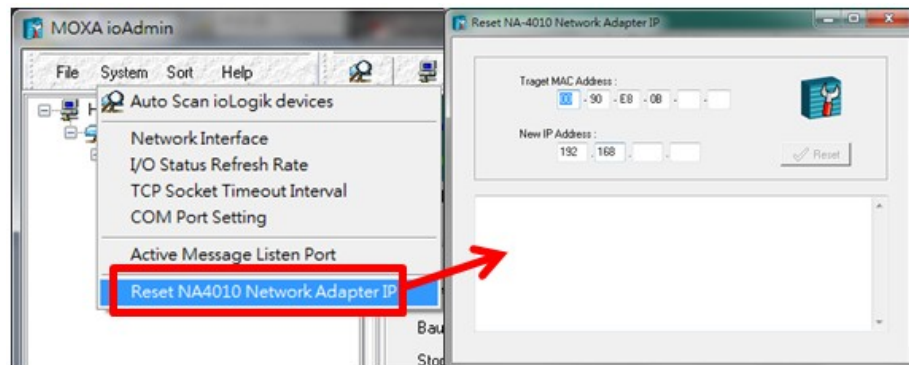
Active Message Listen Port

This operation specifies the port number to use for Active Messages. If your network uses a firewall, you can coordinate this setting with your firewall settings to ensure that active messages get through.



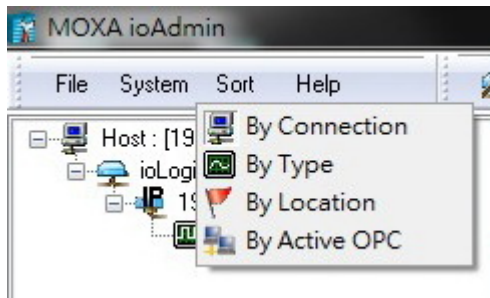
Reset NA4010 Network Adaptor IP

This operation is used to re-assign an IP address to the NA-4010 network as reported by the ioLogik W5300 series adaptor, for ioLogik 4000 systems.



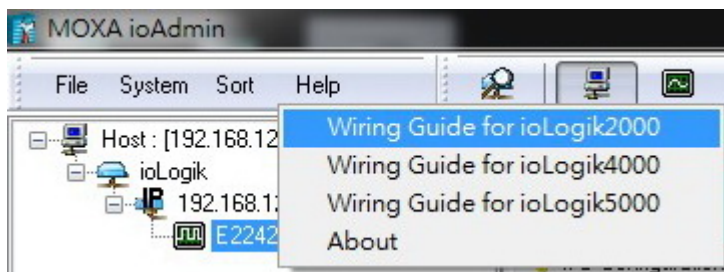
Sort

The **Sort** menu allows the Devices list in the navigation panel to be sorted by connection, model, location, or Active OPC.



Help

In the **Help** menu, you can view wiring guides and information about ioAdmin.

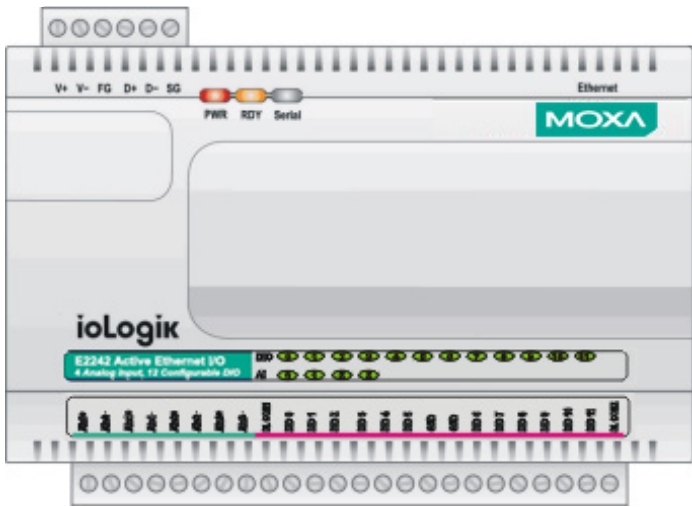


Wiring Guides


ioAdmin provides a wiring guide for the ioLogik E2200 series. You can access the wiring guide by right-clicking the ioLogik figure in the I/O Configuration tab. Select "Wiring Guide" in the submenu to open a help file showing the unit's wiring information and electrical characteristics (or refer to cable wiring).

E2242/E2242-T Active Ethernet micro controller, 4 Analog Inputs and 12 Configurable DIO

System Overview




Ethernet pin assignment



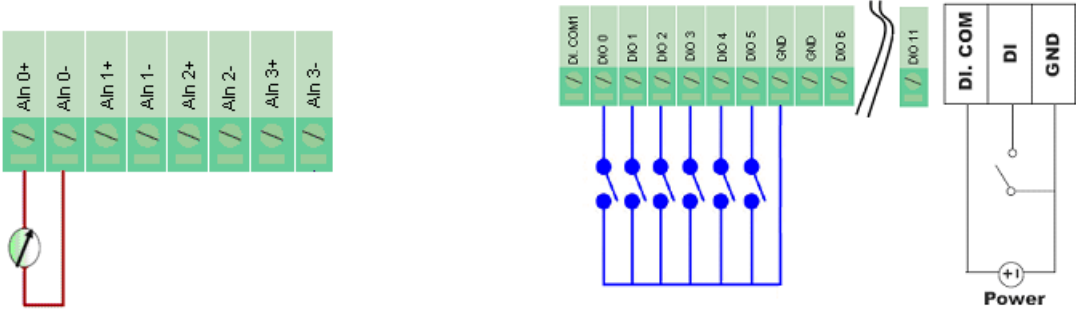
- 1 TX+
- 2 TX-
- 3 RX+
- 6 RX-

RS-485 Communication Settings



- 0: 115200ps, N81
- 1: 57600bps, N81
- 2: 38400bps, N81
- 3: 19200bps, N81
- 4: 9600bps, N81
- 5: 4800bps, N81
- 6: 2400bps, N81
- 7: 1200bps, N81

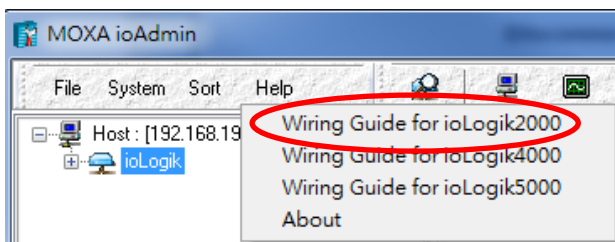
Wiring Examples:



(1) Analog Input

(2) Digital Input (Dry Contact)

You can also access the On-line Wiring Guide through the Help menu on the menu bar.



Quick Links

Quick Links toolbar contains a collection of commonly used functions, including the **Search** and the **Sort** functions.

Auto Scan ioLogik Devices



This icon provides a direct link to start running the **Auto Scan ioLogik Devices** function.

Sorting Methods



These icons allow you to sort the ioLogik devices viewed in the Navigation Panel according to the following criteria:

| Icon | Function Name | Navigation Panel View |
|------|-----------------------------------|-----------------------|
| | Sort by ioLogik Device Connection | |
| | Sort by ioLogik Device Type | |
| | Sort by ioLogik Device Location | |
| | Sort by Active OPC Server | |

NOTE The default location is **Empty**. If you do not specify the location for the ioLogik E2200, the navigation panel will group all **Empty** locations together.

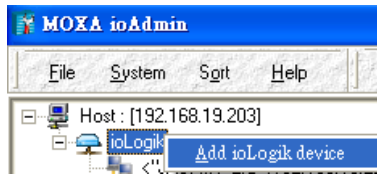
Navigation Panel

The **Navigation Panel** shows an overview of the ioLogik devices on the network as defined by the sorting method. The default sorting view is **By Connection**. You can choose a different sorting method by clicking on a different quick link button. The Navigation Panel also includes additional functions, such as **Connect** and **Disconnect**. More advanced functions require the administrator’s password.

Access the function menu by right-clicking on the ioLogik model name in the navigation panel. The menu lists both basic functions and advanced functions:

Basic Functions: Add, Connect, and Disconnect

Add ioLogik ioLogik device: Select ioLogik tag and right click the tag. Select the "Add ioLogik device" command to add an ioLogik device or Active OPC server manually.

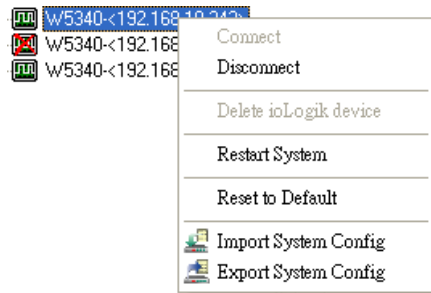


Connect: Select the "Connect" command to try connecting over the network to the selected ioLogik.

Disconnect: Select the "Disconnect" command to drop the network connection with the selected ioLogik.

Advanced Functions: Delete, Restart, Reset, Import/Export Config File

You must be logged in as administrator to use these commands.



Delete ioLogik device: Select this command to remove the selected ioLogik.

Note: The target must be disconnected first to use this command.

Restart System: Select this command to restart the selected ioLogik.

Reset to Default: Select this command to reset all settings on the selected ioLogik, including console password, to factory default values.

Export System Config: Select this command to export the selected ioLogik's configuration to a text file. We strongly recommend that you use this method to back up your configuration after you have finished configuring the ioLogik for your application.

Import System Config: Select this command to load a configuration for the selected ioLogik from a configuration text file. The new configuration will not take effect until the ioLogik has been restarted. This command can be used to restore a configuration after loading the factory defaults, or to duplicate a configuration to multiple ioLogik units.

```
ioLogik W5340 Network I/O Server Configuration
=====
[System Information]
Date: 2009/02/22
Time: 17:34:04
Click&Go= V2.0
MOS= U3.2.26

[1. Model]
-----
MOD_TYPE=W5340 - Active GPRS I/O Server (8DIO + 4AI + 2Relay)
MOD_LOC=
MOD_NAME=

[2. I/O Configurations]
-----
DI00=0,(DI),          DI00_FILTER=100,(50.000ms)
DI01=0,(DI),          DI01_FILTER=100,(50.000ms)
DI02=0,(DI),          DI02_FILTER=100,(50.000ms)
DI03=0,(DI),          DI03_FILTER=100,(50.000ms)

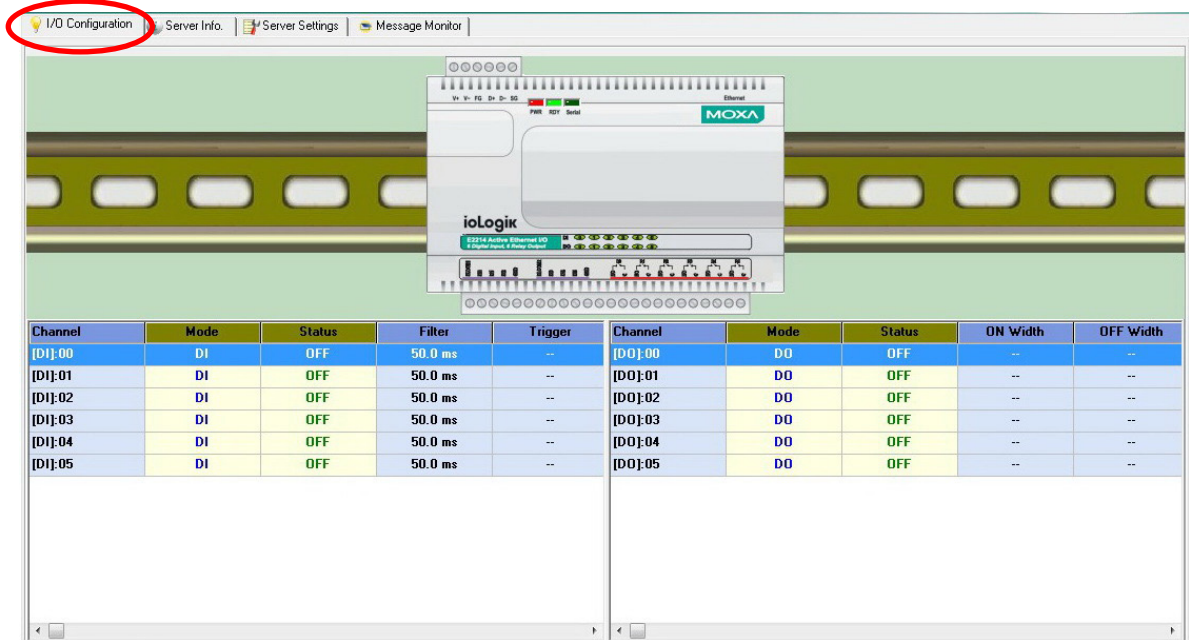
DO04=0,(DO),          DO04_PWN=0,(OFF),          DO04_SAFE=0,(OFF)
DO05=0,(DO),          DO05_PWN=0,(OFF),          DO05_SAFE=0,(OFF)
DO06=0,(DO),          DO06_PWN=0,(OFF),          DO06_SAFE=0,(OFF)
DO07=0,(DO),          DO07_PWN=0,(OFF),          DO07_SAFE=0,(OFF)

Relay00=1,(Pulse),    Relay00_PWN=0,(Stop),    Relay00_SAFE=0,(Stop),    Relay00_LOW=1,(1500.000ms),    Relay00_HIGH=1,(1500.000ms)
Relay01=0,(DO),      Relay01_PWN=0,(OFF),    Relay01_SAFE=1,(On)
```


Main Window

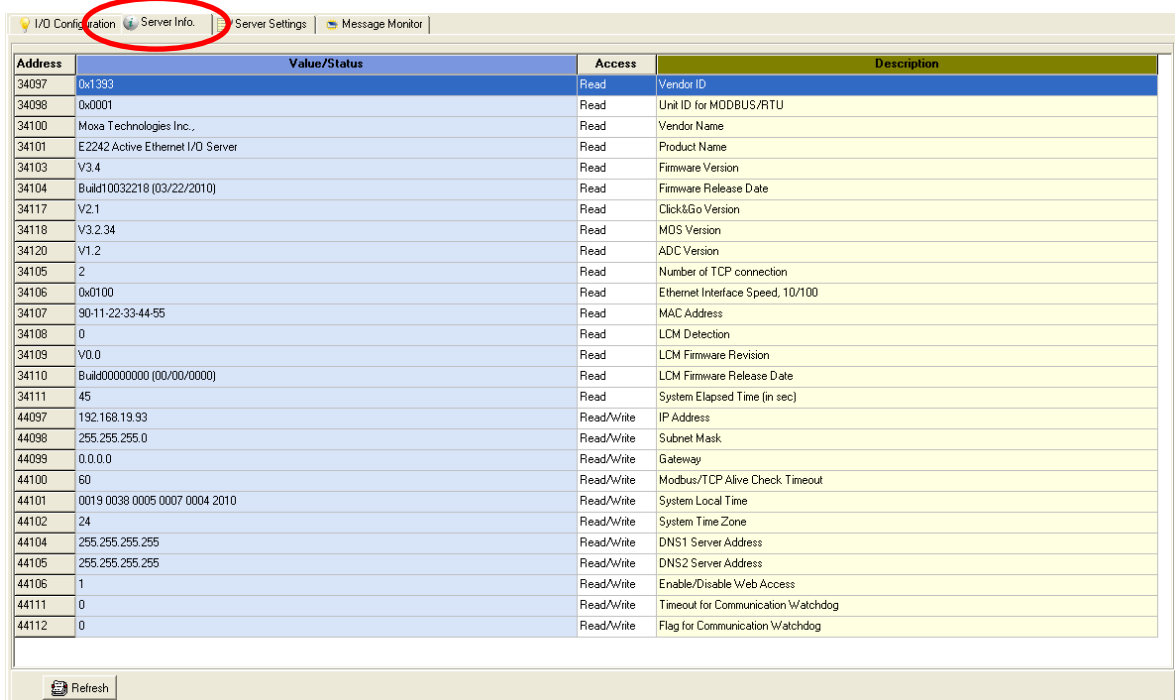
I/O Configuration Tab (General)

The **I/O Configuration** tab shows the status of every I/O channel. This is the default tab when you first open ioAdmin. Input channels are listed on the left and output channels are listed on the right.



Server Info Tab

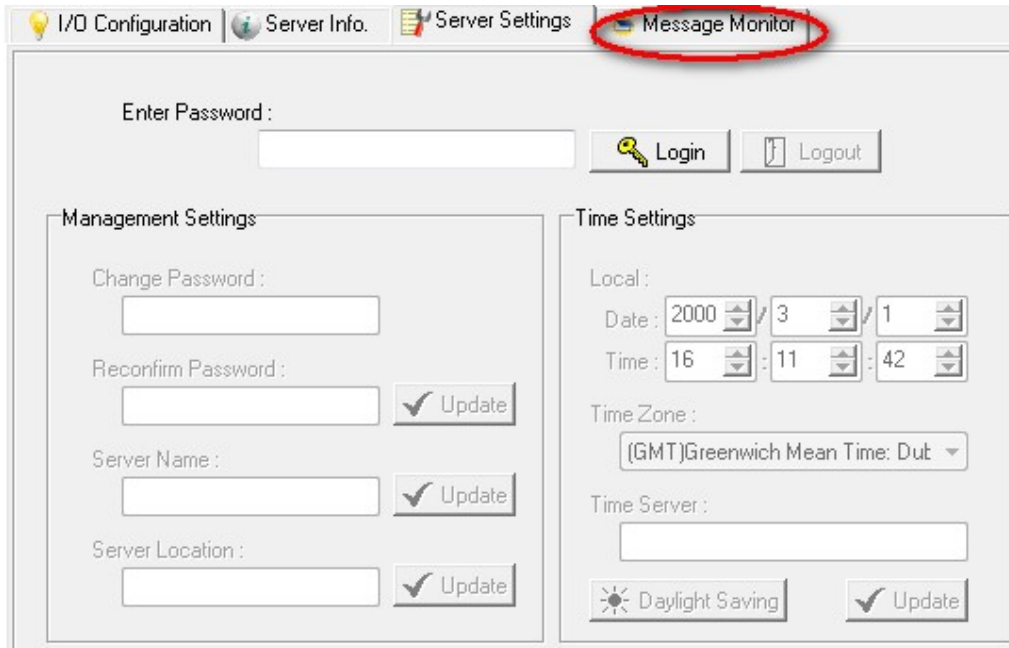
Server information, such as firmware version, is displayed in the **Server Info** tab.



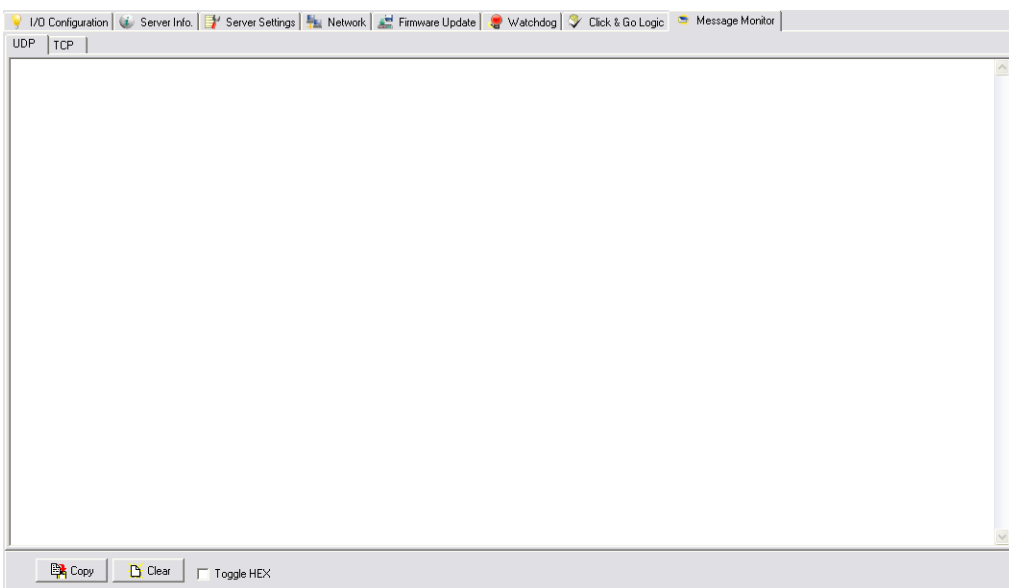
Server Settings Tab (General)

The **Server Settings** tab is where you log in as an ioAdmin administrator. This is required in order to gain access to the ioLogik configuration options. If a password has not been configured, simply click **Login** and leave the **Password** entry field blank. Refer to the ioAdmin Administrator Functions section later on in this chapter for details.

Message Monitor Tab



The **Message Monitor** tab will display any TCP/UDP Active Messages reported by the ioLogik E2200 series. When you install the unit for the first time, the ruleset will not have been defined yet, so there will be no messages in the Message Monitor Tab. When a ruleset has been defined and activated, any TCP/UDP messages that have been triggered by sensor events will be shown in the Message Monitor tab. Please refer to Chapter 5 for information on how to define rules for active I/O messaging.



Messages can be displayed in ASCII or in HEX. To display messages in HEX, make sure that "Toggle HEX" is checked.

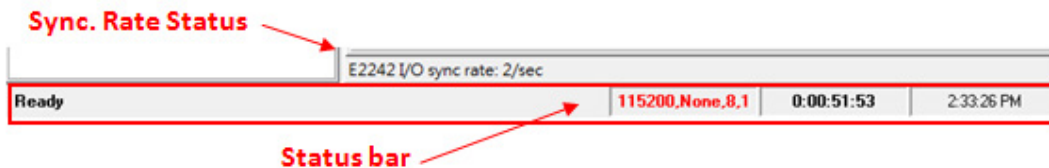
Sync Rate Status

The current sync rate is displayed on the bar at the bottom of the window. The number shows how often the ioLogik is polled for device status from the ioAdmin utility. The rate can be adjusted by clicking **Menu Bar** → **System** → **I/O Status Refresh Rate**

NOTE The higher sync rates result in higher loads on the network.

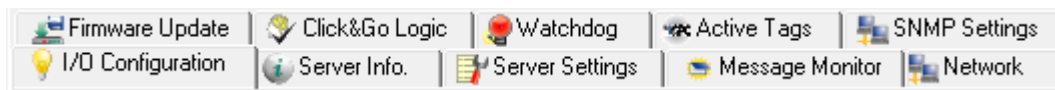
Status Bar

The status bar shows ioAdmin status information, such as program ready, searching ioLogik I/O, time, etc.



ioAdmin Administrator Functions

For full access to all configuration options, log in as an administrator in the Server Settings tab. This is required whenever you start up ioAdmin or boot up/restart the ioLogik. When you install the ioLogik for the first time, the password will be blank and you can simply click **Login**. Additional functions will be available after logging in, including the following new tabs:



When making configuration changes, you will need to click **Update** or **Apply** to save the changes. Some changes will require that the unit be restarted in order to take effect.

1. [I/O Configuration](#)
2. [Server Setting \(Admin\)](#)
3. [Network](#)
4. [Firmware Update](#)
5. [Click&Go Logic](#)
6. [Watchdog](#)
7. [Active Tag](#)
8. [SNMP Setting](#)
9. [Message Monitor](#)

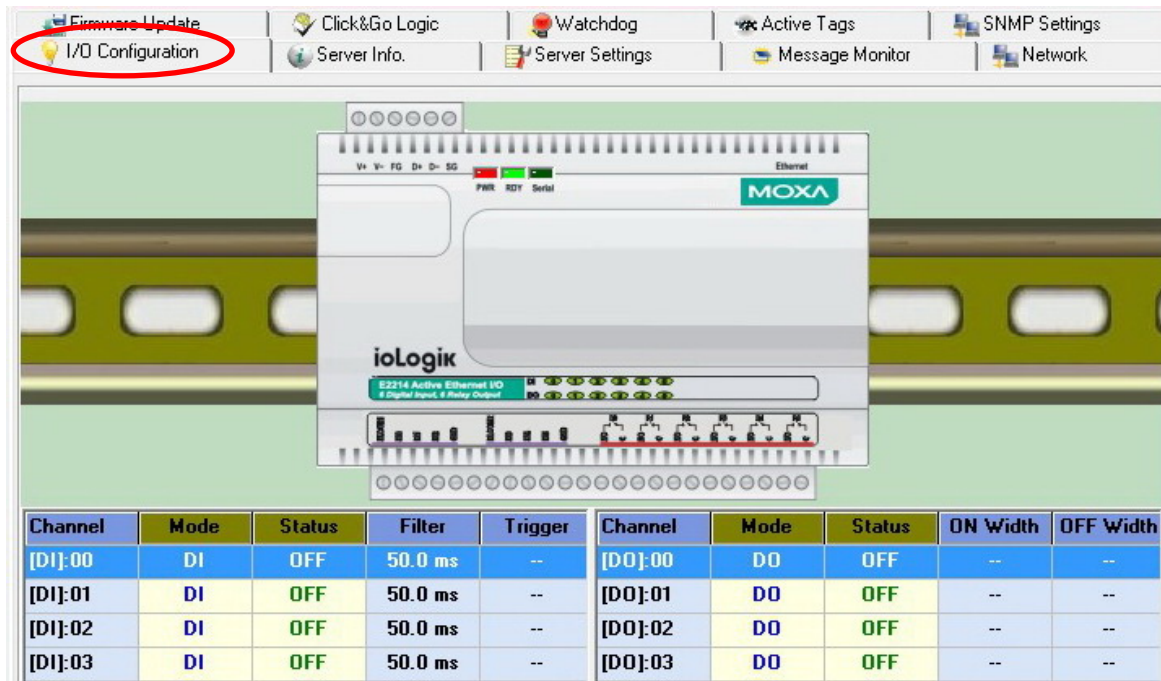


ATTENTION

You **MUST** log in to access administrator functions, including Network, Communication Watchdog Timer, and Firmware Update tabs. If you forget the password, hold down the reset button to clear the password and load factory defaults. **This will result in the loss of all configuration settings and your Click&Go logic rules that have already been configured.**

I/O Configuration Tab (Administrator)

When logged in as an administrator, double-click on a channel in the **I/O Configuration** tab to configure that channel's settings. A window will open with configuration options for that channel. After configuring the channel as desired, click **Apply** to implement the new settings.



1. [Configuring Analog Input Channels](#)
2. [Configuring Analog Output Channels](#)
3. [Configuring DIO Channels](#)
4. [Configuring Digital Input and Event Counter Channels](#)
5. [Configuring Digital Output and Relay output Channels](#)
6. [Relay Count Monitoring](#)
7. [Testing DI and DO Channels](#)
8. [Configuring RTD Channels](#)
9. [Configuring TC Channels](#)

NOTE To show or hide the image of the ioLogik device, right-click on the ioAdmin window. Selecting **Horizontal View** from the dropdown menu will show the ioLogik's picture, whereas selecting **Vertical View** will hide the image.

Configuring Analog Input Channels

The ioLogik analog input channels can be configured individually, or you can set all channels at the same time by selecting the **Apply to all channels** checkbox.

The screenshot shows the 'AI Config' dialog box. The 'Enable Channel' checkbox is checked. Under 'Range Settings', the 'Input Range' is set to '+/-10V'. There are 'Reset Min' and 'Reset Max' buttons. The 'Enable Auto Scaling' checkbox is unchecked. Under 'Point-Slope formula', the 'Actual' section has 'Min(n1): -10.000', 'Max(m1): 10.000', and 'Unit: V'. The 'Scaled' section has 'Min(n2): -10.000', 'Max(m2): 10.000', and 'Unit: V'. The formula is $*Result = n2 + (input - n1) \times [(m2-n2)/(m1-n1)]$. The 'Slope-intercept formula' section has 'M: 1.000', 'D: 0.000', and 'Unit: V', with the formula $*Result = M \times Input + D$. At the bottom, the 'Apply to all channels' checkbox is unchecked, and there are 'OK' and 'Cancel' buttons.

To increase the sampling rate, disable any unused AI channels by deselecting the **Enable Channel** checkbox.

Select the **Enable Auto Scaling** checkbox to linearly convert the actual current or voltage value into other user defined units, such as percentage or ppm (parts per million).

This screenshot is identical to the previous one, but the 'Enable Auto Scaling' checkbox is now checked. The 'Point-Slope formula' section is highlighted in red, and the formula $*Result = n2 + (input - n1) \times [(m2-n2)/(m1-n1)]$ is also in red. The 'Slope-intercept formula' section is now unselected.

Two math formulas are used to convert actual values and user-defined units: (1) the point-slope formula and (2) the slope-intercept formula.

1. Auto Scaling by the point-slope formula

Auto Scaling by the point-slope formula can help eliminate high end and low end extremes. For example, a temperature reading of 17 mA is already dangerously high, so there would be no need to wait for a higher temperature reading before responding. Instead, you can cut off the values beyond 17 mA and convert it to a proprietary level of danger, such as Level 5.

The screenshot shows the 'AI Config' dialog box with the 'Enable Channel' checkbox checked. Under 'Range Settings', the 'Input Range' is set to '+/-10V'. The 'Enable Auto Scaling' checkbox is also checked. The 'Point-Slope formula' radio button is selected and highlighted with a red box. The 'Actual' section has 'Min(n1): -10.000', 'Max(m1): 10.000', and 'Unit: V'. The 'Scaled' section has 'Min(n2): -10.000', 'Max(m2): 10.000', and 'Unit: V'. The formula displayed is $*Result = n2 + (input - n1) \times [(m2-n2)/(m1-n1)]$. Below it, the 'Slope-intercept formula' is unselected. At the bottom, there are 'Apply to all channels', 'OK', and 'Cancel' buttons.

2. Auto Scaling by slope-intercept formula

Auto Scaling by the slope-intercept formula provides linear conversion between a ratio (M) and offset (D) value. The offset (D) can be the initial value of the field device. The ratio (M) specifies the proportion by which to enlarge or reduce the scale. It is also easy to modify the values in the database if you need to use new ratios and offset values in the future.

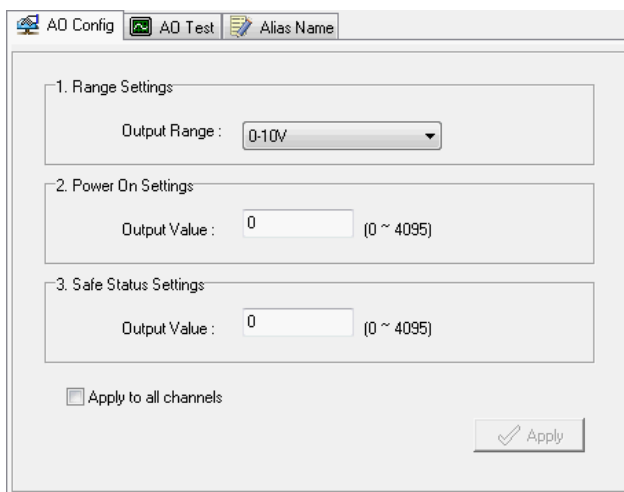
The screenshot shows the 'AI Config' dialog box with the 'Enable Channel' checkbox checked. Under 'Range Settings', the 'Input Range' is set to '+/-10V'. The 'Enable Auto Scaling' checkbox is also checked. The 'Slope-intercept formula' radio button is selected and highlighted with a red box. The 'Actual' section has 'Min(n1): -10.000', 'Max(m1): 10.000', and 'Unit: V'. The 'Scaled' section has 'Min(n2): -10.000', 'Max(m2): 10.000', and 'Unit: V'. The formula displayed is $*Result = M \times Input + D$. Below it, the 'Point-Slope formula' is unselected. At the bottom, there are 'Apply to all channels', 'OK', and 'Cancel' buttons.

The **Reset Min** and **Reset Max** buttons will clear the minimum or maximum values recorded and displayed in the ioAdmin main window.

| Channel# | Range | Value | Min. | Max. |
|----------|--------|---------|---------|---------|
| [AI]:00 | +/-10V | 0.000 V | 0.000 V | 0.683 V |
| [AI]:01 | +/-10V | 0.000 V | 0.000 V | 0.672 V |
| [AI]:02 | +/-10V | 0.001 V | 0.000 V | 0.001 V |
| [AI]:03 | +/-10V | 0.001 V | 0.000 V | 0.001 V |

Configuring Analog Output Channels

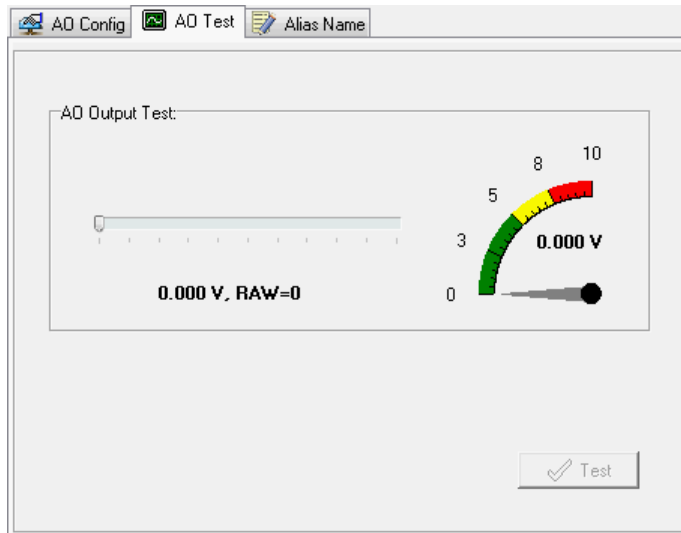
The ioLogik device’s analog output (AO) range can be set to either 0–10 V or 4–20 mA. You may also configure all channels at the same time by selecting the **Apply to all channels** checkbox.



Power On Settings: Use this field to set the initial value for the AO channel when the ioLogik E2240 is powered on. The **Power On Settings** field uses raw data values. If you do not know how to translate the raw data values into real values, use the **Test** function for assistance.

Safe Status Settings: Use this field to specify how the AO channel responds to a break in network communication. When the network connection is lost for the amount of time specified in the Host Connection Watchdog, the ioLogik E2240 enters Safe Status, and the AO channel’s Safe Status settings will go into effect. Note that the Host Connection Watchdog is disabled by default. If the Host Connection Watchdog is disabled, the ioLogik E2240 will never enter Safe Status and the Safe Status settings will have no effect.

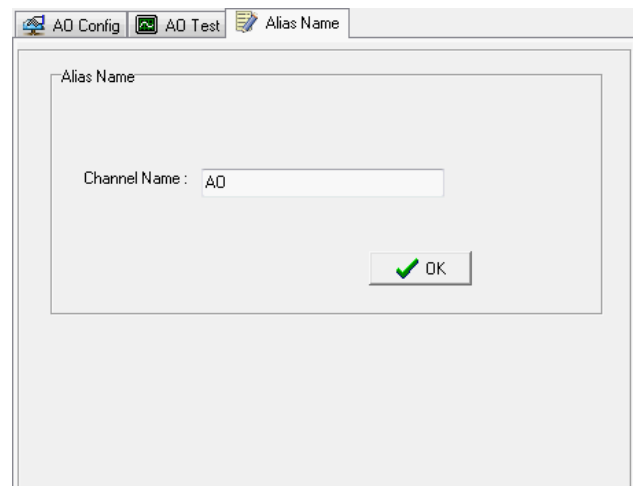
AO Test: Use this tab to test the AO channel.



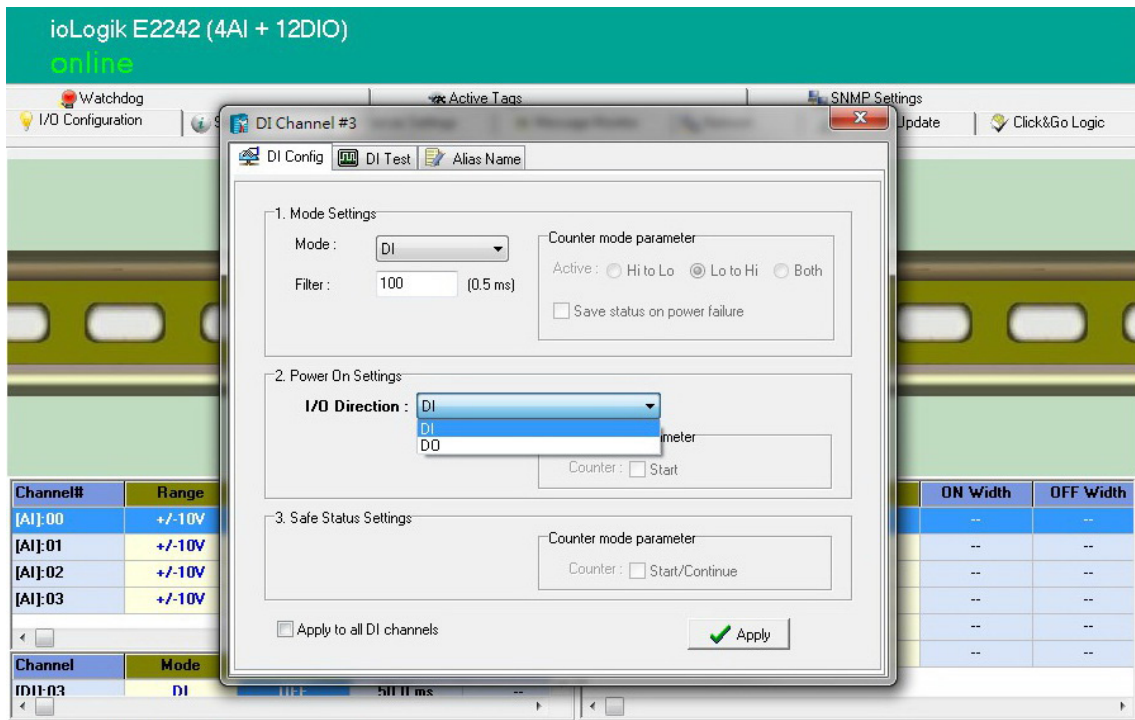
Note that the slider shows both the raw data value and the engineering value (V/mA). You may use this as a guide when entering values for the Power On and Safe Status settings.

Alias Name

Click the **Alias Name** tab to customize the channel name. You may use names with up to 16 characters. If you have already set the Alias Name on the I/O Configuration page, the channel name will appear in Click&Go, Active message, and Web.



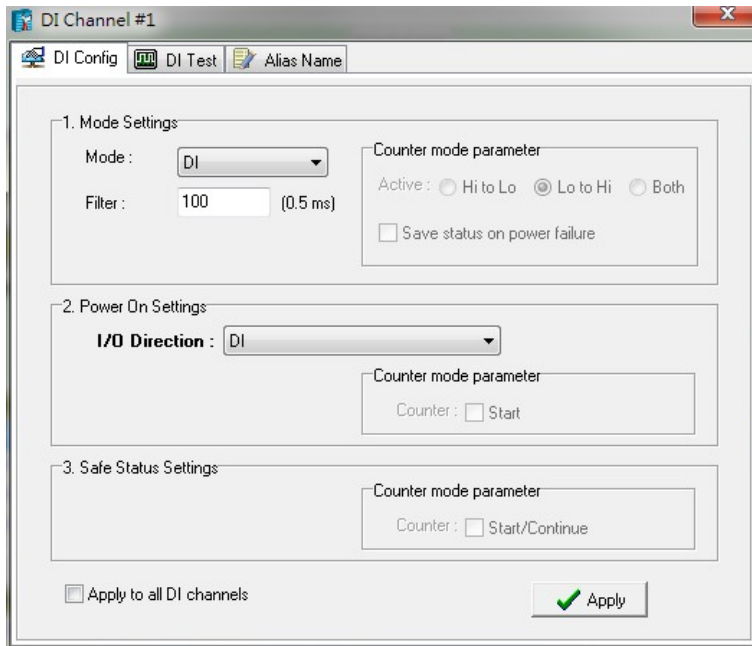
Configuring Selectable DIO Channels



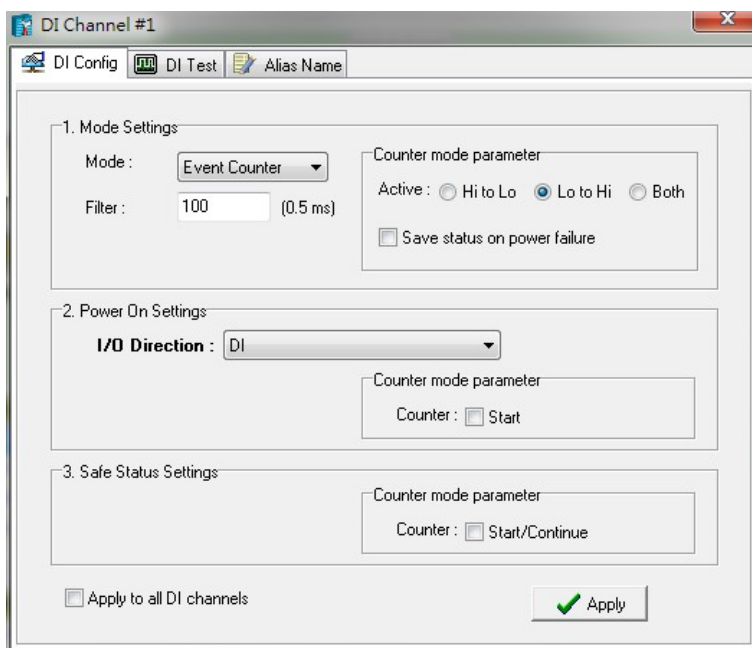
Channels DIO-0 to DIO-11 support both DI and DO channel operations. When the ioLogik E2200 unit is turned on, each DIO channel will be configured to act as either a DI or DO channel, according to the **Power On Settings**. To switch between DI and DO channel operation, select the desired mode in the **I/O Direction** field under **Power On Settings**. After clicking **Apply**, you will need to restart the ioLogik E2242 for the new setting to take effect.

Configuring Digital Input Channels

The ioLogik E2210 can support up to 12 digital input (DI) channels. Software filtering is used to control switch bounces. Under **1. Mode Settings**, the **Filter** field is configurable in multiples of 0.5 ms and accepts values between 1 and 65535. For example, a setting of 100 would mean a 50 ms filter (100 × 0.5 ms).



A DI channel can be set to “DI” or “Event Counter” mode. In DI mode, the specifications are as follows:



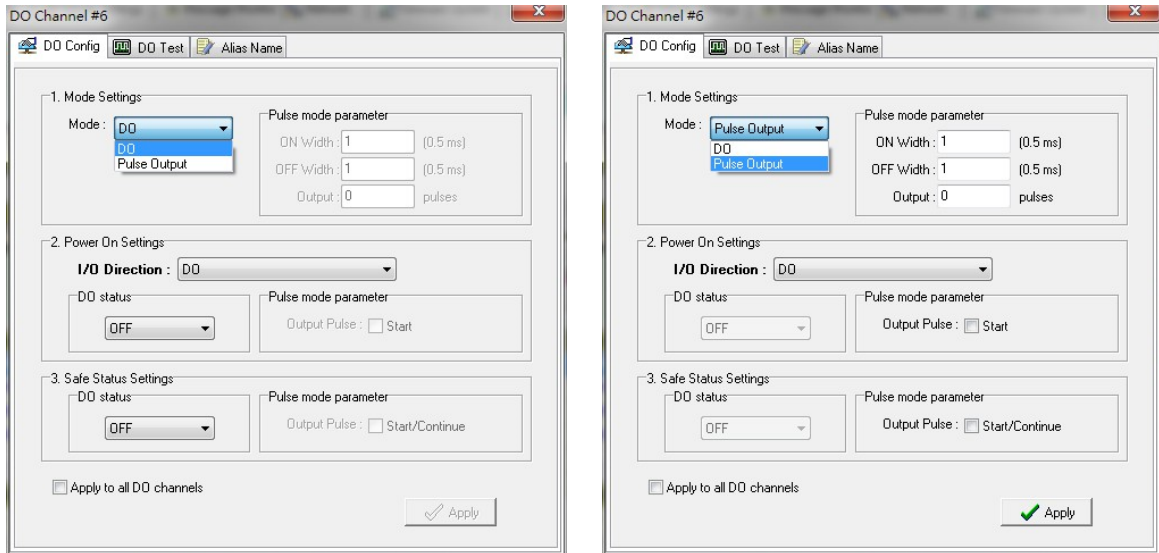
| Type | ON | OFF |
|-------------|--------------|--------------|
| Dry contact | Short to GND | Open |
| Wet contact | 0 to 3 VDC | 10 to 30 VDC |

In **Event Counter mode**, the channel accepts limit or proximity switches and counts events according to the ON/OFF status. When **Lo to Hi** is selected, the counter value increases when the attached switch is pushed. When **Hi to Lo** is selected, the counter value increases when the switch is released. When **Both** is selected, the counter value increases when the attached switch is pushed or released.

Configuring Digital Output / Relay Output Channels

| Channel | Mode | Status | ON Width | OFF Width |
|----------|-------|--------|----------|-----------|
| [DO]:04* | DO | OFF | -- | -- |
| [DO]:05* | DO | OFF | -- | -- |
| [DO]:06* | Pulse | STOP | 0.5 ms | 0.5 ms |
| [DO]:07* | Pulse | STOP | 0.5 ms | 0.5 ms |

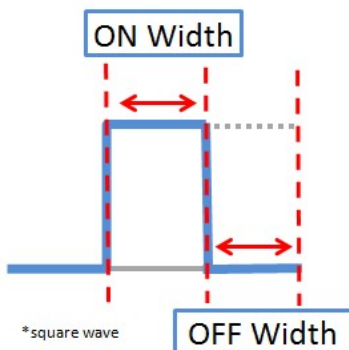
The ioLogik E2200 series digital output and relay output channels can be set to "DO" or "Pulse Output" mode.



In DO mode, the specifications are as follows.

| Type | OFF | ON |
|---------|------|-------|
| DO mode | Open | Short |

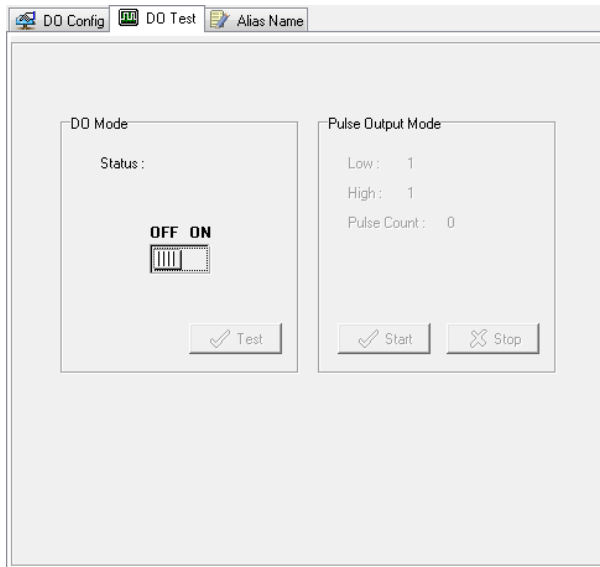
In **Pulse Output mode**, the selected digital output channel will generate a square wave as specified in the pulse mode parameters. The low and high level widths are specified in multiples of 0.5 ms for Digital Output (1.5 s for Relay output), with a maximum setting of 65,535. For digital output, you would enter 1000 for a width of 500 ms. If the OFF width value is 5000 and the ON width value is 5000, the pulse output would be a square wave with a 5-second pulse cycle. You can specify between 1 and 4,294,967,295 pulses or enter "0" for continuous pulse output.



When the ioLogik is first powered on, the status of each DO channel is set to "OFF" by default. This behavior can be modified using the **Power On Settings**. You can set a DO channel to turn "ON" when the ioLogik is powered on, or to commence pulse output.

Testing DI and DO Channels

You can test each channel by opening the channel's configuration window and selecting the Test tab.

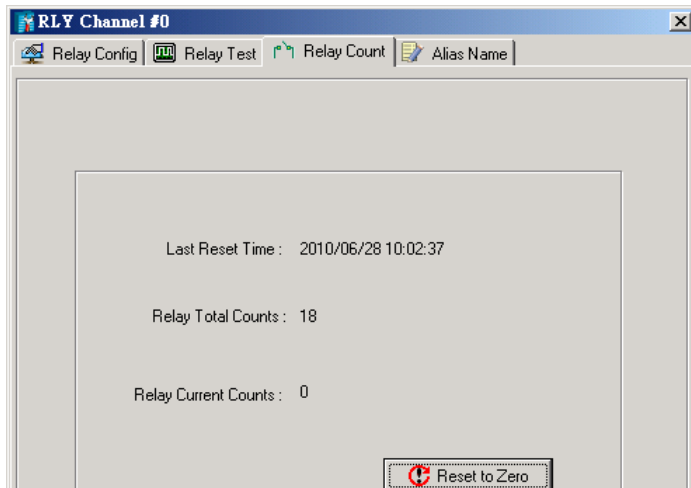


On the Test tab, you can see how a channel's status affects or is affected by the attached device. For DO channels, you can set the on/off status or start and stop pulse output. For DI channels, you can monitor the attached device's on/off status, or monitor the counter.

Relay Count Monitoring

| Channel | Mode | Status | ON Width | OFF Width |
|----------|------|--------|----------|-----------|
| [RLY]:00 | DO | OFF | -- | -- |
| [RLY]:01 | DO | OFF | -- | -- |

Two types of relay counts can be recorded in the ioLogik E2214: Total Counts and Current Counts. **Relay Total Counts** records how many times a Relay Output channel has been used. In general, each relay output channel can be used an average of 1,000,000 times. Users can monitor these counts to see when the module should be replaced, or to switch to a different channel if the total count approaches the upper limit. **Relay Current Counts** can be reset to zero to record the usage of the external device by monitoring the counts. For example, if RLY-0 is connected to an external relay control board, you can monitor the current counts to see when to replace the external relay component in advance before it fails. Last Reset Time records the time when Current Counts was reset. Both Relay Total Counts and Relay Current Counts will be saved when there is a power failure. The Last Reset Time will be saved only when the user manually presses the Reset to Zero button.



You can control how a DO/Relay output channel acts when the network is disconnected by using the **Safe Status Settings** and the **Host Connection Watchdog**. When the **Host Connection Watchdog** is enabled, a network disconnection will activate the **Safe Status Settings**. The DO channel can be configured to turn on, turn off, or commence pulse output. If the **Host Connection Watchdog** is not enabled, then the DO/Relay Output channel status will remain unchanged during a network disconnection.

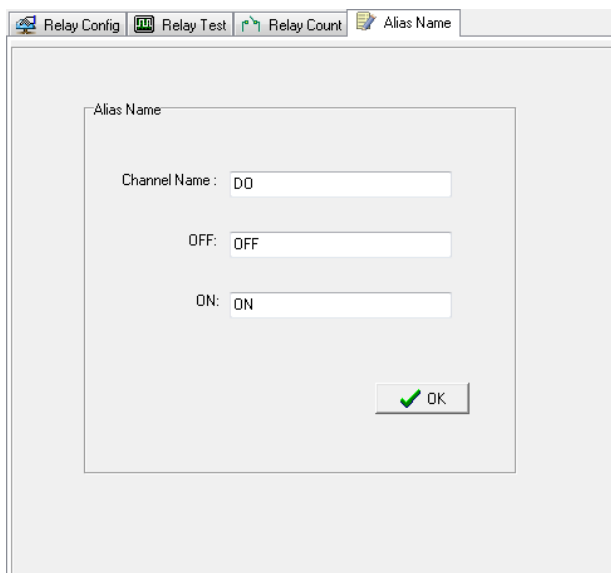


ATTENTION

The Host Connection Watchdog is disabled by default and must be enabled for Safe Status Settings to take effect.

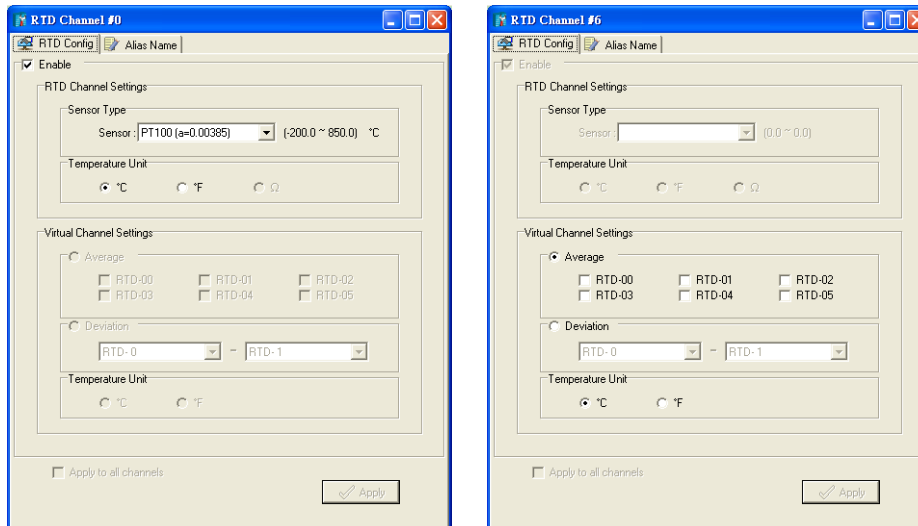
Alias Name Configuration

Alias Name helps users configure the alias of a DI or DO channels and define the logic level (0 or 1) for the ON/OFF status. The Alias can be monitored by the ioAdmin utility, or can be queried using a user-defined program based on the Moxa MXIO library, or a standard Modbus/TCP protocol.



Configuring RTD Input Channels

The ioLogik E2260 provides 6 fixed physical RTD input (Resistance Temperature Detector) channels, each supporting up to 18 different types including PT50, PT100, JPT100, and more. The RTD channels are numbered from channel 0 to channel 5. Channels 6 through 11 are virtual temperature channels that report running averages or deviations of selected RTD channels.



Alias Names

Click the **Alias Name** tab to customize the channel name. You may use names with up to 16 characters. If you have already set the Alias Name on the I/O Configuration page, the channel name will appear in Click&Go, Active message, and Web.

The following table is a list of supported sensor types and ranges.

| Sensor Type | Degree | Degree | Count |
|------------------------|---------------|----------------|---------------|
| Resistance (1 to 2200) | 1 to 2200 Ω | 1 to 2200 Ω | 10 to 22000 |
| Resistance (1 to 1250) | 1 to 1250 Ω | 1 to 1250 Ω | 20 to 25000 |
| Resistance (1 to 620) | 1 to 620 Ω | 1 to 620 Ω | 50 to 31000 |
| Resistance (1 to 310) | 1 to 310 Ω | 1 to 310 Ω | 100 to 31000 |
| PT50, 0.00385 | -200 to 850°C | -328 to 1562°F | -2000 to 8500 |
| PT100, 0.00385 | -200 to 850°C | -328 to 1562°F | -2000 to 8500 |
| PT200, 0.00385 | -200 to 850°C | -328 to 1562°F | -2000 to 8500 |
| PT500, 0.00385 | -200 to 850°C | -328 to 1562°F | -2000 to 8500 |
| PT1000, 0.00385 | -200 to 350°C | -328 to 662°F | -2000 to 3500 |
| JPT100, 0.003916 | -200 to 640°C | -328 to 1184°F | -2000 to 6400 |
| JPT200, 0.003916 | -200 to 640°C | -328 to 1184°F | -2000 to 6400 |
| JPT500, 0.003916 | -200 to 640°C | -328 to 1184°F | -2000 to 6400 |
| JPT1000, 0.003916 | -200 to 350°C | -328 to 662°F | -2000 to 3500 |
| Ni100, 0.00618 | -60 to 250°C | -76 to 482°F | -600 to 2500 |
| Ni200, 0.00618 | -60 to 250°C | -76 to 482°F | -600 to 2500 |
| Ni500, 0.00618 | -60 to 250°C | -76 to 482°F | -600 to 2500 |
| Ni1000, 0.00618 | -60 to 180°C | -76 to 356°F | -600 to 1800 |
| Ni120, 0.00672 | -80 to 260°C | -112 to 500°F | -800 to 2600 |

The status of attached sensors will be reported by the count value, which corresponds to the sensor ranges shown above. For example, for a 100 mΩ resistor, a count value of 10 corresponds to a 1 Ω reading. Moxa can only guarantee accuracy within the ranges shown above. Be sure to verify the sensor type. Accurate readings beyond these ranges cannot be guaranteed.

Virtual Channels

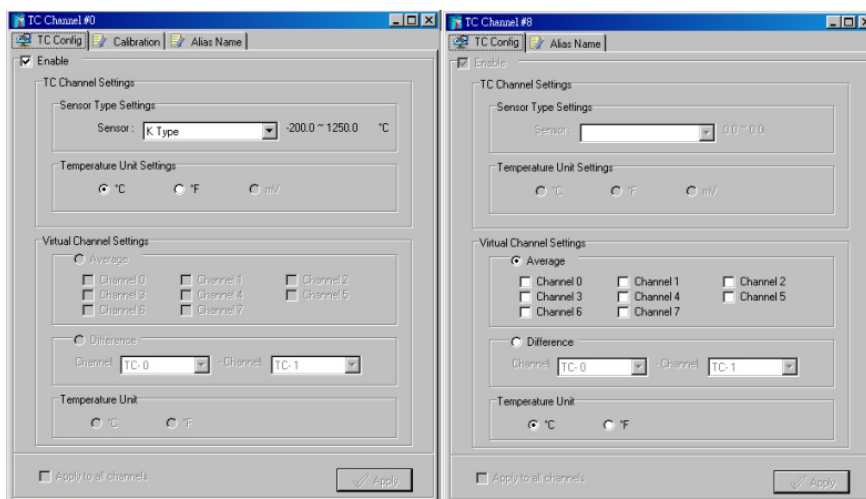
The ioLogik E2260 provides virtual channels so you can easily determine the average or deviation values for any attached temperature sensor. A virtual channel can operate in Average Mode or Deviation Mode. In Average Mode, up to 6 physical channels are selected and the virtual channel reports the average value of the selected channels. In Deviation mode, two physical channels are selected and the virtual channel reports the difference between the channels.

When using virtual channels, if there are errors on any of the selected physical channels, that channel's readings will simply be ignored. You can refer to the LED indicators to see if any errors are encountered with any of the physical channels.

Note that virtual channels only support temperature units and cannot be used with resistance units. Any channel that is connected to a resistance sensor will be treated as an error channel.

Configuring Thermocouple Input Channels

The ioLogik E2262 provides 8 fixed physical TC input (Thermocouple) channels, each supporting up to 8 different types, including J, K, T, E, R, S, B, N types, and mV voltage inputs. The TC channels are numbered from channel 0 to channel 7. Moreover, channels 8 to 15 are virtual temperature channels that report a running average or difference of selected TC channels.



The following table is a list of supported sensor types and ranges.

| Type | Temperature Range | Count Range |
|--------------------|--------------------------|---------------------|
| J | 0°C to 750°C | 0 to 7,500 |
| K | -200°C to 1250°C | -2,000 to 12,500 |
| T | -200°C to 350°C | -2,000 to 3,500 |
| E | -200°C to 900°C | -2,000 to 9,000 |
| R | -50°C to 1600°C | -500 to 16,000 |
| S | -50°C to 1760°C | -500 to 17,600 |
| B | 600°C to 1700°C | 6,000 to 17,000 |
| N | -200°C to 1300°C | -2,000 to 13,000 |
| Voltage: 78.126 mV | - 78.126 mV to 78.126 mV | -781,260 to 781,260 |
| Voltage: 39.062 mV | - 39.062 mV to 39.062 mV | -390,620 to 390,620 |
| Voltage: 19.532 mV | - 19.532 mV to 19.532 mV | -195,320 to 195,320 |

The status of attached sensors will be reported by the count value, which corresponds to the sensor ranges shown above. For example, for a K type TC sensor, a count value of 10 corresponds to a 0.1°C reading. Moxa can only guarantee accuracy within the ranges shown above. Be sure to verify the sensor type. Accurate readings beyond these ranges cannot be guaranteed.



ATTENTION

Before calibrating the temperature, allow the ioLogik E2262 to warm up for at least 30 minutes to ensure correct temperature readings.

Virtual Channels

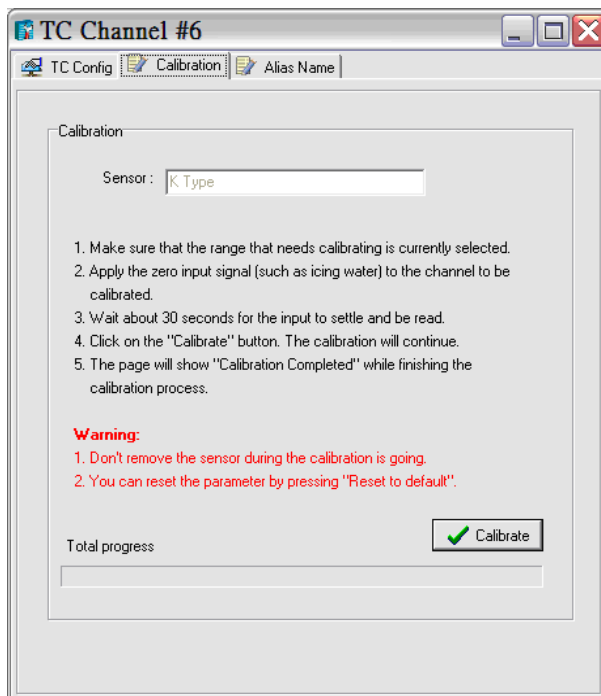
The ioLogik E2262 provides virtual channels so you can easily determine the average or deviation values for any attached temperature sensor. A virtual channel can operate in Average Mode or Deviation Mode. In Average Mode, up to 8 physical channels are selected and the virtual channel reports the average value of the selected channels. In Deviation mode, two physical channels are selected and the virtual channel reports the difference between the channels.

When using virtual channels, if there are errors on any of the selected physical channels, that channel's readings will simply be ignored. You can refer to the LED indicators to see if any errors are encountered with any of the physical channels.

Note that virtual channels only support temperature units and cannot be used with resistance units. Any channel that is connected to a mV voltage input will be treated as an error channel.

Calibration

The ioLogik E2262 allows you to calibrate the TC sensor by user. In each channel configuration section, click "Calibration" and then follow the onscreen instructions to start the TC sensor calibration. Each calibration needs about 20 seconds (per channel). Note that you can press "Reset to default" on the Navigation Panel to reload the factory default value and ignore the user calibrated value. The default value is calibrated in the factory and is stored in the device.



Alias Name

Click the Alias Name tab to customize the channel name. You may use names with up to 16 characters. If you already set the Alias Name on I/O Configuration page, the channel name will appear on Click&Go, Active message, and Web.

Server Settings Tab (Administrator)

You may set the password (up to 16 characters), server name, location, date, time, time zone, and time server in the Server Settings tab. ioAdmin supports long server names and a location description with up to 58 characters.

The screenshot shows the 'Server Settings' tab for an ioLogik E2242 (4AI + 12DIO) device. At the top, there is a green header with the device name and 'online' status. Below this is a navigation bar with icons for various system functions: Firmware Update, Click&Go Logic, Watchdog, Active Tags, SNMP Settings, I/O Configuration, Server Info, Server Settings (selected), Message Monitor, and Network. The main content area is divided into three sections:

- Management Settings:** Includes fields for 'Change Password', 'Reconfirm Password', 'Server Name', and 'Server Location', each with an 'Update' button.
- Time Settings:** Includes 'Local' date and time pickers (Date: 2000 / 3 / 1, Time: 16 : 11 : 42), a 'Time Zone' dropdown menu (set to '(GMT)Greenwich Mean Time: Dut'), a 'Time Server' field, and a 'Daylight Saving' button with an 'Update' button.
- System Log:** Includes a 'Server Address' field, a 'Port' dropdown menu (set to 4040), and an 'Update' button.

At the bottom right of the main content area, there is a 'Refresh' button.

You may set up the Daylight Saving schedule by clicking the "Daylight Saving" button. You may choose EU type, US type, or User defined type. User defined type allows you to define the days and offset hours.

The 'Daylight Saving Time' dialog box is shown with the following configuration:

- Enable**
- EU Type**
Summertime period: 2:00 a.m. last Sunday in March to 2:00 a.m. last Sunday in October.
- US Type**
Summertime period: 2:00 a.m. second Sunday in March to 2:00 a.m. first Sunday in November.
- By Weekday**
Start Date: Month: Jan, last, Day: Sun, Hour: 00
End Date: Month: Jan, last, Day: Sun, Hour: 00
Offset: Hour(s): 0.5

Buttons for 'OK' and 'Cancel' are at the bottom.

If you will be using ioEventLog to receive server status reports, such as for warm or cold starts, you need to specify the IP address and port number for the PC that will be running ioEventLog in the "System Log" field. The default port number is 4040. For additional information, please refer to the ioEventLog section later in this chapter.

Network Tab

The **Network** tab is available after you log in as an administrator. You can now configure IP settings, Modbus/TCP Alive Check Timeout settings, DNS settings, Serial settings, and Web Access settings for the ioLogik.

Number of Modbus/TCP connection(s) : **3**

| | |
|--|---|
| <p>IP Settings</p> <p>IP Configuration : <input type="text" value="Static"/></p> <p>IP Address : <input type="text" value="192.168.15.152"/></p> <p>Subnet Mask : <input type="text" value="255.255.252.0"/></p> <p>Gateway : <input type="text" value="192.168.15.254"/></p> <p>MAC : 00-90-E8-35-73-DD</p> <p><input type="button" value="Accessible IP"/> <input type="button" value="Update"/></p> | <p>Serial Settings</p> <p>Unit ID : 1</p> <p>Baud Rate : 115200</p> <p>Data Bits : 8</p> <p>Stop Bits : 1</p> <p>Parity : None</p> <p>Timeout (ms) : <input type="text" value="2500"/></p> <p><input type="button" value="Update"/></p> |
| <p>Server Socket Idle Timeout</p> <p><input checked="" type="checkbox"/> Enable Server socket idle connection timeout interval :</p> <p><input type="text" value="60"/> sec</p> <p><input type="button" value="Update"/></p> | <p>TCP Alive Check Time</p> <p><input type="text" value="3"/> sec(0-3600)</p> <p><input type="button" value="Update"/></p> |
| <p>DNS Settings</p> <p>DNS #1 : <input type="text" value="192.168.50.41"/></p> <p>DNS #2 : <input type="text" value="192.168.50.42"/></p> <p><input type="button" value="Update"/></p> | |
| <p>Web Access Settings</p> <p><input checked="" type="checkbox"/> Enable</p> <p><input type="button" value="Update"/></p> | <p><input type="button" value="Refresh"/></p> |

IP Settings

You can set up a static or dynamic IP address for the ioLogik, as well as the subnet mask and gateway address. Click **Accessible IP** if you wish to allow only certain IP addresses to have network access to the ioLogik and attached sensors. Access will be granted only to the IP addresses that you list in the Accessible IP screen. Any requests from sources that are not on the accessible IP list will be unable to use Modbus/TCP or ioAdmin to access the ioLogik.

Server Socket Idle Timeout Settings

The Modbus/TCP Server Socket Idle Timeout is designed to avoid TCP connection failures. If the network host is unable to respond due to a hardware failure or network problem, the ioLogik will continue to wait for a response from the host. This will cause the TCP port to be occupied indefinitely by the host. On the other hand, if the Modbus/TCP Server Socket Idle Timeout interval is enabled, when the ioLogik's connection to the server exceeds a specified time period the device will automatically release its Modbus/TCP connection to the server, to free up the port for the next connection.

DNS Settings

Use this field to specify the IP addresses of one or two DNS servers. DNS servers can be used to find available e-mail addresses when setting up Click & Go rules.

Serial Settings

You can view the reserved RS-485 communication parameters here, and set the timeout value for breaks in RS-485 communication. Note that the other serial communication parameters cannot be modified. If you wish to adjust the baudrate, you will need to use the physical dial on the back panel of the ioLogik.

Web Access Settings

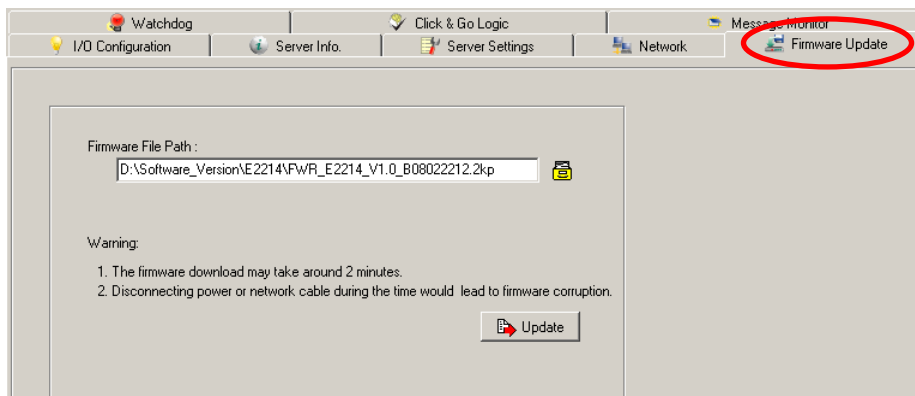
This field enables and disables the web console, which allows the ioLogik to be configured from a web browser. If this field is not enabled, you will not be able to open the web console.

TCP Alive Check Time

The Modbus/TCP Alive Check time is designed to assure TCP connection with the Server. During the specified time period, the ioLogik will send four packages to the server to check for TCP connection. When the server does not response within the specified time period ioLogik will automatically release its modbus/TCP connection to the server. The TCP Alive Check will only be activated again when the connection with the server resumes.

Firmware Update Tab

The **Firmware Update** tab is available after you log in as an administrator. Enter the path to the firmware file or click on the icon to browse for the file. Click **Update** to update the ioLogik firmware. The wizard will lead you through the process until the ioLogik has restarted.



ATTENTION

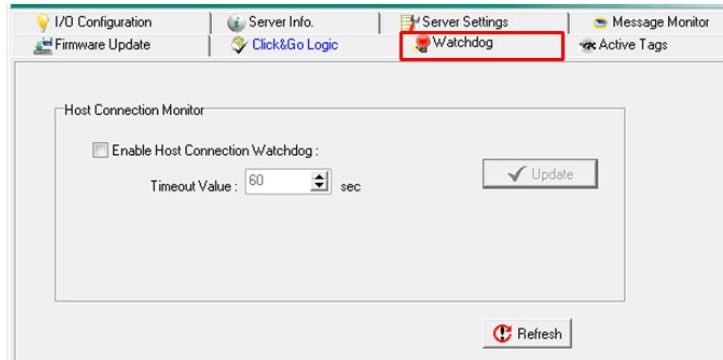
Do not interrupt the firmware update process! An interruption in the process might result in your device becoming unrecoverable.

After the firmware is updated, the ioLogik will restart and you will need to log in again to access administrator functions.

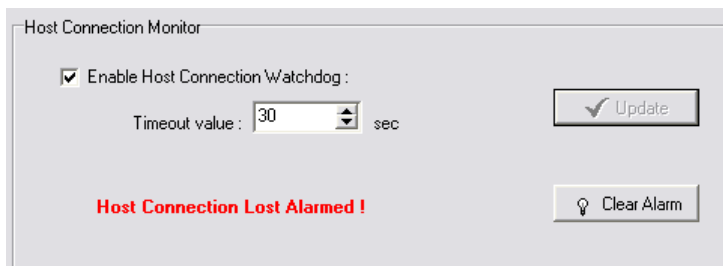
The firmware on any attached I/O expansion module, such as an ioLogik R2100 server, must be updated over the RS-485 bus. Firmware on cascaded modules cannot be updated over an Ethernet network.

Watchdog Tab

The **Watchdog** panel is available after you log in as administrator. When enabled, the **Host Connection Watchdog** monitors the network connection. If the connection is lost for the specified **Timeout value**, the Watchdog will display a warning and activate the Safe Status settings for each DO channel and Event Counter channel. By default, the Watchdog is disabled. To enable the Watchdog, make sure that **Enable Host Connection Watchdog** is checked, set the **Timeout value**, and then click **Update**.



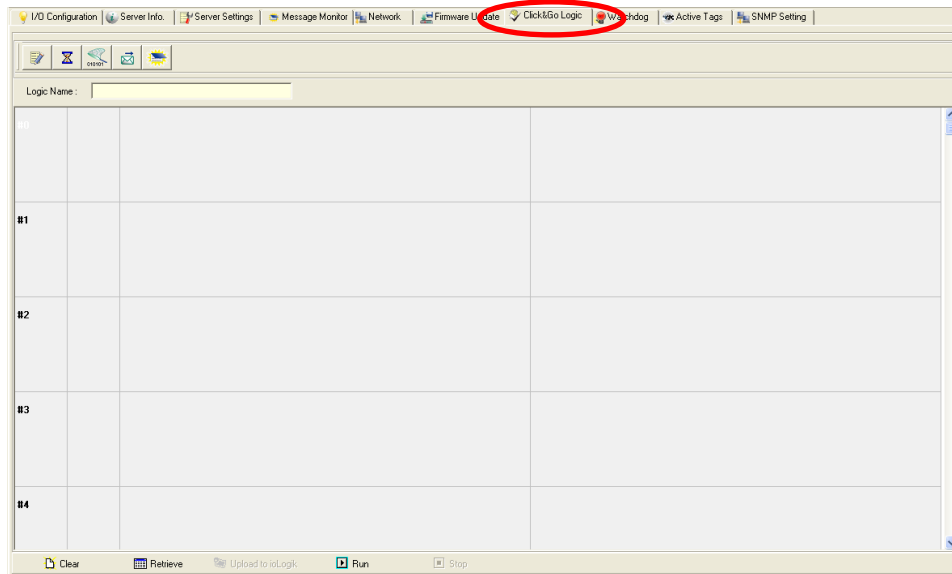
After the Watchdog is enabled, a warning will be displayed on the Watchdog panel if the network connection is lost.



After you restore the network connection, click **Clear Alarm** to reset the Watchdog and return to normal operation.

Click&Go Logic Tab

The Click&Go Logic tab is available after logging in as an administrator. This is where the ioLogik's device system is configured. With a set of rules (known as a ruleset) defined through Click&Go, the ioLogik can report I/O status to a host as soon as user-defined I/O conditions have been met. Refer to the Click&Go V2 User's Manual, which can be downloaded from Moxa's website, for more detailed information on defining rules.



Click&Go Logic changes do not take effect until the ioLogik E2200 series has restarted. Click **Upload** to upload the logic values and restart the ioLogik E2200. After logging back in as an administrator and returning to the Click&Go Logic tab, click **Retrieve** to view the current ruleset. Click **Run** to activate the ruleset and **Stop** to deactivate it.

To learn more about "Click&Go" please refer to the following website:

http://www.moxa.com/remote_io/ClicknGo.htm

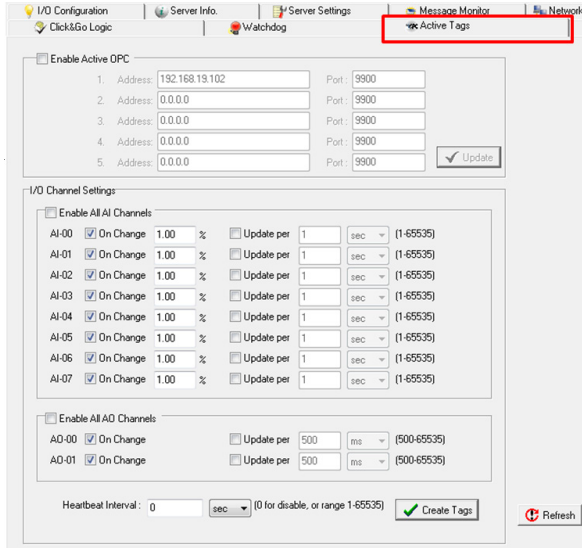


ATTENTION

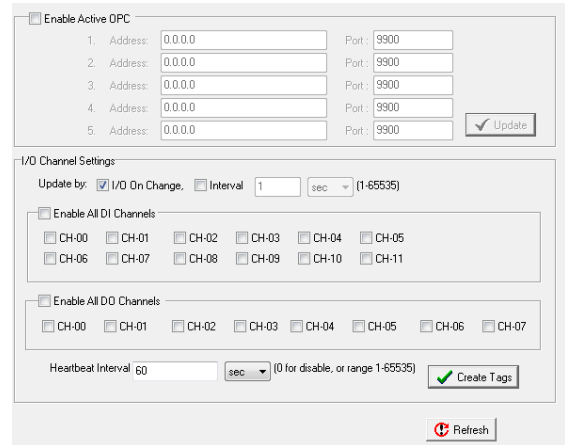
I/O channels used by Click&Go Logic **cannot be controlled externally** using ioAdmin's **Test** function, other Modbus/TCP master software, SCADA software, or SMS commands.

Active Tags Tab

When logged in as administrator, fill in the fixed IP address on the **Active Tags** panel to configure the Active OPC Address and Port settings. The Active OPC Server Address can be filled in using the IP or DNS format. The default port number is 9900. The port number should be the same as the setting in Active OPC Server's "Active Tag Listen Port." After the OPC setting and Channel Tags have been configured, click **Create Tags**. The ioLogik E2200 must be rebooted in order for the settings to take effect.



ioLogik E2240



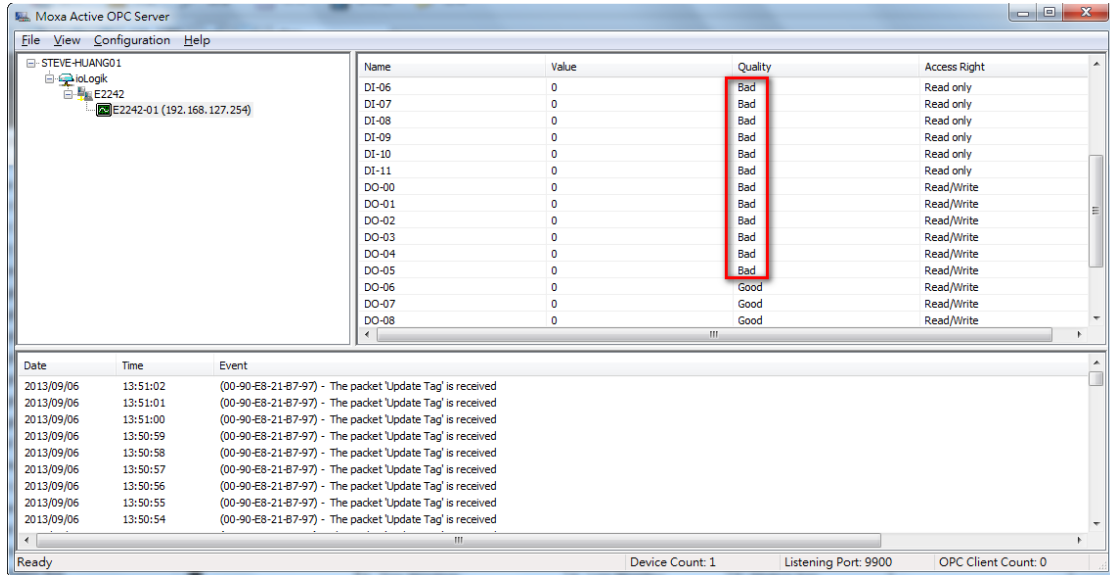
ioLogik E2210

The Heartbeat Interval can be used to determine the connection status between the ioLogik and Active OPC Server, and to ensure that the ioLogik is connected and alive. Set the heartbeat interval to "0" to disable the heartbeat. When the heartbeat is disabled, the SysConnect tag on the Active OPC Server will always be 1, which means that the Active OPC Server will not be notified if a remote ioLogik is disconnected from the network. If the heartbeat interval is set and the network between the ioLogik and Active OPC Server is down, Active OPC Server will detect the stopped heartbeat and the Quality column in the Active OPC will display BAD to indicate the loss of connectivity

Heartbeat Interval

Tags are event-driven and updated only when the status of an I/O channel changes, so when the status remains unchanged, they will not be updated to Active OPC Server. The **Heartbeat Interval** can be used to determine the connection status between the ioLogik and Active OPC Server, and to ensure that the ioLogik is connected and live. If the heartbeat interval is set and the network between the ioLogik and Active OPC Server is down, Active OPC Server will detect the stopped heartbeat and the Quality column will show **BAD** to indicate the loss of the connection.

The ioLogik uses a heartbeat signal to monitor the connection quality between Active OPC server and the device. For the ioLogik series, we suggest using a value greater than 60 seconds.



Read/Write Privilege

An input channel can only be read while an output channel is shown as read/write acceptable in Active OPC Server. Note that a channel is read only if an output channel was used in the Click&Go logic tag of that channel.

Active Tags

A tag selection table shown in the right panel of the browser window shows the details of your selection.

The I/O status of a channel can be updated to the Active OPC Server once it is changed, or updated periodically.

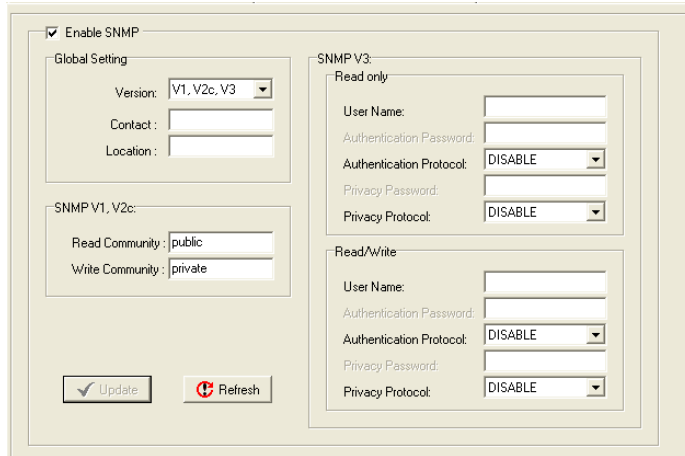
1. Checkmark the "On Change" setting to force an update when there is a signal change for that channel (On to Off or Off to On for digital channels, or percentage change for analog channels).
2. To periodically update the status of the Active OPC Server, specify a time interval after the "Update per:" checkbox.

NOTE If AI is configured to update **on change**, the percentage settings represents the percentage of the full analog range. For example, if the AI is configured to 0 to 10V, **On Change 1%** means the ioLogik will update the Active OPC Server every time there is 0.1 V change.

Refer to the **Active OPC Server** section for more details about how to use Active OPC Server.

SNMP Settings Tab

The ioLogik supports SNMP V1, V2c, and V3 (Simple Network Management Protocol) to monitor network and I/O devices with SNMP Network Management software. It is useful in building automation and telecom applications. Use these fields to enable SNMP and set the read and write community strings for SNMP V1 and V2c, or use authentication for SNMP V3.



The image shows a web-based configuration interface for SNMP settings. It is titled "Enable SNMP" and is checked. The interface is divided into several sections:

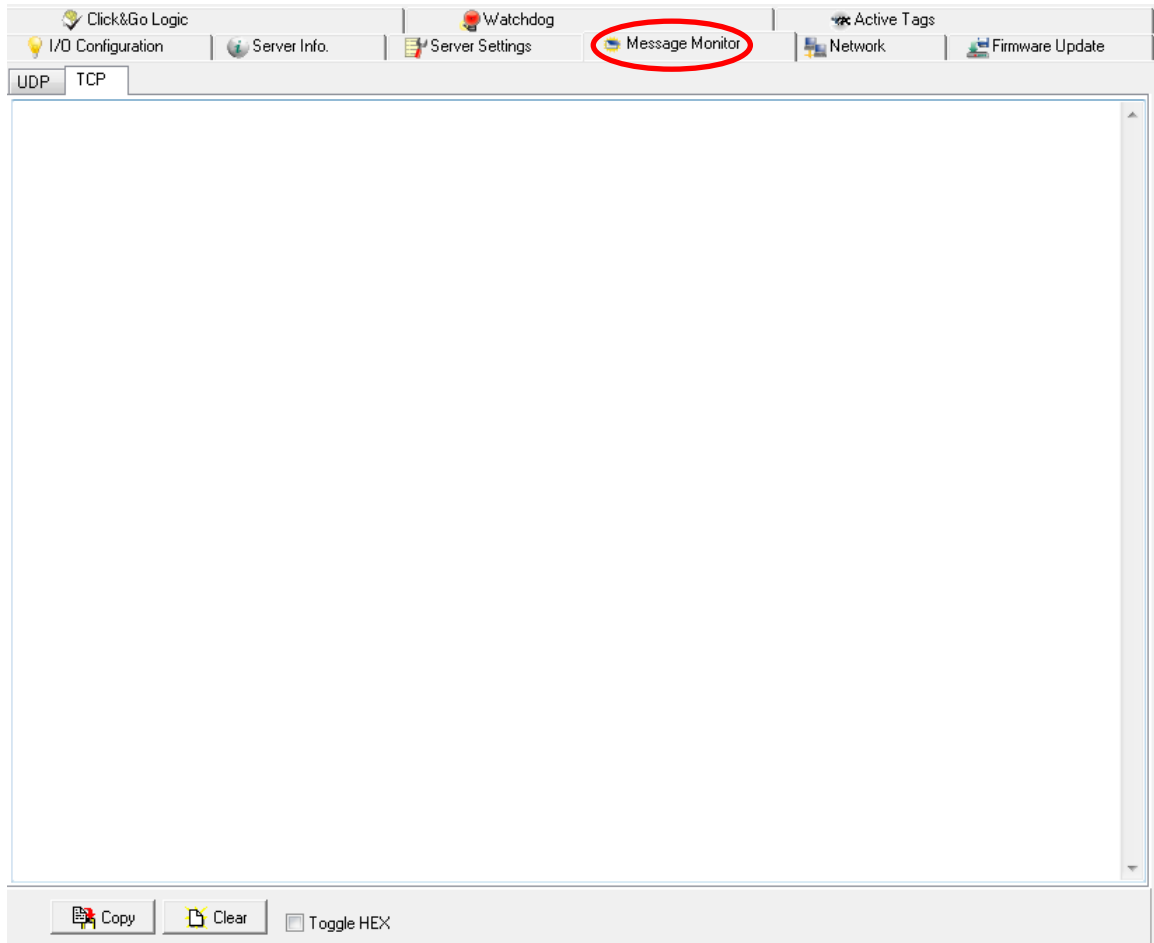
- Global Setting:** Includes a "Version" dropdown menu set to "V1, V2c, V3", and empty text boxes for "Contact" and "Location".
- SNMP V1, V2c:** Includes text boxes for "Read Community" (set to "public") and "Write Community" (set to "private").
- SNMP V3:** This section is further divided into two sub-sections:
 - Read only:** Includes text boxes for "User Name" and "Authentication Password", a dropdown menu for "Authentication Protocol" set to "DISABLE", and text boxes for "Privacy Password" and "Privacy Protocol" set to "DISABLE".
 - Read/Write:** Includes text boxes for "User Name" and "Authentication Password", a dropdown menu for "Authentication Protocol" set to "DISABLE", and text boxes for "Privacy Password" and "Privacy Protocol" set to "DISABLE".

At the bottom of the form, there are two buttons: "Update" (with a checkmark icon) and "Refresh" (with a circular arrow icon).

NOTE SNMP v3 is not supported by E2210 and E2240 hardware version V1.X

Message Monitor Panel (General)

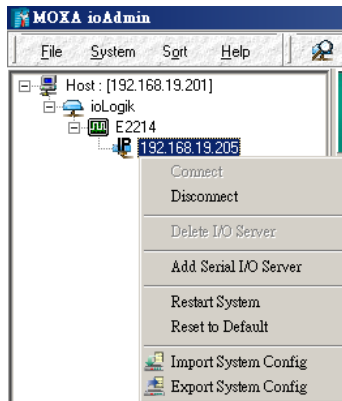
The Message Monitor panel will display any TCP/UDP Active Messages reported by the ioLogik. When you install the unit for the first time, the ruleset will not have been defined yet, so there will be no messages on the Message Monitor Panel. When a ruleset has been defined and activated, any TCP/UDP messages that have been triggered by sensor events will be shown on the Message Monitor panel.



Messages can be displayed in HEX. To display messages in HEX, make sure the "HEX" button at the bottom of the window is checked.

Server Context Menu

The Server context menu is accessed by right clicking on the server model name in the navigation panel.



Connect

Select this command to try connecting over the network to the selected ioLogik.

Disconnect

Select this command to drop the network connection with the selected ioLogik.

Delete I/O Server

Select this command to remove the selected ioLogik. The ioLogik must be disconnected first.

Add Serial I/O Server

Select this command to add an ioLogik I/O server by specifying its Unit ID.

Restart System

Select this command to restart the selected ioLogik. You will need to be logged in as an administrator to use this command.

Reset to Default

Select this command to reset all settings on the selected ioLogik, including console password, to factory default values. You will need to be logged in as an administrator to use this command.

Export System Config

Select this command to export the selected ioLogik's configuration to a text file. You will need to be logged in as an administrator to use this command. It is strongly recommended you use this method to back up your configuration after you have finished configuring the ioLogik for your application.

The following is a sample configuration file:

```

ioLogik E2242 Network I/O Server Configuration
=====
[System Information]
Date: 2010/04/07
Time: 06:10:56
Firmware: V3.4 Build10032218
Click&Go=2.1
MOS= V3.2.34

[1. Model]
-----
MOD_TYPE=E2242 - Active Ethernet I/O Server (12DIO + 4AI)
MOD_LOC=
MOD_NAME=

[2. I/O Configurations]
-----
DI00=1, (Counter), DI00_PWN=0, (Stop), DI00_SAFE=0, (Stop),
DI00_FILTER=1, (0.500ms), DI00_TRIGGER=0, (L2H),
DI01=0, (DI), DI01_FILTER=100, (50.000ms)
DI02=0, (DI), DI02_FILTER=100, (50.000ms)
DI03=0, (DI), DI03_FILTER=100, (50.000ms)
DI04=0, (DI), DI04_FILTER=100, (50.000ms)
DI05=0, (DI), DI05_FILTER=100, (50.000ms)

DO06=1, (Pulse), DO06_PWN=0, (Stop), DO06_LOW=2, (5.000ms),
DO06_SAFE=0, (Stop), DO06_HIGH=2, (5.000ms), DO06_CNT=2000
DO07=1, (Pulse), DO07_PWN=1, (Start), DO07_LOW=1, (5.000ms),
DO07_SAFE=1, (Start), DO07_HIGH=1, (5.000ms), DO07_CNT=0
DO08=0, (DO), DO08_PWN=0, (Off), DO08_SAFE=0, (Off)
DO09=0, (DO), DO09_PWN=0, (Off), DO09_SAFE=0, (Off)
DO10=0, (DO), DO10_PWN=0, (Off), DO10_SAFE=0, (Off)
DO11=0, (DO), DO11_PWN=0, (Off), DO11_SAFE=0, (Off)

AI00=5, (4-20mA), AI00_EN=1
AI01=3, (+/-10V), AI01_EN=1
AI02=3, (+/-10V), AI02_EN=1
AI03=3, (+/-10V), AI03_EN=1
AI00_SCALEN=0, AI00_ACTmin=0.000, AI00_ACTmax=0.000,
AI00_SCALmin=0.000, AI00_SCALmax=0.000,
AI00_UNIT=V
AI01_SCALEN=0, AI01_ACTmin=0.000, AI01_ACTmax=0.000,
AI01_SCALmin=0.000, AI01_SCALmax=0.000,
AI01_UNIT=V
AI02_SCALEN=0, AI02_ACTmin=0.000, AI02_ACTmax=0.000,
AI02_SCALmin=0.000, AI02_SCALmax=0.000,
AI02_UNIT=V
AI03_SCALEN=0, AI03_ACTmin=0.000, AI03_ACTmax=0.000,
AI03_SCALmin=0.000, AI03_SCALmax=0.000,
AI03_UNIT=V
AI00_SCALE2_M=1.000, AI00_SCALE2_D=0.000,
AI01_SCALE2_M=1.000, AI01_SCALE2_D=0.000,
AI02_SCALE2_M=1.000, AI02_SCALE2_D=0.000,
AI03_SCALE2_M=1.000, AI03_SCALE2_D=0.000,

```

Import System Config

Select this command to load a configuration for the selected ioLogik from a configuration text file. You will need to be logged in as an administrator to use this command. The new configuration will not take effect until the ioLogik has been restarted. This command can be used to restore a configuration after loading the factory defaults, or to duplicate a configuration to multiple ioLogik units.

Using ioEventLog

Installing ioEventLog

ioEventLog is a Windows utility provided to monitor the ioLogik E2200 series and attached I/O devices. It can be used from anywhere on the network.

ioEventLog can be downloaded from Moxa's website.

1. Installing ioEventLog from website:

- a. First click on the following link to access the website's search utility:
<http://www.moxa.com/support/search.aspx?type=soft>
- b. When the web page opens, enter the model name of your product in the search box.
- c. Click the model name and navigate to the product page, and then click on ioEventLog, located in the box titled Software.
- d. Download and then unzip the file. Run **SETUP.EXE** from that location.
The installation program will guide you through the installation process and install the software.

2. Open ioEventLog: After installation has finished, run ioEventLog from **Start → Program Files → MOXA → IO Server → Utility → ioEventLog**.

Note: or you can download ioEventlog straight from the following website
(<http://www.moxa.com/support/download.aspx?type=support&id=1152>)

Basic Functions

ioEventLog is installed along with ioAdmin. It is designed to help you keep a record of ioLogik status events over the network. The log is stored on the Windows PC. You will need to set up your ioLogik E2200 to send status events to the PC's IP address. The following events are monitored:

- cold start
- warm start

For each event, the following information is provided. The log can be sorted by any of these fields:

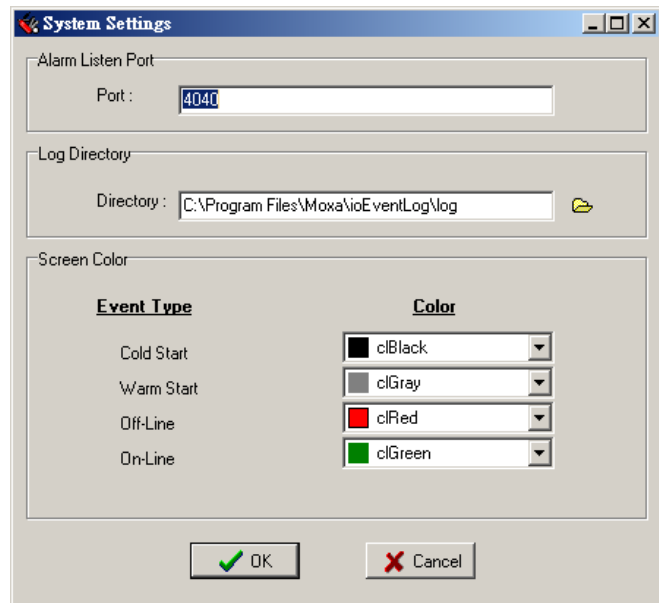


| # | Event type | Event Date/Time | Source Name | Source IP | Destination IP | Host Date/Time | Source Model |
|---|------------|-----------------|-------------|-----------|----------------|----------------|--------------|
| | | | | | | | |

1. event type
2. event date and time
3. ioLogik server source name
4. source IP
5. destination IP
6. host date and time
7. Source model

Configuration

In the System menu, select **Settings** to configure ioEventLog.

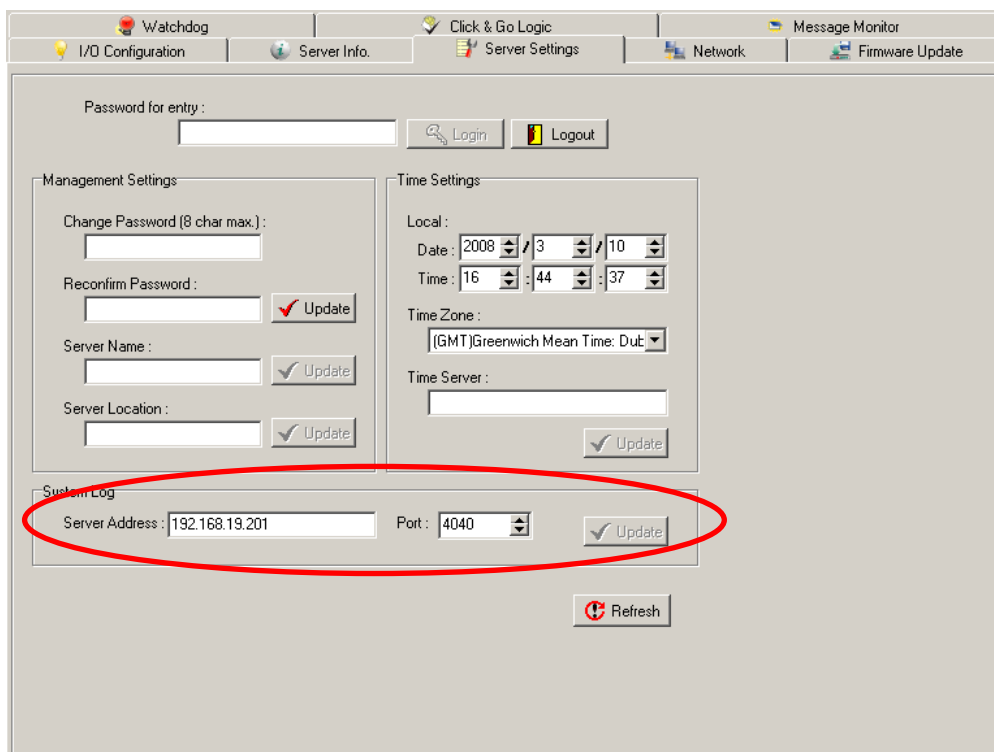


The **Alarm Listen Port** is the TCP port number that will be monitored for status events. You can modify this setting as necessary to receive signals through a firewall. It will need to match the settings for the ioLogik server that is being monitored.

The **Log Directory** is where the log files will be stored. The default directory is C:\Program Files\Moxa\ioEventLog\log. A separate log file is created for each day, with file names assigned automatically.

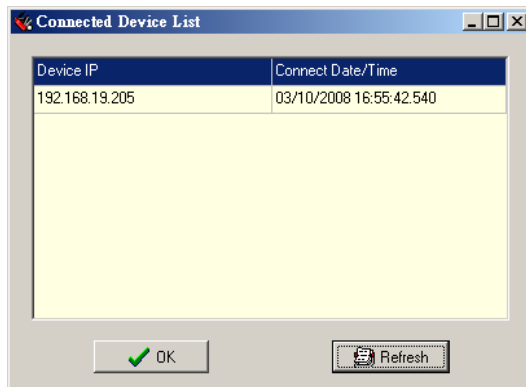
You can also select the color of each event type in the log.

To configure the ioLogik to report to the ioEventLog, use ioAdmin to configure the ioLogik in **Server Settings**.



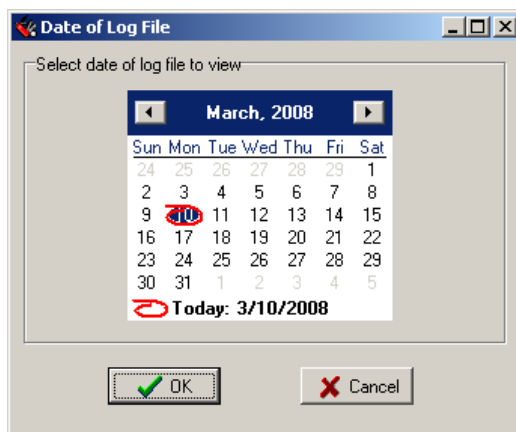
Checking Connected Devices

You can see which I/O servers are already connected to ioEventLog by selecting Connected Device List from the Connection menu. You will be prompted to view which devices are connected.



Opening Log Files

You can view previously saved logs by selecting Open from the Log menu. You will be prompted for the data that you wish to view.



The logs for the day that you select will be displayed in the Alarm Log Viewer window.

Clearing the Log

If you wish to clear the log, you can select Clear from the Log menu. This will clear all events for the current day. The cleared events will not be saved in that day's logs. After the logs are cleared, new events will be displayed and recorded as usual.

Click&Go Logic was developed by Moxa to provide an easy way to program your ioLogik E2200 product for Smart Ethernet Remote I/O operation. In this chapter, we explain how Click&Go Logic works and how to use it to develop your Smart Ethernet Remote I/O device.

The following topics are covered in this chapter:

- ❑ **Overview**
- ❑ **Features**
- ❑ **Click&Go Logic Basics**
- ❑ **Working with Rules**
- ❑ **I/O Configuration**
 - Digital Input Mode Selection
 - Digital Output Mode Selection
 - Analog Input Mode Selection
 - Alias Name Configuration
 - Testing the I/O Channels
- ❑ **Defining Global Variables**
 - Internal Register (Integer) Settings
 - Timer Settings
 - SNMP Trap Server
 - E-Mail Server
 - Active Message Server
- ❑ **Working with Logic**
 - Click&Go Logic Basics
 - IF Conditions
- ❑ **THEN/ELSE Actions**
- ❑ **Activating the Rule-set**
 - Upload, Restart, and Run
 - Rule-set Management Bar
- ❑ **Import/Export Configuration**
- ❑ **More Information about Repeat Interval vs. Edge Detection**

Overview

The ioLogik E2200 series system eliminates the need for host computers to continually poll I/O devices for their status. Instead, the server itself is able to monitor the status of each I/O device and take the appropriate action when the I/O status satisfies a user-defined condition. For example, the ioLogik could be configured to send a TCP/UDP message only when the switch attached to DI-0 is turned on. This event-based structure results in a much improved response time and a much reduced load on the host computer's CPU and network bandwidth.

ioLogik E2200 products are easily configured using Moxa's Click&Go Logic. With Click&Go Logic, you can easily and intuitively configure when and how I/O information is transmitted over the network. Simple **IF-Then-Else** statements are used to specify conditions that are required for certain actions to take place. Up to three conditions and three actions can be combined in a rule, and you can define up to 24 rules. Supported actions include sending SNMP traps or TCP/UDP messages to up to 10 hosts at a time.

Click&Go Function Comparison Table by Product Line

| Product Line | ioLogik E2000 | ioLogik W5300 |
|------------------------------|---------------|----------------------|
| Click&Go Function | | |
| Peer-to-Peer | Yes | No |
| Remote Action | Yes | No |
| CGI Command | Yes | No |
| Trigger Logic | | |
| IF-Then-Else rule | 24 rules | 24 rules |
| Internal Register | 24 | 24 + 28 float points |
| Timer | 24 | 24 |
| Schedule | Yes | Yes |
| Alarms | | |
| TCP/UDP Active Message | Yes | Yes, Unicode support |
| SNMP Traps | Yes | Yes |
| E-Mail | Yes | Yes, Unicode support |
| SMS | No | Yes, Unicode support |

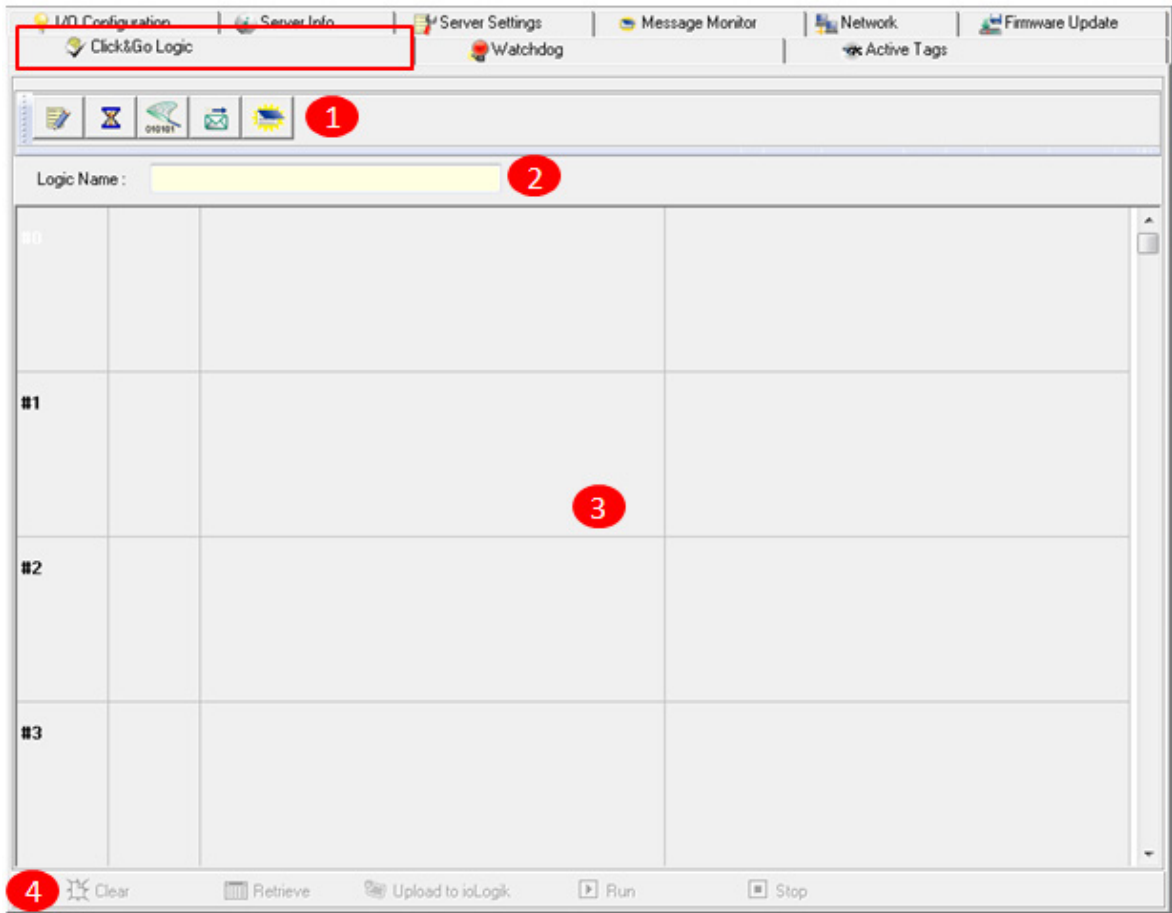
Features

Click&Go Logic has the following key features:

- Easy local logic control using intuitive **IF-Then-Else** style construction.
- Up to 24 user-defined rules.
- Up to 3 I/O-based conditions and 3 DO or network actions per rule.
- Choice of email, TCP, UDP, SNMP trap, and SMS for active I/O messaging.
- Customizable message content with dynamic fields for time, date, IP address, and more.
- Up to 10 simultaneous IP destinations for TCP/UDP messaging.
- Internal register function for remote output control when Click&Go is running.
- Timer Delay function for timing events.
- Configurable interval for time-triggered events.

Click&Go Logic Basics

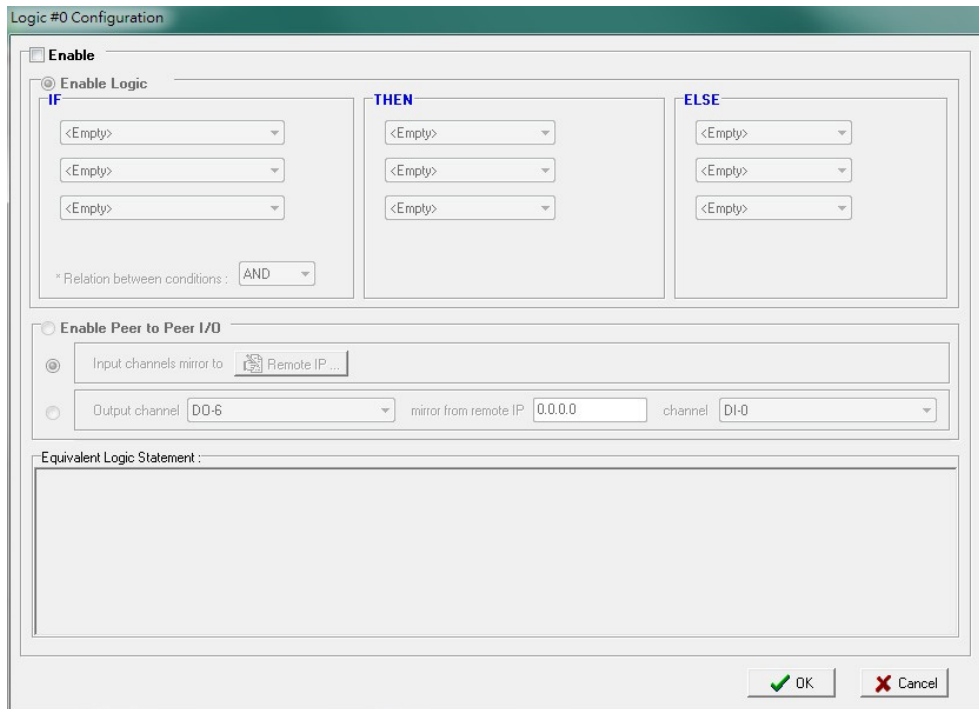
To use Click&Go Logic, open ioAdmin and log on as an ioLogik administrator on the Server Settings panel. Once you are logged on, go to the Click&Go Logic panel. It should appear as below:



| Click&Go Logic Panel |
|---|
| 1. Global Variable: In this field, you can assign a Global Variable for the set of rules. |
| 2. Logic Name: In this field, you can assign a name for the set of rules. |
| 3. Rules List: In this area, each rule's conditions, actions, and status are displayed. |
| 4. Ruleset Management Bar: In this area, you manage the ruleset. |

Working with Rules

Rules are the building blocks of your ioLogik E2200. With rules, you define the exact trigger conditions for transmission of I/O information as well as the content and destination of that information. DO's reaction can also be automated through DI trigger conditions.



In the main screen, you will see a list of the rules in the current rule set. Double click on a rule to open that rule's configuration window, or double click on an empty rule to start a new rule.

The **Equivalent Logic Statement** at the bottom shows a real-time text-based summary of the rule that you are defining, and provides a useful means of making sure that the rule is designed as you intended.

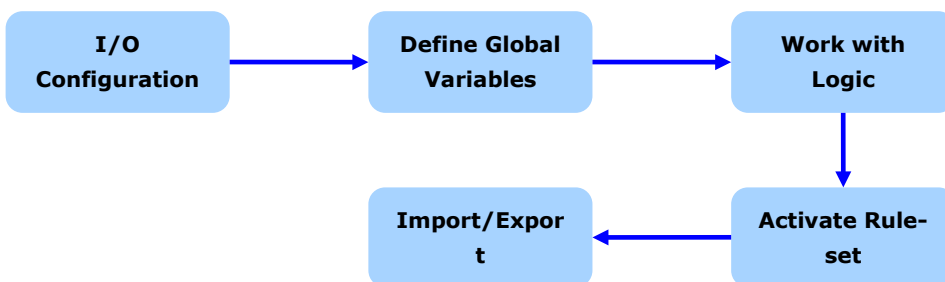


ATTENTION

When configuring input and output control and response values, **you must select the unit of measurement before entering a value.** If you select a unit of measurement after entering a value, the value will not be retained. In addition, when an I/O channel is being used in a Click&Go Logic rule, the channel's range and units cannot be modified.

Click&Go Development Process

After searching and setting up the IP address of an ioLogik Ethernet I/O server, Click&Go logic can be developed by following the procedures below:



I/O Configuration

ioLogik products are embedded with various types of I/O channels, and the mode of each input/output channel must be configured before using the channels. Channels are divided into four categories: digital inputs, digital outputs, analog inputs, and analog outputs.

Digital Input Mode Selection

A DI channel can be set to **DI** or **Event Counter** mode. In DI mode, the channel connects to wet/dry contacts.

In Event Counter mode, the channel accepts limit or proximity switches and counts events according to the ON/OFF status. When "Lo to Hi" is selected, the counter value increases when the attached switch is pushed. When "Hi to Lo" is selected, the counter value increases when the switch is pushed and released.

When logged in as administrator, double click on a channel in the **I/O Configuration** panel to configure that channel's settings. A window will open with configuration options for that channel. Each DI channel will be configured to act as either a DI or Event Counter channel, according to the **Mode Settings**. To switch between DI and Event Counter channel operation, select the desired mode in under **Mode Settings**.



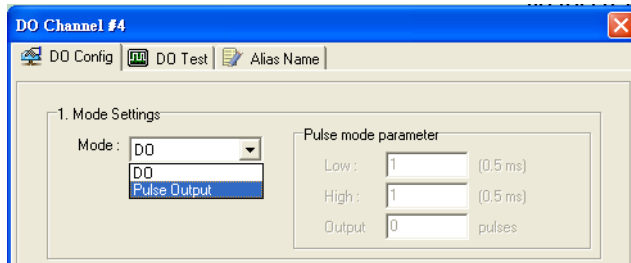
ATTENTION

On this panel, be sure to select **Start** under "Counter mode parameter" on "Power On Settings" to activate the Event Counter channel.

Digital Output Mode Selection

A DO channel can be set to **DO** or **Pulse Output** mode. The Relay Output behavior is same as DO.

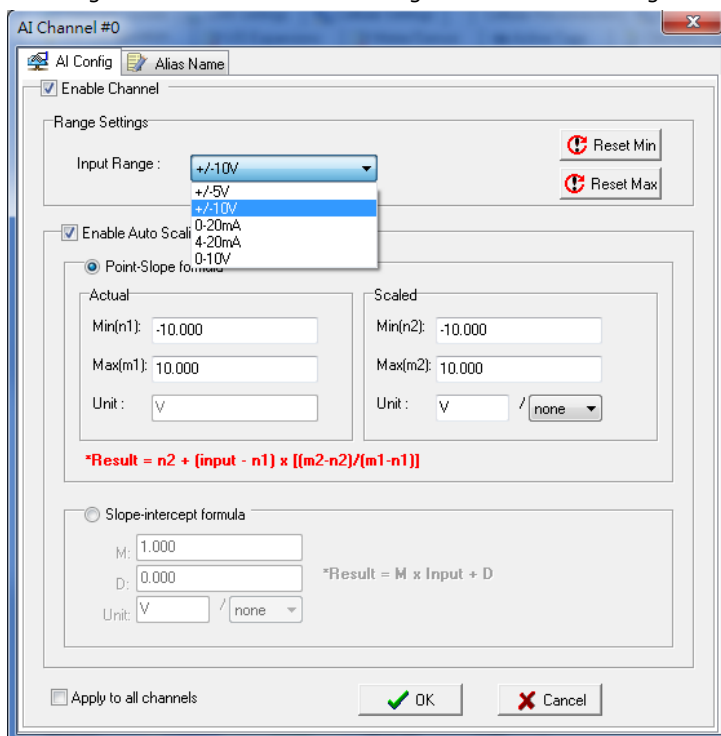
When logged in as an administrator, double click on a channel on the **I/O Configuration** panel to configure that channel's settings. A window will open with configuration options for that channel. Each DO channel will be configured to act as either a DO or Pulse Output channel, according to the **Mode Settings**. To switch between DO and Pulse Output channel operation, select the desired mode under **Mode Settings**.



Analog Input Mode Selection

Analog input channels can use either voltage or current to transmit signals.

When logged in as administrator, double click on a channel on the **I/O Configuration** panel to configure that channel's settings. A window will open with configuration options for that channel. Each AI channel will be configured to measure either voltage or current according to the **Range Settings**.

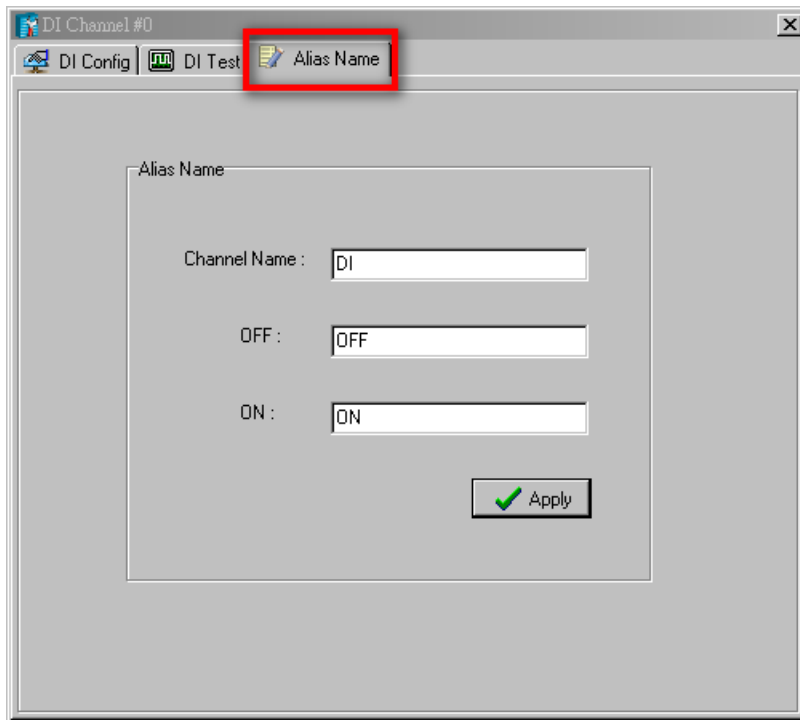


Alias Name Configuration

Alias Name helps users configure the alias of a DI or DO channels and define the logic level (0 or 1) for the ON/OFF status. The Alias can be monitored by the ioAdmin utility, or queried by using a user-defined program based on the Moxa MXIO library or standard Modbus/TCP protocols.

For Click&Go programming, the Alias Name will display the user-defined name when the specified channel is selected. For example, although the first DI channel is represented by **DI-0** in Click&Go, you can change the Alias Name to **Door_0** for easier recognition when programming.

When logged in as an administrator, double-click on a channel in the **I/O Configuration** panel to configure that channel's settings. A window will open with configuration options for that channel. The Alias Name of each input/output channel can be configured by selecting the **Alias Name** panel.

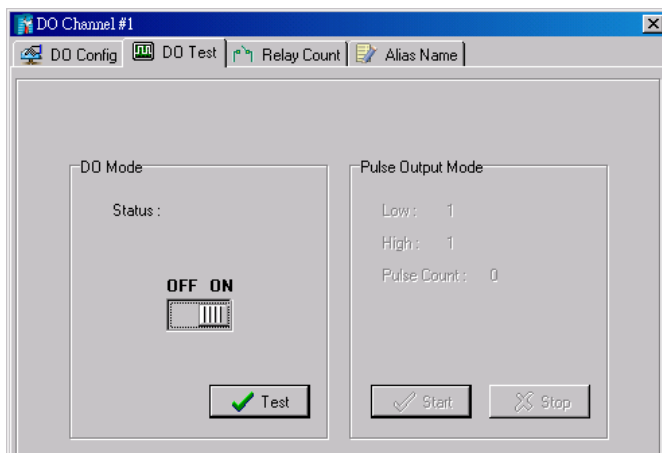


ATTENTION

We strongly recommend configuring the Alias Name for any used I/O channels before performing any further configurations or programming.

Testing the I/O Channels

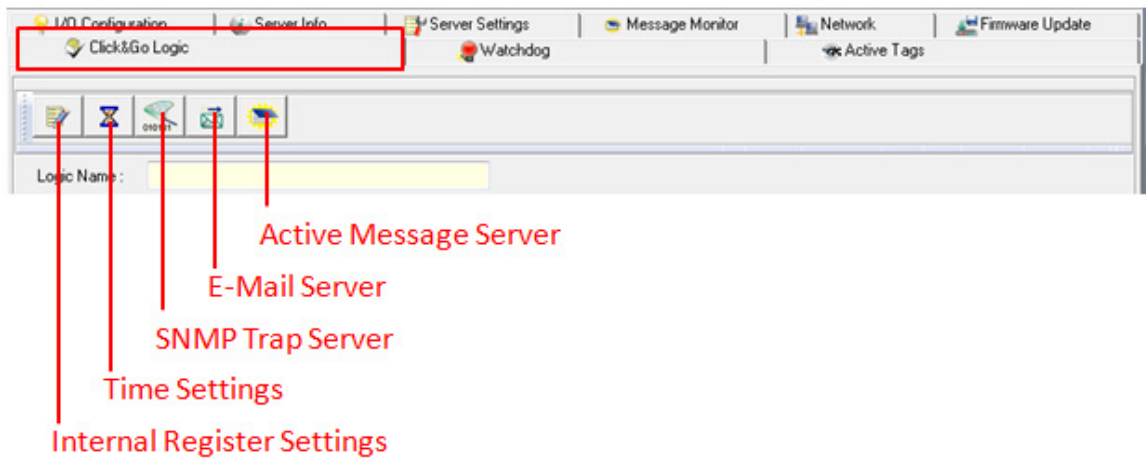
Each I/O channel can be tested and monitored individually. When logged in as administrator, double-click on a channel in the **I/O Configuration** panel to configure that channel's settings. A window will open with configuration options for the channel. Tests can be done by opening the channel's configuration window and selecting the Test panel.



The Test panel shows how a channel's status affects, or is affected by, the connected device. For output channels, you can set the ON/OFF status, start and stop a pulse, or output a voltage or current. For input channels, you can monitor the attached device's on/off status, counter, or input voltage/current.

Defining Global Variables

Global Variables include **Internal Register Settings**, **Timer Settings**, **SNMP Trap Server**, **E-Mail Server**, and **Active Message Server**. If these functions will be used in a Click&Go V2 rule-set, the default configuration must first be set from the Global Variable Menu Bar.



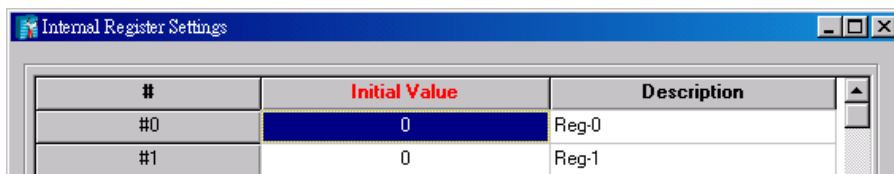
1. [Internal Register Setting](#)
2. [Time Setting](#)
3. [SNMP Trap Server](#)
4. [Email Server](#)
5. [Active Message Server](#)

Internal Register (Integer) Settings

Internal Register (Integer) is a flag that can be used with the Click&Go logic internally or externally. The 24 sets of internal registers can be polled and controlled by SCADA software using standard Modbus/TCP format, or implemented to redirect the result of one Click&Go logic to another.

The default value of an internal register is "0".

| | Register Number | Initial Value |
|-------------------|-----------------|---------------|
| Internal Register | Reg-0 to Reg-23 | *0 to 255 |



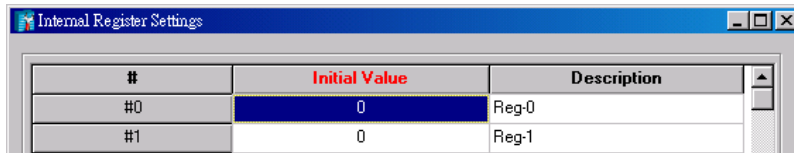
Timer Settings

The **Timer** function allows users to delay an action, trigger an action to run, or repeat an action. A timer is activated by a change of the logic event. After the timed interval has expired, the output will be performed.

The 24 timers that can be implemented with Click&Go V2 logic have the default time interval set to "5 seconds" in the "STOP" state. Be sure to configure the interval before using a timer.

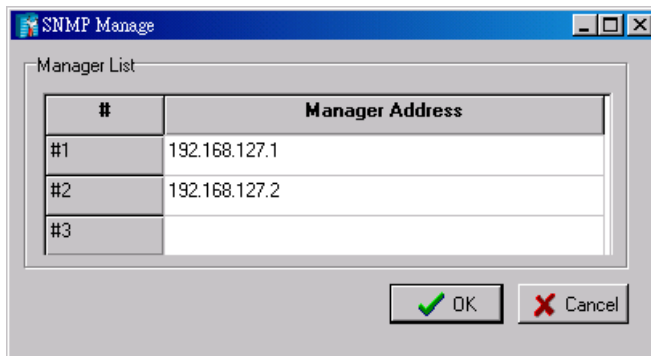
With the default state set to "START" the timer will start when the Click&Go logic is activated.

| | Timer Number | Initial State Configuration |
|-------|---------------------|-----------------------------|
| Timer | Timer-0 to Timer-23 | START, *STOP |



SNMP Trap Server

The ioLogik supports SNMP v3 (Simple Network Management Protocol) to allow monitoring of the network and I/O devices with SNMP Network Management software. It is useful for building automation and telecom applications. When you need to monitor the system information of an ioLogik or Click &Go logic is defined to update the I/O status via SNMP traps, one or up to 10 SNMP trap servers must be defined.



E-Mail Server

The **E-mail Server** configures the parameters of the target e-mail servers and the recipient e-mail addresses. The **Recipient Database** should contain a list of available e-mail addresses for your network environment. The e-mail message defined in the Click&Go logic will be sent to all addresses listed in the **Receiver(s) list**. To add e-mail addresses to the **Available receiver(s) list**, enter the **Name** and **Mail Address** and click the **Add** finger icon to move addresses to the **Recipient Database**; use the **Remove** finger icon to remove it.

E-Mail Server

Mail Address Settings

Name : Mail Address :

Recipient Database

| Name | e-Mail Address |
|--------|----------------------------|
| george | george.liu77@msa.hinet.net |

Mail Server Settings

SMTP Server Address: Login Name :

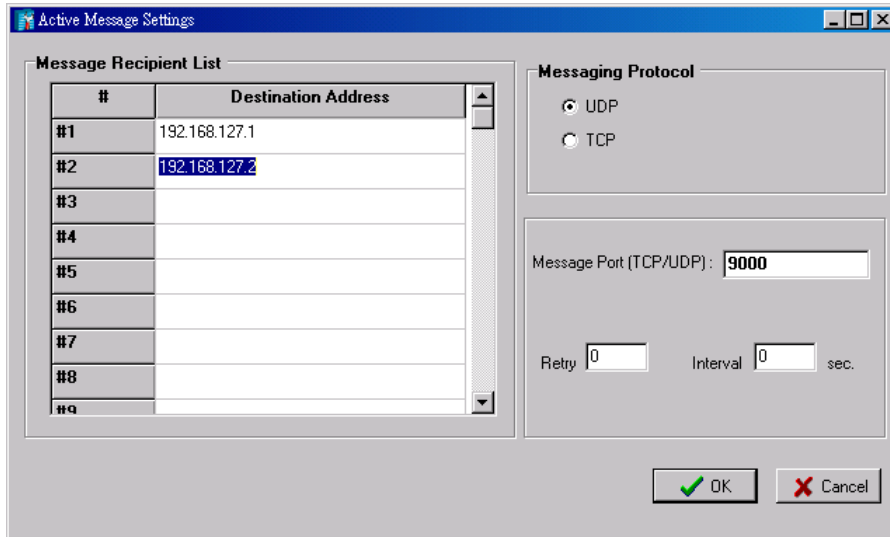
Login Password :

Retry Interval sec.

Active Message Server

The **Active Message Server** configures one or more destination IP addresses of the Message Servers that receive event messages generated by the Click&Go logic. The message protocol (TCP or UDP) and the message socket port must also be configured.

The active message defined in the Click&Go logic will be sent to all addresses listed in the **Message Recipient List**.



Message Port(TCP/UDP): is the Port which the computer use to communicate with the device, and the default port for the TCP/UDP is 9000

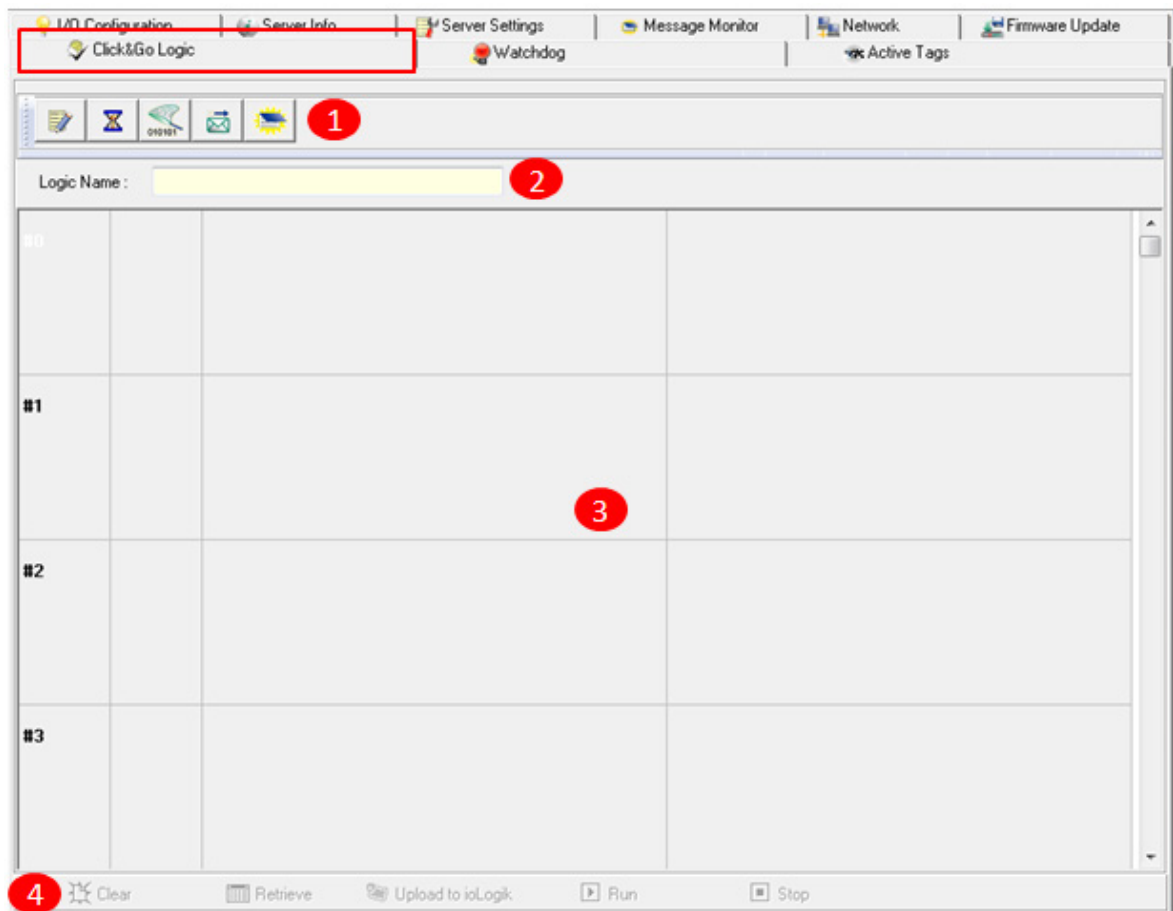
You can specify how many retry and between how many intervals second you want the device to send an Active message.

Working with Logic

Click&Go Logic Basics

The Click&Go Logic panel is available after logging in as administrator. This is where Click&Go logic is configured. With a set of rules (known as a rule-set) defined through Click&Go, the ioLogik can perform local and remote I/O control, report I/O status, and actively send out messages, e-mails, or SNMP traps to a host as soon as the user-defined I/O conditions have been met.

To use Click&Go Logic, start ioAdmin and log in as ioLogik administrator from the Server Settings panel. Once you are logged in, go to the Click&Go Logic panel. The following screen should appear:



Click&Go Logic Panel

1. Global Variable: In this field, you can configure global variable rules.
2. Logic Name: In this field, you can assign a name to the set of rules.
3. Rule-set: In this area, each rule's conditions, actions, and status are displayed.
4. Rule-set Management Bar: In this area, you manage the rule-set.

Rules are the building blocks of your ioLogik system. With rules, you define the exact trigger conditions for transmission of I/O information as well as the content and destination of that information.

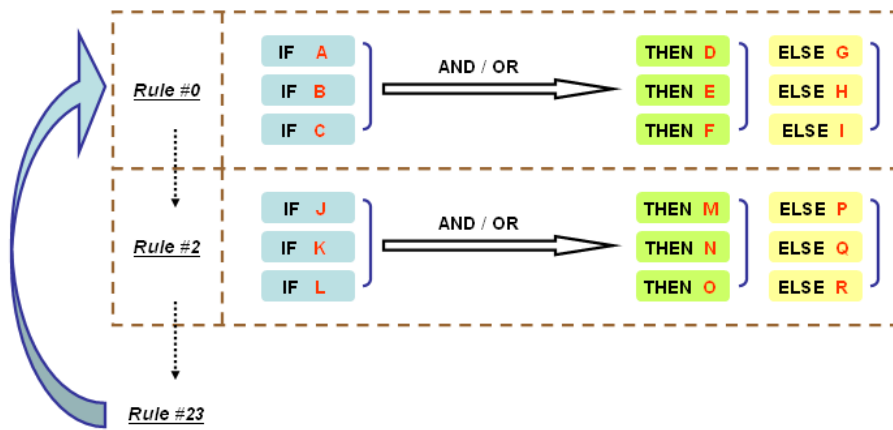
Click&Go Logic can be defined in the following ways:

IF "A" THEN "B", ELSE "C"

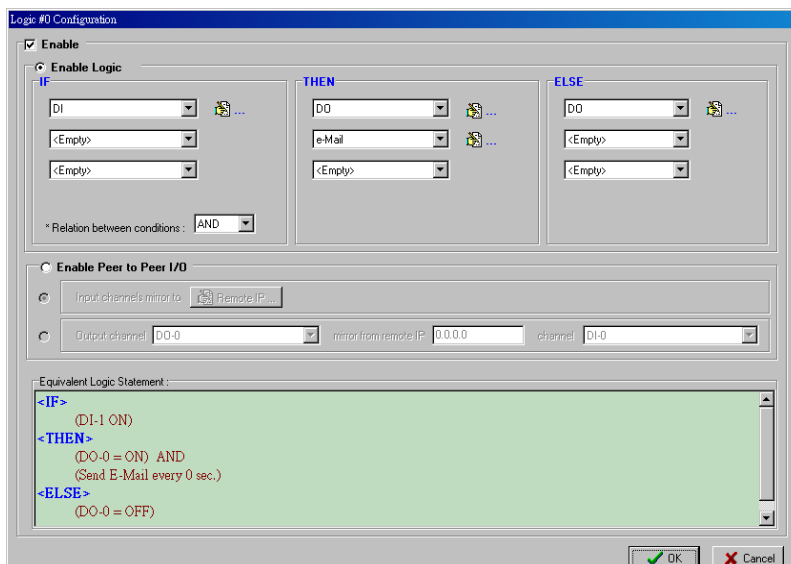
For one control logic rule, there are three "A"s that can be configured. "A" refers to the IF conditions that trigger an action. These three conditions can be operated by "AND" or "OR" logic. If "AND" logic is used, all three conditions must be true to create a positive result. If "OR" logic is used, one or more true conditions must be met to trigger the action.

| A1 | A2 | A3 | Result of AND Logic | A1 | A2 | A3 | Result of OR Logic |
|----|----|----|---------------------|----|----|----|--------------------|
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 0 | 0 | 1 | 0 | 0 | 0 | 1 | 1 |
| 0 | 1 | 0 | 0 | 0 | 1 | 0 | 1 |
| 0 | 1 | 1 | 0 | 0 | 1 | 1 | 1 |
| 1 | 0 | 0 | 1 | 1 | 0 | 0 | 1 |
| 1 | 0 | 1 | 1 | 1 | 0 | 1 | 1 |
| 1 | 1 | 0 | 1 | 0 | 0 | 0 | 1 |
| 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

The 24 rules are defined individually and are executed one by one in a loop. The 2nd rule can only be processed after running the 1st rule, and the entire rule-set will start running from the beginning after the last rule is processed.



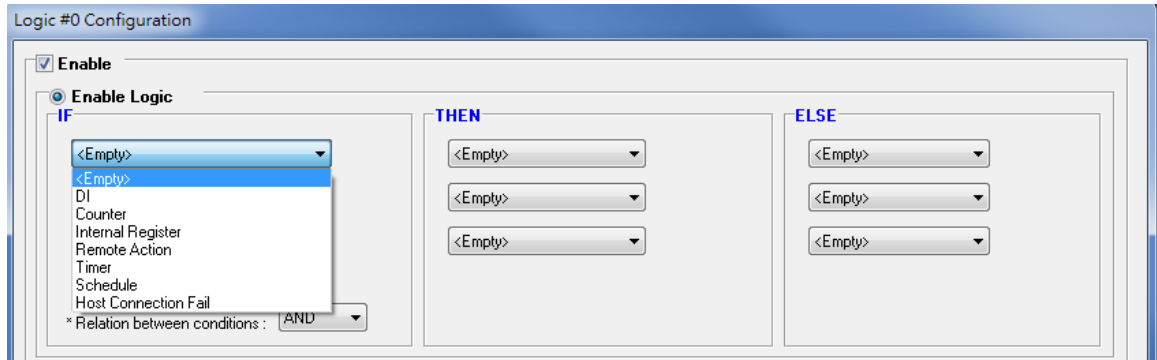
You will see a list of the rules in the current rule-set on the main screen. **Double Click** on a rule to open that rule's configuration window, as shown in the following figure, or double click on an empty rule to start a new rule.



Under **Relation between conditions**, select **AND** to specify that all conditions must be satisfied for the actions to take place; select **OR** to specify that any one of the conditions can be satisfied for the actions to take place. The **Equivalent Logic Statement** at the bottom shows a real-time text-based summary of the rule that you are defining. It provides a useful way to make sure the rule is designed as you intended.

IF Conditions

IF conditions are events that trigger **THEN/ELSE actions**. Under the **IF** column, you can set up to 3 conditions that must be satisfied for the actions under the **THEN/ELSE** column to take place. As soon as the IF conditions are satisfied, the specified THEN/ELSE action is performed. For example, an alarm can be activated when a door is opened. Use the pull downs to specify the conditions and units of measurement (e.g., DI-0=OFF).



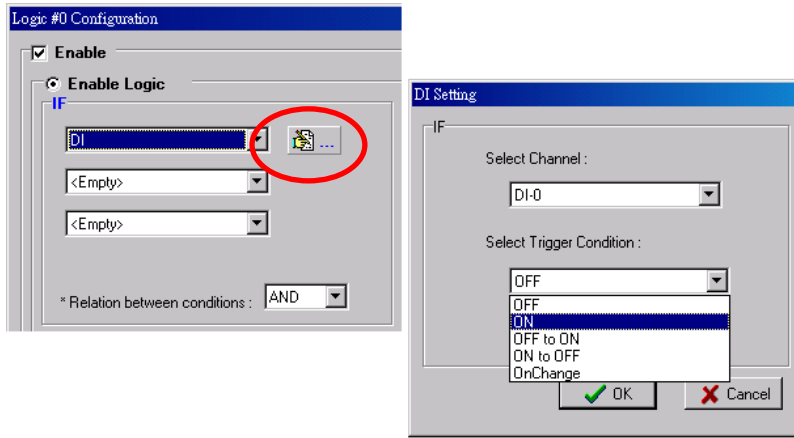
IF conditions can be specified as follows:

| IF Conditions | Operators | Remark |
|----------------------|---------------------------------------|---|
| DI | ON, OFF, ON to OFF, OFF to ON, Change | DI-x represents the channel number |
| Counter | =, >, <, >=, <=, Change | Counter-x represents the channel number. Max Counter Value: 4,294,967,295 |
| AI | =, >, <, >=, <= | AI-x represents the number of the channel. Max Value: Depends on the analog modes or the result of scaling. Internal Register(Float) can be used as the comparison or throughput setting controlled by remote SCADA or a Modbus/TCP program. |
| Relay | =, >, <, >=, <= | CurRelayCNT-x represents the current relay counts for the channel. Max Value: 4,294,967,295 |
| Internal Register | = | Reg-x represents the number of the internal register. x = 00 to 23 / Trigger Value: 0 to 255 |
| Timer | TIMEOUT | Timer-x, x = 00 to 23 Max value: 4,294,967 seconds |
| Schedule | | Time, Range and Recurrence |
| Host Connection Fail | N/A | When Port 502 is disconnected, the function will be activate |

DI

DI refers to the status of a digital input channel. Edge detection can be used to refine the conditions. For example, the condition **DI-0=OFF** is satisfied for as long as DI-0 remains off. The condition **DI-0=ON to OFF**, however, is only satisfied the instant the DI-0 turns off. The transition of the status change can also be handled using "Change" operator so it will trigger the related action whether it is ON-to-OFF or OFF-to-ON.

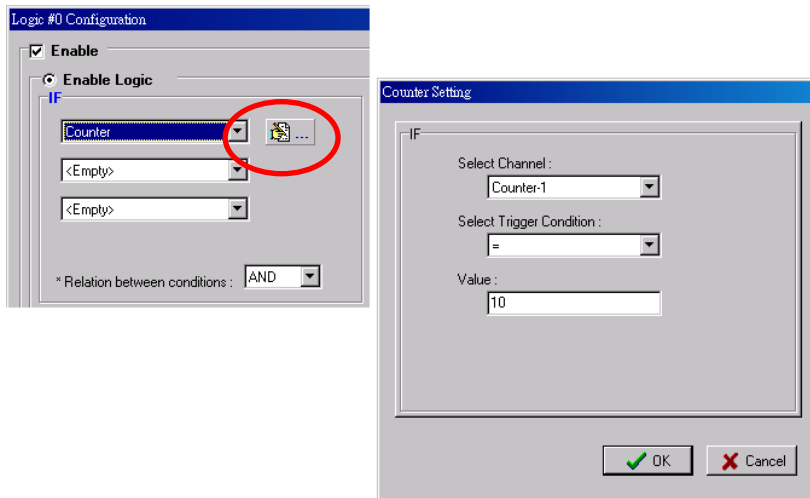
Scroll to select DI and click on the property () button to enter the DI Settings window.



Counter

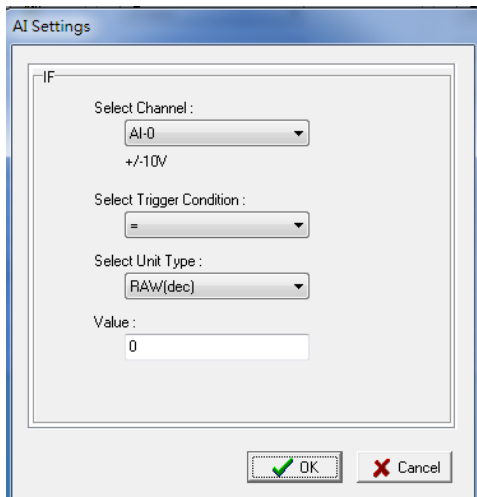
Counter refers to the counts of an Event Counter channel. The counts are stored in the ioLogik internally. Specifying the counts with a proper operator will lead to triggering the action. For example, 10 items should be packed in a box, so the Counter-x should be reset every 10 counts (**Counter-1=10**). Select the IF

condition to Counter and click on the property button () to enter the Counter Settings window.



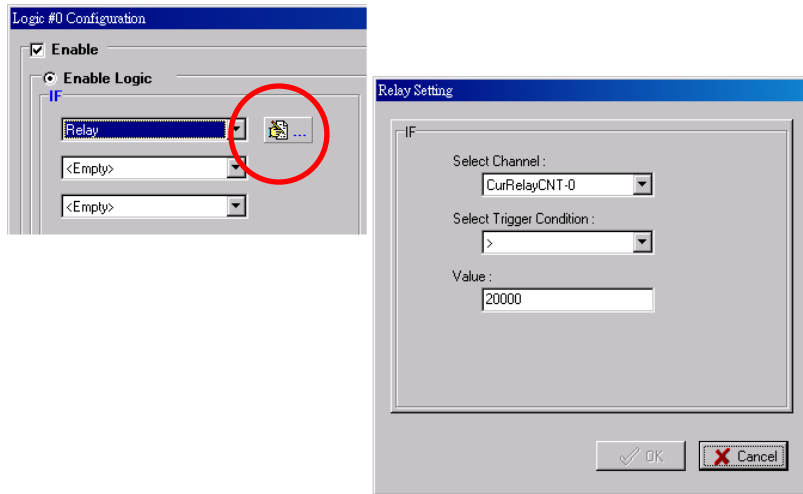
AI

AI refers to the readings of an analog input channel. An analog input value is specified to trigger an action. Units of the value are defined by the selected analog modes (voltage or current), or the scaling results. For example, **AI-0 > 15 mA** represents the high level of a water tank.




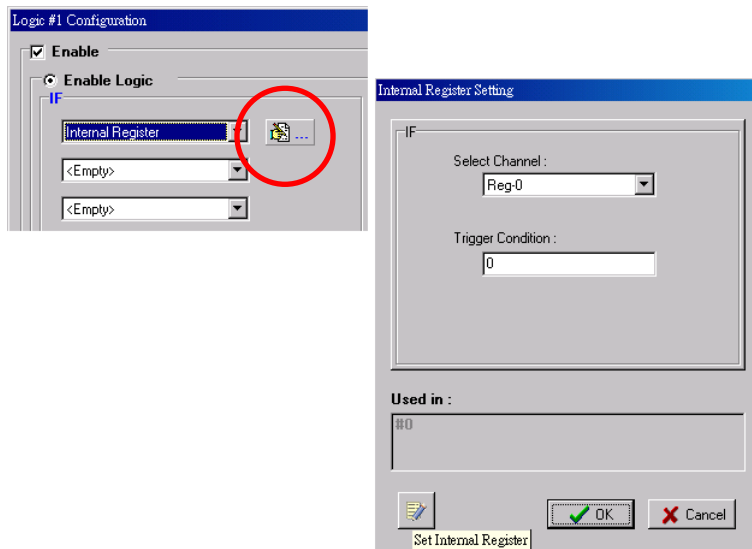
Relay (Counter)


Relay refers to the current counts of the relay usage. In ioLogik E2214, the counts of the relay usage is stored inside the ioLogik. Checking the current counts of a relay will produce the action. For example, the average life-cycle of a relay is 25,000 times. An alarm e-mail may be generated when the counter reaches 20,000 times (**CurRelayCNT-0 > 20000**) to report the need for replacement.



Internal Register (Integer)

Internal Register (Integer) represents a status flag to link the status of the first logic to the second one. It is used most often with the Timer function, or to combine other input statuses together. The Internal Register function also allows a PC to control the ioLogik’s local output when the remote output is controlled by a Click&Go log (e.g., digital output, active message, e-mail, or SNMP Trap). Select the IF condition for the Internal Register and click on the property button () to enter the Set Internal Register window.




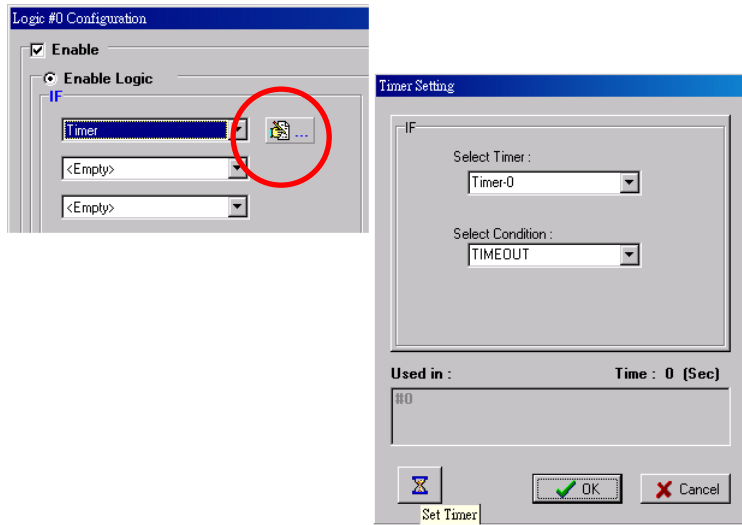
In the above figure, the “Used in:” column indicates that this Internal Register is also used with Rule-0, which helps the user identify the relationship between the rules. Also, the Set Internal Register button () will help to define the default values of all Internal Registers.


NOTE Internal Registers can be controlled by Modbus/TCP protocol. Refer to the appendix for the address list for all Internal Registers.

Timer

The **Timer** function can be used to control the timing of a logic rule in the IF conditions. “TIMEOUT” is the only operator here. For example, you can delay the triggering of an action or repeat an action periodically.


Select the IF condition for Timer and click on the property button () to enter the Timer Settings window.

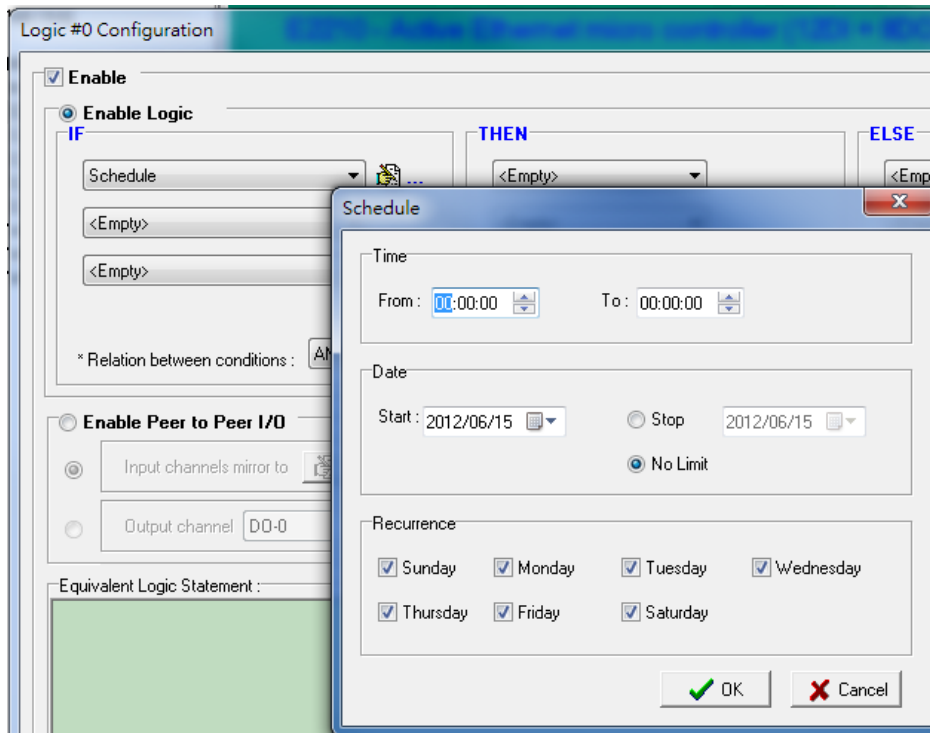


In the above figure, the "Used in:" column indicates this Timer is also used in Rule-0, which helps the user identify the relationship between rules. In addition, the Set Timer button () will help define the default value for the Timer.

Schedule

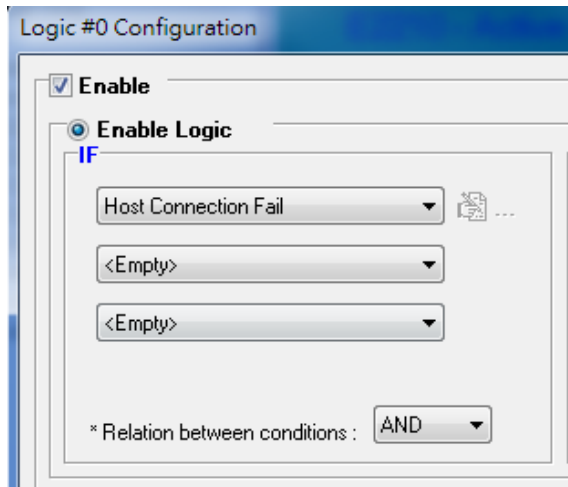
The **Schedule** function allows users to set a starting point or time period for a task. For example, the Schedule function could be used if a pump needs to start at 9: 00 PM and stop at 11:00 PM every Monday, Wednesday, and Friday.

Select the IF condition for Schedule and click on the property button () to enter the setting window. For recurrent actions, select the Recurrence checkbox and select the relevant weekdays. If a time period needs to be defined, specify the stop date in the range column.



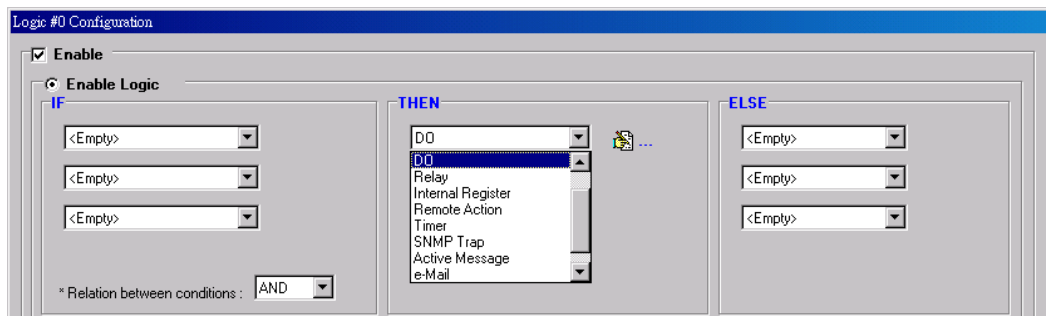
Host Connection Fail

The **Host Connection Fail** function allows the user to set condition when the connection with the Host Computer fails. For Example, IF Host Connection Fail, THEN Email to "xxx@moxa.com" with message "Connection with HOST computer have failed! Please react accordingly".



THEN/ELSE Actions

Under the **THEN** column, you can specify up to 3 actions that will be performed when the **IF** conditions are satisfied. 3 actions under the **ELSE** column will also be performed when the **IF** is **NOT** satisfied. Possible actions include changing the status of a DO channel, starting or stopping an Event Counter, or sending a message by SNMP trap, TCP, UDP, or e-mail.



| If Conditions | | | Result of AND Logic | Trigger of Then Actions | Trigger of ELSE Actions |
|---------------|----|----|------------------------|----------------------------|----------------------------|
| A1 | A2 | A3 | | | |
| 0 | 0 | 0 | 0 | NO | YES |
| 0 | 0 | 1 | 0 | NO | YES |
| 0 | 1 | 0 | 0 | NO | YES |
| 0 | 1 | 1 | 0 | NO | YES |
| 1 | 0 | 0 | 0 | NO | YES |
| 1 | 0 | 1 | 0 | NO | YES |
| 1 | 1 | 0 | 0 | NO | YES |
| 1 | 1 | 1 | 1 | YES | NO |

| If Conditions | | | Result of OR Logic | Trigger of Then Actions | Trigger of ELSE Actions |
|---------------|----|----|-----------------------|----------------------------|----------------------------|
| A1 | A2 | A3 | | | |
| 0 | 0 | 0 | 0 | NO | YES |
| 0 | 0 | 1 | 1 | YES | NO |
| 0 | 1 | 0 | 1 | YES | NO |
| 0 | 1 | 1 | 1 | YES | NO |
| 1 | 0 | 0 | 1 | YES | NO |
| 1 | 0 | 1 | 1 | YES | NO |
| 1 | 1 | 0 | 1 | YES | NO |
| 1 | 1 | 1 | 1 | YES | NO |

THEN/ELSE actions can be specified as follows:


| THEN/ELSE Actions | Operators | Remark |
|-----------------------|-------------------------|---|
| Counter | RESET | Counter-x represents the number of the Event Counter channel |
| DO | ON, OFF | DO-x represents the number of the channel. |
| Pulse Output | STOP, START | Pulse Output-x represents the number of the channel |
| AO | | Built-in or Expansion |
| Relay | RESET | ResetCNT-x represents the number of the relay channel. |
| Internal Register | | Reg-x represents the number of the internal register. x = 00 to 23 / Trigger Value: 0 to 255 |
| Timer | STOP, START, RESTART | Timer-x, x = 00 to 23 Max value: 4,294,967 seconds |
| SNMP Trap | | I/O Status Bindings: 3 sets |
| Active Message | ID / Source IP | Unicode supported |
| e-Mail | | Create the contents of the e-Mail |
| Short Message Service | | Select recipients from the phone book, define the content, and configure the escalation |
| Data Log Start/Stop | Start, Stop | Select which profile to start or stop |
| FTP Service | | Select which profile and FTP server to upload the log file |
| CGI Command | ID / Source IP | Specify the target URL and CGI commands |

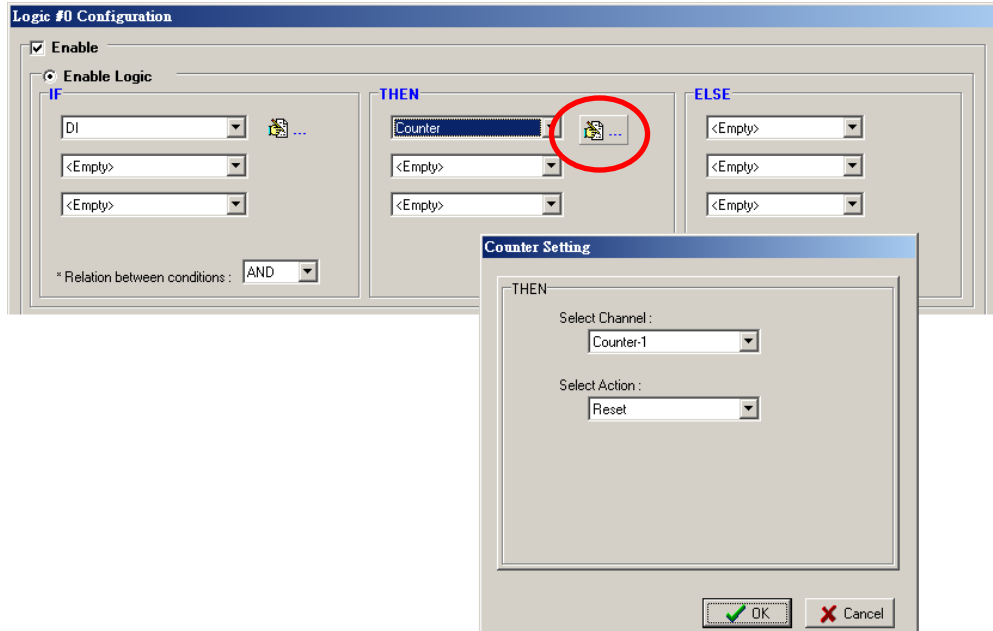
NOTE The following THEN Actions are only supported by ioLogik W5300 Cellular Remote IO devices: **Short Message Service, Data Log Start/Stop, and FTP Service.**

NOTE Click&Go only allows one message-type action (Active Message, e-Mail, Short Message Service, or CGI Command) in each THEN/ELSE row.


Counter

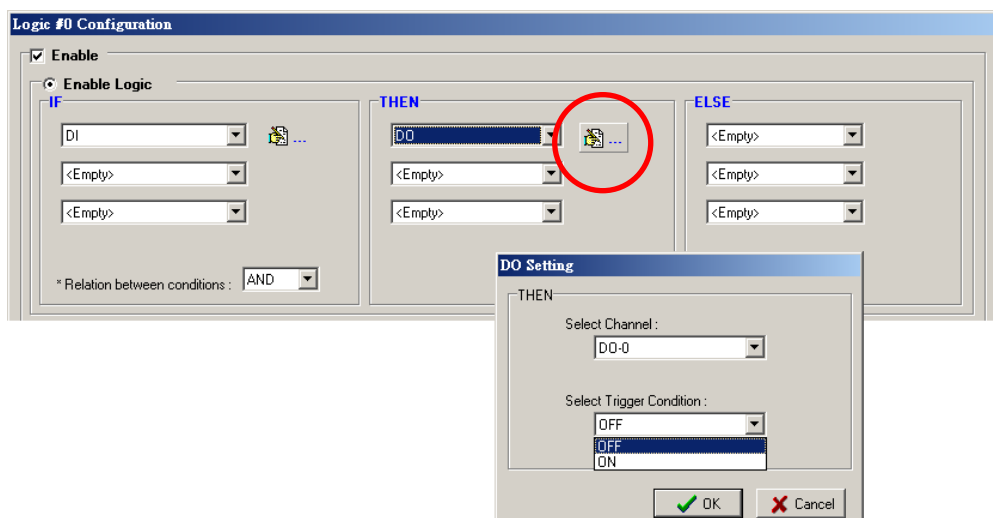
In this THEN/ELSE action, the only operator for the **Counter** function is "RESET", which clears the counts of an Event Counter channel. This function is often used in a charging system to clear the readings of a meter.

Select the THEN/ELSE action to **Counter** and click on the property button () to enter the Counter Settings window.




DO

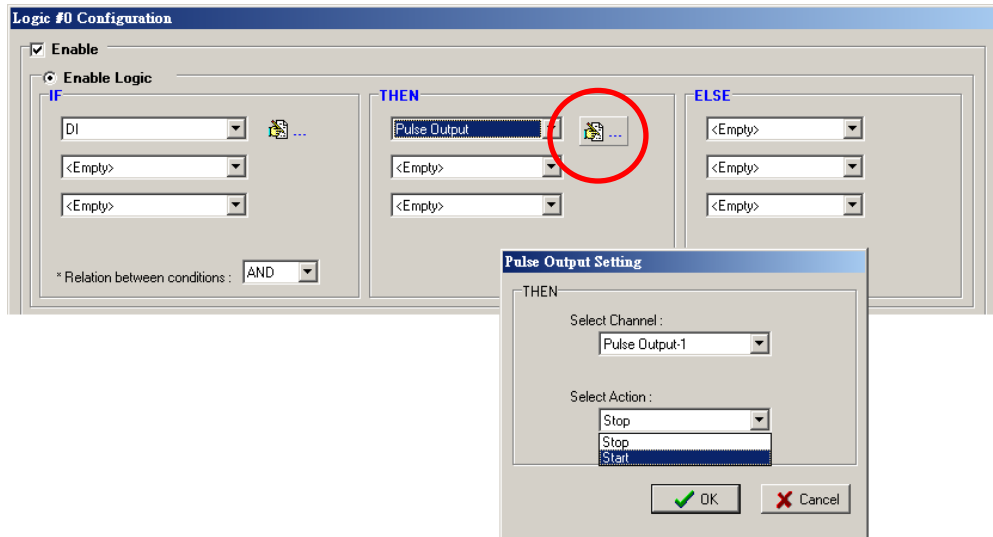
DO refer to the action of controlling the local digital output channels that react to the IF conditions. Select the THEN/ELSE action to DO and click on the property button () to enter the DO Settings window.




NOTE A Relay output channel is also referred to as a DO channel in the THEN/ELSE action fields.

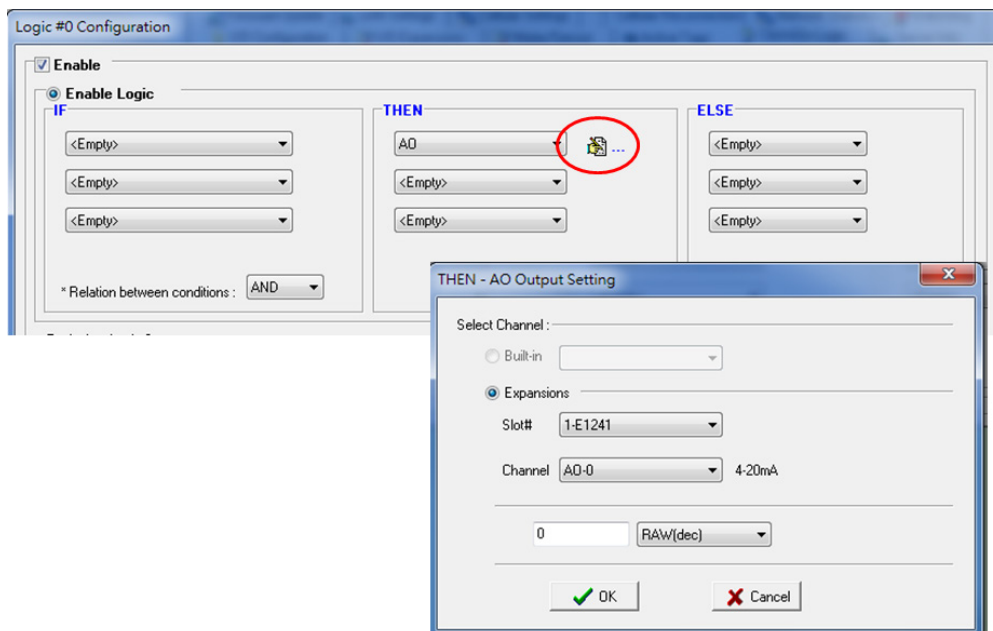
Pulse Output

Pulse Output starts or stops a pulse. It is usually used to create the flash for an alarm light. Select the THEN/ELSE action to Pulse Output and click on the property button () to enter the Pulse Output Settings window.



AO


Analog Output (AO) refers to the action of controlling the local Analog Output channels that react to the IF conditions. Select the THEN/ELSE action to AO and click on the property button () to enter the AO Settings window.

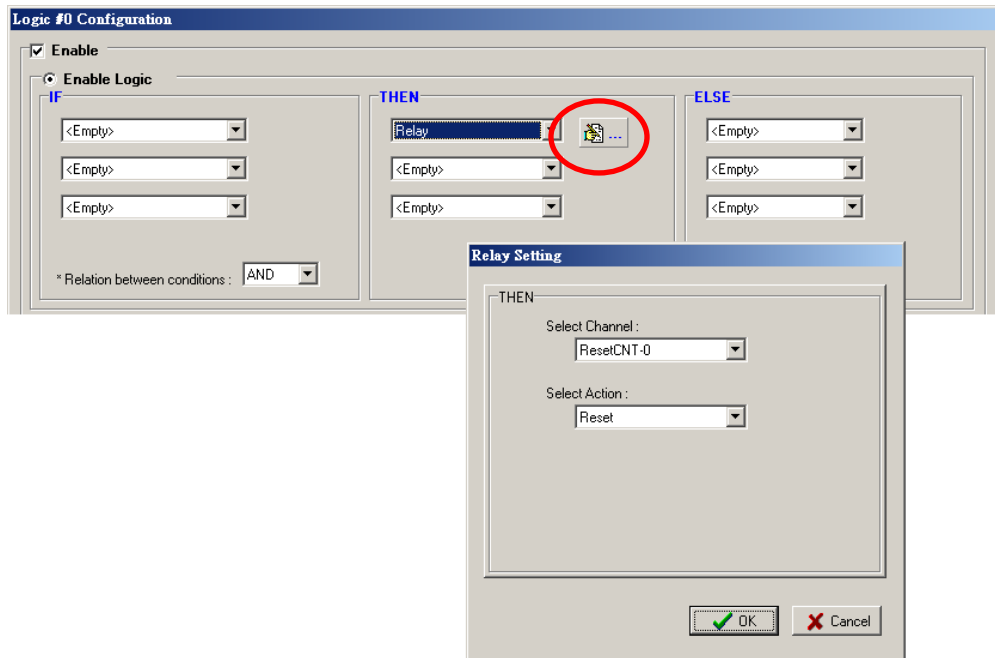


NOTE AO Channels is only built-in in the ioLogik E2240 model.

Relay (Counts)


In the THEN/ELSE action, **Relay** refers to the current counts specifying how many times a relay has been triggered. The counts are stored internally and can be cleared. "RESET" is the only operator. Select the

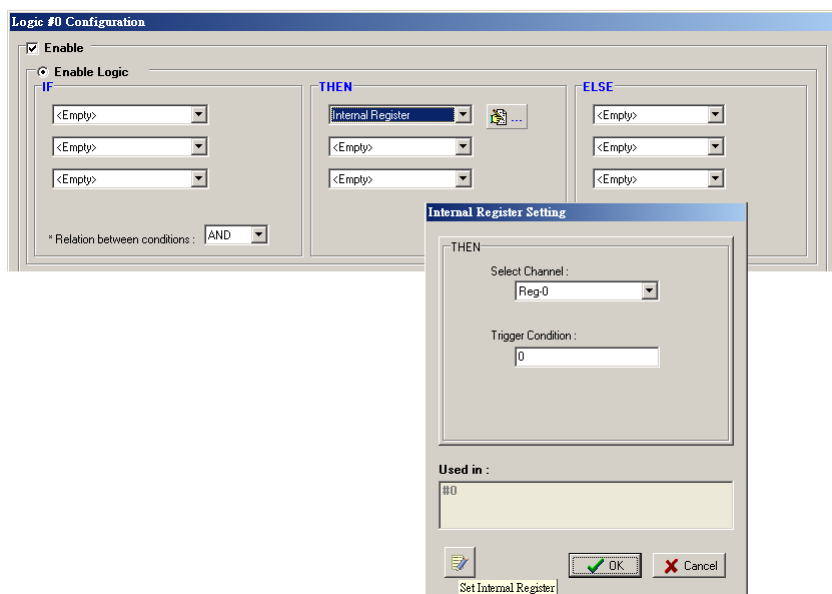
THEN/ELSE action to Relay and click on the property button () to enter the Relay Settings window.




Internal Register (Integer)

Internal Register (Integer) represents a status flag to link the status of the first logic to the second one by specifying other actions in the THEN/ELSE fields. Values from 0 to 255 can be used here. Select the

THEN/ELSE action for Timer and click on the property button () to enter the Internal Register Settings window.




In the above figure, the "Used in:" column indicates that this Internal Register is also used in Rule-0, which helps the user identify the relationship between the rules. In addition, the Set Internal Register button

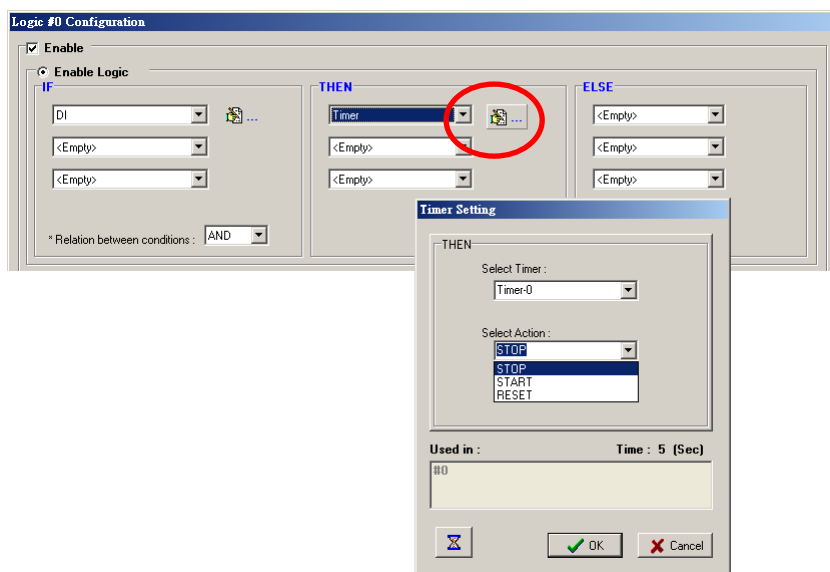
() can be used to define the default values of all registers.


NOTE Internal Register can be controlled by Modbus/TCP protocol. Refer to the appendix for the address list of all Internal Registers.

Timer

The **Timer** function can be used to control the time settings of a logic rule. Actions such as "START", STOP, and "RESTART" can be configured here.

Select the IF condition for Timer and click on the property button () to enter the Timer Settings window.



In the above figure, the "Used in:" column indicates this Timer is also used in Rule-0, which helps the user identify the relationship between the rules. In addition, the Set Timer button () can be used to define the default value of the Timer.

NOTE The "STOP" operator stops the timer and returns to "Initial Timer Value", and the "RESTART" operator clears and restarts the timer.




ATTENTION

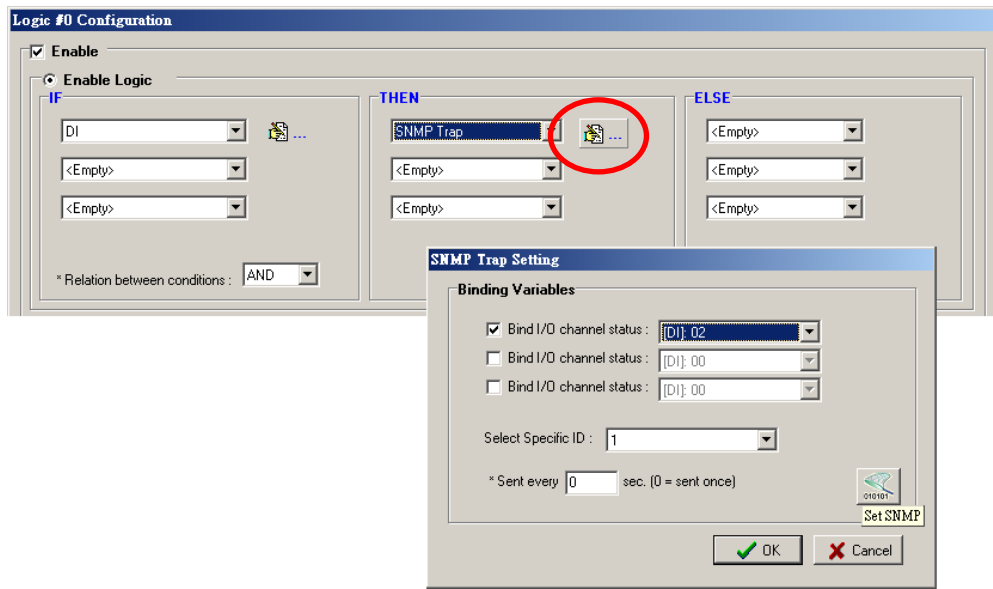
The STOP or RESTART operator should always be used to reset or to restart the timer. If you do not use these operators, the Timer function can only be triggered once.

SNMP Trap

The **SNMP Trap** function sends an SNMP trap to one or more IP destinations. The trap number can be any number between 1 and 20. (You may need to consult with your network administrator to determine how trap numbers will be used and defined on your network.) Select the THEN/ELSE action for SNMP Trap and


click the property button () to enter the SNMP Settings window. You can also bind the status of up


to three I/O channels within each trap. Click the Set SNMP button () to specify up to 10 recipients for the SNMP trap.

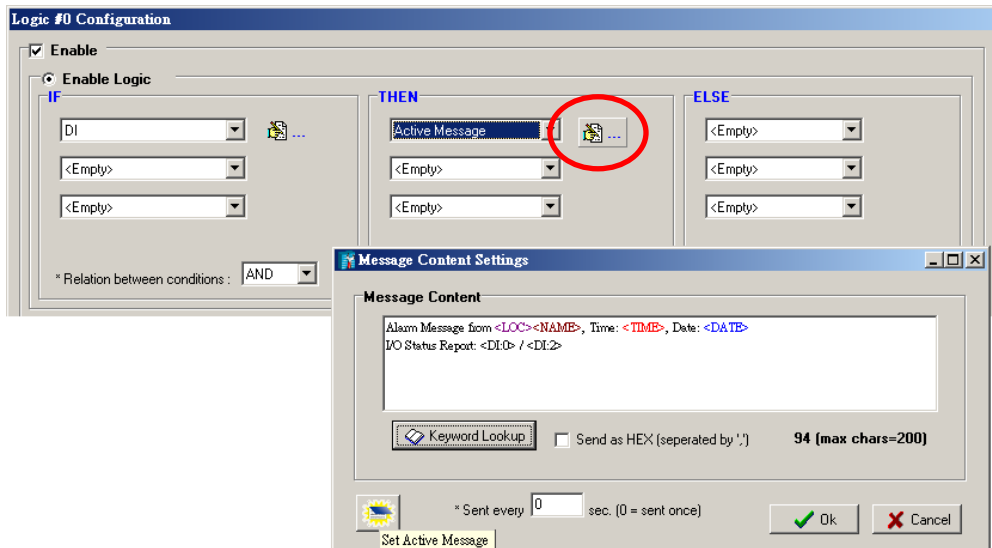


Active Message

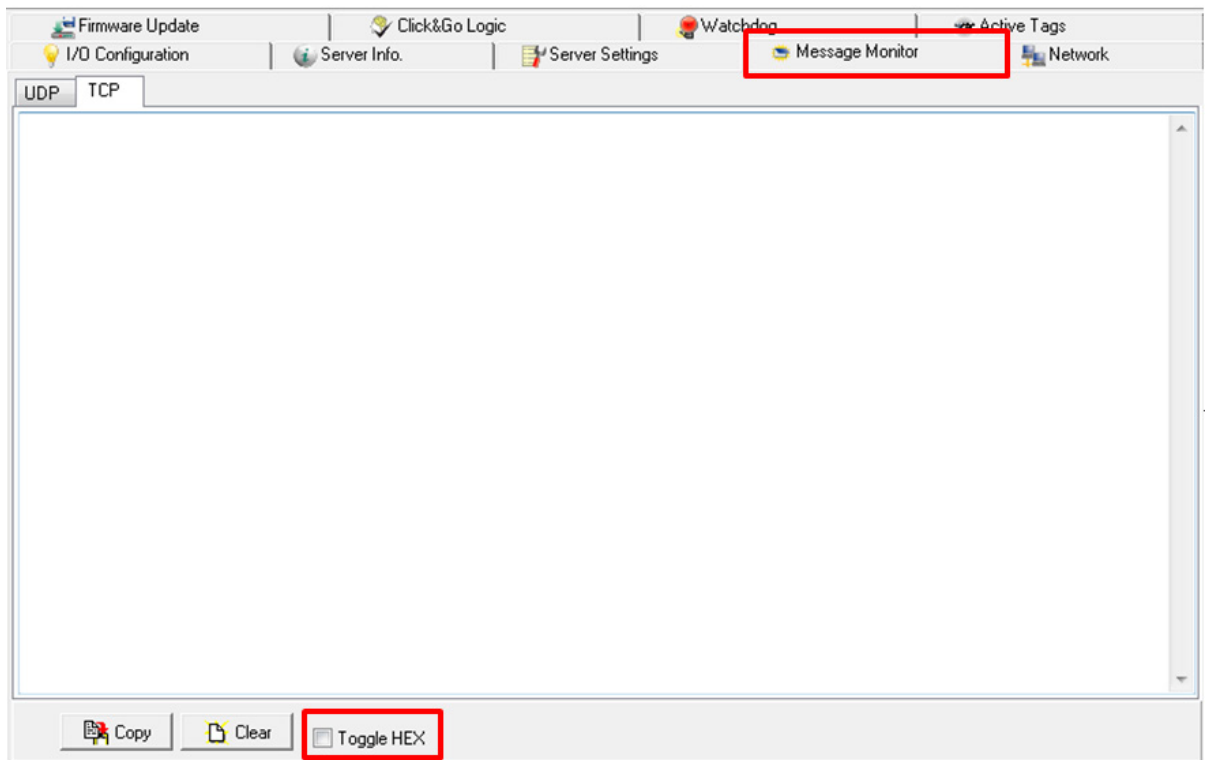
In response to a proper IF condition, the **Active Message** function sends a customized message to one or more IP destinations by TCP or UDP packets. Select the THEN/ELSE action for Active Message and then click

the property button () to enter the Message Content Settings window. Enter your desired message in the **Message Content** column. Dynamic fields such as time, date, IP address, and I/O status can be inserted in your message by clicking **Keyword Lookup**. Messages are sent in ASCII by default, but can be sent in HEX by selecting the "**Send as HEX (separated by ",")**" checkbox.

Click the Set Active Message button () to configure the default parameters such as the messaging protocol (TCP or UDP), socket port (9000 by default), and the up to 10 target message servers.




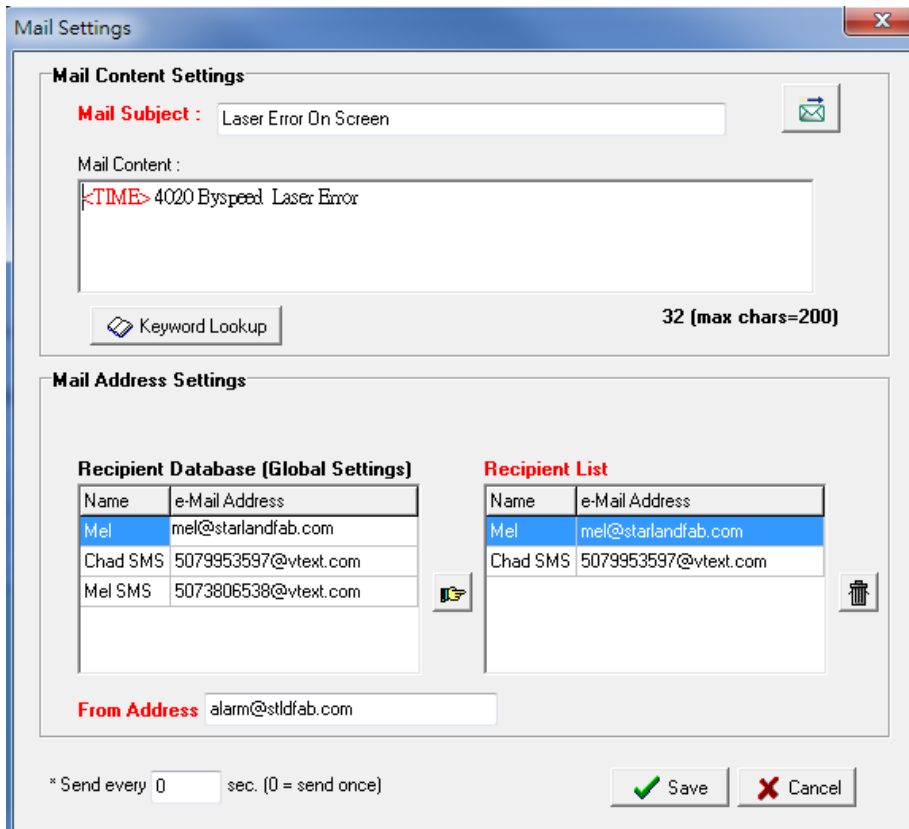
Active Messages can be received by a program using standard sockets, Moxa MXIO library, or ioAdmin’s Message Monitor, as shown in the following screen shot:



When sending a message in HEX, each HEX value must be separated by commas. View the incoming message on the Message Monitor panel and select the **HEX** checkbox. Note that certain numbers are control characters that will not show up in the Message Monitor. The maximum number of characters is 200.

Email

The **E-mail** function sends a customizable e-mail to one or more mail boxes or Blackberry devices. Select the THEN/ELSE action to e-mail and click the property button () to enter the Mail Settings window.



The Mail Settings dialog box is divided into two main sections: Mail Content Settings and Mail Address Settings.

Mail Content Settings:

- Mail Subject:** Laser Error On Screen
- Mail Content:** <TIME> 4020 Byspeed Laser Error
- Keyword Lookup:** A button to insert dynamic fields.
- Character Count:** 32 (max chars=200)

Mail Address Settings:

- Recipient Database (Global Settings):**



| Name | e-Mail Address |
|----------|----------------------|
| Mel | mel@starlandfab.com |
| Chad SMS | 5079953597@vtext.com |
| Mel SMS | 5073806538@vtext.com |
- Recipient List:**

| Name | e-Mail Address |
|----------|----------------------|
| Mel | mel@starlandfab.com |
| Chad SMS | 5079953597@vtext.com |
- From Address:** alarm@stldfab.com
- Frequency:** * Send every 0 sec. (0 = send once)
- Buttons:** Save (green checkmark), Cancel (red X)

After entering the subject of an e-mail, enter the message in the **Mail Content** area. Dynamic fields such as time, date, IP address, and I/O status can be inserted in your message by clicking **Keyword Lookup**.


NOTE Content in the same logic entry can be sent by either Active Message or e-mail, in which case the content of the messages will be the same. If you would like to send an Active Message and e-mail based on the same event but with different content, you will need to use two separate logic entries—one for the Active Message and one for the e-mail.

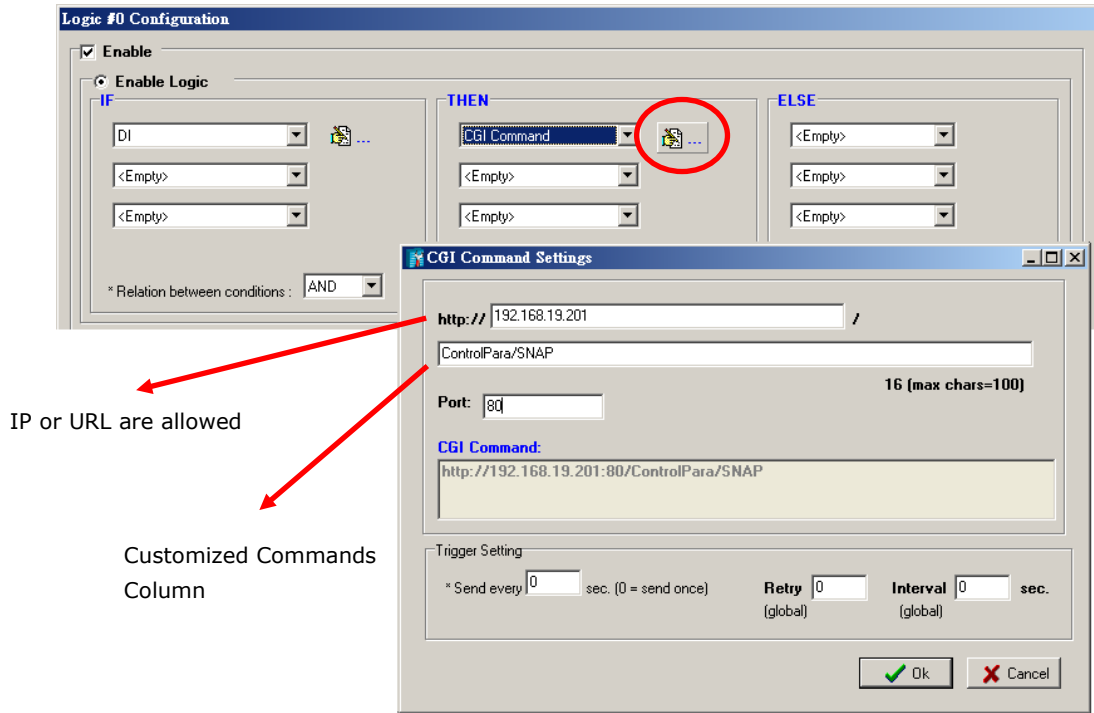
SMTP server information including username/password, and the recipient database can be configured by

clicking the Set Mail Address button (). Click the finger icon () to move the selected address from the Recipient Database to the Recipient List.

To manually add e-mail addresses to the Recipient Database, enter the **Name** and **Mail Address** and click **Add**. Once the address has been added to the **Recipient Database**, use the finger icons to move it to or from the **Recipient List**. Select **Attach data log** to specify that the log profile and period will be attached to the email. Set **Hours** to 24 if you would like to receive all logs generated in the past 24 hours.

CGI Command

Not only do the ioLogik products support CGI commands, they also allow the Click&Go logic to interact with proper IF conditions and send out CGI commands to IP Video devices such as the Moxa V351 video server or VPort 25 IP camera. Support for user-defined CGI commands in the Click&Go THEN/ELSE action turns the ioLogik product into the expansion I/O controller of these video devices. For example, setting a trigger to focus and take a snapshot when there is an intrusion. Select the THEN/ELSE actions for the CGI command and click on the property button () to enter the CGI Command Settings window.



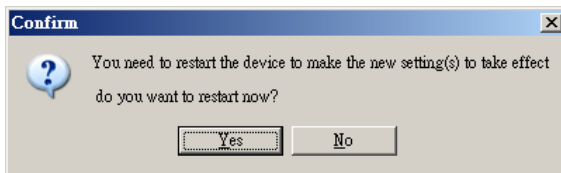
NOTE In the first address column, IP address or URL can be used to specify the target. Only the DNS and Gateway settings of the ioLogik need to be specified. Refer to the target IP video devices' user manual for detail CGI command formats.

Activating the Rule-set

Upload, Restart, and Run

The rules that are displayed on the Click&Go Logic panel include the current rule-set, which acts as the brain of your ioLogik system. The rule-set must be activated as follows for the ioLogik to commence local control operation:

1. The rule-set must first be downloaded from ioAdmin to the ioLogik. To download the rule-set, click **Upload to ioLogik** from the Rule-set Management bar.
2. After the rule-set has been downloaded, ioAdmin will prompt to restart the ioLogik automatically after clicking "yes" to confirm. Do not use the reset button, since doing so will load all factory defaults and erase your rule-set from memory.



3. After the ioLogik has been restarted, the rule-set must be activated. Log in to ioAdmin as administrator, go to the Click&Go Logic panel and click **Run** in the Rule-set Management bar. The rules in the rule-set will now be active.

When the rule-set has been activated, it will remain active even when the ioLogik is disconnected from the host computer or from the network. If the ioLogik is turned off, device operation will resume when it is turned back on, allowing you to use the ioLogik for PC-independent automation.

Rule-set Management Bar

When the rule-set has been activated from the Click&Go panel it will remain active even when the ioLogik is disconnected from the host computer or from the network. If the ioLogik is turned off, device operation will resume when it is turned back on, allowing you to use the ioLogik for PC-independent automation.



- **Clear:** Erases the rule-set in both ioAdmin and the ioLogik series.
- **Retrieve:** Copies the rule-set from the ioLogik into ioAdmin.
- **Upload to ioLogik:** Copies the rule-set from ioAdmin to the ioLogik.
- **Run:** Activates the rule-set that the ioLogik booted up with.
- **Stop:** De-activates the Click&Go rule-set and returns the ioLogik to normal, passive operation.

Import/Export Configuration

The ioLogik's system configuration, including the current Click&Go rule-set, can be imported and exported. As you make changes to a rule-set, you can export the system configuration in order to save that rule-set. Details can be found in Chapter 2.

Log in as ioAdmin administrator from the **Server Settings** panel. You must log in as administrator to gain access to the ioLogik's configuration options. If a password has not been configured, simply click **Login** and leave the **Password** entry field blank.

More Information about Repeat Interval vs. Edge Detection

Combining the Timer function with other IF conditions allows actions to be repeated when the specified logic is sustained over a period of time. However, if a condition is based on edge detection (i.e., **ON to OFF** or **OFF to ON**), it can only be triggered once.

The following scenarios illustrate how edge detection affects the **Timer = N sec**. In each diagram, the statuses of three sensors are shown over a period of time, with a high signal corresponding to a "true" condition. The green shaded area shows the duration of time that the IF conditions have been met.

| | | |
|--|-----------------|-----------------|
| <p>No Edge Detection</p> <p>In this scenario, the rule checks each sensor for "on" status, so edge detection is not involved. As long as the sensors remain on, the required conditions are satisfied, and the THEN actions will repeat at interval N.</p> | | |
| <p>DI-0 = ON</p> <p>DI-1 = ON</p> <p>DI-2 = ON</p> | | |
| Relation between conditions | AND | OR |
| "IF" conditions satisfied | | |
| Repeat interval | "Timer = N sec" | "Timer = N sec" |
| "THEN" action triggered | | |
| <p>Edge Detection for All Conditions</p> <p>In this scenario, the rule checks each sensor for a change from "off" to "on" status, meaning only edge detection conditions are used. As soon as a sensor changes from "off" to "on", the condition is satisfied, but only for that instant. Right after that instant, the condition is no longer satisfied because it is no longer changing from "off" to "on". The repeat interval will have no effect, since edge conditions cannot be sustained over a period of time.</p> | | |
| <p>DI-0 = OFF to ON</p> <p>DI-1 = OFF to ON</p> <p>DI-2 = OFF to ON</p> | | |
| Relation between conditions | AND | OR |
| "IF" conditions satisfied | | |
| Repeat interval | N/A | N/A |
| "THEN" action triggered | | |

| Edge Detection for Two Conditions | | |
|---|-----|-----------------|
| <p>In this scenario, the rule checks DI-0 and DI-1 for a change in status and DI-2 for status only. The repeat interval will not have an effect if the AND relationship is used, because the two edge conditions can never be sustained over a length of time. With the OR relationship, the IF conditions will be satisfied as long as DI-2 is "on", and the THEN actions will be triggered over interval N.</p> | | |
| <p>DI-0 = OFF to ON</p> <p>DI-1 = OFF to ON</p> <p>DI-2 = ON</p> | | |
| Relation between conditions | AND | OR |
| "IF" conditions satisfied | | |
| Repeat interval | N/A | N/A |
| "THEN" action triggered | | |
| Edge Detection for One Condition | | |
| <p>In this scenario, the rule checks DI-0 for a change in status and DI-1 and DI-2 for status only. The repeat interval will not have an effect if the AND relationship is used, because the edge condition for DI-0 can never be sustained over a length of time. With the OR relationship, the IF conditions will be satisfied as long as DI-1 or DI-2 is "on", and the THEN actions will be triggered over interval N.</p> | | |
| <p>DI-0 = OFF to ON</p> <p>DI-1 = ON</p> <p>DI-2 = ON</p> | | |
| Relation between conditions | AND | OR |
| "IF" conditions satisfied | | |
| Repeat interval | N/A | "Timer = N sec" |
| "THEN" action triggered | | |

Using the Web Console

The ioLogik E2200 series has a built-in web console can be used to configure many of the ioLogik's settings.

The following topics are covered in this chapter:

❑ **Introduction to the Web Console**

❑ **Overview**

❑ **Basic Settings**

❑ **Network Settings**

- General Settings
- Ethernet Configurations
- RS-485 Settings

❑ **I/O Settings**

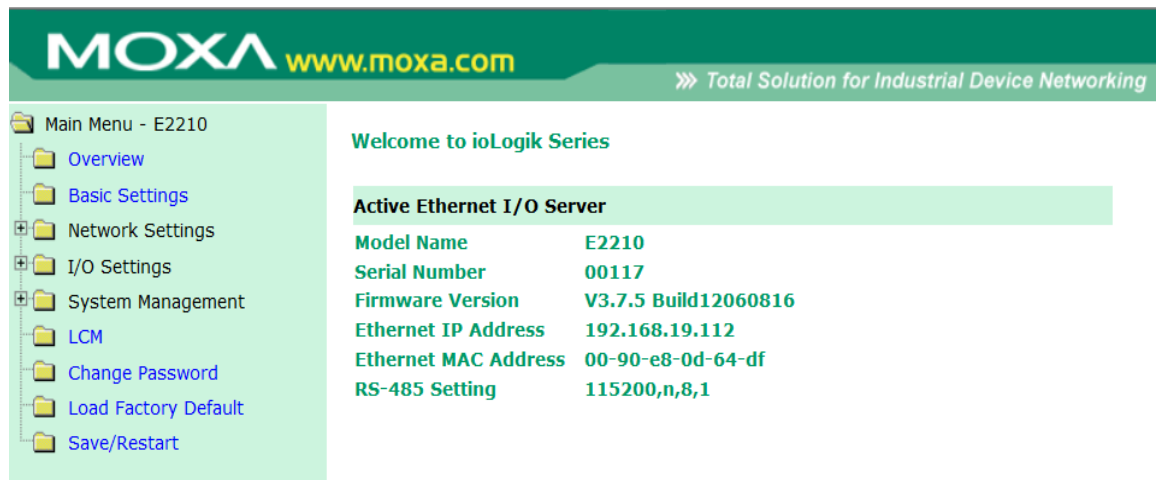
- DI Channels
- DO Channels
- AI Channels
- Alias Name
- AO Channels
- Relay Output Channel
- Relay Count Motoring
- Alias Name set
- RTD Channels
- TC Channels

❑ **System Management**

- Accessible IP Settings
- SNMP Agent
- Network Connection
- Firmware Update
- Import System Config
- Export System Config
- LCM
- Change Password
- Load Factory Default
- Save/Restart

Introduction to the Web Console

The ioLogik web console is a browser-based configuration utility. When the ioLogik is connected to your network, you may enter the server's IP address in your web browser to access the web console.



The left panel is the navigation panel and contains an expandable menu tree for navigating among the various settings and categories. When you click on a menu item in the navigation panel, the main window will display the corresponding options for that item. Configuration changes can then be made in the main window. For example, if you click on **Network Settings** in the navigation panel, the main window will show a page of basic settings that you can configure.

You must click on the **Submit** button after making configuration changes. The **Submit** button will be located at the bottom of every page that has configurable settings. If you navigate to another page without clicking the **Submit** button, your changes will not be retained.

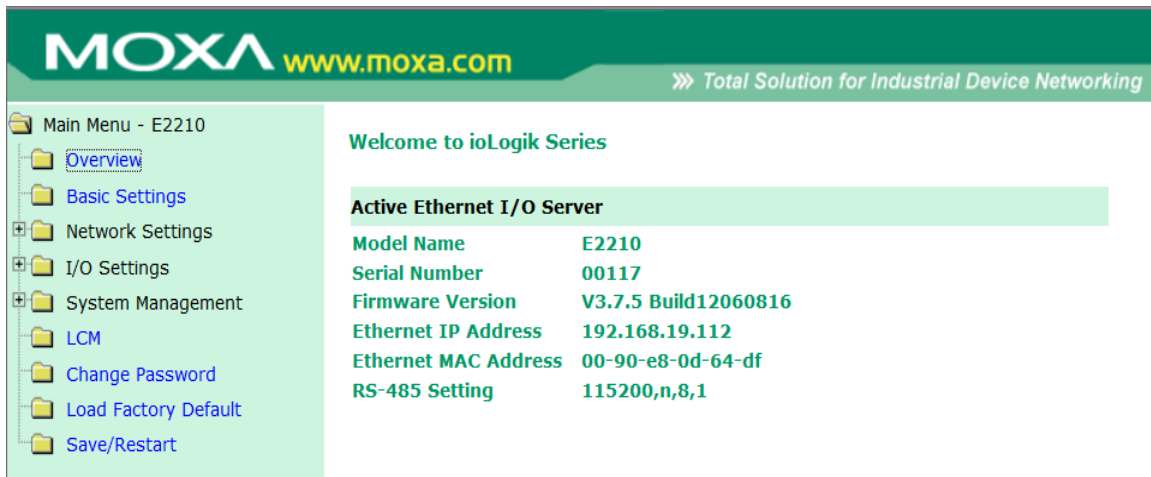
Submitted changes will not take effect until they are saved and the ioLogik is restarted! You may save and restart the server in one step by clicking on the **Save/Restart** button after you submit a change. If you need to make several changes before restarting, you may save your changes without restarting by selecting **Save/Restart** in the navigation panel. If you restart the ioLogik without saving your configuration, the ioLogik will discard all submitted changes.

1. [Overview](#)
2. [Basic Settings](#)
3. [Network Settings](#)
4. [I/O Setting](#)
5. [System Management](#)
6. [LCM](#)
7. [Change Password](#)
8. [Load Factory Default](#)
9. [Save/Restart](#)

NOTE The web console is best viewed with Internet Explorer 9 or higher; some functionality may not be supported when using other browsers.

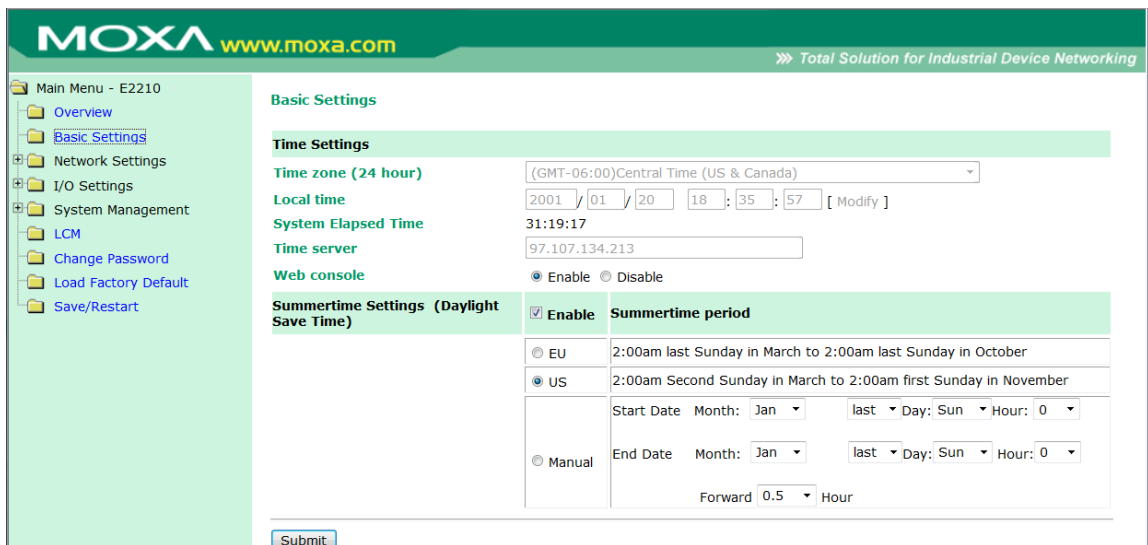
Overview

The Overview page contains basic information about the ioLogik, including the model name, serial number, firmware version, MAC address, and current IP address.



Basic Settings

On the **Basic Settings** page, you can set the ioLogik’s system time or provide the IP address of a time server for time synchronization.



Network Settings

General Settings

On the **General Settings** page, you can assign a server name and location to assist you in differentiating between different I/O servers, and enable the Host Communication Watchdog and define the timeout value.

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Main Menu - E2242

- Overview
- Basic Settings
- Network Settings
 - General Settings
 - Ethernet Configurations
 - RS-485 Settings
- I/O Settings
- System Management
 - LCM
 - Change Password
 - Load Factory Default
 - Save/Restart

General Settings

I/O Server Settings

Server Name

Server Location

DNS Server 1

DNS Server 2

Enable communication watchdog sec

Submit

When enabled, the **communication watchdog** monitors the network connection. If the connection is lost for the specified number of seconds, the watchdog will activate the Safe Status settings for each DO channel and Event Counter channel. By default, the watchdog is disabled. To enable the Watchdog, select **Enable communication watchdog** and set the timeout value.

Ethernet Configurations

On the **Ethernet Configurations** page, you can set up a static or dynamic IP address for the ioLogik to configure the subnet mask and gateway address.

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Main Menu - E2242

- Overview
- Basic Settings
- Network Settings
 - General Settings
 - Ethernet Configurations
 - RS-485 Settings
- I/O Settings
- System Management
 - LCM
 - Change Password
 - Load Factory Default
 - Save/Restart

Ethernet Configurations

Ethernet Parameters

IP Configuration

IP Address

Subnet Mask

Gateway

Submit

RS-485 Settings

On the **RS-485 Settings** page, you can view the serial communication parameters, but no configuration changes are allowed. The baudrate can only be configured using the physical dial on the back of the unit. This is a reserved function.

MOXA www.moxa.com Total Solution for Industrial Device Networking

Main Menu - E2242

- Overview
- Basic Settings
- Network Settings
 - General Settings
 - Ethernet Configurations
 - RS-485 Settings
- I/O Settings
- System Management
 - LCM
 - Change Password
 - Load Factory Default
 - Save/Restart

RS-485 Settings

Serial Parameters

Unit ID

Baud Rate

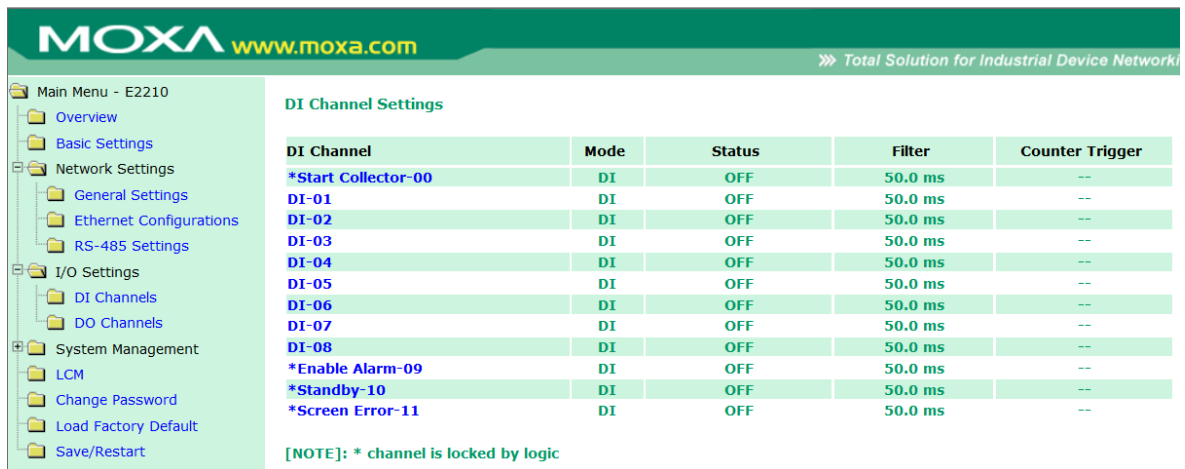
Data Bits

Stop Bits

Parity

I/O Settings

You can view the settings for DI and DO channels in the web console. DIO channels will be listed according to the configured channel type (DI or DO).



DI Channel Settings

| DI Channel | Mode | Status | Filter | Counter Trigger |
|---------------------|------|--------|---------|-----------------|
| *Start Collector-00 | DI | OFF | 50.0 ms | -- |
| DI-01 | DI | OFF | 50.0 ms | -- |
| DI-02 | DI | OFF | 50.0 ms | -- |
| DI-03 | DI | OFF | 50.0 ms | -- |
| DI-04 | DI | OFF | 50.0 ms | -- |
| DI-05 | DI | OFF | 50.0 ms | -- |
| DI-06 | DI | OFF | 50.0 ms | -- |
| DI-07 | DI | OFF | 50.0 ms | -- |
| DI-08 | DI | OFF | 50.0 ms | -- |
| *Enable Alarm-09 | DI | OFF | 50.0 ms | -- |
| *Standby-10 | DI | OFF | 50.0 ms | -- |
| *Screen Error-11 | DI | OFF | 50.0 ms | -- |

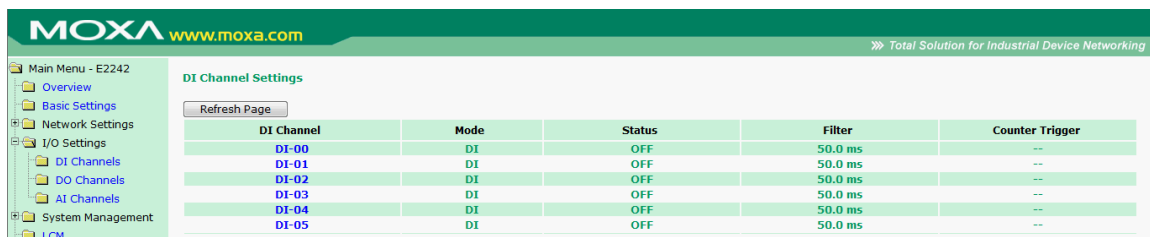
[NOTE]: * channel is locked by logic

ioLogik 2210 (above pic)

1. [DI Channel](#)
2. [DO Channel](#)
3. [AI Channel](#)
4. [AO Channel](#)
5. [Relay Output](#)
6. [Relay Count Monitoring](#)
7. [RTD Channel](#)
8. [TC Channel](#)

DI Channels

On the **DI Channels** page, you can view the status of each DI (digital input) channel. Only DIO channels that are acting as DI channels will be displayed.

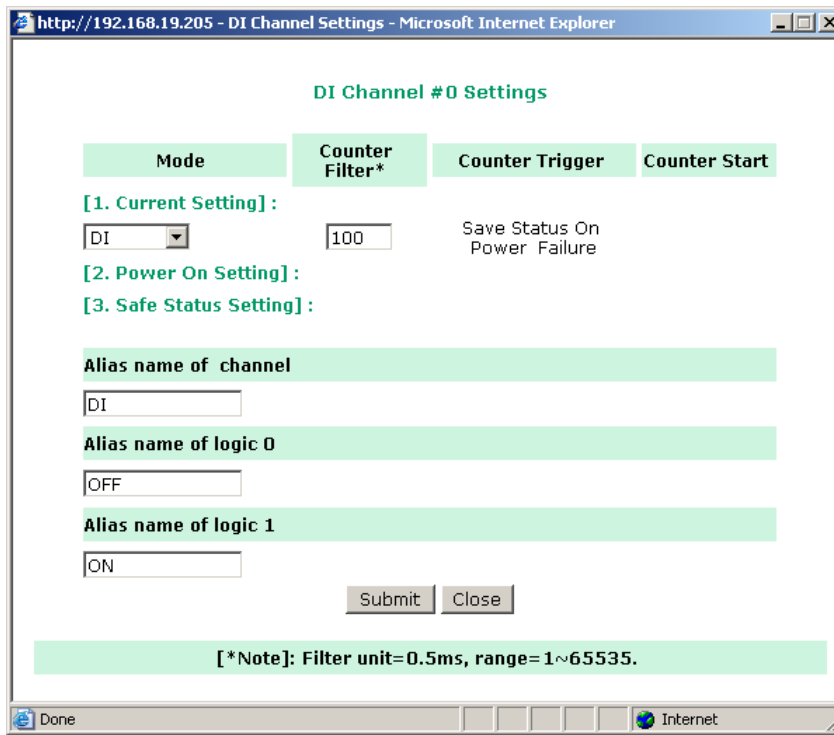


DI Channel Settings

| DI Channel | Mode | Status | Filter | Counter Trigger |
|------------|------|--------|---------|-----------------|
| DI-00 | DI | OFF | 50.0 ms | -- |
| DI-01 | DI | OFF | 50.0 ms | -- |
| DI-02 | DI | OFF | 50.0 ms | -- |
| DI-03 | DI | OFF | 50.0 ms | -- |
| DI-04 | DI | OFF | 50.0 ms | -- |
| DI-05 | DI | OFF | 50.0 ms | -- |

Click on a channel to see that channel's configuration options. DI channels can operate in DI mode or Event Counter mode. Software filtering is used to control switch bounces. The filter is configurable in multiples of 0.5 ms and accepts values between 1 and 65535. For example, a setting of **2** would mean a 1 ms filter (2 × 0.5 ms).

NOTE DI/DO mode must be configured via ioAdmin.



In Event Counter mode, the channel accepts limit or proximity switches and counts events according to the ON/OFF status. When “Lo to Hi” is selected, the counter value increases when the attached switch is pushed. When “Hi to Lo” is selected, the counter value increases when the switch is pushed and released.

By default, the Event Counter value will be reset to zero if power is disconnected. If you select **Save Status on Power Failure**, the Event Counter value will be saved when power is disconnected. When power is reconnected, the value will be as you left it. You can set **Power On Setting** to have counting resume immediately.

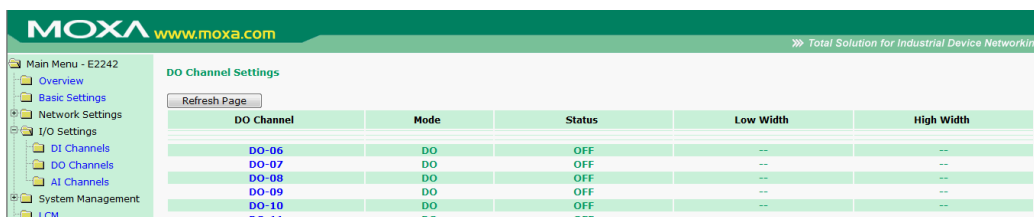
DI channels that are in Event Counter mode can begin counting automatically when the ioLogik is powered on. To activate this function, enable **Power On Setting**. If **Power On Setting** is not enabled, the channel will only start counting events when specified by a Modbus command or Click&Go Logic rule.

You can control how an Event Counter channel behaves during a network disconnection with the **Safe Status Setting** and the **Host Connection Watchdog**. With the Watchdog disabled, the Event Counter continues counting events even when there is a network disconnection. With the Watchdog enabled, the **Safe Status Setting** specifies whether the Event Counter continues or suspends counting when there is a network disconnection. Counting will continue if **Safe Status Setting** is enabled; counting will be suspended if **Safe Status Setting** is not enabled.

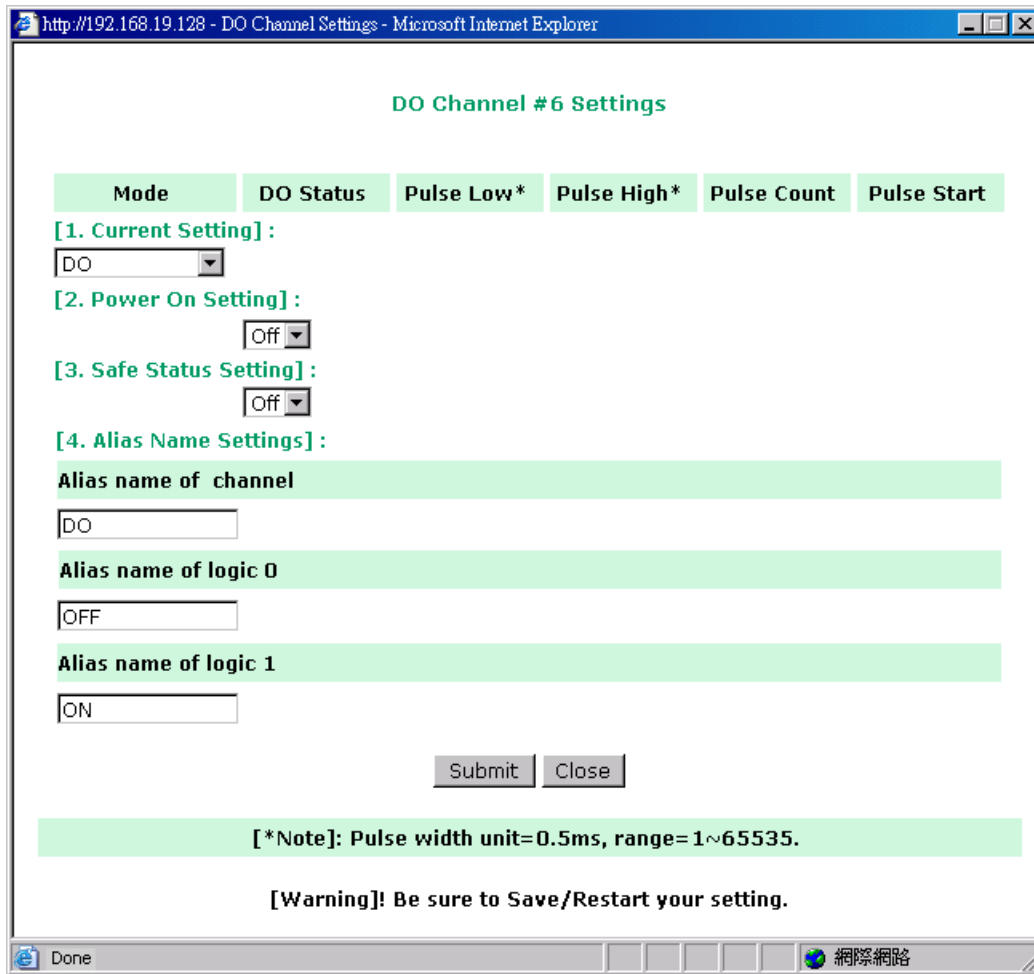
NOTE The ioLogik E2210 does not support the Save Status function in the event of a power failure.

DO Channels

On the **DO Channels** page, you can view the status of each DO (digital output) channel. Only DIO channels that are acting as DO channels will be displayed.



Click on a channel to see that channel’s configuration options. DO Channels can operate in DO mode or Pulse Output mode. In DO mode, output is either on or off. In Pulse Output mode, a configurable square wave is generated.



By default, DO and Pulse Output channels are set to “off” when the ioLogik is powered on. You can set a channel to automatically turn on or begin pulse output when the ioLogik is powered on, by enabling **Power On Setting**.

AI Channels

On the **AI Channels** page, you can view the status of each AI (analog input) channel.

| AI Channel | Range | Value | Min. | Max. |
|------------|--------|--------|---------|--------|
| AI-00 | +/-10V | 0.000V | 0.000V | 0.001V |
| AI-01 | +/-10V | 0.000V | 0.000V | 0.001V |
| AI-02 | +/-10V | 0.000V | -0.000V | 0.000V |
| AI-03 | +/-10V | 0.000V | 0.000V | 0.001V |

Click on a channel to see that channel’s configuration options. AO Channels can operate in different input modes, such as ±10V, or 4-20mA. The Reset Min and Reset Max buttons will clear the minimum or maximum values recorded and displayed in the ioAdmin main window.

AI Channel 0 Settings

AI Channel Enable

Input Range

4~20mA

Auto Scaling Settings

- Scaling Disable
- Point-Slope formula Enable

| | Actual (x.xxx) | | Scaled (x.xxx) |
|---------|---------------------------------|---------|----------------------|
| Min(n1) | <input type="text"/> | Min(n2) | <input type="text"/> |
| Max(m1) | <input type="text"/> | Max(m2) | <input type="text"/> |
| Unit | <input type="text" value="mA"/> | Unit | <input type="text"/> |

*Result = $n2 + (input - n1) \times [(m2-n2)/(m1-n1)]$

Slope-intercept Enable

M=

D=

Unit:

*Result= $M \times Input + D$

Alias Name Settings

Alias Name of Channel:

Warning: Be sure to Save/Restart your setting.

Auto Scaling can also help to eliminate high or low end extremes. For example, if 17 mA represents a dangerous high temperature situation, it will not be necessary to get a temperature that is even higher. In this case, users can cut off values beyond 17 mA and convert it to a proprietary level of danger, such as Level 5.

Alias Name

Alias Name helps users configure the alias of a DI, DO, or AI channel, and define the logic value (0 or 1) of the ON/OFF status.

AO Channels

On the **AO Channels** page, you can configure each AO (analog output) channel by clicking on the channel. The available options are 0–10 V, and 4–20 mA. You may use the **Power On** field to specify the channel's initial value when the ioLogik E2240 is powered on, and the **Safe Status** field to specify the channel's value when the ioLogik E2240 enters Safe Status. Note that Safe Status is controlled by the Host Connection Watchdog, which is disabled by default. If the Host Connection Watchdog is disabled, the ioLogik E2240 will never enter Safe Status and your Safe Status settings will have no effect.

AO Channel #0 Settings

| Output Range | Output Value |
|--|-----------------------------------|
| [1. Current Range] : | |
| 4~20mA <input type="text"/> | |
| [2. Power On Setting] : | |
| | <input type="text" value="0"/> |
| [3. Safe Status Setting] : | |
| | <input type="text" value="4094"/> |
| <input type="button" value="Submit"/> <input type="button" value="Close"/> | |

Relay Output Channel

On the **DO Channels** page, you can view the status of each DO (digital output) channel. Both fixed DO channels and DIO channels that are acting as DO channels will be displayed.

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- Main Menu - E2214
- Overview
- Basic Settings
- Network Settings
- I/O Settings
 - DI Channels
 - DO Channels
 - System Management
 - LCM
 - Change Password

DO Channel Settings

| DO Channel # | Mode | Status | Low Width | High Width |
|--------------|------|--------|-----------|------------|
| [DO-00] | DO | OFF | -- | -- |
| [DO-01] | DO | OFF | -- | -- |
| [DO-02] | DO | OFF | -- | -- |
| [DO-03] | DO | OFF | -- | -- |
| [DO-04] | DO | OFF | -- | -- |
| [DO-05] | DO | OFF | -- | -- |

[NOTE]: * channel is locked by logic

Click on a channel to see that channel's configuration options. DO Channels can operate in DO mode or Pulse Output mode. In DO mode, output is either on or off. In Pulse Output mode, a configurable square wave is generated.

| Mode | DO Status | Pulse Low* | Pulse High* | Pulse Count | Pulse Start |
|---------------------------------------|-----------|------------|-------------|-------------|-------------|
| 1. Current Setting : | | | | | |
| DO | Off | | | | |
| 2. Power On Setting : | | | | | |
| | Off | | | | |
| 3. Safe Status Setting : | | | | | |
| | Off | | | | |
| 4. Power On Delay Sec(Max:300) | | | | | |
| 5. Alias Name | | | | | |
| Alias name of channel | | | | | |
| DO | | | | | |
| Alias name of "OFF" status | | | | | |
| ON | | | | | |
| Alias name of "ON" status | | | | | |
| OFF | | | | | |
| 6. Relay Count | | | | | |
| Last Reset Time: 0000/00/00 00:00:00 | | | | | |
| Relay Total Counts: 24623 | | | | | |
| Relay Current Counts: 0 | | | | | |

By default, DO and Pulse Output channels are set to "off" when the ioLogik is powered on. You can set a channel to automatically turn on or begin pulse output when the ioLogik is powered on, by enabling **Power On Setting**.

The Interval for **Power On Settings** provides sequential control of the DO outputs while powering up the ioLogik E2214. The value ranges from 0 to 300 seconds. For example, if all of the DO channels are configured to be On, and the interval is set to "0" seconds, then all of the DO channels will be switched to On at the same time. If the DO 0 is set to On and 10 sec, there will be a 10-second delay, and then the DO will be switched to On as the default status after the ioLogik E2214 system is ready. The Interval with DO default status setting provides the ability to switch on the DO channels sequentially to avoid the sudden high power burst of the attached devices and sensors.

You can control how a DO or Pulse Output channel behaves during a network disconnection with the **Safe Status Setting** and the **Host Connection Watchdog**. With the Watchdog disabled, there is no change to the channel's status when there is a network disconnection. With the Watchdog enabled, the **Safe Status Setting** determines whether the channel will turn off, on, or begin pulse output when there is a network disconnection. The channel will turn on or begin pulse output if **Safe Status Setting** is enabled; the channel will turn off if **Safe Status Setting** is not enabled.

Relay Count Motoring

Two types of relay counts can be recorded in the ioLogik E2214: **Total Counts** and **Current Counts**. **Total Counts** records how many times a DO (relay) channel has been used. In general, each DO (relay) channel can be used an average of 100,000 times. Users can monitor these counts to determine when the module should be replaced, or to switch to a different channel if the total counts approaches the upper limit. **Current Counts** can be reset to zero to record the usage of the external device by monitoring the counts. For example, if DO 0 is connected to an external relay control board, you can monitor the current counts to determine when to replace the external relay component in advance before it fails.

Last Reset Time records the time when **Current Counts** was reset. Both **Total Counts** and **Current Counts** will be saved when there is a power failure. The **Last Reset Time** will be saved only when the user manually presses the **Reset to Zero** button.

Alias Name set

Alias Name Set helps users configure the alias of a DI or DO channel and define the status for **on/off** to be vice versa.

RTD Channels

On the RTD Channels page, you may view the status of all RTD channels, which includes both physical and virtual channels.

| Channel # | Sensor Type | Range | Status | Value | Min | Max |
|------------|-------------|--------------|----------|-------|-----|-----|
| [RTD-00] | PT 100 | -200 ~ 850°C | Enabled | -- | -- | -- |
| [RTD-01] | -- | -- | Disabled | -- | -- | -- |
| [RTD-02] | -- | -- | Disabled | -- | -- | -- |
| [RTD-03] | -- | -- | Disabled | -- | -- | -- |
| [RTD-04] | -- | -- | Disabled | -- | -- | -- |
| [RTD-05] | -- | -- | Disabled | -- | -- | -- |

| Virtual Channel # | Mode | Unit | Value | Min | Max |
|-------------------|------|------|-------|-----|-----|
| [RTD-06] | AVG | °C | 0.0 | 0.0 | 0.0 |
| [RTD-07] | AVG | °C | 0.0 | 0.0 | 0.0 |
| [RTD-08] | AVG | °C | 0.0 | 0.0 | 0.0 |
| [RTD-09] | AVG | °C | 0.0 | 0.0 | 0.0 |
| [RTD-10] | AVG | °C | 0.0 | 0.0 | 0.0 |
| [RTD-11] | AVG | °C | 0.0 | 0.0 | 0.0 |

[NOTE]: * channel is locked by logic

Clear (Max & Min) Refresh

You may click on each channel to enable or disable it, or to configure the RTD input mode. When a channel has been disabled, the sample rate of the remaining channels will be increased automatically.

The following table is a list of supported sensor types and ranges.

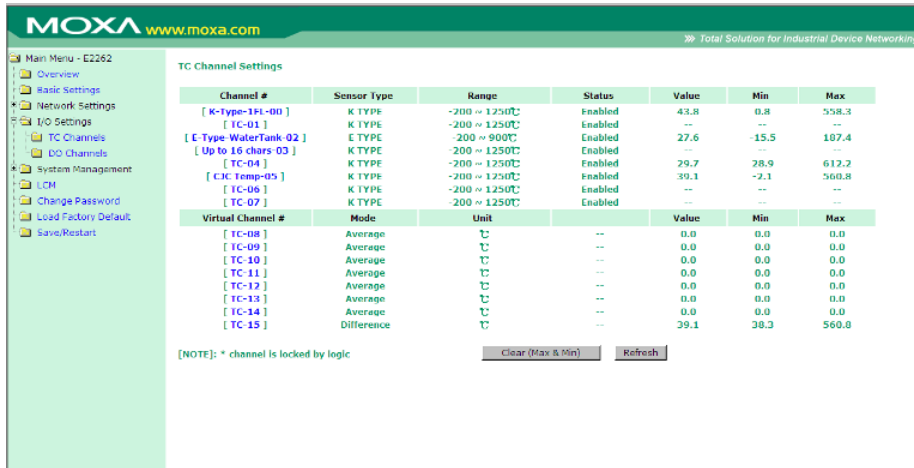
| Sensor Type | Degree | Count |
|---------------------|---------------|---------------|
| PT50, 0.00385 | -200 to 850°C | -2000 to 8500 |
| PT100, 0.00385 | -200 to 850°C | -2000 to 8500 |
| PT200, 0.00385 | -200 to 850°C | -2000 to 8500 |
| PT500, 0.00385 | -200 to 850°C | -2000 to 8500 |
| PT1000, 0.00385 | -200 to 350°C | -2000 to 3500 |
| JPT100, 0.003916 | -200 to 640°C | -2000 to 6400 |
| JPT200, 0.003916 | -200 to 640°C | -2000 to 6400 |
| JPT500, 0.003916 | -200 to 640°C | -2000 to 6400 |
| JPT1000, 0.003916 | -200 to 350°C | -2000 to 3500 |
| Resistance (1-2200) | 1 to 2200 Ω | 10 to 22000 |
| Resistance (1-1250) | 1 to 1250 Ω | 20 to 25000 |
| Resistance (1-620) | 1 to 620 Ω | 50 to 31000 |
| Resistance (1-310) | 1 to 310 Ω | 100 to 31000 |
| Ni100, 0.00618 | -60 to 250°C | -600 to 2500 |
| Ni200, 0.00618 | -60 to 250°C | -600 to 2500 |
| Ni500, 0.00618 | -60 to 250°C | -600 to 2500 |

| Sensor Type | Degree | Count |
|-----------------|--------------|--------------|
| Ni1000, 0.00618 | -60 to 180°C | -600 to 1800 |
| Ni120, 0.00672 | -80 to 260°C | -800 to 2600 |

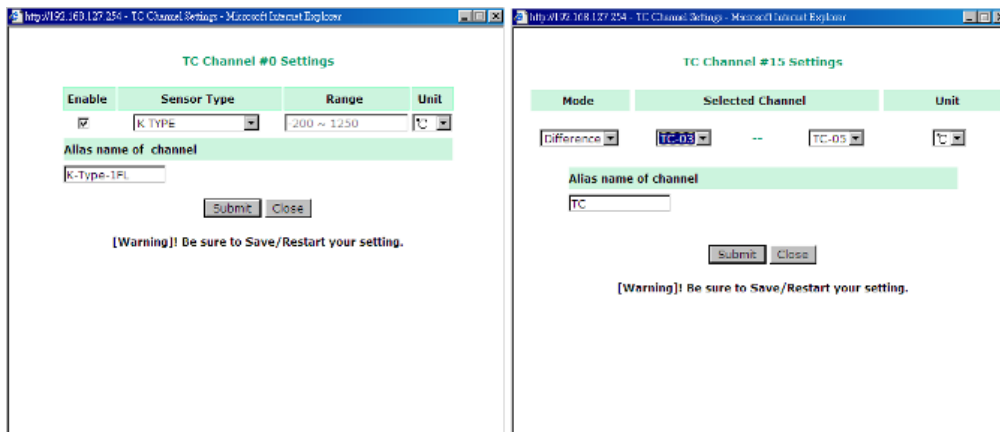
Channels 6 through 11 are virtual channels. You can click on a virtual channel to configure whether it will return current averages or deviations for the specified physical channels (RTD-00 through RTD-05).

TC Channels

On the TC Channels page, you can view the status of all TC channels, which includes both physical and virtual channels. You can click the **Channel Name** to enter settings page on which can set the **Alias Name**.



You can click on each channel to enable or disable it, or to configure the TC input mode. When a channel has been disabled, the sample rate of the remaining channels will be increased automatically.



The following table is a list of supported sensor types and ranges.

| Type | Temperature Range | Count Range |
|--------------------|--------------------------|---------------------|
| J | 0°C to 750°C | 0 to 7,500 |
| K | -200°C to 1250°C | -2,000 to 12,500 |
| T | -200°C to 350°C | -2,000 to 3,500 |
| E | -200°C to 900°C | -2,000 to 9,000 |
| R | -50°C to 1600°C | -500 to 16,000 |
| S | -50°C to 1760°C | -500 to 17,600 |
| B | 600°C to 1700°C | 6,000 to 17,000 |
| N | -200°C to 1300°C | -2,000 to 13,000 |
| Voltage: 78.126 mV | - 78.126 mV to 78.126 mV | -781,260 to 781,260 |
| Voltage: 39.062 mV | - 39.062 mV to 39.062 mV | -390,620 to 390,620 |
| Voltage: 19.532 mV | - 19.532 mV to 19.532 mV | -195,320 to 195,320 |

Channels 8 through 15 are virtual channels. You can click on a virtual channel to configure whether it will return current averages or deviations for the specified physical channels (TC-00 through TC-07).

System Management

Under system management you can set IP accessibility and SNMP Agent. You can also check your network connection and do firmware update. Also you Import and Export your system configuration under here too.

1. [IP Accessibility](#)
2. [SNMP Agent](#)
3. [Network Connection](#)
4. [Firmware Update](#)
5. [Import System Config](#)
6. [Export System Config](#)

Accessible IP Settings

On the **Accessible IP Settings** page, you can control network access to the ioLogik by allowing only specific IP addresses. When the accessible IP list is enabled, a host's IP address must be listed in order to obtain access to the ioLogik.

The screenshot shows the 'Accessible IP Settings' page in the MOXA web console. The page title is 'MOXA www.moxa.com' and the tagline is 'Total Solution for Industrial Device Networking'. The left navigation menu includes: Main Menu - E2242, Overview, Basic Settings, Network Settings, I/O Settings, System Management (with sub-items: Accessible IP Settings, SNMP Agent, Network Connection, Firmware Update, Import System Config, Export System Config), LCM, Change Password, Load Factory Default, and Save/Restart. The main content area is titled 'Accessible IP Settings' and contains a checkbox labeled 'Enable the accessible IP list ("Disable" will not allow all IP's connection request.)'. Below this is a table with the following columns: No., Active, IP Address, and Netmask. The table has 10 rows, each with a 'No.' from 1 to 10, an 'Active' checkbox, and input fields for 'IP Address' and 'Netmask'. A 'Submit' button is located at the bottom of the table.

You can add a specific address or range of addresses by using a combination of IP address and netmask, as follows:

- **To allow access to a specific IP address**
Enter the IP address in the corresponding field; enter 255.255.255.255 for the netmask
- **To allow access from hosts on a specific subnet**
For both the IP address and netmask, use 0 for the last digit (e.g., 192.168.1.0 and 255.255.255.0).
- **To allow unrestricted access**
Deselect the Enable the accessible IP list option.

The following table shows additional configuration examples.

| Allowed Hosts | IP address | Netmask |
|--------------------------------|---------------|-----------------|
| Any host | Disable | Disable |
| 192.168.1.120 | 192.168.1.120 | 255.255.255.255 |
| 192.168.1.1 to 192.168.1.254 | 192.168.1.0 | 255.255.255.0 |
| 192.168.0.1 to 192.168.255.254 | 192.168.0.0 | 255.255.0.0 |
| 192.168.1.1 to 192.168.1.126 | 192.168.1.0 | 255.255.255.128 |
| 192.168.1.129 to 192.168.1.254 | 192.168.1.128 | 255.255.255.128 |

SNMP Agent

On the SNMP Agent page, you can enable SNMP and setting SNMP. The ioLogik supports SNMP v1, v2c, and V3 (Simple Network Management Protocol) to allow monitoring of network and I/O devices with SNMP Network Management software.

SNMP Agent

Configurations

SNMP Enable Disable

SNMP Agent Version: v1,v2c,v3

Read Community Name: public

Write Community Name: private

Contact: _____

Location: _____

Read only (for Snmp V3)

User Name: _____

Authentication Password: _____

Authentication protocol: DISABLE

Privacy Password: _____

Privacy protocol: DISABLE

Read/Write (for Snmp V3)

User Name: _____

Authentication Password: _____

Authentication protocol: DISABLE

Privacy Password: _____

Privacy protocol: DISABLE

Submit

Network Connection

On the **Network Connection** page, you can view TCP connections from other hosts.

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Network Connection

Total TCP/IP Connection(s): 2

| Source Host Address | Connection Type |
|---------------------|-----------------|
| 192.168.19.201 | MODBUS/TCP |
| 192.168.19.201 | Web/HTTP |

Destination Host Address: _____

Connection Type: _____

Firmware Update

On the **Firmware Update** page, you can updated firmware into the ioLogik.

MOXA www.moxa.com

Firmware Update

Choose a new firmware file path :

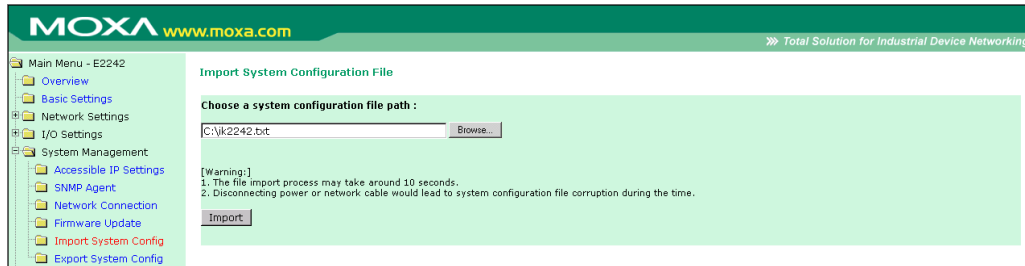
C:\FWR_E2242_V1.0_Build08050910_STD.2kp

[Warning:]

- The firmware update process may take about 20 seconds.
- Attention! Once you press the "Update" button, this progress cannot be reversed.
- Disconnecting power or network cable would lead to firmware corruption during the time.

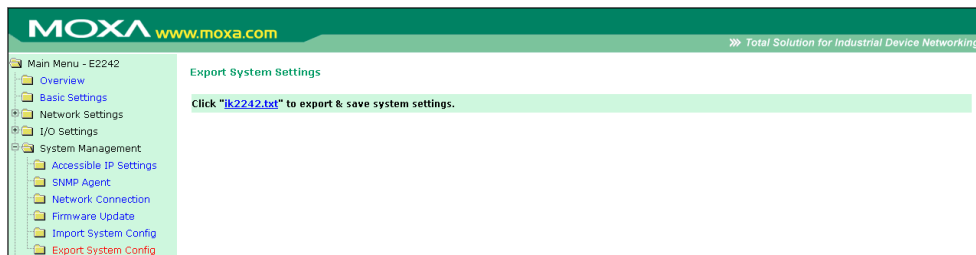
Import System Config

On the **Import System Config** page, you can import a configuration into the ioLogik server. The configuration file can be generated by ioAdmin or through the web console. This function can be used to duplicate settings between ioLogik servers. You will be prompted for the location of the configuration file (e.g., "ik2242.txt").



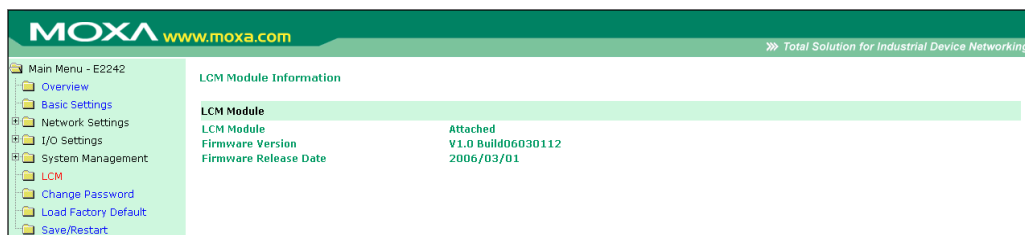
Export System Config

On the **Export System Config** page, you can save the ioLogik's configuration into a file for backup or for importing into another ioLogik server.

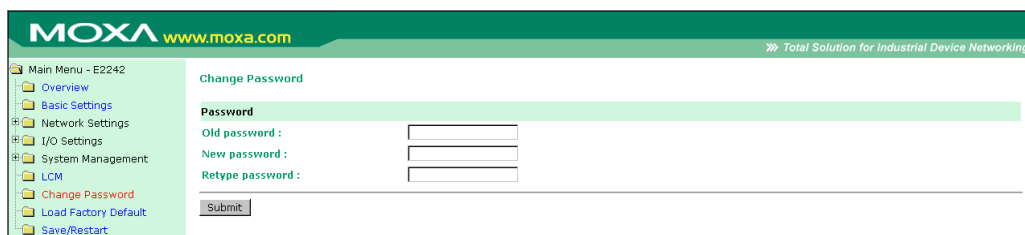


LCM

If you have installed the optional LCM, you can view the status and firmware details on the LCM page.



Change Password



For all changes to the ioLogik E2200's password protection settings, you will first need to enter the old password. Leave this blank if you are setting up password protection for the first time. To set up a new password or change the existing password, enter your desired password under both **New password** and

Confirm password. To remove password protection, leave **New password** and **Confirm password** blank.



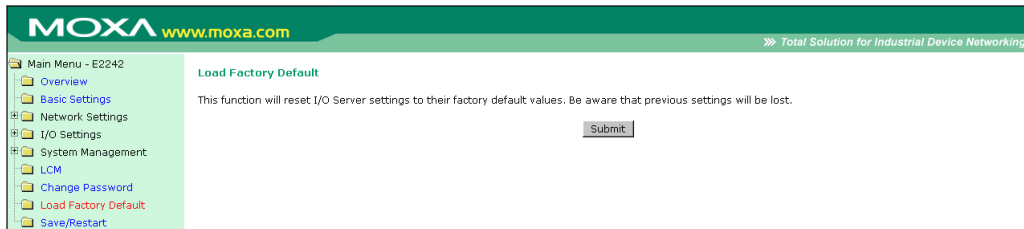
ATTENTION

If you forget the password, the **ONLY** way to configure the ioLogik is by using the reset button to load the factory defaults.

Before you set a password for the first time, it is a good idea to export the configuration to a file when you have finished setting up your ioLogik. Your configuration can then be easily imported back into the ioLogik. This will be useful if the ioLogik has been reset to factory defaults due to a forgotten password or for other reasons.

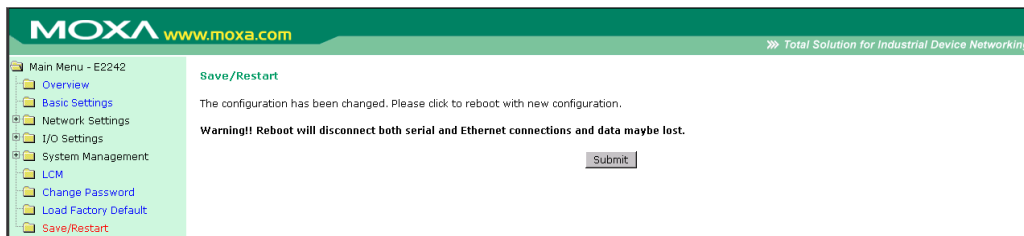
Load Factory Default

This function will reset the ioLogik to factory default settings. All previous settings, including the password, will be lost.



Save/Restart

If you change the configuration, do not forget to reboot the system.



Active OPC Server

The following topics are covered in this chapter:

- ❑ **Active OPC Server**
- ❑ **OLE for Process Control**
- ❑ **Introduction to Active OPC Server**
- ❑ **Active OPC Server—From Pull to Push**
- ❑ **Features of Active OPC Server**
 - One Click to Create Active Tags
 - Faster, More Accurate Data Collection than Traditional “Pull Technology”
- ❑ **Active OPC Server Overview**
 - Installing Active OPC Server
 - Main Screen Overview
 - Menu Bar
- ❑ **Tag Generation**
 - Configuring Push Tag from ioAdmin
 - Heartbeat Interval
 - Read/Write Privilege

Active OPC Server

Moxa Active OPC Server is a software package that operates as an OPC driver of an HMI or SCADA system. It offers seamless connection from Moxa ioLogik series products to SCADA systems, including the most popular—Wonderware, Citect, and iFix. Active OPC Server meets the latest OPC DA3.0 standard for connecting various kinds of devices and host OPC machines.

Active OPC Server Lite System Requirements

| Hardware Requirements | |
|---------------------------|---|
| CPU | Intel Pentium (Pentium 4 and above) |
| RAM | 512 MB (1024 MB recommended) |
| Network Interface | 10/100 Mbps Ethernet |
| Software Requirements | |
| Operating System | Microsoft Windows 2000, XP or later |
| Editor (not necessary) | Microsoft Office 2003 (Access 2003) or later |
| OPC Server Specifications | |
| OPC Data Access | 1.0a, 2.0, 2.05a, 3.0 |
| Max. No. of Tags | 256 |
| ioLogik Support | |
| Product Models | ioLogik E1200 series, E2200 series, E4200, and W5300 series |
| Firmware version | V3.0 or above |
| ioAdmin version | V3.0 or above |

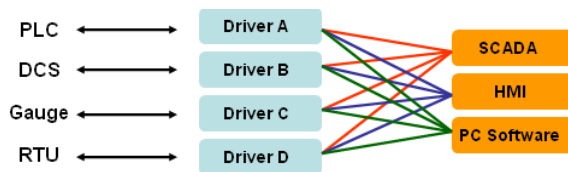
OLE for Process Control

OPC (originally “OLE for process control”) is an industry standard created with the collaboration of a number of leading worldwide automation hardware and software suppliers working in cooperation with Microsoft. The standard defines methods for exchanging real-time automation data between PC-based clients using Microsoft operating systems. The organization that manages this standard is the OPC Foundation.

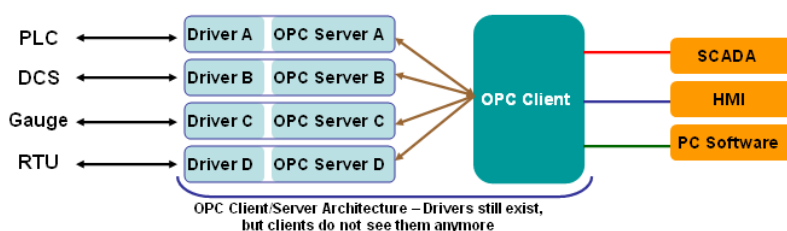
The OPC Specification is a non-proprietary technical specification that defines a set of standard interfaces based on Microsoft’s OLE/COM/DCOM platform and .NET technology. The application of the OPC standard interface enables interoperability between automation/control applications, field systems/devices, and business/office applications.

Traditionally, each software or application developer was required to write a custom interface, or server/driver, to exchange data with hardware field devices. OPC eliminates this requirement by defining a common, high performance interface that permits this work to be done once, and then easily reused by HMI, SCADA, control, and custom applications.

[Drivers must be installed several times to connect to different devices]



[OPC Client/Server creates a common interface connecting to different devices]



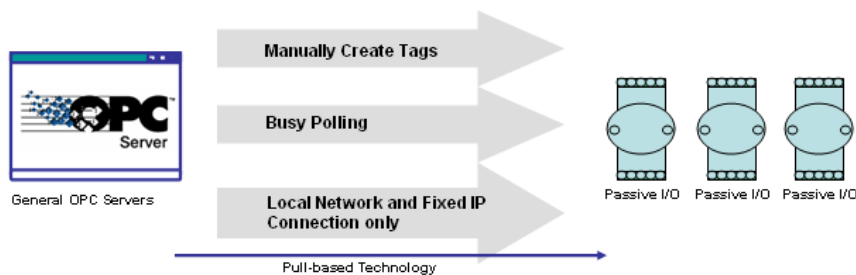
Introduction to Active OPC Server

Moxa Active OPC Server Lite is a software package that operates as an OPC driver of an HMI or SCADA system. It offers seamless connection from Moxa ioLogik series products to SCADA systems, including the most popular Wonderware, Citect, and iFix. Active OPC Server Lite meets the latest OPC DA3.0 standard that allows connections to various kinds of devices and host OPC machines.

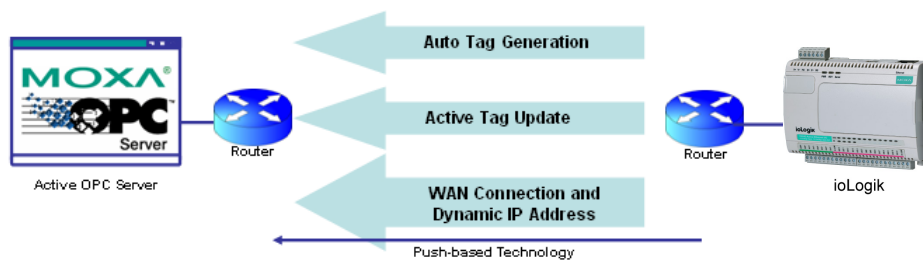
Active OPC Server—From Pull to Push

The first time a user looks up an I/O device’s Modbus table, 19 or more steps (including specifying the IP address, selecting protocols, and defining data type) may be required to create one tag. The procedure needs to be repeated again and again until tags for all devices are created. A technician can expect to take 1 minute to create just one tag. But what if there are 400 tags in the OPC system? In addition, creating more and more tags can put a big load on your CPU.

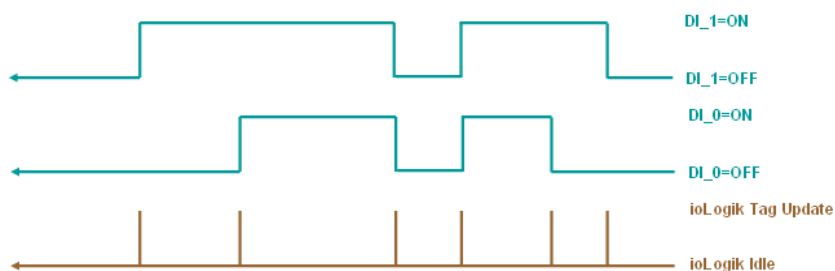
OPC also requires connected I/O devices to use fixed IP addresses. For applications running on a public network (which usually means dynamic IPs) or when portable wireless equipment is used, there is no way to connect to an I/O device using OPC. This architecture is also called “pull” technology because the OPC server continuously polls I/O devices (based on the tags) and then “pulls” the data back to the server.



Moxa’s Smart Ethernet Remote I/O Devices have extended the concept of Active Reporting from TCP/UDP messages, emails, and SNMP Traps to the OPC Server. It is easy to set the IP address of an Active OPC server and choose updated I/O tags. An Active OPC server running on the host PC will receive these I/O tags and tag data automatically.



With “push” technology, which also supports tag updates, the ioLogik only sends updates to Active OPC Server Lite when the I/O status changes. Compared to constantly polling (i.e., pull-based) the status, this feature efficiently reduces network bandwidth usage and speeds up the response time with event-driven, push-based status updates. At the same time, the heartbeat function visually confirms that the ioLogik is “alive” and working.





Features of Active OPC Server

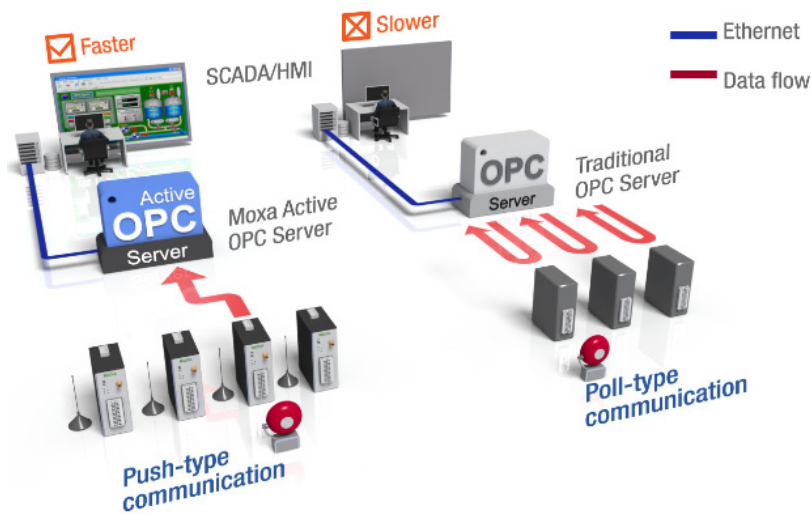
One Click to Create Active Tags

Moxa's remote I/O devices and Active OPC Servers support automatic tag generation, which eliminates the headache of specifying individual target IP addresses, I/O channels, and data formats, while even eliminating any need for editing and importing configuration files. Working from either of Moxa's ioAdmin or ioSearch utilities, users only need to select specific I/O channels, set the update criteria, and then click a single button for their active tags to be automatically generated and configured.



Faster, More Accurate Data Collection than Traditional “Pull Technology”

Moxa has pioneered the concept of “active type” OPC software in the automation industry. The patented Active OPC Server offers nonpolling architecture alongside the standard OPC protocol, giving users the alternative of active, push-based communication from Moxa’s remote I/O devices. This adaptation of push technology means that I/O status will be updated at the Active OPC Server only when there is an I/O status change, a pre-configured interval is reached, or when a request is issued by a user. This application of push technology cuts metadata overhead, resulting in faster I/O response times and more accurate data collection than traditional pull-based architectures. With Moxa’s “active technology” advantage, users can now instantly receive alarms and real time updates allowing for timely risk response.



Active OPC Server Overview

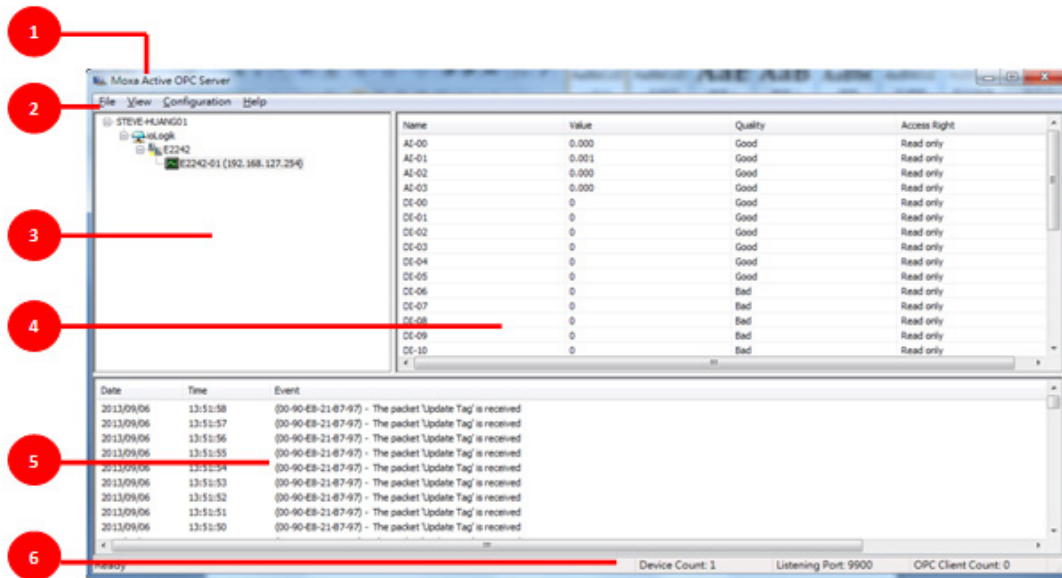
Installing Active OPC Server

Active OPC Server can be downloaded from Moxa’s website.

1. **Installing Active OPC Server from website:**
 - a. First click on the following link to access the website’s search utility:
<http://www.moxa.com/support/search.aspx?type=soft>
 - b. When the web page opens, enter the model name of your product in the search box.
 - c. Click the model name and navigate to the product page, and then click on Active OPC Server, located in the box titled Software.
 - d. Download and then unzip the file. Run **SETUP.EXE** from that location.
The installation program will guide you through the installation process and install the software.
2. **Open Active OPC Server:** After installation is finished, run Active OPC Server from the Windows Start menu: **Start** → **Program Files** → **MOXA** → **IO Server** → **ActiveOPC** → **ActiveOPC**

Main Screen Overview

Active OPC Server Lite’s main screen displays a figure of the mapped iologik with the status of every I/O tag. Note that configuration and tags are not available until you have the ioLogik to create the tags.

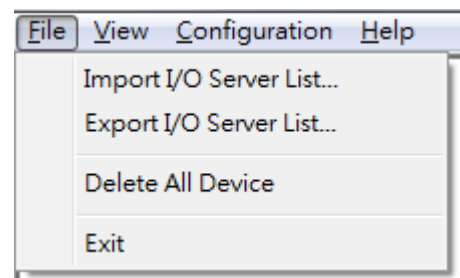


| | | |
|---------------|----------------|---------------------|
| 1. Title | 2. Menu bar | 3. Navigation panel |
| 4. Tag window | 5. Log monitor | 6. Status bar |

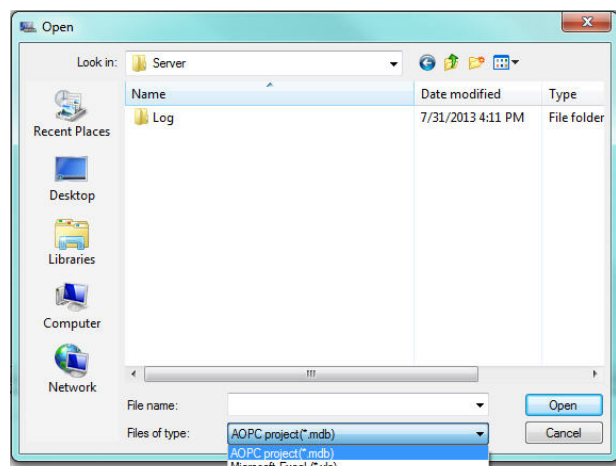
Menu Bar

File

From the File menu, select Export I/O Server List... to export a list of the ioLogik servers currently displayed in the navigation panel, and then Import I/O Server List... to import the list into Active OPC Server.

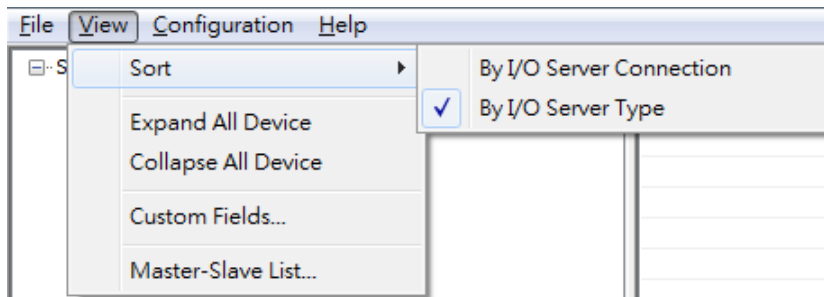


The server list file can have either a .mdb or .xls extension, so it can be opened using Microsoft Office Access or Microsoft Excel. The server list includes the current tag information of the mapped ioLogik servers.



View

The **View** menu provides the following options for customizing the information displayed on the main screen.



Sort

The **Sort** option allows the server list in the navigation panel to be sorted by connection and type (model).

Expand All Device

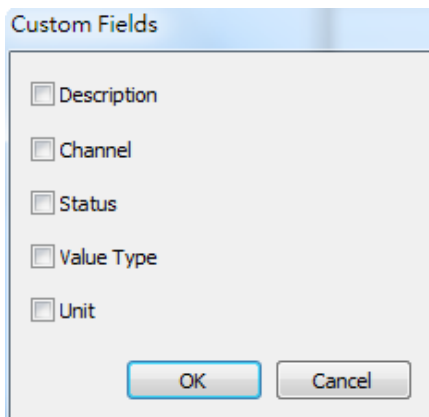
The **Expand All Device** option will expand all the devices in the Navigation panel.

Collapse All Device

The **Collapse All Device** option will collapse all the devices in Navigation panel.

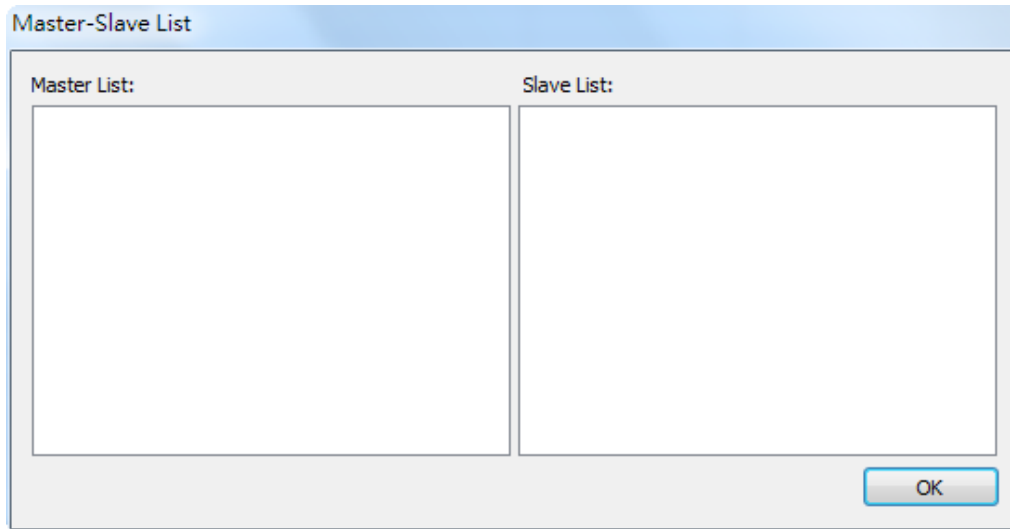
Custom Fields...

The **Custom Fields...** option allows you select additional information to be displayed in the tag window.



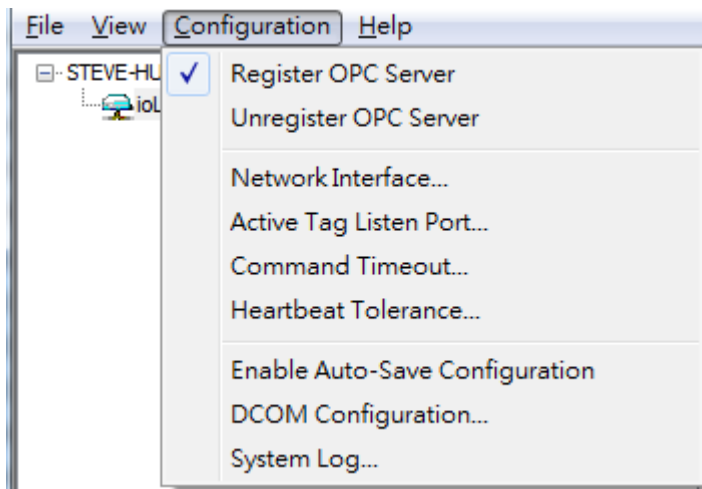
Master-Slave List...

The **Master-Slave List...** opens a window that identifies the Master and Slave devices on your network.



Configuration

Several operations can be accessed from the **Configuration** menu.



Register OPC Server

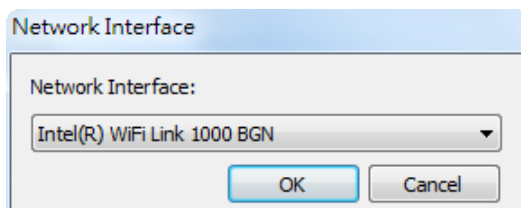
This operation registers the DCOM components to a Windows system. After Active OPC Server Lite is installed, it will automatically configure the DCOM.

Unregister OPC Server

This operation cancels the registration of the DCOM components from the Windows system.

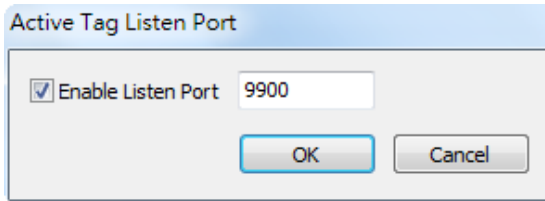
Network Interface...

Use this operation to select which network to use if the PC has multiple network adaptors installed.



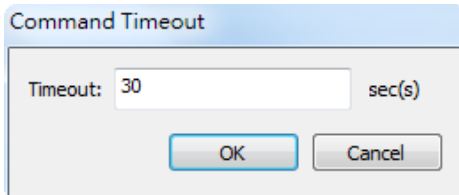
Active Tag Listen Port...

Use this operation to select the preferred TCP socket port for tag generation from the ioAdmin utility.



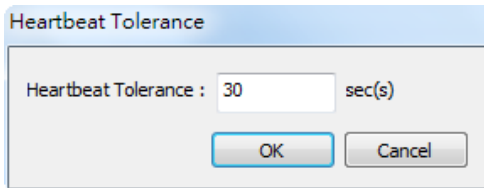
Command Timeout...

This operation defines the timeout interval for controlling an output channel on a remote ioLogik device.



Heartbeat Tolerance...

This operation defines the amount of time to wait for a heartbeat signal from a remote ioLogik device (default: 60 seconds).



Enable Auto-Save Configuration

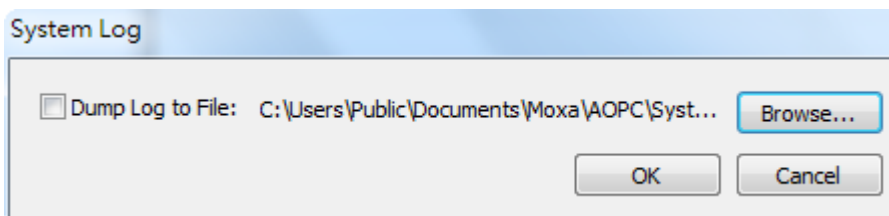
When **Auto Save** is enabled, Active OPC will automatically save the configuration when Access synchronizes.

DCOM Configuration...

This operation launches the Windows DCOM configuration utility.

System Log

Selecting **Dump Log to File** will store a copy of the Active OPC Server system log in a designated folder.



Tag Generation

Configuring Push Tag from ioAdmin

Tag configuration of an ioLogik is specified by the ioAdmin configuration utility. Start ioAdmin, log in as an administrator and then click on the **Active Tags** tab.

The screenshot shows the ioAdmin configuration utility with the 'Active Tags' tab selected. The configuration is as follows:

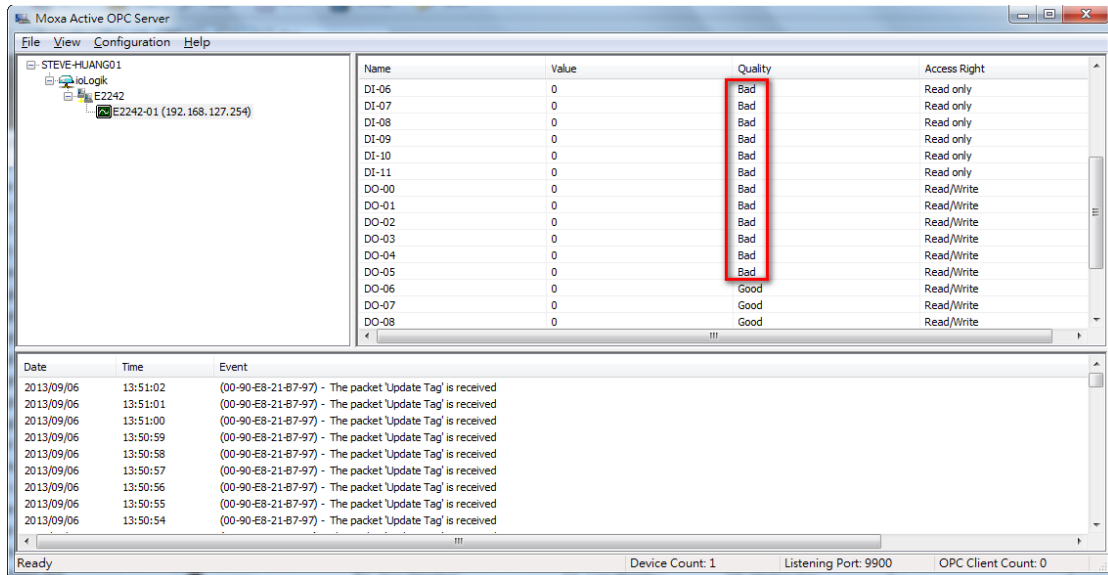
- Enable Active OPC:** Checked. Five entries for Address (0.0.0.0) and Port (9900). An 'Update' button is present.
- I/O Channel Settings:**
 - Enable All AI Channels:** Unchecked. Four AI channels (AI-00 to AI-03) are listed with 'On Change' checked, 'Update per' set to 1 sec, and a range of (1-65535).
- DI/DO Channels:**
 - Update by:** 'I/O On Change' is selected, 'Interval' is 1 sec, and the range is (1-65535).
 - Enable All DI Channels:** Checked. All channels (CH-00 to CH-11) are checked.
 - Enable All DO Channels:** Checked. All channels (CH-00 to CH-11) are checked.
- Heartbeat Interval:** 60 sec (0 for disable, or range 1-65535). A 'Create Tags' button is visible.
- Refresh:** A 'Refresh' button is located at the bottom right.

Take the following steps to create the tags.

1. Check mark the "Enable Active OPC" checkbox
2. Type in the Active OPC server IP Address
3. Select that I/O you would like to update
4. Specify the update timing
5. Click on the Create Tags button to push the tag configuration to Active OPC Server Lite
6. Start Active OPC Server Lite from the Windows Start Menu. A message will appear in the log monitor to confirm that the configuration was received. Tags will be created automatically.

Heartbeat Interval

Tags are event-driven and updated only when the status of an I/O channel changes, so when the status remains unchanged, there an update will not be sent to Active OPC Server. To ensure that the ioLogik is connected and alive, **Heartbeat Interval** can be used to determine the connection status between the ioLogik and Active OPC Server. If the heartbeat interval is set and the network between the ioLogik and Active OPC Server is down, Active OPC Server will detect the stop of the heartbeat and the Quality column will show **BAD** to indicate the loss of the connection. The default interval is set to 0 seconds, which disables the heartbeat. The maximum allowed interval is 65,535 seconds.



Read/Write Privilege

The R/W column shows whether a tag is read only, or provides both read and write access. The input channels can be read, but cannot be written to, whereas the output channels can be both read and written to. Note that if an output channel has been used by the Click&Go logic, the tags for that channel are read-only.

A

Liquid Crystal Display Module (LCM) (Phased Out)

The ioLogik E2200 supports an optional detachable Liquid Crystal Display Module (LCM) for easier field maintenance. The LCM is hot-pluggable and can be used to configure the network settings and display other settings. When plugged in, the LCM displays the ioLogik "home page." Other pages and information are accessed by pressing the buttons on the LCM.

The following topics are covered in this appendix:

- ❑ **LCM Controls**
- ❑ **LCM Options**

LCM Controls

The up and down buttons navigate between the current options. The right and left buttons enter and exit the submenus. The center button is used when modifying settings or restarting the server.

| Button | Function |
|--------|--|
| Up | go to the previous item |
| Down | go to the next item |
| Left | exit the current submenu and return to the previous menu (go up one level) |
| Right | enter the selected submenu (go down one level) |
| Center | enter/exit editing mode |

An **e** in the upper right hand corner of the display indicates that the parameter can be modified. Press the center button on the LCM to modify that parameter's settings.

LCM Options

| Display | Explanation / Actions |
|--------------------------------|--|
| <ioLogik E2242> | This is the default "home page" showing the IP address. Press the down button to view the submenus. |
| <ioLogik E2242> server | Enter this submenu to display information about the specific server you are viewing: <ul style="list-style-type: none"> • serial number • name • location • e2242 f/w ver • lcm f/w ver • model name |
| <ioLogik E2242> network | Enter this submenu to display information and settings for the network: <ul style="list-style-type: none"> • ethernet link • mac address • ip mode • ip address • netmask • gateway • dns server-1 • dns server-2 |
| <ioLogik E2242> click&go | Enter this submenu to display information about the Click&Go Logic ruleset currently loaded on the ioLogik: <ul style="list-style-type: none"> • name • status |
| <ioLogik E2242> serial port | Enter this submenu to display the RS-485 cascade port settings. |
| <ioLogik E2242> i/o setting | Enter this submenu to access I/O channel status. Here are examples settings that you might see: <ul style="list-style-type: none"> • DI-00 [di]=off • DO-00 [pulse]=stop Press up or down to navigate through the different I/O channels without needing to return to the previous menu. |
| <ioLogik E2242> console | Enter this submenu to see if the web console is enabled or disabled. |

| Display | Explanation / Actions |
|---------------------------------|--|
| <ioLogik E2242> ping | Select this option to enter an IP address to ping. If you get a "timeout" error, it indicates that the ioLogik cannot reach that IP address. Otherwise, the display will show the response time. |
| <ioLogik E2242> save/restart | Enter this submenu to display the restart now submenu. Enter the restart now submenu to display the restart option. Press the center button to modify this option, then select "enable" to save changes and reboot the I/O server. The disable option has no effect. |

**ATTENTION**

Any configuration changes that are made through the LCM will not take effect until the ioLogik is restarted.

Used Network Port Numbers

ioLogik E2200 Smart Ethernet Remote I/O Device Network Port Usage

| Port | Type | Usage |
|-------|------|-------------------------------|
| 68 | UDP | BOOTPC |
| 68 | UDP | DHCP |
| 69 | UDP | Export/import file |
| 80 | TCP | Web Server |
| 161 | TCP | SNMP |
| 502 | TCP | Modbus Communication |
| 4800 | UDP | Auto search |
| 9020 | TCP | Peer-to-Peer function |
| 9000 | TCP | Active Message (Default) |
| 9000 | UDP | Active Message (Default) |
| 9900 | TCP | Active Tags updates (default) |
| 4040 | TCP | ioEventLog |
| 4900 | TCP | ioAdmin |
| 14900 | TCP | ioAdmin |
| 4800 | UDP | ioAdmin |
| 137 | UDP | WIN Server |
| 9010 | TCP | Remote Action |

Factory Default Settings

The factory default settings for the ioLogik E2200 Series are as follows:

IP address: 192.168.127.254

Netmask: 255.255.255.0

Gateway: None

Communication Watchdog: Disable

Modbus/TCP Alive Check: ON

Modbus/TCP Timeout Interval: 60 sec

DI Mode:

DI Safe Status: Off

Filter Time for Counter: 10 × 0.5 ms

Counter Trigger Type: Lo to Hi

Counter Status: Stop

AI Mode: ±10 V

AO Mode: 4 to 20 mA

DO Mode:

DO Safe Status: Off

Pulse Low Width: 1

Pulse Hi Width: 1

No. of Pulses: 0 (continuous)

RTD Mode: PT 100

Unit: °C

TC Sensor Type: K type

TC Enable: Enable

TC Unit Type: °C

Filter Time for Counter: 10 × 0.5 ms

Counter Trigger Type: Lo to Hi

Counter Status: Stop

Counter status: Stop

Password: "empty"

Module Name: "empty"

Module Location: "empty"

SNMP: Enable

Versions: V1, V2c, V3

SNMP V1, V2c

Read Community: public

Write Community: private

SNMP V3

Authentication Protocol: Disable

Privacy Protocol: Disable

D

Cable Wiring

The following topics are covered in this appendix:

□ **Device Wiring Diagrams**

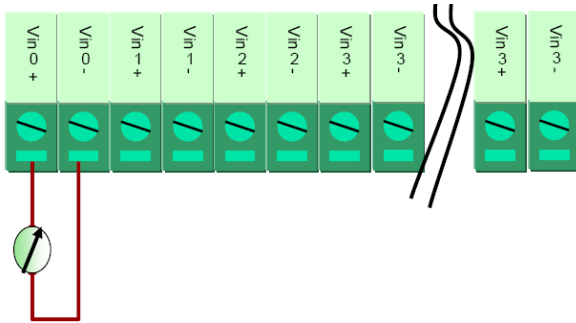
- Analog Input
- Analog Output
- Digital Input Dry Contact
- Digital Input Wet Contact

□ **RTD Input Wiring**

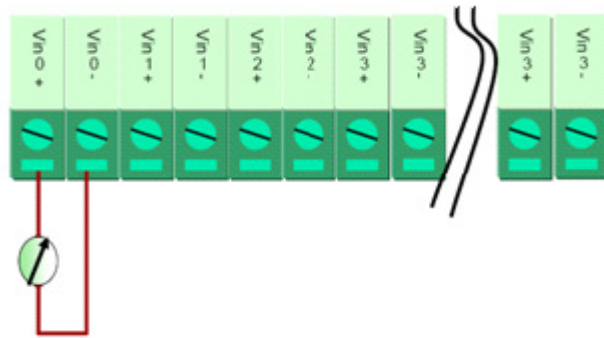
□ **Thermocouple Input Wiring**

Device Wiring Diagrams

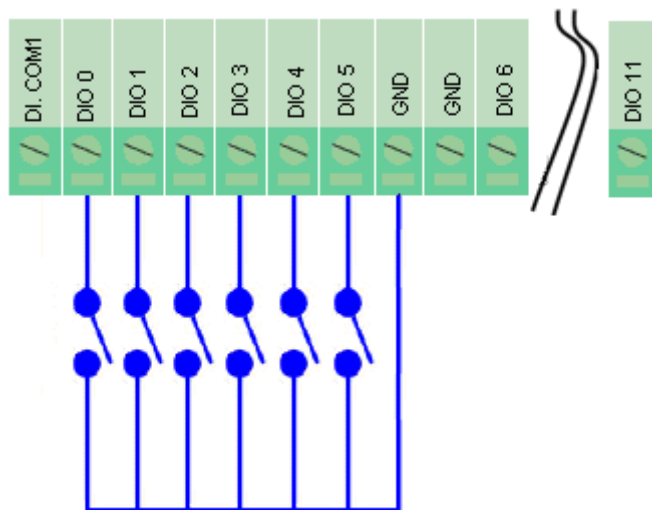
Analog Input



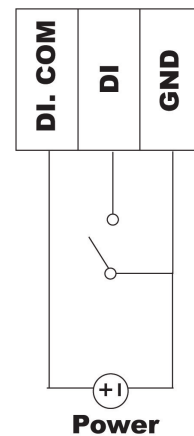
Analog Output



Digital Input Dry Contact



DI Dry Contact

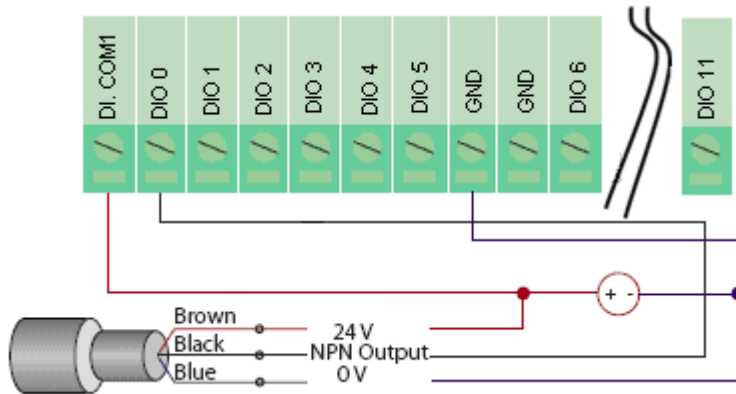


ATTENTION

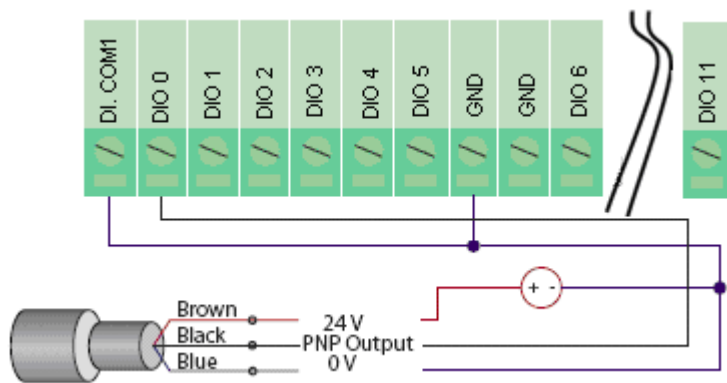
When connecting the I/O device to the ioLogik's dry contacts, we strongly recommended connecting DI.Com to the power of the external sensor to avoid affecting other channels.

Digital Input Wet Contact

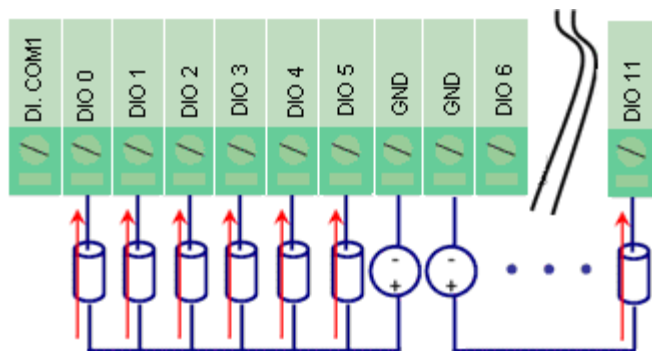
NPN Type Sensors Connection



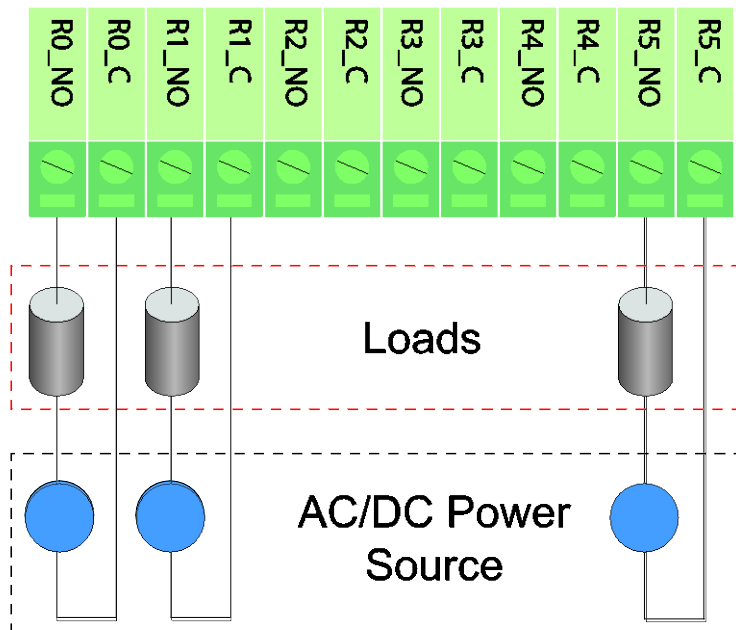
PNP Type Sensors Connection



Digital Output (Sink Type)

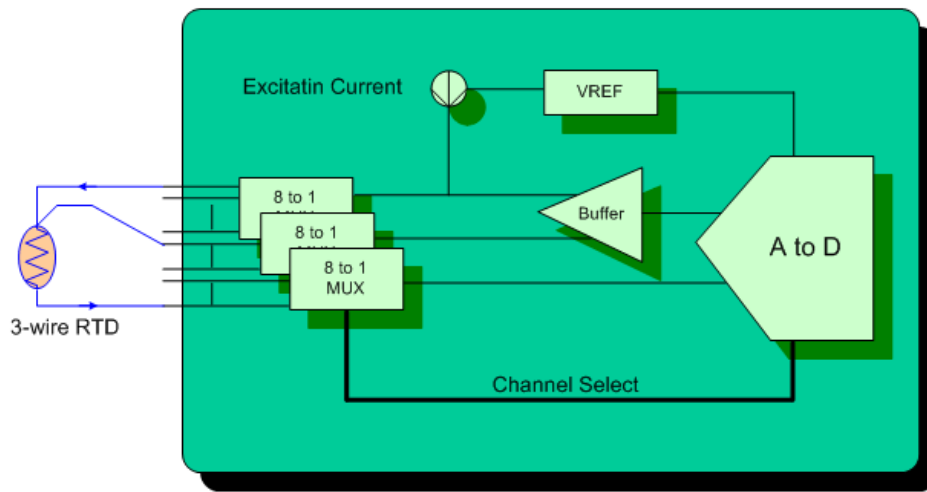


Relay Output

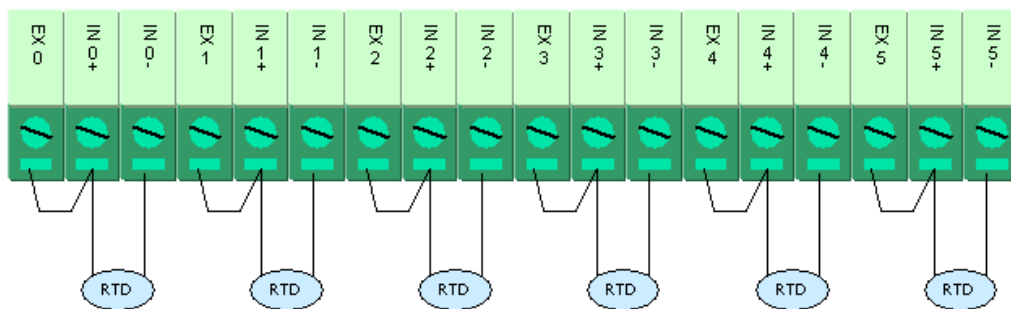


RTD Input Wiring

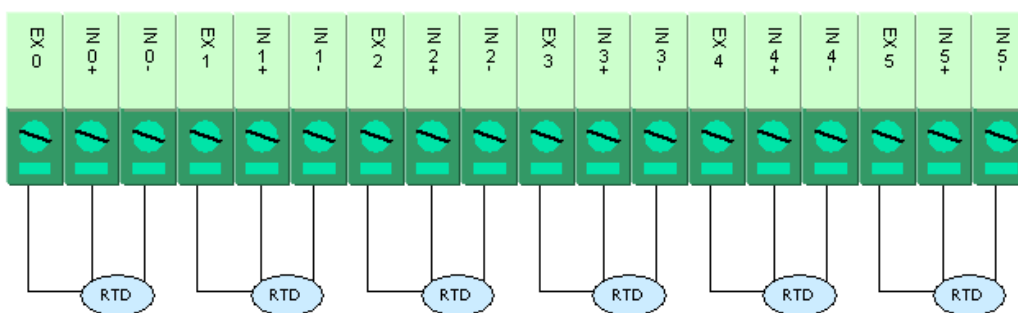
Structure



2-wire

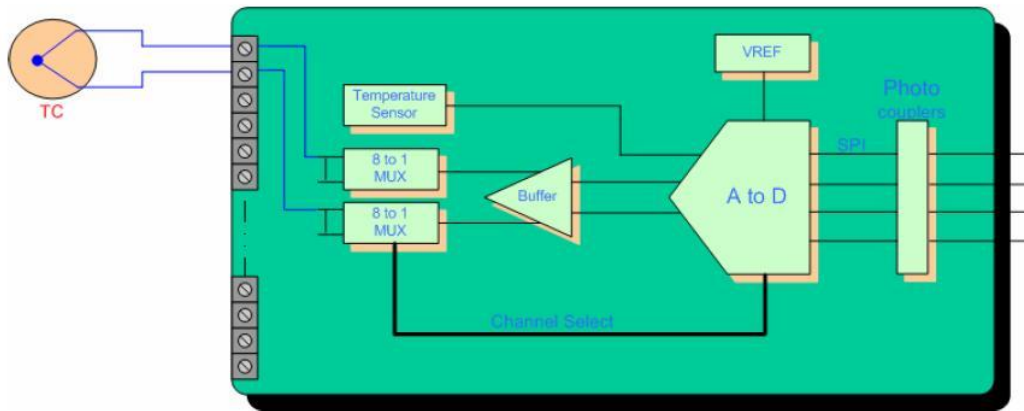


3-wire

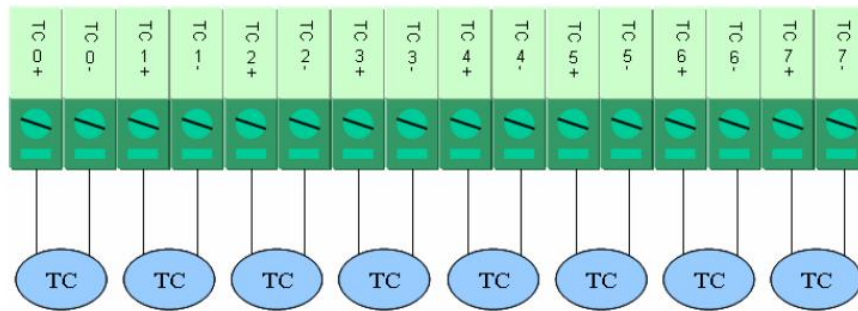


Thermocouple Input Wiring

Structure



2-wire



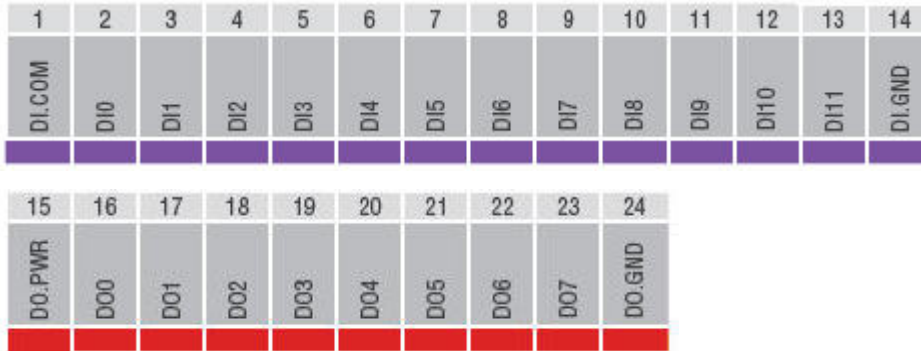
Input and Output Terminal

This appendix includes the pin-outs of the all E2200 series products:

- **ioLogik E2210**
- **ioLogik E2212**
- **ioLogik E2214**
- **ioLogik E2240**
- **ioLogik E2242**
- **ioLogik E2260**
- **ioLogik E2262**

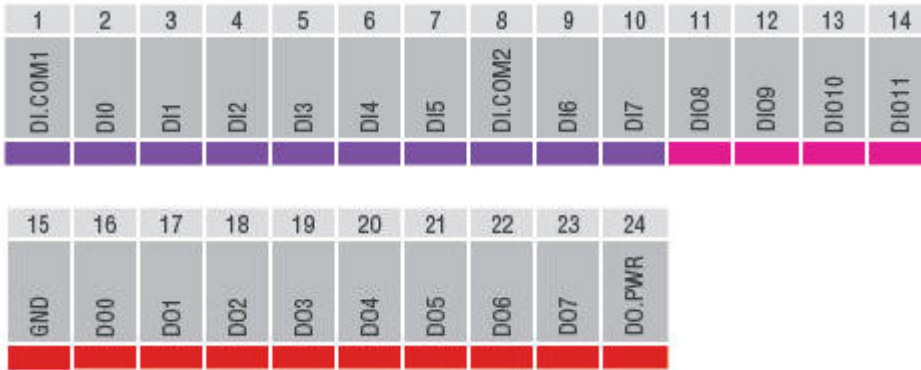
ioLogik E2210

I/O (left to right)



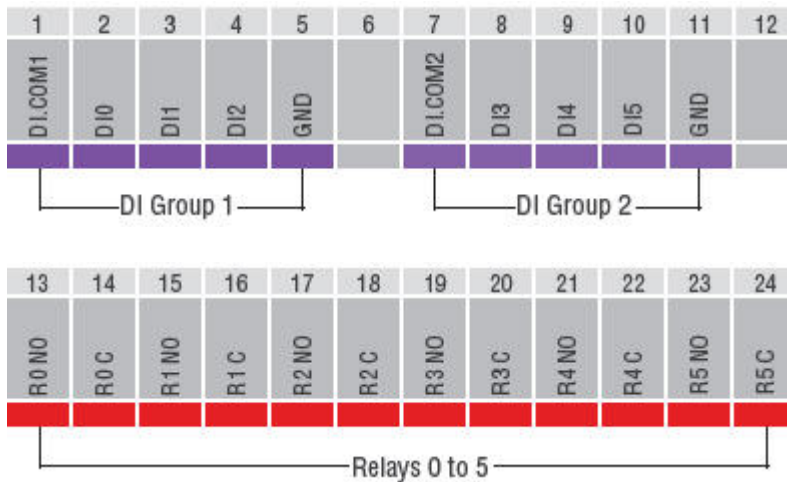
ioLogik E2212

I/O (left to right)



ioLogik E2214

I/O (left to right)



ioLogik E2240

I/O (left to right)

| | | | | | | | | | | | |
|-------|-------|-------|-------|--------|--------|--------|--------|--------|--------|--------|--------|
| 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 |
| Vin0+ | Vin0- | Vin1+ | Vin1- | Vin2+ | Vin2- | Vin3+ | Vin3- | Vin4+ | Vin4- | Vin5+ | Vin5- |
| | | | | | | | | | | | |
| 13 | 14 | 15 | 16 | 17 | 18 | 19 | 20 | 21 | 22 | 23 | 24 |
| Vin6+ | Vin6- | Vin7+ | Vin7- | Vout0+ | Vout0- | Iout0+ | Iout0- | Vout1+ | Vout1- | Iout1+ | Iout1- |
| | | | | | | | | | | | |

ioLogik E2242

I/O (left to right)

| | | | | | | | | | | | |
|-------|-------|-------|-------|-------|-------|-------|-------|---------|-------|-------|---------|
| 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 |
| Ain0+ | Ain0- | Ain1+ | Ain1- | Ain2+ | Ain2- | Ain3+ | Ain3- | DI.COM1 | DIO0 | DIO1 | DIO2 |
| | | | | | | | | | | | |
| 13 | 14 | 15 | 16 | 17 | 18 | 19 | 20 | 21 | 22 | 23 | 24 |
| DIO3 | DIO4 | DIO5 | GND | GND | DIO6 | DIO7 | DIO8 | DIO9 | DIO10 | DIO11 | DI.COM2 |
| | | | | | | | | | | | |

ioLogik E2260

I/O (left to right)

| | | | | | | | | | | | |
|-----|------|------|-----|------|------|--------|------|------|-----|------|--------|
| 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 |
| EX0 | IN0+ | IN0- | EX1 | IN1+ | IN1- | EX2 | IN2+ | IN2- | EX3 | IN3+ | IN3- |
| | | | | | | | | | | | |
| 13 | 14 | 15 | 16 | 17 | 18 | 19 | 20 | 21 | 22 | 23 | 24 |
| EX4 | IN4+ | IN4- | EX5 | IN5+ | IN5- | D0.GND | D00 | D01 | D02 | D03 | D0.PWR |
| | | | | | | | | | | | |

ioLogik E2262

I/O (left to right)

| | | | | | | | | | | | |
|-------|-------|-------|-------|-------|--------|--------|-------|-------|-------|-------|--------|
| 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 |
| TC0 + | TC0 - | TC1 + | TC1 - | TC2 + | TC2 - | TC3 + | TC3 - | TC4 + | TC4 - | TC5 + | TC5 - |
| | | | | | | | | | | | |
| 13 | 14 | 15 | 16 | 17 | 18 | 19 | 20 | 21 | 22 | 23 | 24 |
| TC6 + | TC6 - | TC7 + | TC7 - | | DO.GND | DO.GND | D00 | D01 | D02 | D03 | DO.PWR |
| | | | | | | | | | | | |

Calibration

The ioLogik E2260 achieves accuracy in temperature measurements as follows:

1. At room temperature ($25 \pm 3^{\circ}\text{C}$), accuracy should be within 0.1% FSR. The measurement range of a PT-100 sensor is -200°C to 850°C . That means that readings are accurate to within $\pm 1.05^{\circ}\text{C}$. If an object's temperature is measured at 100°C , the actual temperature should be between 98.95°C and 101.05°C . A reading of 600°C would include temperatures between 598.95°C and 601.05°C .
2. At an ambient temperature of -10°C or 60°C , accuracy should be within 0.3% FSR. If an object's temperature is measured at 100°C the actual temperature should be between 96.85°C and 103.15°C . A reading of 600°C would include temperatures between 596.85°C and 603.15°C .

A calibrator, such as provided by Yokogawa or Fluke, is used for the standard signal source. These products allow Moxa to guarantee accurate measurements to within $\pm 0.1\%$ of FSR. The actual error rates may differ between products. For example, when measuring a 500°C object, one product might achieve accuracy to within 0.1°C , while another product may achieve accuracy to within 0.5°C .

Simple Verification at Your Site

Product specifications may be verified by using a qualified RTD sensor. The sensor can be placed into 0°C or 100°C water to see if the temperature readings are correct. A high precision resistor may also be used for measurement.

Verification with RTD Sensor

When using an RTD sensor, measurement errors are introduced through the sensor itself and through the analog-to-digital signal processing. For example, suppose that the RTD sensor introduces 0.05% error and the AD conversion introduces 0.1% error. For water at a 100°C , the measured temperature would fall somewhere within $100 \pm 1050 * (0.1\% + 0.05\%)$, or between 98.425°C and 101.575°C . The 1050 corresponds to the full range of the PT100 RTD sensor, which is -200°C to 850°C .

Therefore, with an RTD sensor that boasts accuracy within 0.05%, the measured temperature will be accurate to within 0.15% of FSR.

Verification with Precision Resistor

A resistor with Ohm input could be used for verification. Suppose that you use the ioLogik E2260, which is rated at 100Ω 1%, and select 1-310 Ω mode. The measured temperature would fall within $100 \pm (100 \times 1\% + 310 \Omega \times 0.1\%)$, or between 98.69Ω and 101.31Ω . The 310 corresponds to the full scale range of 1-310 Ω mode.

CGI Commands

Using a web browser or standard HTTP protocol will make it easier for a Security SCADA system to monitor and control an ioLogik via CGI commands.

Syntax to get the settings is as follows. Starting with the ioLogik's IP or URL, specify **getParam.cgi** with a question mark. Then specify the command with another question mark as the ending. The commands are case sensitive and the **&** sign is used to combine multiple commands.

[**http://IP/getParam.cgi?command_channel=?&command_channel=?&.....\(Max 200 char\)**](http://IP/getParam.cgi?command_channel=?&command_channel=?&.....(Max 200 char))

- ioLogik E2210**
- ioLogik E2212**
- ioLogik E2214**
- ioLogik E2240**
- ioLogik E2242**
- ioLogik E2260**
- ioLogik E2262**

ioLogik E2210

| Commands to get system information | Commands to get system information |
|------------------------------------|------------------------------------|
| DATE | FWR_V |
| TIME | MOD_NAME |
| IP | SN_NUM |
| LOC | MAC_ADDR |
| DESC | |

| Commands to get DI information | Commands to get DI information |
|--|--|
| DIMode_00 (0:DI, 1:COUNTER) | DIMode_01 (0:DI, 1:COUNTER) |
| DIStatus_00 (0:OFF, 1:ON) | DIStatus_01 (0:OFF, 1:ON) |
| DIFilter_00 | DIFilter_01 |
| DITrigger_00 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_01 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_00 (0:STOP, 1:START) | DICntStart_01 (0:STOP, 1:START) |
| DICNT_00 | DICNT_01 |
| DIMode_02 (0:DI, 1:COUNTER) | DIMode_03 (0:DI, 1:COUNTER) |
| DIStatus_02 (0:OFF, 1:ON) | DIStatus_03 (0:OFF, 1:ON) |
| DIFilter_02 | DIFilter_03 |
| DITrigger_02 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_03 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_02 (0:STOP, 1:START) | DICntStart_03 (0:STOP, 1:START) |
| DICNT_02 | DICNT_03 |
| DIMode_04 (0:DI, 1:COUNTER) | DIMode_05 (0:DI, 1:COUNTER) |
| DIStatus_04 (0:OFF, 1:ON) | DIStatus_05 (0:OFF, 1:ON) |
| DIFilter_04 | DIFilter_05 |
| DITrigger_04 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_05 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_04 (0:STOP, 1:START) | DICntStart_05 (0:STOP, 1:START) |
| DICNT_04 | DICNT_05 |
| DIMode_06 (0:DI, 1:COUNTER) | DIMode_07 (0:DI, 1:COUNTER) |
| DIStatus_06 (0:OFF, 1:ON) | DIStatus_07 (0:OFF, 1:ON) |
| DIFilter_06 | DIFilter_07 |
| DITrigger_06 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_07 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_06(0:STOP, 1:START) | DICntStart_07(0:STOP, 1:START) |
| DICNT_06 | DICNT_07 |
| DIMode_08 (0:DI, 1:COUNTER) | DIMode_09 (0:DI, 1:COUNTER) |
| DIStatus_08 (0:OFF, 1:ON) | DIStatus_09 (0:OFF, 1:ON) |

| Commands to get DI information | Commands to get DI information |
|--|--|
| DIFilter_08 | DIFilter_09 |
| DITrigger_08 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_09 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_08 (0:STOP, 1:START) | DICntStart_09 (0:STOP, 1:START) |
| DICNT_08 | DICNT_09 |
| DIMode_10 (0:DI, 1:COUNTER) | DIMode_11 (0:DI, 1:COUNTER) |
| DIStatus_10(0:OFF, 1:ON) | DIStatus_11(0:OFF, 1:ON) |
| DIFilter_10 | DIFilter_11 |
| DITrigger_10 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_11 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_10 (0:STOP, 1:START) | DICntStart_11 (0:STOP, 1:START) |
| DICNT_10 | DICNT_11 |

| Commands to get DO information | Commands to get DO information |
|--------------------------------------|--------------------------------------|
| DOMode_00 (0:DO, 1:PULSE OUTPUT) | DOMode_01 (0:DO, 1:PULSE OUTPUT) |
| DOStatus_00 (0:OFF, 1:ON) | DOStatus_01 (0:OFF, 1:ON) |
| DOLowWidth_00 | DOLowWidth_01 |
| DOHighWidth_00 | DOHighWidth_01 |
| DOPulseStart_00 (0:STOP, 1:START) | DOPulseStart_01 (0:STOP, 1:START) |
| DOMode_02 (0:DO, 1:PULSE OUTPUT) | DOMode_03 (0:DO, 1:PULSE OUTPUT) |
| DOStatus_02 (0:OFF, 1:ON) | DOStatus_03 (0:OFF, 1:ON) |
| DOLowWidth_02 | DOLowWidth_03 |
| DOHighWidth_02 | DOHighWidth_03 |
| DOPulseStart_02 (0:STOP, 1:START) | DOPulseStart_03 (0:STOP, 1:START) |
| DOMode_04 (0:DO, 1:PULSE OUTPUT) | DOMode_05 (0:DO, 1:PULSE OUTPUT) |
| DOStatus_04 (0:OFF, 1:ON) | DOStatus_05 (0:OFF, 1:ON) |
| DOLowWidth_04 | DOLowWidth_05 |
| DOHighWidth_04 | DOHighWidth_05 |
| DOPulseStart_04 (0:STOP, 1:START) | DOPulseStart_05 (0:STOP, 1:START) |
| DOMode_06 (0:DO, 1:PULSE OUTPUT) | DOMode_07 (0:DO, 1:PULSE OUTPUT) |
| DOStatus_06 (0:OFF, 1:ON) | DOStatus_07 (0:OFF, 1:ON) |
| DOLowWidth_06 | DOLowWidth_07 |
| DOHighWidth_06 | DOHighWidth_07 |
| DOPulseStart_06 (0:STOP, 1:START) | DOPulseStart_07 (0:STOP, 1:START) |

Syntax to get the settings is as follows. Starting with the ioLogik's IP or URL, specify **setParam.cgi** with a question mark. Then specify the command with another question mark as the ending. Those commands are case sensitive and the **&** sign is used to combine multiple commands.

| Commands to set DI channels | Commands to set DI channels |
|--|--|
| DIMode_00 (0:DI, 1:COUNTER) | DIMode_01 (0:DI, 1:COUNTER) |
| DIFilter_00 | DIFilter_01 |
| DITrigger_00 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_01 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_00 (0:STOP, 1:START) | DICntStart_01 (0:STOP, 1:START) |
| DIMode_02 (0:DI, 1:COUNTER) | DIMode_03 (0:DI, 1:COUNTER) |
| DIFilter_02 | DIFilter_03 |
| DITrigger_02 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_03 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_02 (0:STOP, 1:START) | DICntStart_03 (0:STOP, 1:START) |
| DIMode_04 (0:DI, 1:COUNTER) | DIMode_05 (0:DI, 1:COUNTER) |
| DIFilter_04 | DIFilter_05 |
| DITrigger_04 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_05 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_04 (0:STOP, 1:START) | DICntStart_05 (0:STOP, 1:START) |
| DIMode_06 (0:DI, 1:COUNTER) | DIMode_07 (0:DI, 1:COUNTER) |
| DIFilter_06 | DIFilter_07 |
| DITrigger_06 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_07 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_06 (0:STOP, 1:START) | DICntStart_07 (0:STOP, 1:START) |
| DIMode_08 (0:DI, 1:COUNTER) | DIMode_09 (0:DI, 1:COUNTER) |
| DIFilter_08 | DIFilter_09 |
| DITrigger_08 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_09 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_08 (0:STOP, 1:START) | DICntStart_09 (0:STOP, 1:START) |
| DIMode_10 (0:DI, 1:COUNTER) | DIMode_11 (0:DI, 1:COUNTER) |
| DIFilter_10 | DIFilter_11 |
| DITrigger_10 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_11 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_10 (0:STOP, 1:START) | DICntStart_11 (0:STOP, 1:START) |

| Commands to set DO channels | Commands to set DO channels |
|--------------------------------------|--------------------------------------|
| DOMode_00 (0:DO, 1:PULSE OUTPUT) | DOMode_01 (0:DO, 1:PULSE OUTPUT) |
| DOSTatus_00 (0:OFF, 1:ON) | DOSTatus_01 (0:OFF, 1:ON) |
| DOLowWidth_00 | DOLowWidth_01 |
| DOHighWidth_00 | DOHighWidth_01 |
| DOPulseStart_00 (0:STOP, 1:START) | DOPulseStart_01 (0:STOP, 1:START) |
| DOMode_02 (0:DO, 1:PULSE OUTPUT) | DOMode_03 (0:DO, 1:PULSE OUTPUT) |
| DOSTatus_02 (0:OFF, 1:ON) | DOSTatus_03 (0:OFF, 1:ON) |
| DOLowWidth_02 | DOLowWidth_03 |
| DOHighWidth_02 | DOHighWidth_03 |
| DOPulseStart_02 (0:STOP, 1:START) | DOPulseStart_03 (0:STOP, 1:START) |
| DOMode_04 (0:DO, 1:PULSE OUTPUT) | DOMode_05 (0:DO, 1:PULSE OUTPUT) |
| DOSTatus_04 (0:OFF, 1:ON) | DOSTatus_05 (0:OFF, 1:ON) |
| DOLowWidth_04 | DOLowWidth_05 |
| DOHighWidth_04 | DOHighWidth_05 |
| DOPulseStart_04 (0:STOP, 1:START) | DOPulseStart_05 (0:STOP, 1:START) |
| DOMode_06 (0:DO, 1:PULSE OUTPUT) | DOMode_07 (0:DO, 1:PULSE OUTPUT) |
| DOSTatus_06 (0:OFF, 1:ON) | DOSTatus_07 (0:OFF, 1:ON) |
| DOLowWidth_06 | DOLowWidth_07 |
| DOHighWidth_06 | DOHighWidth_07 |
| DOPulseStart_06 (0:STOP, 1:START) | DOPulseStart_07 (0:STOP, 1:START) |

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| Commands to get system information | Commands to get system information |
|------------------------------------|------------------------------------|
| DATE | FWR_V |
| TIME | MOD_NAME |
| IP | SN_NUM |
| LOC | MAC_ADDR |
| DESC | |

| Commands to get DI information | Commands to get DI information |
|--|--|
| DIMode_00 (0:DI, 1:COUNTER) | DIMode_01 (0:DI, 1:COUNTER) |
| DIStatus_00 (0:OFF, 1:ON) | DIStatus_01 (0:OFF, 1:ON) |
| DIFilter_00 | DIFilter_01 |
| DITrigger_00 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_01 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_00 (0:STOP, 1:START) | DICntStart_01 (0:STOP, 1:START) |
| DICNT_00 | DICNT_01 |
| DIMode_02 (0:DI, 1:COUNTER) | DIMode_03 (0:DI, 1:COUNTER) |
| DIStatus_02 (0:OFF, 1:ON) | DIStatus_03 (0:OFF, 1:ON) |
| DIFilter_02 | DIFilter_03 |
| DITrigger_02 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_03 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_02 (0:STOP, 1:START) | DICntStart_03 (0:STOP, 1:START) |
| DICNT_02 | DICNT_03 |
| DIMode_04 (0:DI, 1:COUNTER) | DIMode_05 (0:DI, 1:COUNTER) |
| DIStatus_04 (0:OFF, 1:ON) | DIStatus_05 (0:OFF, 1:ON) |
| DIFilter_04 | DIFilter_05 |
| DITrigger_04 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_05 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_04 (0:STOP, 1:START) | DICntStart_05 (0:STOP, 1:START) |
| DICNT_04 | DICNT_05 |
| DIMode_06 (0:DI, 1:COUNTER) | DIMode_07 (0:DI, 1:COUNTER) |
| DIStatus_06 (0:OFF, 1:ON) | DIStatus_07 (0:OFF, 1:ON) |
| DIFilter_06 | DIFilter_07 |
| DITrigger_06 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_07 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_06 (0:STOP, 1:START) | DICntStart_07 (0:STOP, 1:START) |
| DICNT_06 | DICNT_07 |
| DIMode_08 (0:DI, 1:COUNTER) | DIMode_09 (0:DI, 1:COUNTER) |

| Commands to get DI information | Commands to get DI information |
|--|--|
| DIStatus_08 (0:OFF, 1:ON) | DIStatus_09 (0:OFF, 1:ON) |
| DIFilter_08 | DIFilter_09 |
| DITrigger_08 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_09 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_08 (0:STOP, 1:START) | DICntStart_09 (0:STOP, 1:START) |
| DICNT_08 | DICNT_09 |
| DIMode_10 (0:DI, 1:COUNTER) | DIMode_11 (0:DI, 1:COUNTER) |
| DIStatus_10 (0:OFF, 1:ON) | DIStatus_11 (0:OFF, 1:ON) |
| DIFilter_10 | DIFilter_11 |
| DITrigger_10 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_11 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_10 (0:STOP, 1:START) | DICntStart_11(0:STOP, 1:START) |
| DICNT_10 | DICNT_11 |

| Commands to get DO information | Commands to get DO information |
|--------------------------------------|--------------------------------------|
| DOMode_00 (0:DO, 1:PULSE OUTPUT) | DOMode_01 (0:DO, 1:PULSE OUTPUT) |
| DOStatus_00 (0:OFF, 1:ON) | DOStatus_01 (0:OFF, 1:ON) |
| DOLowWidth_00 | DOLowWidth_01 |
| DOHighWidth_00 | DOHighWidth_01 |
| DOPulseStart_00 (0:STOP, 1:START) | DOPulseStart_01 (0:STOP, 1:START) |
| DOMode_02 (0:DO, 1:PULSE OUTPUT) | DOMode_03 (0:DO, 1:PULSE OUTPUT) |
| DOStatus_02 (0:OFF, 1:ON) | DOStatus_03 (0:OFF, 1:ON) |
| DOLowWidth_02 | DOLowWidth_03 |
| DOHighWidth_02 | DOHighWidth_03 |
| DOPulseStart_02 (0:STOP, 1:START) | DOPulseStart_03 (0:STOP, 1:START) |
| DOMode_04 (0:DO, 1:PULSE OUTPUT) | DOMode_05 (0:DO, 1:PULSE OUTPUT) |
| DOStatus_04 (0:OFF, 1:ON) | DOStatus_05 (0:OFF, 1:ON) |
| DOLowWidth_04 | DOLowWidth_05 |
| DOHighWidth_04 | DOHighWidth_05 |
| DOPulseStart_04 (0:STOP, 1:START) | DOPulseStart_05 (0:STOP, 1:START) |
| DOMode_06 (0:DO, 1:PULSE OUTPUT) | DOMode_07 (0:DO, 1:PULSE OUTPUT) |
| DOStatus_06 (0:OFF, 1:ON) | DOStatus_07 (0:OFF, 1:ON) |
| DOLowWidth_06 | DOLowWidth_07 |
| DOHighWidth_06 | DOHighWidth_07 |
| DOPulseStart_06 (0:STOP, 1:START) | DOPulseStart_07 (0:STOP, 1:START) |

Syntax to get the settings is as follows. Starting with the ioLogik's IP or URL, specify **setParam.cgi** with a question mark. Then specify the command with another question mark as the ending. Those commands are case sensitive and the **&** sign is used to combine multiple commands.

[http://IP/setParam.cgi?command_channel=value&command_channel=value&..\(Max 200 char\)](http://IP/setParam.cgi?command_channel=value&command_channel=value&..(Max 200 char))

| Commands to set DI channels | Commands to set DI channels |
|--|--|
| DIMode_00 (0:DI, 1:COUNTER) | DIMode_01 (0:DI, 1:COUNTER) |
| DIFilter_00 | DIFilter_01 |
| DITrigger_00 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_01 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_00 (0:STOP, 1:START) | DICntStart_01 (0:STOP, 1:START) |
| DIMode_02 (0:DI, 1:COUNTER) | DIMode_03 (0:DI, 1:COUNTER) |
| DIFilter_02 | DIFilter_03 |
| DITrigger_02 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_03 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_02 (0:STOP, 1:START) | DICntStart_03 (0:STOP, 1:START) |
| DIMode_04 (0:DI, 1:COUNTER) | DIMode_05 (0:DI, 1:COUNTER) |
| DIFilter_04 | DIFilter_05 |
| DITrigger_04 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_05 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_04 (0:STOP, 1:START) | DICntStart_05 (0:STOP, 1:START) |
| DIMode_06 (0:DI, 1:COUNTER) | DIMode_07 (0:DI, 1:COUNTER) |
| DIFilter_06 | DIFilter_07 |
| DITrigger_06 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_07 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_06 (0:STOP, 1:START) | DICntStart_07 (0:STOP, 1:START) |
| DIMode_08 (0:DI, 1:COUNTER) | DIMode_09 (0:DI, 1:COUNTER) |
| DIFilter_08 | DIFilter_09 |
| DITrigger_08 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_09 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_08 (0:STOP, 1:START) | DICntStart_09 (0:STOP, 1:START) |
| DIMode_10 (0:DI, 1:COUNTER) | DIMode_11 (0:DI, 1:COUNTER) |
| DIFilter_10 | DIFilter_11 |
| DITrigger_10 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_11 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_10 (0:STOP, 1:START) | DICntStart_11 (0:STOP, 1:START) |

| Commands to set DO channels | Commands to set DO channels |
|--------------------------------------|--------------------------------------|
| DOMode_00 (0:DO, 1:PULSE OUTPUT) | DOMode_01 (0:DO, 1:PULSE OUTPUT) |
| DOSTatus_00 (0:OFF, 1:ON) | DOSTatus_01 (0:OFF, 1:ON) |
| DOLowWidth_00 | DOLowWidth_01 |
| DOHighWidth_00 | DOHighWidth_01 |
| DOPulseStart_00 (0:STOP, 1:START) | DOPulseStart_01 (0:STOP, 1:START) |
| DOMode_02 (0:DO, 1:PULSE OUTPUT) | DOMode_03 (0:DO, 1:PULSE OUTPUT) |
| DOSTatus_02 (0:OFF, 1:ON) | DOSTatus_03 (0:OFF, 1:ON) |
| DOLowWidth_02 | DOLowWidth_03 |
| DOHighWidth_02 | DOHighWidth_03 |
| DOPulseStart_02 (0:STOP, 1:START) | DOPulseStart_03 (0:STOP, 1:START) |
| DOMode_04 (0:DO, 1:PULSE OUTPUT) | DOMode_05 (0:DO, 1:PULSE OUTPUT) |
| DOSTatus_04 (0:OFF, 1:ON) | DOSTatus_05 (0:OFF, 1:ON) |
| DOLowWidth_04 | DOLowWidth_05 |
| DOHighWidth_04 | DOHighWidth_05 |
| DOPulseStart_04 (0:STOP, 1:START) | DOPulseStart_05 (0:STOP, 1:START) |
| DOMode_06 (0:DO, 1:PULSE OUTPUT) | DOMode_07 (0:DO, 1:PULSE OUTPUT) |
| DOSTatus_06 (0:OFF, 1:ON) | DOSTatus_07 (0:OFF, 1:ON) |
| DOLowWidth_06 | DOLowWidth_07 |
| DOHighWidth_06 | DOHighWidth_07 |
| DOPulseStart_06 (0:STOP, 1:START) | DOPulseStart_07 (0:STOP, 1:START) |
| DOMode_08 (0:DO, 1:PULSE OUTPUT) | DOMode_09 (0:DO, 1:PULSE OUTPUT) |
| DOSTatus_08 (0:OFF, 1:ON) | DOSTatus_09 (0:OFF, 1:ON) |
| DOLowWidth_08 | DOLowWidth_09 |
| DOHighWidth_08 | DOHighWidth_09 |
| DOPulseStart_08 (0:STOP, 1:START) | DOPulseStart_09 (0:STOP, 1:START) |
| DOMode_10 (0:DO, 1:PULSE OUTPUT) | DOMode_11 (0:DO, 1:PULSE OUTPUT) |
| DOSTatus_10 (0:OFF, 1:ON) | DOSTatus_11 (0:OFF, 1:ON) |
| DOLowWidth_10 | DOLowWidth_11 |
| DOHighWidth_10 | DOHighWidth_11 |
| DOPulseStart_10 (0:STOP, 1:START) | DOPulseStart_11 (0:STOP, 1:START) |

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| Commands to get system information | Commands to get system information |
|------------------------------------|------------------------------------|
| DATE | FWR_V |
| TIME | MOD_NAME |
| IP | SN_NUM |
| LOC | MAC_ADDR |
| DESC | |

| Commands to get DI information | Commands to get DI information |
|--|--|
| DIMode_00 (0:DI, 1:COUNTER) | DIMode_01 (0:DI, 1:COUNTER) |
| DIStatus_00 (0:OFF, 1:ON) | DIStatus_01 (0:OFF, 1:ON) |
| DIFilter_00 | DIFilter_01 |
| DITrigger_00 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_01 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_00 (0:STOP, 1:START) | DICntStart_01 (0:STOP, 1:START) |
| DICNT_00 | DICNT_01 |
| DIMode_02 (0:DI, 1:COUNTER) | DIMode_03 (0:DI, 1:COUNTER) |
| DIStatus_02 (0:OFF, 1:ON) | DIStatus_03 (0:OFF, 1:ON) |
| DIFilter_02 | DIFilter_03 |
| DITrigger_02 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_03 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_02 (0:STOP, 1:START) | DICntStart_03 (0:STOP, 1:START) |
| DICNT_02 | DICNT_03 |
| DIMode_04 (0:DI, 1:COUNTER) | DIMode_05 (0:DI, 1:COUNTER) |
| DIStatus_04 (0:OFF, 1:ON) | DIStatus_05 (0:OFF, 1:ON) |
| DIFilter_04 | DIFilter_05 |
| DITrigger_04 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_05 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_04 (0:STOP, 1:START) | DICntStart_05 (0:STOP, 1:START) |
| DICNT_04 | DICNT_05 |

| Commands to get DO information | Commands to get DO information |
|--------------------------------------|--------------------------------------|
| DOMode_00 (0:DO, 1:PULSE OUTPUT) | DOMode_01 (0:DO, 1:PULSE OUTPUT) |
| DOStatus_00 (0:OFF, 1:ON) | DOStatus_01 (0:OFF, 1:ON) |
| DOLowWidth_00 | DOLowWidth_01 |
| DOHighWidth_00 | DOHighWidth_01 |
| DOPulseStart_00 (0:STOP, 1:START) | DOPulseStart_01 (0:STOP, 1:START) |
| DOTotalRelayCNT_00 | DOTotalRelayCNT_01 |
| DOCurrentRelayCNT_00 | DOCurrentRelayCNT_01 |

| Commands to get DO information | Commands to get DO information |
|--------------------------------------|--------------------------------------|
| DOMode_02 (0:DO, 1:PULSE OUTPUT) | DOMode_03 (0:DO, 1:PULSE OUTPUT) |
| DOSTatus_02 (0:OFF, 1:ON) | DOSTatus_03 (0:OFF, 1:ON) |
| DOLowWidth_02 | DOLowWidth_03 |
| DOHighWidth_02 | DOHighWidth_03 |
| DOPulseStart_02 (0:STOP, 1:START) | DOPulseStart_03 (0:STOP, 1:START) |
| DOTotalRelayCNT_02 | DOTotalRelayCNT_03 |
| DOCurrentRelayCNT_02 | DOCurrentRelayCNT_03 |
| DOMode_04 (0:DO, 1:PULSE OUTPUT) | DOMode_05 (0:DO, 1:PULSE OUTPUT) |
| DOSTatus_04 (0:OFF, 1:ON) | DOSTatus_05 (0:OFF, 1:ON) |
| DOLowWidth_04 | DOLowWidth_05 |
| DOHighWidth_04 | DOHighWidth_05 |
| DOPulseStart_04 (0:STOP, 1:START) | DOPulseStart_05 (0:STOP, 1:START) |
| DOTotalRelayCNT_04 | DOTotalRelayCNT_05 |
| DOCurrentRelayCNT_04 | DOCurrentRelayCNT_05 |

Syntax to get the settings is as follows. Starting with the ioLogik's IP or URL, specify **setParam.cgi** with a question mark. Then specify the command with another question mark as the ending. Those commands are case sensitive and the **&** sign is used to combine multiple commands.

[**http://IP/setParam.cgi?command_channel=value&command_channel=value&..\(Max 200 char\)**](http://IP/setParam.cgi?command_channel=value&command_channel=value&..(Max 200 char))

| Commands to set DI channels | Commands to set DI channels |
|--|--|
| DIMode_00 (0:DI, 1:COUNTER) | DIMode_01 (0:DI, 1:COUNTER) |
| DIFilter_00 | DIFilter_01 |
| DITrigger_00 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_01 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_00 (0:STOP, 1:START) | DICntStart_01 (0:STOP, 1:START) |
| DIMode_02 (0:DI, 1:COUNTER) | DIMode_03 (0:DI, 1:COUNTER) |
| DIFilter_02 | DIFilter_03 |
| DITrigger_02 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_03 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_02 (0:STOP, 1:START) | DICntStart_03 (0:STOP, 1:START) |
| DIMode_04 (0:DI, 1:COUNTER) | DIMode_05 (0:DI, 1:COUNTER) |
| DIFilter_04 | DIFilter_05 |
| DITrigger_04 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_05 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_04 (0:STOP, 1:START) | DICntStart_05 (0:STOP, 1:START) |

| Commands to set DO channels | Commands to set DO channels |
|--------------------------------------|--------------------------------------|
| DOMode_00 (0:DO, 1:PULSE OUTPUT) | DOMode_01 (0:DO, 1:PULSE OUTPUT) |
| DOSTatus_00 (0:OFF, 1:ON) | DOSTatus_01 (0:OFF, 1:ON) |
| DOLowWidth_00 | DOLowWidth_01 |
| DOHighWidth_00 | DOHighWidth_01 |
| DOPulseStart_00 (0:STOP, 1:START) | DOPulseStart_01 (0:STOP, 1:START) |
| DOCurrentRelayCNT_00 | DOCurrentRelayCNT_01 |
| DOMode_02 (0:DO, 1:PULSE OUTPUT) | DOMode_03 (0:DO, 1:PULSE OUTPUT) |
| DOSTatus_02 (0:OFF, 1:ON) | DOSTatus_03 (0:OFF, 1:ON) |
| DOLowWidth_02 | DOLowWidth_03 |
| DOHighWidth_02 | DOHighWidth_03 |
| DOPulseStart_02 (0:STOP, 1:START) | DOPulseStart_03 (0:STOP, 1:START) |
| DOCurrentRelayCNT_02 | DOCurrentRelayCNT_03 |
| DOMode_04 (0:DO, 1:PULSE OUTPUT) | DOMode_05 (0:DO, 1:PULSE OUTPUT) |
| DOSTatus_04 (0:OFF, 1:ON) | DOSTatus_05 (0:OFF, 1:ON) |
| DOLowWidth_04 | DOLowWidth_05 |
| DOHighWidth_04 | DOHighWidth_05 |
| DOPulseStart_04 (0:STOP, 1:START) | DOPulseStart_05 (0:STOP, 1:START) |
| DOCurrentRelayCNT_04 | DOCurrentRelayCNT_05 |

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| Commands to get system information | Commands to get system information |
|------------------------------------|------------------------------------|
| DATE | FWR_V |
| TIME | MOD_NAME |
| IP | SN_NUM |
| LOC | MAC_ADDR |
| DESC | |

| Commands to get AI information | Commands to get AI information |
|--|--|
| AIValue_00 | AIValue_01 |
| AIRange_00 (0:+/-150mV, 1:+/-500mV, 2:+/-5V, 3:+/-10V, 4:0-20mA, 5:4-20mA) | AIRange_01 (0:+/-150mV, 1:+/-500mV, 2:+/-5V, 3:+/-10V, 4:0-20mA, 5:4-20mA) |
| AIMin_00 | AIMin_01 |
| AIMax_00 | AIMax_01 |
| AIValue_02 | AIValue_03 |
| AIRange_02 (0:+/-150mV, 1:+/-500mV, 2:+/-5V, 3:+/-10V, 4:0-20mA, 5:4-20mA) | AIRange_03 (0:+/-150mV, 1:+/-500mV, 2:+/-5V, 3:+/-10V, 4:0-20mA, 5:4-20mA) |
| AIMin_02 | AIMin_03 |
| AIMax_02 | AIMax_03 |
| AIValue_04 | AIValue_05 |

| Commands to get AI information | Commands to get AI information |
|--|--|
| AIRange_04 (0: +/-150mV, 1: +/-500mV, 2: +/-5V, 3: +/-10V, 4: 0-20mA, 5: 4-20mA) | AIRange_05 (0: +/-150mV, 1: +/-500mV, 2: +/-5V, 3: +/-10V, 4: 0-20mA, 5: 4-20mA) |
| AIMin_04 | AIMin_05 |
| AIMax_04 | AIMax_05 |
| AIValue_06 | AIValue_07 |
| AIRange_06 (0: +/-150mV, 1: +/-500mV, 2: +/-5V, 3: +/-10V, 4: 0-20mA, 5: 4-20mA) | AIRange_07 (0: +/-150mV, 1: +/-500mV, 2: +/-5V, 3: +/-10V, 4: 0-20mA, 5: 4-20mA) |
| AIMin_06 | AIMin_07 |
| AIMax_06 | AIMax_07 |

| Commands to get AO information | Commands to get AO information |
|-------------------------------------|-------------------------------------|
| AOValue_00 | AOValue_01 |
| AOValueP_00 (Power On Value) | AOValueP_01 (Power On Value) |
| AOValueS_00 (Safe Mode Value) | AOValueS_01 (Safe Mode Value) |
| AORange_00 (0: 0-10V, 1: 4-20mA) | AORange_01 (0: 0-10V, 1: 4-20mA) |

Syntax to get the settings is as follows. Starting with the ioLogik's IP or URL, specify **setParam.cgi** with a question mark. Then specify the command with another question mark as the ending. Those commands are case sensitive and the **&** sign is used to combine multiple commands.

| Commands to set AI channels | Commands to set AI channels |
|--|--|
| AIRange_00 (0: +/-150mV, 1: +/-500mV, 2: +/-5V, 3: +/-10V, 4: 0-20mA, 5: 4-20mA) | AIRange_01 (0: +/-150mV, 1: +/-500mV, 2: +/-5V, 3: +/-10V, 4: 0-20mA, 5: 4-20mA) |
| AIRange_02 (0: +/-150mV, 1: +/-500mV, 2: +/-5V, 3: +/-10V, 4: 0-20mA, 5: 4-20mA) | AIRange_03 (0: +/-150mV, 1: +/-500mV, 2: +/-5V, 3: +/-10V, 4: 0-20mA, 5: 4-20mA) |
| AIRange_04 (0: +/-150mV, 1: +/-500mV, 2: +/-5V, 3: +/-10V, 4: 0-20mA, 5: 4-20mA) | AIRange_05 (0: +/-150mV, 1: +/-500mV, 2: +/-5V, 3: +/-10V, 4: 0-20mA, 5: 4-20mA) |
| AIRange_06 (0: +/-150mV, 1: +/-500mV, 2: +/-5V, 3: +/-10V, 4: 0-20mA, 5: 4-20mA) | AIRange_07 (0: +/-150mV, 1: +/-500mV, 2: +/-5V, 3: +/-10V, 4: 0-20mA, 5: 4-20mA) |

| Commands to set AO channels | Commands to set AO Channels |
|-------------------------------------|-------------------------------------|
| AOValue_00 | AOValue_01 |
| AOValueP_00 (Power On Value) | AOValueP_01 (Power On Value) |
| AOValueS_00 (Safe Mode Value) | AOValueS_01 (Safe Mode Value) |
| AORange_00 (0: 0-10V, 1: 4-20mA) | AORange_01 (0: 0-10V, 1: 4-20mA) |

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| Commands to get system information | Commands to get system information |
|------------------------------------|------------------------------------|
| DATE | FWR_V |
| TIME | MOD_NAME |
| IP | SN_NUM |
| LOC | MAC_ADDR |
| DESC | |

| Commands to get AI information | Commands to get AI information |
|---|---|
| AIEnable_00 (0:Disable, 1:Enable) | AIEnable_01 (0:Disable, 1:Enable) |
| AIValue_00 | AIValue_01 |
| AIRange_00 (0:+/-150mV, 1:+/-500mV, 2:+/-5V, 3:+/-10V, 4:0-20mA, 5:4-20mA, 6:0-100mV, 7:0-500mV, 8:0- 5V, 9:0-10V) | AIRange_01 (0:+/-150mV, 1:+/-500mV, 2:+/-5V, 3:+/-10V, 4:0-20mA, 5:4-20mA, 6:0-100mV, 7:0-500mV, 8:0- 5V, 9:0-10V) |
| AIMin_00 | AIMin_01 |
| AIMax_00 | AIMax_01 |
| AIEnable_02 (0:Disable, 1:Enable) | AIEnable_03 (0:Disable, 1:Enable) |
| AIValue_02 | AIValue_03 |
| AIRange_02 (0:+/-150mV, 1:+/-500mV, 2:+/-5V, 3:+/-10V, 4:0-20mA, 5:4-20mA, 6:0-100mV, 7:0-500mV, 8:0- 5V, 9:0-10V) | AIRange_03 (0:+/-150mV, 1:+/-500mV, 2:+/-5V, 3:+/-10V, 4:0-20mA, 5:4-20mA, 6:0-100mV, 7:0-500mV, 8:0- 5V, 9:0-10V) |
| AIMin_02 | AIMin_03 |
| AIMax_02 | AIMax_03 |

| Commands to get DI information | Commands to get DI information |
|--|--|
| DIMode_00 (0:DI, 1:COUNTER) | DIMode_01 (0:DI, 1:COUNTER) |
| DIStatus_00 (0:OFF, 1:ON) | DIStatus_01 (0:OFF, 1:ON) |
| DIFilter_00 | DIFilter_01 |
| DITrigger_00 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_01 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_00 (0:STOP, 1:START) | DICntStart_01 (0:STOP, 1:START) |
| DICNT_00 | DICNT_01 |
| DIMode_02 (0:DI, 1:COUNTER) | DIMode_03 (0:DI, 1:COUNTER) |
| DIStatus_02 (0:OFF, 1:ON) | DIStatus_03 (0:OFF, 1:ON) |
| DIFilter_02 | DIFilter_03 |
| DITrigger_02 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_03 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_02 (0:STOP, 1:START) | DICntStart_03 (0:STOP, 1:START) |
| DICNT_02 | DICNT_03 |
| DIMode_04 (0:DI, 1:COUNTER) | DIMode_05 (0:DI, 1:COUNTER) |
| DIStatus_04 (0:OFF, 1:ON) | DIStatus_05 (0:OFF, 1:ON) |
| DIFilter_04 | DIFilter_05 |

| Commands to get DI information | Commands to get DI information |
|--|--|
| DITrigger_04 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_05 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_04 (0:STOP, 1:START) | DICntStart_05 (0:STOP, 1:START) |
| DICNT_04 | DICNT_05 |
| DIMode_06 (0:DI, 1:COUNTER) | DIMode_07 (0:DI, 1:COUNTER) |
| DIStatus_06 (0:OFF, 1:ON) | DIStatus_07 (0:OFF, 1:ON) |
| DIFilter_06 | DIFilter_07 |
| DITrigger_06 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_07 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_06 (0:STOP, 1:START) | DICntStart_07 (0:STOP, 1:START) |
| DICNT_06 | DICNT_07 |
| DIMode_08 (0:DI, 1:COUNTER) | DIMode_09 (0:DI, 1:COUNTER) |
| DIStatus_08 (0:OFF, 1:ON) | DIStatus_09 (0:OFF, 1:ON) |
| DIFilter_08 | DIFilter_09 |
| DITrigger_08 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_09 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_08 (0:STOP, 1:START) | DICntStart_09 (0:STOP, 1:START) |
| DICNT_08 | DICNT_09 |
| DIMode_10 (0:DI, 1:COUNTER) | DIMode_11 (0:DI, 1:COUNTER) |
| DIStatus_10 (0:OFF, 1:ON) | DIStatus_11 (0:OFF, 1:ON) |
| DIFilter_10 | DIFilter_11 |
| DITrigger_10 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_11 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_10 (0:STOP, 1:START) | DICntStart_11 (0:STOP, 1:START) |
| DICNT_10 | DICNT_11 |

| Commands to get DO information | Commands to get DO information |
|--------------------------------------|--------------------------------------|
| DOMode_00 (0:DO, 1:PULSE OUTPUT) | DOMode_01 (0:DO, 1:PULSE OUTPUT) |
| DOStatus_00 (0:OFF, 1:ON) | DOStatus_01 (0:OFF, 1:ON) |
| DOLowWidth_00 | DOLowWidth_01 |
| DOHighWidth_00 | DOHighWidth_01 |
| DOPulseStart_00 (0:STOP, 1:START) | DOPulseStart_01 (0:STOP, 1:START) |
| DOMode_02 (0:DO, 1:PULSE OUTPUT) | DOMode_03 (0:DO, 1:PULSE OUTPUT) |
| DOStatus_02 (0:OFF, 1:ON) | DOStatus_03 (0:OFF, 1:ON) |
| DOLowWidth_02 | DOLowWidth_03 |
| DOHighWidth_02 | DOHighWidth_03 |

| Commands to get DO information | Commands to get DO information |
|--------------------------------------|--------------------------------------|
| DOPulseStart_02 (0:STOP, 1:START) | DOPulseStart_03 (0:STOP, 1:START) |
| DOMode_04 (0:DO, 1:PULSE OUTPUT) | DOMode_05 (0:DO, 1:PULSE OUTPUT) |
| DOSTatus_04 (0:OFF, 1:ON) | DOSTatus_05 (0:OFF, 1:ON) |
| DOLowWidth_04 | DOLowWidth_05 |
| DOHighWidth_04 | DOHighWidth_05 |
| DOPulseStart_04 (0:STOP, 1:START) | DOPulseStart_05 (0:STOP, 1:START) |
| DOMode_06 (0:DO, 1:PULSE OUTPUT) | DOMode_07 (0:DO, 1:PULSE OUTPUT) |
| DOSTatus_06 (0:OFF, 1:ON) | DOSTatus_07 (0:OFF, 1:ON) |
| DOLowWidth_06 | DOLowWidth_07 |
| DOHighWidth_06 | DOHighWidth_07 |
| DOPulseStart_06 (0:STOP, 1:START) | DOPulseStart_07 (0:STOP, 1:START) |
| DOMode_08 (0:DO, 1:PULSE OUTPUT) | DOMode_09 (0:DO, 1:PULSE OUTPUT) |
| DOSTatus_08 (0:OFF, 1:ON) | DOSTatus_09 (0:OFF, 1:ON) |
| DOLowWidth_08 | DOLowWidth_09 |
| DOHighWidth_08 | DOHighWidth_09 |
| DOPulseStart_08 (0:STOP, 1:START) | DOPulseStart_09 (0:STOP, 1:START) |
| DOMode_10 (0:DO, 1:PULSE OUTPUT) | DOMode_11 (0:DO, 1:PULSE OUTPUT) |
| DOSTatus_10 (0:OFF, 1:ON) | DOSTatus_11 (0:OFF, 1:ON) |
| DOLowWidth_10 | DOLowWidth_11 |
| DOHighWidth_10 | DOHighWidth_11 |
| DOPulseStart_10 (0:STOP, 1:START) | DOPulseStart_11 (0:STOP, 1:START) |

Syntax to get the settings is as follows. Starting with the ioLogik's IP or URL, specify **setParam.cgi** with a question mark. Then specify the command with another question mark as the ending. Those commands are case sensitive and the **&** sign is used to combine multiple commands.

| Commands to set AI channels | Commands to set AI channels |
|---|---|
| AIEnable_00 (0:Disable, 1:Enable) | AIEnable_01 (0:Disable, 1:Enable) |
| AIRange_00 (0:+/-150mV, 1:+/-500mV, 2:+/-5V, 3:+/-10V, 4:0-20mA, 5:4-20mA, 6:0-100mV, 7:0-500mV, 8:0- 5V, 9:0-10V) | AIRange_01 (0:+/-150mV, 1:+/-500mV, 2:+/-5V, 3:+/-10V, 4:0-20mA, 5:4-20mA, 6:0-100mV, 7:0-500mV, 8:0- 5V, 9:0-10V) |
| AIEnable_02 (0:Disable, 1:Enable) | AIEnable_03 (0:Disable, 1:Enable) |
| AIRange_02 (0:+/-150mV, 1:+/-500mV, 2:+/-5V, 3:+/-10V, 4:0-20mA, 5:4-20mA, 6:0-100mV, 7:0-500mV, 8:0- 5V, 9:0-10V) | AIRange_03 (0:+/-150mV, 1:+/-500mV, 2:+/-5V, 3:+/-10V, 4:0-20mA, 5:4-20mA, 6:0-100mV, 7:0-500mV, 8:0- 5V, 9:0-10V) |

| Commands to set DI channels | Commands to set DI Channels |
|--|--|
| DIMode_00 (0:DI, 1:COUNTER) | DIMode_01 (0:DI, 1:COUNTER) |
| DIFilter_00 | DIFilter_01 |
| DITrigger_00 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_01 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_00 (0:STOP, 1:START) | DICntStart_01 (0:STOP, 1:START) |
| DIMode_02 (0:DI, 1:COUNTER) | DIMode_03 (0:DI, 1:COUNTER) |
| DIFilter_02 | DIFilter_03 |
| DITrigger_02 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_03 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_02 (0:STOP, 1:START) | DICntStart_03 (0:STOP, 1:START) |
| DIMode_04 (0:DI, 1:COUNTER) | DIMode_05 (0:DI, 1:COUNTER) |
| DIFilter_04 | DIFilter_05 |
| DITrigger_04 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_05 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_04 (0:STOP, 1:START) | DICntStart_05 (0:STOP, 1:START) |
| DIMode_06 (0:DI, 1:COUNTER) | DIMode_07 (0:DI, 1:COUNTER) |
| DIFilter_06 | DIFilter_07 |
| DITrigger_06 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_07 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_06 (0:STOP, 1:START) | DICntStart_07 (0:STOP, 1:START) |
| DIMode_08 (0:DI, 1:COUNTER) | DIMode_09 (0:DI, 1:COUNTER) |
| DIFilter_08 | DIFilter_09 |
| DITrigger_08 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_09 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_08 (0:STOP, 1:START) | DICntStart_09 (0:STOP, 1:START) |
| DIMode_10 (0:DI, 1:COUNTER) | DIMode_11 (0:DI, 1:COUNTER) |
| DIFilter_10 | DIFilter_11 |
| DITrigger_10 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) | DITrigger_11 (0:LOW TO HIGH, 1:HIGH TO LOW, 2:BOTH) |
| DICntStart_10 (0:STOP, 1:START) | DICntStart_11 (0:STOP, 1:START) |

| Commands to set DO channels | Commands to set DO Channels |
|--------------------------------------|--------------------------------------|
| DOMode_00 (0:DO, 1:PULSE OUTPUT) | DOMode_01 (0:DO, 1:PULSE OUTPUT) |
| DOStatus_00 (0:OFF, 1:ON) | DOStatus_01 (0:OFF, 1:ON) |
| DOLowWidth_00 | DOLowWidth_01 |
| DOHighWidth_00 | DOHighWidth_01 |
| DOPulseStart_00 (0:STOP, 1:START) | DOPulseStart_01 (0:STOP, 1:START) |

| Commands to set DO channels | Commands to set DO Channels |
|--------------------------------------|--------------------------------------|
| DOMode_02 (0:DO, 1:PULSE OUTPUT) | DOMode_03 (0:DO, 1:PULSE OUTPUT) |
| DOSTatus_02 (0:OFF, 1:ON) | DOSTatus_03 (0:OFF, 1:ON) |
| DOLowWidth_02 | DOLowWidth_03 |
| DOHighWidth_02 | DOHighWidth_03 |
| DOPulseStart_02 (0:STOP, 1:START) | DOPulseStart_03 (0:STOP, 1:START) |
| DOMode_04 (0:DO, 1:PULSE OUTPUT) | DOMode_05 (0:DO, 1:PULSE OUTPUT) |
| DOSTatus_04 (0:OFF, 1:ON) | DOSTatus_05 (0:OFF, 1:ON) |
| DOLowWidth_04 | DOLowWidth_05 |
| DOHighWidth_04 | DOHighWidth_05 |
| DOPulseStart_04 (0:STOP, 1:START) | DOPulseStart_05 (0:STOP, 1:START) |
| DOMode_06 (0:DO, 1:PULSE OUTPUT) | DOMode_07 (0:DO, 1:PULSE OUTPUT) |
| DOSTatus_06 (0:OFF, 1:ON) | DOSTatus_07 (0:OFF, 1:ON) |
| DOLowWidth_06 | DOLowWidth_07 |
| DOHighWidth_06 | DOHighWidth_07 |
| DOPulseStart_06 (0:STOP, 1:START) | DOPulseStart_07 (0:STOP, 1:START) |
| DOMode_08 (0:DO, 1:PULSE OUTPUT) | DOMode_09 (0:DO, 1:PULSE OUTPUT) |
| DOSTatus_08 (0:OFF, 1:ON) | DOSTatus_09 (0:OFF, 1:ON) |
| DOLowWidth_08 | DOLowWidth_09 |
| DOHighWidth_08 | DOHighWidth_09 |
| DOPulseStart_08 (0:STOP, 1:START) | DOPulseStart_09 (0:STOP, 1:START) |
| DOMode_10 (0:DO, 1:PULSE OUTPUT) | DOMode_11 (0:DO, 1:PULSE OUTPUT) |
| DOSTatus_10 (0:OFF, 1:ON) | DOSTatus_11 (0:OFF, 1:ON) |
| DOLowWidth_10 | DOLowWidth_11 |
| DOHighWidth_10 | DOHighWidth_11 |
| DOPulseStart_10 (0:STOP, 1:START) | DOPulseStart_11 (0:STOP, 1:START) |

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| Commands to get system information | Commands to get system information |
|------------------------------------|------------------------------------|
| DATE | FWR_V |
| TIME | MOD_NAME |
| IP | SN_NUM |
| LOC | MAC_ADDR |
| DESC | |

| Commands to get RTD information | Commands to get RTD information |
|--|--|
| RtdEnable_00 (0:Disable, 1:Enable) | RtdEnable_01 (0:Disable, 1:Enable) |
| RtdStype_00 (0:PT50, 1:Pt100, 2:Pt200, 3:Pt500, 4:Pt1000, 5:JPt100, 6:JPt200, 7:JPt500, 8:JPt1000, 9 :Ni 100, 10 :Ni 200, 11 :Ni 500, 12 :Ni 1000, 13 :Ni 120, 14 :Resistance (1-310 mΩ), 15:Resistance (1-620 mΩ), 16 :Resistance (1-1250 mΩ), 17:Resistance (1-2200 mΩ)) | RtdStype_01 (0:PT50, 1:Pt100, 2:Pt200, 3:Pt500, 4:Pt1000, 5:JPt100, 6:JPt200, 7:JPt500, 8:JPt1000, 9 :Ni 100, 10 :Ni 200, 11 :Ni 500, 12 :Ni 1000, 13 :Ni 120, 14 :Resistance (1-310 mΩ), 15:Resistance (1-620 mΩ), 16 :Resistance (1-1250 mΩ), 17:Resistance (1-2200 mΩ)) |
| RtdUtype_00 (Unit Types. 0:°C, 1:°F, 2:Ω) | RtdUtype_01 (Unit Types. 0:°C, 1:°F, 2:Ω) |
| RtdStatus_00 | RtdStatus_01 |
| RtdEnable_02 (0:Disable, 1:Enable) | RtdEnable_03 (0:Disable, 1:Enable) |
| RtdStype_02 (0:PT50, 1:Pt100, 2:Pt200, 3:Pt500, 4:Pt1000, 5:JPt100, 6:JPt200, 7:JPt500, 8:JPt1000, 9 :Ni 100, 10 :Ni 200, 11 :Ni 500, 12 :Ni 1000, 13 :Ni 120, 14 :Resistance (1-310 mΩ), 15:Resistance (1-620 mΩ), 16 :Resistance (1-1250 mΩ), 17:Resistance (1-2200 mΩ)) | RtdStype_03 (0:PT50, 1:Pt100, 2:Pt200, 3:Pt500, 4:Pt1000, 5:JPt100, 6:JPt200, 7:JPt500, 8:JPt1000, 9 :Ni 100, 10 :Ni 200, 11 :Ni 500, 12 :Ni 1000, 13 :Ni 120, 14 :Resistance (1-310 mΩ), 15:Resistance (1-620 mΩ), 16 :Resistance (1-1250 mΩ), 17:Resistance (1-2200 mΩ)) |
| RtdUtype_02 (Unit Types. 0:°C, 1:°F, 2:Ω) | RtdUtype_03 (Unit Types. 0:°C, 1:°F, 2:Ω) |
| RtdStatus_02 | RtdStatus_03 |
| RtdEnable_04 (0:Disable, 1:Enable) | RtdEnable_05 (0:Disable, 1:Enable) |
| RtdStype_04 (0:PT50, 1:Pt100, 2:Pt200, 3:Pt500, 4:Pt1000, 5:JPt100, 6:JPt200, 7:JPt500, 8:JPt1000, 9 :Ni 100, 10 :Ni 200, 11 :Ni 500, 12 :Ni 1000, 13 :Ni 120, 14 :Resistance (1-310 mΩ), 15:Resistance (1-620 mΩ), 16 :Resistance (1-1250 mΩ), 17:Resistance (1-2200 mΩ)) | RtdStype_05 (0:PT50, 1:Pt100, 2:Pt200, 3:Pt500, 4:Pt1000, 5:JPt100, 6:JPt200, 7:JPt500, 8:JPt1000, 9 :Ni 100, 10 :Ni 200, 11 :Ni 500, 12 :Ni 1000, 13 :Ni 120, 14 :Resistance (1-310 mΩ), 15:Resistance (1-620 mΩ), 16 :Resistance (1-1250 mΩ), 17:Resistance (1-2200 mΩ)) |
| RtdUtype_04 (Unit Types. 0:°C, 1:°F, 2:Ω) | RtdUtype_05 (Unit Types. 0:°C, 1:°F, 2:Ω) |
| RtdStatus_04 | RtdStatus_05 |

| Commands to get RTD Virtual Channel information | Commands to get RTD Virtual Channel information |
|--|--|
| RtdEnable_06 (0:Disable, 1:Enable) | RtdEnable_07 (0:Disable, 1:Enable) |
| RtdStype_06 (20:Average – For Virtual Channel only, 21: Deviation – For Virtual Channel Only) | RtdStype_07 (20:Average – For Virtual Channel only, 21: Deviation – For Virtual Channel Only) |
| RtdUtype_06 (Unit Types. 0:°C, 1:°F, 2:Ω) | RtdUtype_07 (Unit Types. 0:°C, 1:°F, 2:Ω) |
| RtdStatus_06 | RtdStatus_07 |
| RtdEnable_08 (0:Disable, 1:Enable) | RtdEnable_09 (0:Disable, 1:Enable) |
| RtdStype_08 (20:Average – For Virtual Channel only, 21: Deviation – For Virtual Channel Only) | RtdStype_09 (20:Average – For Virtual Channel only, 21: Deviation – For Virtual Channel Only) |
| RtdUtype_08 (Unit Types. 0:°C, 1:°F, 2:Ω) | RtdUtype_09 (Unit Types. 0:°C, 1:°F, 2:Ω) |
| RtdStatus_08 | RtdStatus_09 |
| RtdEnable_10 (0:Disable, 1:Enable) | RtdEnable_11 (0:Disable, 1:Enable) |
| RtdStype_10 (20:Average – For Virtual Channel only, 21: Deviation – For Virtual Channel Only) | RtdStype_11 (20:Average – For Virtual Channel only, 21: Deviation – For Virtual Channel Only) |
| RtdUtype_10 (Unit Types. 0:°C, 1:°F, 2:Ω) | RtdUtype_11 (Unit Types. 0:°C, 1:°F, 2:Ω) |
| RtdStatus_10 | RtdStatus_11 |

| Commands to get DO information | Commands to get DO information |
|--------------------------------------|--------------------------------------|
| DOMode_00 (0:DO, 1:PULSE OUTPUT) | DOMode_01 (0:DO, 1:PULSE OUTPUT) |
| DOStatus_00 (0:OFF, 1:ON) | DOStatus_01 (0:OFF, 1:ON) |
| DOLowWidth_00 | DOLowWidth_01 |
| DOHighWidth_00 | DOHighWidth_01 |
| DOPulseStart_00 (0:STOP, 1:START) | DOPulseStart_01 (0:STOP, 1:START) |
| DOMode_02 (0:DO, 1:PULSE OUTPUT) | DOMode_03 (0:DO, 1:PULSE OUTPUT) |
| DOStatus_02 (0:OFF, 1:ON) | DOStatus_03 (0:OFF, 1:ON) |
| DOLowWidth_02 | DOLowWidth_03 |
| DOHighWidth_02 | DOHighWidth_03 |
| DOPulseStart_02 (0:STOP, 1:START) | DOPulseStart_03 (0:STOP, 1:START) |

Syntax to get the settings is as follows. Starting with the ioLogik's IP or URL, specify **setParam.cgi** with a question mark. Then specify the command with another question mark as the ending. Those commands are case sensitive and the **&** sign is used to combine multiple commands.

| Commands to set RTD channels | Commands to set RTD channels |
|---|---|
| RtdEnable_00 (0:Disable, 1:Enable) | RtdEnable_01 (0:Disable, 1:Enable) |
| RtdStype_00 (0:PT50, 1:Pt100, 2:Pt200, 3:Pt500, 4:Pt1000, 5:JPt100, 6:JPt200, 7:JPt500, 8:JPt1000, 9 :Ni 100, 10 :Ni 200, 11 :Ni 500, 12 :Ni 1000, 13 :Ni 120, 14 :Resistance (1-310 mΩ), 15:Resistance (1-620 mΩ), 16 :Resistance (1-1250 mΩ), 17:Resistance (1-2200 mΩ)) | RtdStype_01 (0:PT50, 1:Pt100, 2:Pt200, 3:Pt500, 4:Pt1000, 5:JPt100, 6:JPt200, 7:JPt500, 8:JPt1000, 9 :Ni 100, 10 :Ni 200, 11 :Ni 500, 12 :Ni 1000, 13 :Ni 120, 14 :Resistance (1-310 mΩ), 15:Resistance (1-620 mΩ), 16 :Resistance (1-1250 mΩ), 17:Resistance (1-2200 mΩ)) |
| RtdUtype_00 (Unit Types. 0:°C, 1:°F, 2:Ω) | RtdUtype_01 (Unit Types. 0:°C, 1:°F, 2:Ω) |
| RtdEnable_02 (0:Disable, 1:Enable) | RtdEnable_03 (0:Disable, 1:Enable) |
| RtdStype_02 (0:PT50, 1:Pt100, 2:Pt200, 3:Pt500, 4:Pt1000, 5:JPt100, 6:JPt200, 7:JPt500, 8:JPt1000, 9 :Ni 100, 10 :Ni 200, 11 :Ni 500, 12 :Ni 1000, 13 :Ni 120, 14 :Resistance (1-310 mΩ), 15:Resistance (1-620 mΩ), 16 :Resistance (1-1250 mΩ), 17:Resistance (1-2200 mΩ)) | RtdStype_03 (0:PT50, 1:Pt100, 2:Pt200, 3:Pt500, 4:Pt1000, 5:JPt100, 6:JPt200, 7:JPt500, 8:JPt1000, 9 :Ni 100, 10 :Ni 200, 11 :Ni 500, 12 :Ni 1000, 13 :Ni 120, 14 :Resistance (1-310 mΩ), 15:Resistance (1-620 mΩ), 16 :Resistance (1-1250 mΩ), 17:Resistance (1-2200 mΩ)) |
| RtdUtype_02 (Unit Types. 0:°C, 1:°F, 2:Ω) | RtdUtype_03 (Unit Types. 0:°C, 1:°F, 2:Ω) |
| RtdEnable_04 (0:Disable, 1:Enable) | RtdEnable_05 (0:Disable, 1:Enable) |
| RtdStype_04 (0:PT50, 1:Pt100, 2:Pt200, 3:Pt500, 4:Pt1000, 5:JPt100, 6:JPt200, 7:JPt500, 8:JPt1000, 9 :Ni 100, 10 :Ni 200, 11 :Ni 500, 12 :Ni 1000, 13 :Ni 120, 14 :Resistance (1-310 mΩ), 15:Resistance (1-620 mΩ), 16 :Resistance (1-1250 mΩ), 17:Resistance (1-2200 mΩ)) | RtdStype_05 (0:PT50, 1:Pt100, 2:Pt200, 3:Pt500, 4:Pt1000, 5:JPt100, 6:JPt200, 7:JPt500, 8:JPt1000, 9 :Ni 100, 10 :Ni 200, 11 :Ni 500, 12 :Ni 1000, 13 :Ni 120, 14 :Resistance (1-310 mΩ), 15:Resistance (1-620 mΩ), 16 :Resistance (1-1250 mΩ), 17:Resistance (1-2200 mΩ)) |
| RtdUtype_04 (Unit Types. 0:°C, 1:°F, 2:Ω) | RtdUtype_05 (Unit Types. 0:°C, 1:°F, 2:Ω) |

| Commands to set RTD Virtual Channel information | Commands to set RTD Virtual Channel information |
|---|---|
| RtdStype_06 (20:Average, 21: Deviation) | RtdStype_07 (20:Average, 21: Deviation) |
| RtdUtype_06 (Unit Types. 0:°C, 1:°F, 2:Ω) | RtdUtype_07 (Unit Types. 0:°C, 1:°F, 2:Ω) |
| RtdStype_08 (20:Average, 21: Deviation) | RtdStype_09 (20:Average, 21: Deviation) |
| RtdUtype_08 (Unit Types. 0:°C, 1:°F, 2:Ω) | RtdUtype_09 (Unit Types. 0:°C, 1:°F, 2:Ω) |
| RtdStype_10 (20:Average, 21: Deviation) | RtdStype_11 (20:Average, 21: Deviation) |
| RtdUtype_10 (Unit Types. 0:°C, 1:°F, 2:Ω) | RtdUtype_11 (Unit Types. 0:°C, 1:°F, 2:Ω) |

| Commands to set DO channels | Commands to set DO Channels |
|--------------------------------------|--------------------------------------|
| DOMode_00 (0:DO, 1:PULSE OUTPUT) | DOMode_01 (0:DO, 1:PULSE OUTPUT) |
| DOSTatus_00 (0:OFF, 1:ON) | DOSTatus_01 (0:OFF, 1:ON) |
| DOLowWidth_00 | DOLowWidth_01 |
| DOHighWidth_00 | DOHighWidth_01 |
| DOPulseStart_00 (0:STOP, 1:START) | DOPulseStart_01 (0:STOP, 1:START) |
| DOMode_02 (0:DO, 1:PULSE OUTPUT) | DOMode_03 (0:DO, 1:PULSE OUTPUT) |
| DOSTatus_02 (0:OFF, 1:ON) | DOSTatus_03 (0:OFF, 1:ON) |
| DOLowWidth_02 | DOLowWidth_03 |
| DOHighWidth_02 | DOHighWidth_03 |
| DOPulseStart_02 (0:STOP, 1:START) | DOPulseStart_03 (0:STOP, 1:START) |

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| Commands to get system information | Commands to get system information |
|------------------------------------|------------------------------------|
| DATE | FWR_V |
| TIME | MOD_NAME |
| IP | SN_NUM |
| LOC | MAC_ADDR |
| DESC | |

| Commands to get TC information | Commands to get TC information |
|---|---|
| TcEnable_00 (0:Disable, 1:Enable) | TcEnable_01 (0:Disable, 1:Enable) |
| TcStype_00 (0:J, 1:K, 2:T, 3:E, 4:R, 5:S, 6:B, 7:N Type and 8:78.126mV, 9:39.062mV, 10:19.532mV) | TcStype_01 (0:J, 1:K, 2:T, 3:E, 4:R, 5:S, 6:B, 7:N Type and 8:78.126mV, 9:39.062mV, 10:19.532mV) |
| TcUtype_00 (Unit Types. 0:°C, 1:°F, 2:mV) | TcUtype_01 (Unit Types. 0:°C, 1:°F, 2:mV) |
| TcStatus_00 | TcStatus_01 |
| TcEnable_02 (0:Disable, 1:Enable) | TcEnable_03 (0:Disable, 1:Enable) |
| TcStype_02 (0:J, 1:K, 2:T, 3:E, 4:R, 5:S, 6:B, 7:N Type and 8:78.126mV, 9:39.062mV, 10:19.532mV) | TcStype_03 (0:J, 1:K, 2:T, 3:E, 4:R, 5:S, 6:B, 7:N Type and 8:78.126mV, 9:39.062mV, 10:19.532mV) |
| TcUtype_02 (Unit Types. 0:°C, 1:°F, 2:mV) | TcUtype_03 (Unit Types. 0:°C, 1:°F, 2:mV) |
| TcStatus_02 | TcStatus_03 |
| TcEnable_04 (0:Disable, 1:Enable) | TcEnable_05 (0:Disable, 1:Enable) |
| TcStype_04 (0:J, 1:K, 2:T, 3:E, 4:R, 5:S, 6:B, 7:N Type and 8:78.126mV, 9:39.062mV, 10:19.532mV) | TcStype_05 (0:J, 1:K, 2:T, 3:E, 4:R, 5:S, 6:B, 7:N Type and 8:78.126mV, 9:39.062mV, 10:19.532mV) |
| TcUtype_04 (Unit Types. 0:°C, 1:°F, 2:mV) | TcUtype_05 (Unit Types. 0:°C, 1:°F, 2:mV) |
| TcStatus_04 | TcStatus_05 |

| Commands to get TC information | Commands to get TC information |
|--|--|
| TcEnable_06 (0:Disable, 1:Enable) | TcEnable_07 (0:Disable, 1:Enable) |
| TcStype_06 (0:J, 1:K, 2:T, 3:E, 4:R, 5:S, 6:B, 7:N Type and 8:78.126mV, 9:39.062mV, 10:19.532mV) | TcStype_07 (0:J, 1:K, 2:T, 3:E, 4:R, 5:S, 6:B, 7:N Type and 8:78.126mV, 9:39.062mV, 10:19.532mV) |
| TcUtype_06 (Unit Types. 0:°C, 1:°F, 2:mV) | TcUtype_07 (Unit Types. 0:°C, 1:°F, 2:mV) |
| TcStatus_06 | TcStatus_07 |

| Commands to get TC Virtual channels | Commands to get TC Virtual channels |
|--|--|
| TcEnable_08 (0:Disable, 1:Enable) | TcEnable_09 (0:Disable, 1:Enable) |
| TcStype_08 (20: Average, 21: Difference) | TcStype_09 (20: Average, 21: Difference) |
| TcUtype_08 (Unit Types. 0:°C, 1:°F, 2:mV) | TcUtype_09 (Unit Types. 0:°C, 1:°F, 2:mV) |
| TcStatus_08 | TcStatus_09 |
| TcEnable_10 (0:Disable, 1:Enable) | TcEnable_11 (0:Disable, 1:Enable) |
| TcStype_10 (20: Average, 21: Difference) | TcStype_11 (20: Average, 21: Difference) |
| TcUtype_10 (Unit Types. 0:°C, 1:°F, 2:mV) | TcUtype_11 (Unit Types. 0:°C, 1:°F, 2:mV) |
| TcStatus_10 | TcStatus_11 |
| TcEnable_12 (0:Disable, 1:Enable) | TcEnable_13 (0:Disable, 1:Enable) |
| TcStype_12 (20: Average, 21: Difference) | TcStype_13 (20: Average, 21: Difference) |
| TcUtype_12 (Unit Types. 0:°C, 1:°F, 2:mV) | TcUtype_13 (Unit Types. 0:°C, 1:°F, 2:mV) |
| TcStatus_12 | TcStatus_13 |
| TcEnable_14 (0:Disable, 1:Enable) | TcEnable_15 (0:Disable, 1:Enable) |
| TcStype_14 (20: Average, 21: Difference) | TcStype_15 (20: Average, 21: Difference) |
| TcUtype_14 (Unit Types. 0:°C, 1:°F, 2:mV) | TcUtype_15 (Unit Types. 0:°C, 1:°F, 2:mV) |
| TcStatus_14 | TcStatus_15 |

| Commands to get DO information | Commands to get DO information |
|--------------------------------------|--------------------------------------|
| DOMode_00 (0:DO, 1:PULSE OUTPUT) | DOMode_01 (0:DO, 1:PULSE OUTPUT) |
| DOSTatus_00 (0:OFF, 1:ON) | DOSTatus_01 (0:OFF, 1:ON) |
| DOLowWidth_00 | DOLowWidth_01 |
| DOHighWidth_00 | DOHighWidth_01 |
| DOPulseStart_00 (0:STOP, 1:START) | DOPulseStart_01 (0:STOP, 1:START) |
| DOMode_02 (0:DO, 1:PULSE OUTPUT) | DOMode_03 (0:DO, 1:PULSE OUTPUT) |
| DOSTatus_02 (0:OFF, 1:ON) | DOSTatus_03 (0:OFF, 1:ON) |

| Commands to get DO information | Commands to get DO information |
|--------------------------------------|--------------------------------------|
| DOLowWidth_02 | DOLowWidth_03 |
| DOHighWidth_02 | DOHighWidth_03 |
| DOPulseStart_02 (0:STOP, 1:START) | DOPulseStart_03 (0:STOP, 1:START) |

Syntax to get the settings is as follows. Starting with the ioLogik's IP or URL, specify **setParam.cgi** with a question mark. Then specify the command with another question mark as the ending. Those commands are case sensitive and the **&** sign is used to combine multiple commands.

| Commands to set TC channels | Commands to set TC channels |
|--|--|
| TcEnable_00 (0:Disable, 1:Enable) | TcEnable_01 (0:Disable, 1:Enable) |
| TcStype_00 (0:J, 1:K, 2:T, 3:E, 4:R, 5:S, 6:B, 7:N Type and 8:78.126mV, 9:39.062mV, 10:19.532mV) | TcStype_01 (0:J, 1:K, 2:T, 3:E, 4:R, 5:S, 6:B, 7:N Type and 8:78.126mV, 9:39.062mV, 10:19.532mV) |
| TcUtype_00 (Unit Types. 0:°C, 1:°F, 2:mV) | TcUtype_01 (Unit Types. 0:°C, 1:°F, 2:mV) |
| TcEnable_02 (0:Disable, 1:Enable) | TcEnable_03 (0:Disable, 1:Enable) |
| TcStype_02 (0:J, 1:K, 2:T, 3:E, 4:R, 5:S, 6:B, 7:N Type and 8:78.126mV, 9:39.062mV, 10:19.532mV) | TcStype_03 (0:J, 1:K, 2:T, 3:E, 4:R, 5:S, 6:B, 7:N Type and 8:78.126mV, 9:39.062mV, 10:19.532mV) |
| TcUtype_02 (Unit Types. 0:°C, 1:°F, 2:mV) | TcUtype_03 (Unit Types. 0:°C, 1:°F, 2:mV) |
| TcEnable_04 (0:Disable, 1:Enable) | TcEnable_05 (0:Disable, 1:Enable) |
| TcStype_04 (0:J, 1:K, 2:T, 3:E, 4:R, 5:S, 6:B, 7:N Type and 8:78.126mV, 9:39.062mV, 10:19.532mV) | TcStype_05 (0:J, 1:K, 2:T, 3:E, 4:R, 5:S, 6:B, 7:N Type and 8:78.126mV, 9:39.062mV, 10:19.532mV) |
| TcUtype_04 (Unit Types. 0:°C, 1:°F, 2:mV) | TcUtype_05 (Unit Types. 0:°C, 1:°F, 2:mV) |
| TcEnable_06 (0:Disable, 1:Enable) | TcEnable_07 (0:Disable, 1:Enable) |
| TcStype_06 (0:J, 1:K, 2:T, 3:E, 4:R, 5:S, 6:B, 7:N Type and 8:78.126mV, 9:39.062mV, 10:19.532mV) | TcStype_07 (0:J, 1:K, 2:T, 3:E, 4:R, 5:S, 6:B, 7:N Type and 8:78.126mV, 9:39.062mV, 10:19.532mV) |
| TcUtype_06 (Unit Types. 0:°C, 1:°F, 2:mV) | TcUtype_07 (Unit Types. 0:°C, 1:°F, 2:mV) |

| Commands to set TC Virtual channels | Commands to set TC Virtual channels |
|--|--|
| TcStype_08 (20: Average, 21: Difference) | TcStype_09 (20: Average, 21: Difference) |
| TcUtype_08 (Unit Types. 0:°C, 1:°F, 2:mV) | TcUtype_09 (Unit Types. 0:°C, 1:°F, 2:mV) |
| TcStype_10 (20: Average, 21: Difference) | TcStype_11 (20: Average, 21: Difference) |
| TcUtype_10 (Unit Types. 0:°C, 1:°F, 2:mV) | TcUtype_11 (Unit Types. 0:°C, 1:°F, 2:mV) |
| TcStype_12 (20: Average, 21: Difference) | TcStype_13 (20: Average, 21: Difference) |
| TcUtype_12 (Unit Types. 0:°C, 1:°F, 2:mV) | TcUtype_13 (Unit Types. 0:°C, 1:°F, 2:mV) |
| TcStype_14 (20: Average, 21: Difference) | TcStype_15 (20: Average, 21: Difference) |

| Commands to set TC Virtual channels | Commands to set TC Virtual channels |
|--|--|
| TcUtype_14 (Unit Types. 0:°C, 1:°F, 2:mV) | TcUtype_15 (Unit Types. 0:°C, 1:°F, 2:mV) |

| Commands to set DO channels | Commands to set DO Channels |
|--------------------------------------|--------------------------------------|
| DOMode_00 (0:DO, 1:PULSE OUTPUT) | DOMode_01 (0:DO, 1:PULSE OUTPUT) |
| DOSTatus_00 (0:OFF, 1:ON) | DOSTatus_01 (0:OFF, 1:ON) |
| DOLowWidth_00 | DOLowWidth_01 |
| DOHighWidth_00 | DOHighWidth_01 |
| DOPulseStart_00 (0:STOP, 1:START) | DOPulseStart_01 (0:STOP, 1:START) |
| DOMode_02 (0:DO, 1:PULSE OUTPUT) | DOMode_03 (0:DO, 1:PULSE OUTPUT) |
| DOSTatus_02 (0:OFF, 1:ON) | DOSTatus_03 (0:OFF, 1:ON) |
| DOLowWidth_02 | DOLowWidth_03 |
| DOHighWidth_02 | DOHighWidth_03 |
| DOPulseStart_02 (0:STOP, 1:START) | DOPulseStart_03 (0:STOP, 1:START) |

SNMP Agents with MIB II, RS-232-like Groups

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RFC1213 MIB II Supported SNMP Variables

The following SNMP variables are built into the ioLogik firmware and are compliant with RFC1213 MIB II.

| System MIB | Interfaces MIB | IP MIB | ICMP MIB |
|-------------|-------------------|---------------------|----------------------|
| SysDescr | ifNumber | ipForwarding | IcmpInMsgs |
| SysObjectID | ifIndex | ipDefaultTTL | IcmpInErrors |
| SysUpTime | ifDescr | ipInreceives | IcmpInDestUnreachs |
| SysContact | ifType | ipInHdrErrors | IcmpInTimeExcds |
| SysName | ifMtu | ipInAddrErrors | IcmpInParmProbs |
| SysLocation | ifSpeed | ipForwDatagrams | IcmpInSrcQuenchs |
| SysServices | ifPhysAddress | ipInUnknownProtos | IcmpInRedirects |
| SysServices | ifAdminStatus | ipInDiscards | IcmpInEchos |
| | ifOperStatus | ipInDelivers | IcmpInEchoReps |
| | ifLastChange | ipOutRequests | IcmpInTimestamps |
| | ifInOctets | ipOutDiscards | IcmpTimestampReps |
| | ifInUcastPkts | ipOutNoRoutes | IcmpInAddrMasks |
| | ifInNUcastPkts | ipReasmTimeout | IcmpOutMsgs |
| | ifInDiscards | ipReasmReqds | IcmpOutErrors |
| | ifInErrors | ipReasmOKs | IcmpOutDestUnreachs |
| | ifInUnknownProtos | ipReasmFails | IcmpOutTimeExcds |
| | ifOutOctets | ipFragOKs | IcmpOutParmProbs |
| | ifOutUcastPkts | ipFragFails | IcmpOutSrcQuenchs |
| | ifOutNUcastPkts | ipFragCreates | IcmpOutRedirects |
| | ifOutDiscards | ipAdEntAddr | IcmpOutEchos |
| | ifOutErrors | ipAdEntIfIndex | IcmpOutEchoReps |
| | ifOutQLen | ipAdEntNetMask | IcmpOutTimestamps |
| | ifSpecific | ipAdEntBcastAddr | IcmpOutTimestampReps |
| | | ipAdEntReasmMaxSize | IcmpOutAddrMasks |
| | | ipRouteDest | IcmpOutAddrMaskReps |
| | | ipRouteIfIndex | |
| | | ipRouteMetric1 | |
| | | ipRouteMetric2 | |
| | | ipRouteMetric3 | |
| | | ipRouteMetric4 | |
| | | ipRouteNextHop | |
| | | ipRouteType | |
| | | ipRouteProto | |
| | | ipRouteAge | |
| | | ipRouteMask | |

| System MIB | Interfaces MIB | IP MIB | ICMP MIB |
|------------|----------------|-------------------------|----------|
| | | ipRouteMetric5 | |
| | | ipRouteInfo | |
| | | IpNetToMediaIfIndex | |
| | | IpNetToMediaPhysAddress | |
| | | IpNetToMediaNetAddress | |
| | | IpNetToMediaType | |
| | | IpRoutingDiscards | |

| UDP MIB | TCP MIB | SNMP MIB |
|--------------------------------|---------------------|-------------------------|
| UdpInDatagrams | tcpRtoAlgorithm | snmpInPkts |
| UdpNoPorts | tcpRtoMin | snmpOutPkts |
| UdpInErrors | tcpRtoMax | snmpInBadVersions |
| UdpOutDatagrams | tcpMaxConn | snmpInBadCommunityNames |
| UdpLocalAddress | tcpActiveOpens | snmpInBadCommunityUses |
| UdpLocalPort | tcpPassiveOpens | snmpInASNParseErrs |
| | tcpAttempFails | snmpInTooBig |
| | tcpEstabResets | snmpInNoSuchNames |
| Address Translation MIB | tcpCurrEstab | snmpInBadValues |
| AtIfIndex | tcpInSegs | snmpInReadOnly |
| AtPhysAddress | tcpOutSegs | snmpInGenErrs |
| AtNetAddress | tcpRetransSegs | snmpInTotalReqVars |
| AtNetAddress | tcpConnState | snmpInTotalSetVars |
| | tcpConnLocalAddress | snmpInGetRequests |
| | tcpConnLocalPort | snmpInGetNexts |
| | tcpConnRemAddress | snmpInSetRequests |
| | tcpConnRemPort | snmpInGetResponses |
| | tcpInErrs | snmpInTraps |
| | tcpOutRsts | snmpOutTooBig |
| | | snmpOutNoSuchNames |
| | | snmpOutBadValues |
| | | snmpOutGenErrs |
| | | snmpOutGetRequests |
| | | snmpOutGetNexts |
| | | snmpOutSetRequests |
| | | snmpOutGetResponses |
| | | snmpOutTraps |
| | | snmpEnableAuthenTraps |

Private MIB File and SNMP Variables

Moxa also provides an SNMP to I/O MIB file that can help you monitor I/O status with SNMP software. You can find the MIB file from Moxa's website.

| Moxa IO MIB | Moxa IO MIB |
|--------------------|-----------------|
| totalChannelNumber | DI004-Tigger |
| serverModel | DI004-CntStart |
| systemTime | DI004-LowWidth |
| firmwareVersion | DI004-HighWidth |
| DI000-Index | DI005-LowWidth |
| DI000-Type | DI005-HighWidth |
| DI000-Mode | DI006-Index |
| DI000-Status | DI006-Type |
| DI000-Filter | DI006-Mode |
| DI000-Tigger | DI006-Status |
| DI000-CntStart | DI006-Filter |
| DI000-LowWidth | DI006-Tigger |
| DI000-HighWidth | DI006-CntStart |
| DI001-Index | DI006-LowWidth |
| DI001-Type | DI006-HighWidth |
| DI001-Mode | DI007-Index |
| DI001-Status | DI007-Type |
| DI001-Filter | DI007-Mode |
| DI001-Tigger | DI007-Status |
| DI001-CntStart | DI007-Filter |
| DI001-LowWidth | DI007-Tigger |
| DI001-HighWidth | DI007-CntStart |
| DI002-Index | DI007-LowWidth |
| DI002-Type | DI007-HighWidth |
| DI002-Mode | DI008-Index |
| DI002-Status | DI008-Type |
| DI002-Filter | DI008-Mode |
| DI002-Tigger | DI008-Status |
| DI002-CntStart | DI008-Filter |
| DI002-LowWidth | DI008-Tigger |
| DI002-HighWidth | DI008-CntStart |
| DI003-Index | DI008-LowWidth |
| DI003-Type | DI008-HighWidth |
| DI003-Mode | DI009-Index |
| DI003-Status | DI009-Type |
| DI003-Filter | DI009-Mode |
| DI003-Tigger | DI009-Status |
| DI003-CntStart | DI009-Filter |
| DI003-LowWidth | DI009-Tigger |
| DI003-HighWidth | DI009-CntStart |
| DI004-Index | DI009-LowWidth |
| DI004-Type | DI009-HighWidth |
| DI004-Mode | DI010-Index |
| DI004-Status | DI010-Type |
| DI004-Filter | DI010-Mode |
| DI010-Status | |
| DI010-Filter | |
| DI010-Tigger | |

| Moxa IO MIB | Moxa IO MIB |
|--------------------|--------------------|
| DI010-CntStart | |
| DI010-LowWidth | |
| DI010-HighWidth | |
| DI011-Index | |
| DI011-Type | |
| DI011-Mode | |
| DI011-Status | |
| DI011-Filter | |
| DI011-Tigger | |
| DI011-CntStart | |
| DI011-LowWidth | |
| DI011-HighWidth | |

| Moxa IO MIB | Moxa IO MIB |
|--------------------|--------------------|
| AI00-Index | AI02-Index |
| AI00-Type | AI02-Type |
| AI00-Range | AI02-Range |
| AI00-Value | AI02-Value |
| AI00-Min | AI02-Min |
| AI00-Max | AI02-Max |
| AI01-Index | AI03-Index |
| AI01-Type | AI03-Type |
| AI01-Range | AI03-Range |
| AI01-Value | AI03-Value |
| AI01-Min | AI03-Min |
| AI01-Max | AI03-Max |

Modbus/TCP Address Mappings

The following topics are covered in this chapter:

- ❑ **ioLogik E2210 Modbus Mapping**
- ❑ **ioLogik E2212 Modbus Mapping**
- ❑ **ioLogik E2214 Modbus Mapping**
- ❑ **ioLogik E2240 Modbus Mapping**
- ❑ **ioLogik E2242 Modbus Mapping**
- ❑ **ioLogik E2260 Modbus Mapping**
- ❑ **ioLogik E2262 Modbus Mapping**

ioLogik E2210 Modbus Mapping

0xxxx Read/Write Coils (Functions 1, 5, 15)

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 00001 | 0x0000 | 1 bit | CH0 DO Value 0: Off 1: On |
| 00002 | 0x0001 | 1 bit | CH1 DO Value 0: Off 1: On |
| 00003 | 0x0002 | 1 bit | CH2 DO Value 0: Off 1: On |
| 00004 | 0x0003 | 1 bit | CH3 DO Value 0: Off 1: On |
| 00005 | 0x0004 | 1 bit | CH4 DO Value 0: Off 1: On |
| 00006 | 0x0005 | 1 bit | CH5 DO Value 0: Off 1: On |
| 00007 | 0x0006 | 1 bit | CH6 DO Value 0: Off 1: On |
| 00008 | 0x0007 | 1 bit | CH7 DO Value 0: Off 1: On |
| 00009 | 0x0008 | 1 bit | CH0 DO Power On Value 0: Off 1: On |
| 00010 | 0x0009 | 1 bit | CH1 DO Power On Value 0: Off 1: On |
| 00011 | 0x000A | 1 bit | CH2 DO Power On Value 0: Off 1: On |
| 00012 | 0x000B | 1 bit | CH3 DO Power On Value 0: Off 1: On |
| 00013 | 0x000C | 1 bit | CH4 DO Power On Value 0: Off 1: On |
| 00014 | 0x000D | 1 bit | CH5 DO Power On Value 0: Off 1: On |
| 00015 | 0x000E | 1 bit | CH6 DO Power On Value 0: Off 1: On |
| 00016 | 0x000F | 1 bit | CH7 DO Power On Value 0: Off 1: On |
| 00017 | 0x0010 | 1 bit | CH0 DO Safe Value 0: Off 1: On |
| 00018 | 0x0011 | 1 bit | CH1 DO Safe Value 0: Off 1: On |
| 00019 | 0x0012 | 1 bit | CH2 DO Safe Value 0: Off 1: On |
| 00020 | 0x0013 | 1 bit | CH3 DO Safe Value 0: Off 1: On |
| 00021 | 0x0014 | 1 bit | CH4 DO Safe Value 0: Off 1: On |
| 00022 | 0x0015 | 1 bit | CH5 DO Safe Value 0: Off 1: On |
| 00023 | 0x0016 | 1 bit | CH6 DO Safe Value 0: Off 1: On |
| 00024 | 0x0017 | 1 bit | CH7 DO Safe Value 0: Off 1: On |
| 00025 | 0x0018 | 1 bit | CH0 DO Pulse Operate Status 0: Off 1: On |
| 00026 | 0x0019 | 1 bit | CH1 DO Pulse Operate Status 0: Off 1: On |
| 00027 | 0x001A | 1 bit | CH2 DO Pulse Operate Status 0: Off 1: On |
| 00028 | 0x001B | 1 bit | CH3 DO Pulse Operate Status 0: Off 1: On |
| 00029 | 0x001C | 1 bit | CH4 DO Pulse Operate Status 0: Off 1: On |
| 00030 | 0x001D | 1 bit | CH5 DO Pulse Operate Status 0: Off 1: On |
| 00031 | 0x001E | 1 bit | CH6 DO Pulse Operate Status 0: Off 1: On |
| 00032 | 0x001F | 1 bit | CH7 DO Pulse Operate Status 0: Off 1: On |
| 00033 | 0x0020 | 1 bit | CH0 DO Pulse Power On Status 0: Off 1: On |
| 00034 | 0x0021 | 1 bit | CH1 DO Pulse Power On Status 0: Off 1: On |
| 00035 | 0x0022 | 1 bit | CH2 DO Pulse Power On Status 0: Off 1: On |
| 00036 | 0x0023 | 1 bit | CH3 DO Pulse Power On Status 0: Off 1: On |
| 00037 | 0x0024 | 1 bit | CH4 DO Pulse Power On Status 0: Off 1: On |
| 00038 | 0x0025 | 1 bit | CH5 DO Pulse Power On Status 0: Off 1: On |
| 00039 | 0x0026 | 1 bit | CH6 DO Pulse Power On Status 0: Off 1: On |
| 00040 | 0x0027 | 1 bit | CH7 DO Pulse Power On Status 0: Off 1: On |
| 00041 | 0x0028 | 1 bit | CH0 DO Pulse Safe Mode Status 0: Off 1: On |
| 00042 | 0x0029 | 1 bit | CH1 DO Pulse Safe Mode Status 0: Off 1: On |
| 00043 | 0x002A | 1 bit | CH2 DO Pulse Safe Mode Status 0: Off 1: On |
| 00044 | 0x002B | 1 bit | CH3 DO Pulse Safe Mode Status 0: Off 1: On |
| 00045 | 0x002C | 1 bit | CH4 DO Pulse Safe Mode Status 0: Off 1: On |
| 00046 | 0x002D | 1 bit | CH5 DO Pulse Safe Mode Status 0: Off 1: On |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 00047 | 0x002E | 1 bit | CH6 DO Pulse Safe Mode Status 0: Off 1: On |
| 00048 | 0x002F | 1 bit | CH7 DO Pulse Safe Mode Status 0: Off 1: On |
| 00049 | 0x0030 | 1 bit | CH0 DI Counter Status 0: Stop 1: Start |
| 00050 | 0x0031 | 1 bit | CH1 DI Counter Status 0: Stop 1: Start |
| 00051 | 0x0032 | 1 bit | CH2 DI Counter Status 0: Stop 1: Start |
| 00052 | 0x0033 | 1 bit | CH3 DI Counter Status 0: Stop 1: Start |
| 00053 | 0x0034 | 1 bit | CH4 DI Counter Status 0: Stop 1: Start |
| 00054 | 0x0035 | 1 bit | CH5 DI Counter Status 0: Stop 1: Start |
| 00055 | 0x0036 | 1 bit | CH6 DI Counter Status 0: Stop 1: Start |
| 00056 | 0x0037 | 1 bit | CH7 DI Counter Status 0: Stop 1: Start |
| 00057 | 0x0038 | 1 bit | CH8 DI Counter Status 0: Stop 1: Start |
| 00058 | 0x0039 | 1 bit | CH9 DI Counter Status 0: Stop 1: Start |
| 00059 | 0x003A | 1 bit | CH10 DI Counter Status 0: Stop 1: Start |
| 00060 | 0x003B | 1 bit | CH11 DI Counter Status 0: Stop 1: Start |
| 00061 | 0x003C | 1 bit | CH0 DI Clear Counter Value Read: Always 0 Write: 1 : Clear Counter Value 0 : Return Illegal Data Value |
| 00062 | 0x003D | 1 bit | CH1 DI Clear Counter Value Read: Always 0 Write: 1 : Clear Counter Value 0 : Return Illegal Data Value |
| 00063 | 0x003E | 1 bit | CH2 DI Clear Counter Value Read: Always 0 Write: 1 : Clear Counter Value 0 : Return Illegal Data Value |
| 00064 | 0x003F | 1 bit | CH3 DI Clear Counter Value Read: Always 0 Write: 1 : Clear Counter Value 0 : Return Illegal Data Value |
| 00065 | 0x0040 | 1 bit | CH4 DI Clear Counter Value Read: Always 0 Write: 1 : Clear Counter Value 0 : Return Illegal Data Value |
| 00066 | 0x0041 | 1 bit | CH5 DI Clear Counter Value Read: Always 0 Write: 1 : Clear Counter Value 0 : Return Illegal Data Value |
| 00067 | 0x0042 | 1 bit | CH6 DI Clear Counter Value Read: Always 0 Write: 1 : Clear Counter Value 0 : Return Illegal Data Value |
| 00068 | 0x0043 | 1 bit | CH7 DI Clear Counter Value Read: Always 0 Write: 1 : Clear Counter Value 0 : Return Illegal Data Value |
| 00069 | 0x0044 | 1 bit | CH8 DI Clear Counter Value Read: Always 0 Write: 1 : Clear Counter Value 0 : Return Illegal Data Value |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 00070 | 0x0045 | 1 bit | CH9 DI Clear Counter Value Read: Always 0 Write: 1 : Clear Counter Value 0 : Return Illegal Data Value |
| 00071 | 0x0046 | 1 bit | CH10 DI Clear Counter Value Read: Always 0 Write: 1 : Clear Counter Value 0 : Return Illegal Data Value |
| 00072 | 0x0047 | 1 bit | CH11 DI Clear Counter Value Read: Always 0 Write: 1 : Clear Counter Value 0 : Return Illegal Data Value |
| 00073 | 0x0048 | 1 bit | CH0 DI Overflow Status Read: 0 : Normal 1 : Overflow Write: 0 : Clear Overflow Status 1 : Return Illegal Data Value |
| 00074 | 0x0049 | 1 bit | CH1 DI Overflow Status Read: 0 : Normal 1 : Overflow Write: 0 : Clear Overflow Status 1 : Return Illegal Data Value |
| 00075 | 0x004A | 1 bit | CH2 DI Overflow Status Read: 0 : Normal 1 : Overflow Write: 0 : Clear Overflow Status 1 : Return Illegal Data Value |
| 00076 | 0x004B | 1 bit | CH3 DI Overflow Status Read: 0 : Normal 1 : Overflow Write: 0 : Clear Overflow Status 1 : Return Illegal Data Value |
| 00077 | 0x004C | 1 bit | CH4 DI Overflow Status Read: 0 : Normal 1 : Overflow Write: 0 : Clear Overflow Status 1 : Return Illegal Data Value |
| 00078 | 0x004D | 1 bit | CH5 DI Overflow Status Read: 0 : Normal 1 : Overflow Write: 0 : Clear Overflow Status 1 : Return Illegal Data Value |
| 00079 | 0x004E | 1 bit | CH6 DI Overflow Status Read: 0 : Normal 1 : Overflow Write: 0 : Clear Overflow Status 1 : Return Illegal Data Value |
| 00080 | 0x004F | 1 bit | CH7 DI Overflow Status Read: 0 : Normal 1 : Overflow Write: 0 : Clear Overflow Status 1 : Return Illegal Data Value |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 00081 | 0x0050 | 1 bit | CH8 DI Overflow Status Read: 0 : Normal 1 : Overflow Write: 0 : Clear Overflow Status 1 : Return Illegal Data Value |
| 00082 | 0x0051 | 1 bit | CH9 DI Overflow Status Read: 0 : Normal 1 : Overflow Write: 0 : Clear Overflow Status 1 : Return Illegal Data Value |
| 00083 | 0x0052 | 1 bit | CH10 DI Overflow Status Read: 0 : Normal 1 : Overflow Write: 0 : Clear Overflow Status 1 : Return Illegal Data Value |
| 00084 | 0x0053 | 1 bit | CH11 DI Overflow Status Read: 0 : Normal 1 : Overflow Write: 0 : Clear Overflow Status 1 : Return Illegal Data Value |
| 00085 | 0x0054 | 1 bit | CH0 DI Trigger Status Read: 0 : Normal 1 : Trigger Write: 0 : Clear Trigger Status 1 : Return Illegal Data Value |
| 00086 | 0x0055 | 1 bit | CH1 DI Trigger Status Read: 0 : Normal 1 : Trigger Write: 0 : Clear Trigger Status 1 : Return Illegal Data Value |
| 00087 | 0x0056 | 1 bit | CH2 DI Trigger Status Read: 0 : Normal 1 : Trigger Write: 0 : Clear Trigger Status 1 : Return Illegal Data Value |
| 00088 | 0x0057 | 1 bit | CH3 DI Trigger Status Read: 0 : Normal 1 : Trigger Write: 0 : Clear Trigger Status 1 : Return Illegal Data Value |
| 00089 | 0x0058 | 1 bit | CH4 DI Trigger Status Read: 0 : Normal 1 : Trigger Write: 0 : Clear Trigger Status 1 : Return Illegal Data Value |
| 00090 | 0x0059 | 1 bit | CH5 DI Trigger Status Read: 0 : Normal 1 : Trigger Write: 0 : Clear Trigger Status 1 : Return Illegal Data Value |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 00091 | 0x005A | 1 bit | CH6 DI Trigger Status Read: 0 : Normal 1 : Trigger Write: 0 : Clear Trigger Status 1 : Return Illegal Data Value |
| 00092 | 0x005B | 1 bit | CH7 DI Trigger Status Read: 0 : Normal 1 : Trigger Write: 0 : Clear Trigger Status 1 : Return Illegal Data Value |
| 00093 | 0x005C | 1 bit | CH8 DI Trigger Status Read: 0 : Normal 1 : Trigger Write: 0 : Clear Trigger Status 1 : Return Illegal Data Value |
| 00094 | 0x005D | 1 bit | CH9 DI Trigger Status Read: 0 : Normal 1 : Trigger Write: 0 : Clear Trigger Status 1 : Return Illegal Data Value |
| 00095 | 0x005E | 1 bit | CH10 DI Trigger Status Read: 0 : Normal 1 : Trigger Write: 0 : Clear Trigger Status 1 : Return Illegal Data Value |
| 00096 | 0x005F | 1 bit | CH11 DI Trigger Status Read: 0 : Normal 1 : Trigger Write: 0 : Clear Trigger Status 1 : Return Illegal Data Value |
| 00097 | 0x0060 | 1 bit | CH0 DI Counter Power On Status 0: Off 1: On |
| 00098 | 0x0061 | 1 bit | CH1 DI Counter Power On Status 0: Off 1: On |
| 00099 | 0x0062 | 1 bit | CH2 DI Counter Power On Status 0: Off 1: On |
| 00100 | 0x0063 | 1 bit | CH3 DI Counter Power On Status 0: Off 1: On |
| 00101 | 0x0064 | 1 bit | CH4 DI Counter Power On Status 0: Off 1: On |
| 00102 | 0x0065 | 1 bit | CH5 DI Counter Power On Status 0: Off 1: On |
| 00103 | 0x0066 | 1 bit | CH6 DI Counter Power On Status 0: Off 1: On |
| 00104 | 0x0067 | 1 bit | CH7 DI Counter Power On Status 0: Off 1: On |
| 00105 | 0x0068 | 1 bit | CH8 DI Counter Power On Status 0: Off 1: On |
| 00106 | 0x0069 | 1 bit | CH9 DI Counter Power On Status 0: Off 1: On |
| 00107 | 0x006A | 1 bit | CH10 DI Counter Power On Status 0: Off 1: On |
| 00108 | 0x006B | 1 bit | CH11 DI Counter Power On Status 0: Off 1: On |
| 00109 | 0x006C | 1 bit | CH0 DI Counter Safe Mode Status Read: 0 : Stop 1 : Start Write: 0 : Stop 1 : Start |
| 00110 | 0x006D | 1 bit | CH1 DI Counter Safe Mode Status Read: 0 : Stop 1 : Start Write: 0 : Stop 1 : Start |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 00111 | 0x006E | 1 bit | CH2 DI Counter Safe Mode Status Read: 0 : Stop 1 : Start Write: 0 : Stop 1 : Start |
| 00112 | 0x006F | 1 bit | CH3 DI Counter Safe Mode Status Read: 0 : Stop 1 : Start Write: 0 : Stop 1 : Start |
| 00113 | 0x0070 | 1 bit | CH4 DI Counter Safe Mode Status Read: 0 : Stop 1 : Start Write: 0 : Stop 1 : Start |
| 00114 | 0x0071 | 1 bit | CH5 DI Counter Safe Mode Status Read: 0 : Stop 1 : Start Write: 0 : Stop 1 : Start |
| 00115 | 0x0072 | 1 bit | CH6 DI Counter Safe Mode Status Read: 0 : Stop 1 : Start Write: 0 : Stop 1 : Start |
| 00116 | 0x0073 | 1 bit | CH7 DI Counter Safe Mode Status Read: 0 : Stop 1 : Start Write: 0 : Stop 1 : Start |
| 00117 | 0x0074 | 1 bit | CH8 DI Counter Safe Mode Status Read: 0 : Stop 1 : Start Write: 0 : Stop 1 : Start |
| 00118 | 0x0075 | 1 bit | CH9 DI Counter Safe Mode Status Read: 0 : Stop 1 : Start Write: 0 : Stop 1 : Start |
| 00119 | 0x0076 | 1 bit | CH10 DI Counter Safe Mode Status Read: 0 : Stop 1 : Start Write: 0 : Stop 1 : Start |
| 00120 | 0x0077 | 1 bit | CH11 DI Counter Safe Mode Status Read: 0 : Stop 1 : Start Write: 0 : Stop 1 : Start |

1xxxx Read Only Coils (Function 2)

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---------------|
| 10001 | 0x0000 | 1 bit | CH0 DI Value |
| 10002 | 0x0001 | 1 bit | CH1 DI Value |
| 10003 | 0x0002 | 1 bit | CH2 DI Value |
| 10004 | 0x0003 | 1 bit | CH3 DI Value |
| 10005 | 0x0004 | 1 bit | CH4 DI Value |
| 10006 | 0x0005 | 1 bit | CH5 DI Value |
| 10007 | 0x0006 | 1 bit | CH6 DI Value |
| 10008 | 0x0007 | 1 bit | CH7 DI Value |
| 10009 | 0x0008 | 1 bit | CH8 DI Value |
| 10010 | 0x0009 | 1 bit | CH9 DI Value |
| 10011 | 0x000A | 1 bit | CH10 DI Value |
| 10012 | 0x000B | 1 bit | CH11 DI Value |

3xxxx Read Only Registers (Function 4)

| Reference | Address | Data Type | Description |
|---|---------|-----------|-----------------------------|
| 30001 | 0x0000 | word | CH0 DI Count Value Hi-Byte |
| 30002 | 0x0001 | word | CH0 DI Count Value Lo-Byte |
| 30003 | 0x0002 | word | CH1 DI Count Value Hi-Byte |
| 30004 | 0x0003 | word | CH1 DI Count Value Lo-Byte |
| 30005 | 0x0004 | word | CH2 DI Count Value Hi-Byte |
| 30006 | 0x0005 | word | CH2 DI Count Value Lo-Byte |
| 30007 | 0x0006 | word | CH3 DI Count Value Hi-Byte |
| 30008 | 0x0007 | word | CH3 DI Count Value Lo-Byte |
| 30009 | 0x0008 | word | CH4 DI Count Value Hi-Byte |
| 30010 | 0x0009 | word | CH4 DI Count Value Lo-Byte |
| 30011 | 0x000A | word | CH5 DI Count Value Hi-Byte |
| 30012 | 0x000B | word | CH5 DI Count Value Lo-Byte |
| 30013 | 0x000C | word | CH6 DI Count Value Hi-Byte |
| 30014 | 0x000D | word | CH6 DI Count Value Lo-Byte |
| 30015 | 0x000E | word | CH7 DI Count Value Hi-Byte |
| 30016 | 0x000F | word | CH7 DI Count Value Lo-Byte |
| 30017 | 0x0010 | word | CH8 DI Count Value Hi-Byte |
| 30018 | 0x0011 | word | CH8 DI Count Value Lo-Byte |
| 30019 | 0x0012 | word | CH9 DI Count Value Hi-Byte |
| 30020 | 0x0013 | word | CH9 DI Count Value Lo-Byte |
| 30021 | 0x0014 | word | CH10 DI Count Value Hi-Byte |
| 30022 | 0x0015 | word | CH10 DI Count Value Lo-Byte |
| 30023 | 0x0016 | word | CH11 DI Count Value Hi-Byte |
| 30024 | 0x0017 | word | CH11 DI Count Value Lo-Byte |
| // for Citect SCADA compatibility, I/O data can be WORD accessed as well | | | |
| 312289 | 0x3000 | word | CH0 DI Value |
| 312290 | 0x3001 | word | CH1 DI Value |
| 312291 | 0x3002 | word | CH2 DI Value |
| 312292 | 0x3003 | word | CH3 DI Value |
| 312293 | 0x3004 | word | CH4 DI Value |
| 312294 | 0x3005 | word | CH5 DI Value |
| 312295 | 0x3006 | word | CH6 DI Value |
| 312296 | 0x3007 | word | CH7 DI Value |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---------------|
| 312297 | 0x3008 | word | CH8 DI Value |
| 312298 | 0x3009 | word | CH9 DI Value |
| 312299 | 0x300A | word | CH10 DI Value |
| 312300 | 0x300B | word | CH11 DI Value |

4xxxx Read/Write Registers (Functions 3, 6, 16)

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 40001 | 0x0000 | word | CH0 DO Pulse Output Count Value Hi-Byte |
| 40002 | 0x0001 | word | CH0 DO Pulse Output Count Value Lo-Byte |
| 40003 | 0x0002 | word | CH1 DO Pulse Output Count Value Hi-Byte |
| 40004 | 0x0003 | word | CH1 DO Pulse Output Count Value Lo-Byte |
| 40005 | 0x0004 | word | CH2 DO Pulse Output Count Value Hi-Byte |
| 40006 | 0x0005 | word | CH2 DO Pulse Output Count Value Lo-Byte |
| 40007 | 0x0006 | word | CH3 DO Pulse Output Count Value Hi-Byte |
| 40008 | 0x0007 | word | CH3 DO Pulse Output Count Value Lo-Byte |
| 40009 | 0x0008 | word | CH4 DO Pulse Output Count Value Hi-Byte |
| 40010 | 0x0009 | word | CH4 DO Pulse Output Count Value Lo-Byte |
| 40011 | 0x000A | word | CH5 DO Pulse Output Count Value Hi-Byte |
| 40012 | 0x000B | word | CH5 DO Pulse Output Count Value Lo-Byte |
| 40013 | 0x000C | word | CH6 DO Pulse Output Count Value Hi-Byte |
| 40014 | 0x000D | word | CH6 DO Pulse Output Count Value Lo-Byte |
| 40015 | 0x000E | word | CH7 DO Pulse Output Count Value Hi-Byte |
| 40016 | 0x000F | word | CH7 DO Pulse Output Count Value Lo-Byte |
| 40017 | 0x0010 | word | CH0 DO Pulse Low Signal Width |
| 40018 | 0x0011 | word | CH1 DO Pulse Low Signal Width |
| 40019 | 0x0012 | word | CH2 DO Pulse Low Signal Width |
| 40020 | 0x0013 | word | CH3 DO Pulse Low Signal Width |
| 40021 | 0x0014 | word | CH4 DO Pulse Low Signal Width |
| 40022 | 0x0015 | word | CH5 DO Pulse Low Signal Width |
| 40023 | 0x0016 | word | CH6 DO Pulse Low Signal Width |
| 40024 | 0x0017 | word | CH7 DO Pulse Low Signal Width |
| 40025 | 0x0018 | word | CH0 DO PulseHigh Signal Width |
| 40026 | 0x0019 | word | CH1 DO PulseHigh Signal Width |
| 40027 | 0x001A | word | CH2 DO PulseHigh Signal Width |
| 40028 | 0x001B | word | CH3 DO PulseHigh Signal Width |
| 40029 | 0x001C | word | CH4 DO PulseHigh Signal Width |
| 40030 | 0x001D | word | CH5 DO PulseHigh Signal Width |
| 40031 | 0x001E | word | CH6 DO PulseHigh Signal Width |
| 40032 | 0x001F | word | CH7 DO PulseHigh Signal Width |
| 40033 | 0x0020 | word | CH0 DO Mode 0: DO 1: Pulse |
| 40034 | 0x0021 | word | CH1 DO Mode 0: DO 1: Pulse |
| 40035 | 0x0022 | word | CH2 DO Mode 0: DO 1: Pulse |
| 40036 | 0x0023 | word | CH3 DO Mode 0: DO 1: Pulse |
| 40037 | 0x0024 | word | CH4 DO Mode 0: DO 1: Pulse |
| 40038 | 0x0025 | word | CH5 DO Mode 0: DO 1: Pulse |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 40039 | 0x0026 | word | CH6 DO Mode 0: DO 1: Pulse |
| 40040 | 0x0027 | word | CH7 DO Mode 0: DO 1: Pulse |
| 40041 | 0x0028 | word | CH0 DI Count Filter |
| 40042 | 0x0029 | word | CH1 DI Count Filter |
| 40043 | 0x002A | word | CH2 DI Count Filter |
| 40044 | 0x002B | word | CH3 DI Count Filter |
| 40045 | 0x002C | word | CH4 DI Count Filter |
| 40046 | 0x002D | word | CH5 DI Count Filter |
| 40047 | 0x002E | word | CH6 DI Count Filter |
| 40048 | 0x002F | word | CH7 DI Count Filter |
| 40049 | 0x0030 | word | CH8 DI Count Filter |
| 40050 | 0x0031 | word | CH9 DI Count Filter |
| 40051 | 0x0032 | word | CH10 DI Count Filter |
| 40052 | 0x0033 | word | CH11 DI Count Filter |
| 40053 | 0x0034 | word | CH0 DI Mode 0: DI 1: Count Others : return Illegal Data Value |
| 40054 | 0x0035 | word | CH1 DI Mode 0: DI 1: Count Others : return Illegal Data Value |
| 40055 | 0x0036 | word | CH2 DI Mode 0: DI 1: Count Others : return Illegal Data Value |
| 40056 | 0x0037 | word | CH3 DI Mode 0: DI 1: Count Others : return Illegal Data Value |
| 40057 | 0x0038 | word | CH4 DI Mode 0: DI 1: Count Others : return Illegal Data Value |
| 40058 | 0x0039 | word | CH5 DI Mode 0: DI 1: Count Others : return Illegal Data Value |
| 40059 | 0x003A | word | CH6 DI Mode 0: DI 1: Count Others : return Illegal Data Value |
| 40060 | 0x003B | word | CH7 DI Mode 0: DI 1: Count Others : return Illegal Data Value |
| 40061 | 0x003C | word | CH8 DI Mode 0: DI 1: Count Others : return Illegal Data Value |
| 40062 | 0x003D | word | CH9 DI Mode 0: DI 1: Count Others : return Illegal Data Value |
| 40063 | 0x003E | word | CH10 DI Mode 0: DI 1: Count Others : return Illegal Data Value |
| 40064 | 0x003F | word | CH11 DI Mode 0: DI 1: Count Others : return Illegal Data Value |
| 40377 | 0x0178 | word | Internal Register 00 Initial Value |

| Reference | Address | Data Type | Description |
|---|---------|-----------|------------------------------------|
| 40378 | 0x0179 | word | Internal Register 01 Initial Value |
| 40379 | 0x017A | word | Internal Register 02 Initial Value |
| 40380 | 0x017B | word | Internal Register 03 Initial Value |
| 40381 | 0x017C | word | Internal Register 04 Initial Value |
| 40382 | 0x017D | word | Internal Register 05 Initial Value |
| 40383 | 0x017E | word | Internal Register 06 Initial Value |
| 40384 | 0x017F | word | Internal Register 07 Initial Value |
| 40385 | 0x0180 | word | Internal Register 08 Initial Value |
| 40386 | 0x0181 | word | Internal Register 09 Initial Value |
| 40387 | 0x0182 | word | Internal Register 10 Initial Value |
| 40388 | 0x0183 | word | Internal Register 11 Initial Value |
| 40389 | 0x0184 | word | Internal Register 12 Initial Value |
| 40390 | 0x0185 | word | Internal Register 13 Initial Value |
| 40391 | 0x0186 | word | Internal Register 14 Initial Value |
| 40392 | 0x0187 | word | Internal Register 15 Initial Value |
| 40393 | 0x0188 | word | Internal Register 16 Initial Value |
| 40394 | 0x0189 | word | Internal Register 17 Initial Value |
| 40395 | 0x018A | word | Internal Register 18 Initial Value |
| 40396 | 0x018B | word | Internal Register 19 Initial Value |
| 40397 | 0x018C | word | Internal Register 20 Initial Value |
| 40398 | 0x018D | word | Internal Register 21 Initial Value |
| 40399 | 0x018E | word | Internal Register 22 Initial Value |
| 40400 | 0x018F | word | Internal Register 23 Initial Value |
| 42921 | 0x0B68 | word | Internal Register 00 Working Value |
| 42922 | 0x0B69 | word | Internal Register 01 Working Value |
| 42923 | 0x0B6A | word | Internal Register 02 Working Value |
| 42924 | 0x0B6B | word | Internal Register 03 Working Value |
| 42925 | 0x0B6C | word | Internal Register 04 Working Value |
| 42926 | 0x0B6D | word | Internal Register 05 Working Value |
| 42927 | 0x0B6E | word | Internal Register 06 Working Value |
| 42928 | 0x0B6F | word | Internal Register 07 Working Value |
| 42929 | 0x0B70 | word | Internal Register 08 Working Value |
| 42930 | 0x0B71 | word | Internal Register 09 Working Value |
| 42931 | 0x0B72 | word | Internal Register 10 Working Value |
| 42932 | 0x0B73 | word | Internal Register 11 Working Value |
| 42933 | 0x0B74 | word | Internal Register 12 Working Value |
| 42934 | 0x0B75 | word | Internal Register 13 Working Value |
| 42935 | 0x0B76 | word | Internal Register 14 Working Value |
| 42936 | 0x0B77 | word | Internal Register 15 Working Value |
| 42937 | 0x0B78 | word | Internal Register 16 Working Value |
| 42938 | 0x0B79 | word | Internal Register 17 Working Value |
| 42939 | 0x0B7A | word | Internal Register 18 Working Value |
| 42940 | 0x0B7B | word | Internal Register 19 Working Value |
| 42941 | 0x0B7C | word | Internal Register 20 Working Value |
| 42942 | 0x0B7D | word | Internal Register 21 Working Value |
| 42943 | 0x0B7E | word | Internal Register 22 Working Value |
| 42944 | 0x0B7F | word | Internal Register 23 Working Value |
| // for Citect SCADA compatibility, I/O data can be WORD accessed as well | | | |
| 40257 | 0x0100 | 1 word | CH0 DO Value 0: Off 1: On |
| 40258 | 0x0101 | 1 word | CH1 DO Value 0: Off 1: On |
| 40259 | 0x0102 | 1 word | CH2 DO Value 0: Off 1: On |
| 40260 | 0x0103 | 1 word | CH3 DO Value 0: Off 1: On |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 40261 | 0x0104 | 1 word | CH4 DO Value 0: Off 1: On |
| 40262 | 0x0105 | 1 word | CH5 DO Value 0: Off 1: On |
| 40263 | 0x0106 | 1 word | CH6 DO Value 0: Off 1: On |
| 40264 | 0x0107 | 1 word | CH7 DO Value 0: Off 1: On |
| 40265 | 0x0108 | 1 word | CH0 DO Power On Value 0: Off 1: On |
| 40266 | 0x0109 | 1 word | CH1 DO Power On Value 0: Off 1: On |
| 40267 | 0x010A | 1 word | CH2 DO Power On Value 0: Off 1: On |
| 40268 | 0x010B | 1 word | CH3 DO Power On Value 0: Off 1: On |
| 40269 | 0x010C | 1 word | CH4 DO Power On Value 0: Off 1: On |
| 40270 | 0x010D | 1 word | CH5 DO Power On Value 0: Off 1: On |
| 40271 | 0x010E | 1 word | CH6 DO Power On Value 0: Off 1: On |
| 40272 | 0x010F | 1 word | CH7 DO Power On Value 0: Off 1: On |
| 40273 | 0x0110 | 1 word | CH0 DO Safe Mode Value 0: Off 1: On |
| 40274 | 0x0111 | 1 word | CH1 DO Safe Mode Value 0: Off 1: On |
| 40275 | 0x0112 | 1 word | CH2 DO Safe Mode Value 0: Off 1: On |
| 40276 | 0x0113 | 1 word | CH3 DO Safe Mode Value 0: Off 1: On |
| 40277 | 0x0114 | 1 word | CH4 DO Safe Mode Value 0: Off 1: On |
| 40278 | 0x0115 | 1 word | CH5 DO Safe Mode Value 0: Off 1: On |
| 40279 | 0x0116 | 1 word | CH6 DO Safe Mode Value 0: Off 1: On |
| 40280 | 0x0117 | 1 word | CH7 DO Safe Mode Value 0: Off 1: On |
| 40281 | 0x0118 | 1 word | CH0 DO Pulse Operate Status 0: Stop 1: Start |
| 40282 | 0x0119 | 1 word | CH1 DO Pulse Operate Status 0: Stop 1: Start |
| 40283 | 0x011A | 1 word | CH2 DO Pulse Operate Status 0: Stop 1: Start |
| 40284 | 0x011B | 1 word | CH3 DO Pulse Operate Status 0: Stop 1: Start |
| 40285 | 0x011C | 1 word | CH4 DO Pulse Operate Status 0: Stop 1: Start |
| 40286 | 0x011D | 1 word | CH5 DO Pulse Operate Status 0: Stop 1: Start |
| 40287 | 0x011E | 1 word | CH6 DO Pulse Operate Status 0: Stop 1: Start |
| 40288 | 0x011F | 1 word | CH7 DO Pulse Operate Status 0: Stop 1: Start |
| 40289 | 0x0120 | 1 word | CH0 DO PowerOn Pulse Operate Status 0: Stop 1: Start |
| 40290 | 0x0121 | 1 word | CH1 DO PowerOn Pulse Operate Status 0: Stop 1: Start |
| 40291 | 0x0122 | 1 word | CH2 DO PowerOn Pulse Operate Status 0: Stop 1: Start |
| 40292 | 0x0123 | 1 word | CH3 DO PowerOn Pulse Operate Status 0: Stop 1: Start |
| 40293 | 0x0124 | 1 word | CH4 DO PowerOn Pulse Operate Status 0: Stop 1: Start |
| 40294 | 0x0125 | 1 word | CH5 DO PowerOn Pulse Operate Status 0: Stop 1: Start |
| 40295 | 0x0126 | 1 word | CH6 DO PowerOn Pulse Operate Status 0: Stop 1: Start |
| 40296 | 0x0127 | 1 word | CH7 DO PowerOn Pulse Operate Status 0: Stop 1: Start |
| 40297 | 0x0128 | 1 word | CH0 DO Safe Mode Pulse Operate Status 0: Stop 1: Start |
| 40298 | 0x0129 | 1 word | CH1 DO Safe Mode Pulse Operate Status 0: Stop 1: Start |
| 40299 | 0x012A | 1 word | CH2 DO Safe Mode Pulse Operate Status 0: Stop 1: Start |
| 40300 | 0x012B | 1 word | CH3 DO Safe Mode Pulse Operate Status 0: Stop 1: Start |
| 40301 | 0x012C | 1 word | CH4 DO Safe Mode Pulse Operate Status 0: Stop 1: Start |
| 40302 | 0x012D | 1 word | CH5 DO Safe Mode Pulse Operate Status 0: Stop 1: Start |
| 40303 | 0x012E | 1 word | CH6 DO Safe Mode Pulse Operate Status 0: Stop 1: Start |
| 40304 | 0x012F | 1 word | CH7 DO Safe Mode Pulse Operate Status 0: Stop 1: Start |
| 40305 | 0x0130 | 1 word | CH0 DI Counter Operate Status 0: Stop 1: Start |
| 40306 | 0x0131 | 1 word | CH1 DI Counter Operate Status 0: Stop 1: Start |
| 40307 | 0x0132 | 1 word | CH2 DI Counter Operate Status 0: Stop 1: Start |
| 40308 | 0x0133 | 1 word | CH3 DI Counter Operate Status 0: Stop 1: Start |
| 40309 | 0x0134 | 1 word | CH4 DI Counter Operate Status 0: Stop 1: Start |
| 40310 | 0x0135 | 1 word | CH5 DI Counter Operate Status 0: Stop 1: Start |
| 40311 | 0x0136 | 1 word | CH6 DI Counter Operate Status 0: Stop 1: Start |
| 40312 | 0x0137 | 1 word | CH7 DI Counter Operate Status 0: Stop 1: Start |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 40313 | 0x0138 | 1 word | CH8 DI Counter Operate Status 0: Stop 1: Start |
| 40314 | 0x0139 | 1 word | CH9 DI Counter Operate Status 0: Stop 1: Start |
| 40315 | 0x013A | 1 word | CH10 DI Counter Operate Status 0: Stop 1: Start |
| 40316 | 0x013B | 1 word | CH11 DI Counter Operate Status 0: Stop 1: Start |
| 40317 | 0x013C | 1 word | CH0 DI Clear Count Value Read: always return: 0 Write: 1 : Clear counter value0 : Return illegal data value(0x03) |
| 40318 | 0x013D | 1 word | CH1 DI Clear Count Value Read: always return: 0 Write: 1 : Clear counter value 0 : Return illegal data value(0x03) |
| 40319 | 0x013E | 1 word | CH2 DI Clear Count Value Read: always return: 0 Write: 1 : Clear counter value 0 : Return illegal data value(0x03) |
| 40320 | 0x013F | 1 word | CH3 DI Clear Count Value Read: always return: 0 Write: 1 : Clear counter value 0 : Return illegal data value(0x03) |
| 40321 | 0x0140 | 1 word | CH4 DI Clear Count Value Read: always return: 0 Write: 1 : Clear counter value 0 : Return illegal data value(0x03) |
| 40322 | 0x0141 | 1 word | CH5 DI Clear Count Value Read: always return: 0 Write: 1 : Clear counter value 0 : Return illegal data value(0x03) |
| 40323 | 0x0142 | 1 word | CH6 DI Clear Count Value Read: always return: 0 Write: 1 : Clear counter value 0 : Return illegal data value(0x03) |
| 40324 | 0x0143 | 1 word | CH7 DI Clear Count Value Read: always return: 0 Write: 1 : Clear counter value 0 : Return illegal data value(0x03) |
| 40325 | 0x0144 | 1 word | CH8 DI Clear Count Value Read: always return: 0 Write: 1 : Clear counter value 0 : Return illegal data value(0x03) |
| 40326 | 0x0145 | 1 word | CH9 DI Clear Count Value Read: always return: 0 Write: 1 : Clear counter value 0 : Return illegal data value(0x03) |
| 40327 | 0x0146 | 1 word | CH10 DI Clear Count Value Read: always return: 0 Write: 1 : Clear counter value 0 : Return illegal data value(0x03) |
| 40328 | 0x0147 | 1 word | CH11 DI Clear Count Value Read: always return: 0 Write: 1 : Clear counter value0 : Return illegal data value(0x03) |
| 40329 | 0x0148 | 1 word | CH0 DI OverFlow Status Read: 0 : Normal 1 : Overflow Write: 0 : Clear overflow status 1 : Return illegal data value (0x03) |
| 40330 | 0x0149 | 1 word | CH1 DI OverFlow Status Read: 0 : Normal 1 : Overflow Write: 0 : Clear overflow status 1 : Return illegal data value (0x03) |
| 40331 | 0x014A | 1 word | CH2 DI OverFlow Status Read: 0 : Normal 1 : Overflow Write: 0 : Clear overflow status 1 : Return illegal data value (0x03) |
| 40332 | 0x014B | 1 word | CH3 DI OverFlow Status Read: 0 : Normal 1 : Overflow Write: 0 : Clear overflow status 1 : Return illegal data value (0x03) |
| 40333 | 0x014C | 1 word | CH4 DI OverFlow Status Read: 0 : Normal 1 : Overflow Write: 0 : Clear overflow status 1 : Return illegal data value (0x03) |
| 40334 | 0x014D | 1 word | CH5 DI OverFlow Status Read: 0 : Normal 1 : Overflow Write: 0 : Clear overflow status 1 : Return illegal data value (0x03) |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 40335 | 0x014E | 1 word | CH6 DI OverFlow Status Read: 0 : Normal 1 : Overflow Write: 0 : Clear overflow status 1 : Return illegal data value (0x03) |
| 40336 | 0x014F | 1 word | CH7 DI OverFlow Status Read: 0 : Normal 1 : Overflow Write: 0 : Clear overflow status 1 : Return illegal data value (0x03) |
| 40337 | 0x0150 | 1 word | CH8 DI OverFlow Status Read: 0 : Normal 1 : Overflow Write: 0 : Clear overflow status 1 : Return illegal data value (0x03) |
| 40338 | 0x0151 | 1 word | CH9 DI OverFlow Status Read: 0 : Normal 1 : Overflow Write: 0 : Clear overflow status 1 : Return illegal data value (0x03) |
| 40339 | 0x0152 | 1 word | CH10 DI OverFlow Status Read: 0 : Normal 1 : Overflow Write: 0 : Clear overflow status 1 : Return illegal data value (0x03) |
| 40340 | 0x0153 | 1 word | CH11 DI OverFlow Status Read: 0 : Normal 1 : Overflow Write: 0 : Clear overflow stat 1 : Return illegal data value (0x03) |
| 40341 | 0x0154 | 1 word | CH0 DI Counter Trigger · 0=Low to High, 1=High to Low |
| 40342 | 0x0155 | 1 word | CH1 DI Counter Trigger · 0=Low to High, 1=High to Low |
| 40343 | 0x0156 | 1 word | CH2 DI Counter Trigger · 0=Low to High, 1=High to Low |
| 40344 | 0x0157 | 1 word | CH3 DI Counter Trigger · 0=Low to High, 1=High to Low |
| 40345 | 0x0158 | 1 word | CH4 DI Counter Trigger · 0=Low to High, 1=High to Low |
| 40346 | 0x0159 | 1 word | CH5 DI Counter Trigger · 0=Low to High, 1=High to Low |
| 40347 | 0x015A | 1 word | CH6 DI Counter Trigger · 0=Low to High, 1=High to Low |
| 40348 | 0x015B | 1 word | CH7 DI Counter Trigger · 0=Low to High, 1=High to Low |
| 40349 | 0x015C | 1 word | CH8 DI Counter Trigger · 0=Low to High, 1=High to Low |
| 40350 | 0x015D | 1 word | CH9 DI Counter Trigger · 0=Low to High, 1=High to Low |
| 40351 | 0x015E | 1 word | CH10 DI Counter Trigger · 0=Low to High, 1=High to Low |
| 40352 | 0x015F | 1 word | CH11 DI Counter Trigger · 0=Low to High, 1=High to Low |
| 40353 | 0x0160 | 1 word | CH0 DI PowerOn Counter Operate Status 0: Stop 1: Start |
| 40354 | 0x0161 | 1 word | CH1 DI PowerOn Counter Operate Status 0: Stop 1: Start |
| 40355 | 0x0162 | 1 word | CH2 DI PowerOn Counter Operate Status 0: Stop 1: Start |
| 40356 | 0x0163 | 1 word | CH3 DI PowerOn Counter Operate Status 0: Stop 1: Start |
| 40357 | 0x0164 | 1 word | CH4 DI PowerOn Counter Operate Status 0: Stop 1: Start |
| 40358 | 0x0165 | 1 word | CH5 DI PowerOn Counter Operate Status 0: Stop 1: Start |
| 40359 | 0x0166 | 1 word | CH6 DI PowerOn Counter Operate Status 0: Stop 1: Start |
| 40360 | 0x0167 | 1 word | CH7 DI PowerOn Counter Operate Status 0: Stop 1: Start |
| 40361 | 0x0168 | 1 word | CH8 DI PowerOn Counter Operate Status 0: Stop 1: Start |
| 40362 | 0x0169 | 1 word | CH9 DI PowerOn Counter Operate Status 0: Stop 1: Start |
| 40363 | 0x016A | 1 word | CH10 DI PowerOn Counter Operate Status 0: Stop 1: Start |
| 40364 | 0x016B | 1 word | CH11 DI PowerOn Counter Operate Status 0: Stop 1: Start |
| 40365 | 0x016C | 1 word | CH0 DI Safe Mode Counter Operate Status 0: Stop 1: Start |
| 40366 | 0x016D | 1 word | CH1 DI Safe Mode Counter Operate Status 0: Stop 1: Start |
| 40367 | 0x016E | 1 word | CH2 DI Safe Mode Counter Operate Status 0: Stop 1: Start |
| 40368 | 0x016F | 1 word | CH3 DI Safe Mode Counter Operate Status 0: Stop 1: Start |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 40369 | 0x0170 | 1 word | CH4 DI Safe Mode Counter Operate Status 0: Stop 1: Start |
| 40370 | 0x0171 | 1 word | CH5 DI Safe Mode Counter Operate Status 0: Stop 1: Start |
| 40371 | 0x0172 | 1 word | CH6 DI Safe Mode Counter Operate Status 0: Stop 1: Start |
| 40372 | 0x0173 | 1 word | CH7 DI Safe Mode Counter Operate Status 0: Stop 1: Start |
| 40373 | 0x0174 | 1 word | CH8 DI Safe Mode Counter Operate Status 0: Stop 1: Start |
| 40374 | 0x0175 | 1 word | CH9 DI Safe Mode Counter Operate Status 0: Stop 1: Start |
| 40375 | 0x0176 | 1 word | CH10 DI Safe Mode Counter Operate Status 0: Stop 1: Start |
| 40376 | 0x0177 | 1 word | CH11 DI Safe Mode Counter Operate Status 0: Stop 1: Start |
| 43329 | 0x0D00 | 2 word | CH0 DI - Counter mode value |
| 43330 | 0x0D01 | 2 word | CH1 DI - Counter mode value |
| 43331 | 0x0D02 | 2 word | CH2 DI - Counter mode value |
| 43332 | 0x0D03 | 2 word | CH3 DI - Counter mode value |
| 43333 | 0x0D04 | 2 word | CH4 DI - Counter mode value |
| 43334 | 0x0D05 | 2 word | CH5 DI - Counter mode value |
| 43335 | 0x0D06 | 2 word | CH6 DI - Counter mode value |
| 43336 | 0x0D07 | 2 word | CH7 DI - Counter mode value |
| 43337 | 0x0D08 | 2 word | CH8 DI - Counter mode value |
| 43338 | 0x0D09 | 2 word | CH9 DI - Counter mode value |
| 43339 | 0x0D0A | 2 word | CH10 DI - Counter mode value |
| 43340 | 0x0D0B | 2 word | CH11 DI - Counter mode value |

ioLogik E2212 Modbus Mapping

0xxxx Read/Write Coils (Functions 1, 5, 15)

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|-------------------------------|
| 00001 | 0x0000 | 1 bit | CH0 DO value 0: off 1: on |
| 00002 | 0x0001 | 1 bit | CH1 DO value 0: off 1: on |
| 00003 | 0x0002 | 1 bit | CH2 DO value 0: off 1: on |
| 00004 | 0x0003 | 1 bit | CH3 DO value 0: off 1: on |
| 00005 | 0x0004 | 1 bit | CH4 DO value 0: off 1: on |
| 00006 | 0x0005 | 1 bit | CH5 DO value 0: off 1: on |
| 00007 | 0x0006 | 1 bit | CH6 DO value 0: off 1: on |
| 00008 | 0x0007 | 1 bit | CH7 DO value 0: off 1: on |
| 00009 | 0x0008 | 1 bit | CH8 DO value 0: off 1: on |
| 00010 | 0x0009 | 1 bit | CH9 DO value 0: off 1: on |
| 00011 | 0x000A | 1 bit | CH10 DO value 0: off 1: on |
| 00012 | 0x000B | 1 bit | CH11 DO value 0: off 1: on |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 00013 | 0x000C | 1 bit | CH0 DO power-on value 0: off 1: on |
| 00014 | 0x000D | 1 bit | CH1 DO power-on value 0: off 1: on |
| 00015 | 0x000E | 1 bit | CH2 DO power-on value 0: off 1: on |
| 00016 | 0x000F | 1 bit | CH3 DO power-on value 0: off 1: on |
| 00017 | 0x0010 | 1 bit | CH4 DO power-on value 0: off 1: on |
| 00018 | 0x0011 | 1 bit | CH5 DO power-on value 0: off 1: on |
| 00019 | 0x0012 | 1 bit | CH6 DO power-on value 0: off 1: on |
| 00020 | 0x0013 | 1 bit | CH7 DO power-on value 0: off 1: on |
| 00021 | 0x0014 | 1 bit | CH8 DO power-on value 0: off 1: on |
| 00022 | 0x0015 | 1 bit | CH9 DO power-on value 0: off 1: on |
| 00023 | 0x0016 | 1 bit | CH10 DO power-on value 0: off 1: on |
| 00024 | 0x0017 | 1 bit | CH11 DO power-on value 0: off 1: on |
| 00025 | 0x0018 | 1 bit | CH0 DO safe value 0: off 1: on |
| 00026 | 0x0019 | 1 bit | CH1 DO safe value 0: off 1: on |
| 00027 | 0x001A | 1 bit | CH2 DO safe value 0: off 1: on |
| 00028 | 0x001B | 1 bit | CH3 DO safe value 0: off 1: on |
| 00029 | 0x001C | 1 bit | CH4 DO safe value 0: off 1: on |
| 00030 | 0x001D | 1 bit | CH5 DO safe value 0: off 1: on |
| 00031 | 0x001E | 1 bit | CH6 DO safe value 0: off 1: on |
| 00032 | 0x001F | 1 bit | CH7 DO safe value 0: off 1: on |
| 00033 | 0x0020 | 1 bit | CH8 DO safe value 0: off 1: on |
| 00034 | 0x0021 | 1 bit | CH9 DO safe value 0: off 1: on |
| 00035 | 0x0022 | 1 bit | CH10 DO safe value 0: off 1: on |
| 00036 | 0x0023 | 1 bit | CH11 DO safe value 0: off 1: on |
| 00037 | 0x0024 | 1 bit | CH0 DO pulse operate status 0: off 1: on |
| 00038 | 0x0025 | 1 bit | CH1 DO pulse operate status 0: off 1: on |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 00039 | 0x0026 | 1 bit | CH2 DO pulse operate status 0: off 1: on |
| 00040 | 0x0027 | 1 bit | CH3 DO pulse operate status 0: off 1: on |
| 00041 | 0x0028 | 1 bit | CH4 DO pulse operate status 0: off 1: on |
| 00042 | 0x0029 | 1 bit | CH5 DO pulse operate status 0: off 1: on |
| 00043 | 0x002A | 1 bit | CH6 DO pulse operate status 0: off 1: on |
| 00044 | 0x002B | 1 bit | CH7 DO pulse operate status 0: off 1: on |
| 00045 | 0x002C | 1 bit | CH8 DO pulse operate status 0: off 1: on |
| 00046 | 0x002D | 1 bit | CH9 DO pulse operate status 0: off 1: on |
| 00047 | 0x002E | 1 bit | CH10 DO pulse operate status 0: off 1: on |
| 00048 | 0x002F | 1 bit | CH11 DO pulse operate status 0: off 1: on |
| 00049 | 0x0030 | 1 bit | CH0 DO power-on pulse operate status 0: off 1: on |
| 00050 | 0x0031 | 1 bit | CH1 DO power-on pulse operate status 0: off 1: on |
| 00051 | 0x0032 | 1 bit | CH2 DO power-on pulse operate status 0: off 1: on |
| 00052 | 0x0033 | 1 bit | CH3 DO power-on pulse operate status 0: off 1: on |
| 00053 | 0x0034 | 1 bit | CH4 DO power-on pulse operate status 0: off 1: on |
| 00054 | 0x0035 | 1 bit | CH5 DO power-on pulse operate status 0: off 1: on |
| 00055 | 0x0036 | 1 bit | CH6 DO power-on pulse operate status 0: off 1: on |
| 00056 | 0x0037 | 1 bit | CH7 DO power-on pulse operate status 0: off 1: on |
| 00057 | 0x0038 | 1 bit | CH8 DO power-on pulse operate status 0: off 1: on |
| 00058 | 0x0039 | 1 bit | CH9 DO power-on pulse operate status 0: off 1: on |
| 00059 | 0x003A | 1 bit | CH10 DO power-on pulse operate status 0: off 1: on |
| 00060 | 0x003B | 1 bit | CH11 DO power-on pulse operate status 0: off 1: on |
| 00061 | 0x003C | 1 bit | CH0 DO safe pulse operate status 0: off 1: on |
| 00062 | 0x003D | 1 bit | CH1 DO safe pulse operate status 0: off 1: on |
| 00063 | 0x003E | 1 bit | CH2 DO safe pulse operate status 0: off 1: on |
| 00064 | 0x003F | 1 bit | CH3 DO safe pulse operate status 0: off 1: on |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 00065 | 0x0040 | 1 bit | CH4 DO safe pulse operate status 0: off 1: on |
| 00066 | 0x0041 | 1 bit | CH5 DO safe pulse operate status 0: off 1: on |
| 00067 | 0x0042 | 1 bit | CH6 DO safe pulse operate status 0: off 1: on |
| 00068 | 0x0043 | 1 bit | CH7 DO safe pulse operate status 0: off 1: on |
| 00069 | 0x0044 | 1 bit | CH8 DO safe pulse operate status 0: off 1: on |
| 00070 | 0x0045 | 1 bit | CH9 DO safe pulse operate status 0: off 1: on |
| 00071 | 0x0046 | 1 bit | CH10 DO safe pulse operate status 0: off 1: on |
| 00072 | 0x0047 | 1 bit | CH11 DO safe pulse operate status 0: off 1: on |
| 00073 | 0x0048 | 1 bit | CH0 DI counter status 0: off 1: on |
| 00074 | 0x0049 | 1 bit | CH1 DI counter status 0: off 1: on |
| 00075 | 0x004A | 1 bit | CH2 DI counter status 0: off 1: on |
| 00076 | 0x004B | 1 bit | CH3 DI counter status 0: off 1: on |
| 00077 | 0x004C | 1 bit | CH4 DI counter status 0: off 1: on |
| 00078 | 0x004D | 1 bit | CH5 DI counter status 0: off 1: on |
| 00079 | 0x004E | 1 bit | CH6 DI counter status 0: off 1: on |
| 00080 | 0x004F | 1 bit | CH7 DI counter status 0: off 1: on |
| 00081 | 0x0050 | 1 bit | CH8 DI counter status 0: off 1: on |
| 00082 | 0x0051 | 1 bit | CH9 DI counter status 0: off 1: on |
| 00083 | 0x0052 | 1 bit | CH10 DI counter status 0: off 1: on |
| 00084 | 0x0053 | 1 bit | CH11 DI counter status 0: off 1: on |
| 00085 | 0x0054 | 1 bit | CH0 DI clear count value Read: 0: no action Write: 1: clear counter value 0: return illegal data value |
| 00086 | 0x0055 | 1 bit | CH1 DI clear count value Read: 0: no action Write: 1: clear counter value 0: return illegal data value |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 00087 | 0x0056 | 1 bit | CH2 DI clear count value Read: 0: no action Write: 1: clear counter value 0: return illegal data value |
| 00088 | 0x0057 | 1 bit | CH3 DI clear count value Read: 0: no action Write: 1: clear counter value 0: return illegal data value |
| 00089 | 0x0058 | 1 bit | CH4 DI clear count value Read: 0: no action Write: 1: clear counter value 0: return illegal data value |
| 00090 | 0x0059 | 1 bit | CH5 DI clear count value Read: 0: no action Write: 1: clear counter value 0: return illegal data value |
| 00091 | 0x005A | 1 bit | CH6 DI clear count value Read: 0: no action Write: 1: clear counter value 0: return illegal data value |
| 00092 | 0x005B | 1 bit | CH7 DI clear count value Read: 0: no action Write: 1: clear counter value 0: return illegal data value |
| 00093 | 0x005C | 1 bit | CH8 DI clear count value Read: 0: no action Write: 1: clear counter value 0: return illegal data value |
| 00094 | 0x005D | 1 bit | CH9 DI clear count value Read: 0: no action Write: 1: clear counter value 0: return illegal data value |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 00095 | 0x005E | 1 bit | CH10 DI clear count value Read: 0: no action Write: 1: clear counter value 0: return illegal data value |
| 00096 | 0x005F | 1 bit | CH11 DI clear count value Read: 0: no action Write: 1: clear counter value 0: return illegal data value |
| 00097 | 0x0060 | 1 bit | CH0 DI overflow status Read: 0: normal 1: overflow Write: 0: clear overflow status 1: return illegal data value |
| 00098 | 0x0061 | 1 bit | CH1 DI overflow status Read: 0: normal 1: overflow Write: 0: clear overflow status 1: return illegal data value |
| 00099 | 0x0062 | 1 bit | CH2 DI overflow status Read: 0: normal 1: overflow Write: 0: clear overflow status 1: return illegal data value |
| 00100 | 0x0063 | 1 bit | CH3 DI overflow status Read: 0: normal 1: overflow Write: 0: clear overflow status 1: return illegal data value |
| 00101 | 0x0064 | 1 bit | CH4 DI overflow status Read: 0: normal 1: overflow Write: 0: clear overflow status 1: return illegal data value |
| 00102 | 0x0065 | 1 bit | CH5 DI overflow status Read: 0: normal 1: overflow Write: 0: clear overflow status 1: return illegal data value |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 00103 | 0x0066 | 1 bit | CH6 DI overflow status Read: 0: normal 1: overflow Write: 0: clear overflow status 1: return illegal data value |
| 00104 | 0x0067 | 1 bit | CH7 DI overflow status Read: 0: normal 1: overflow Write: 0: clear overflow status 1: return illegal data value |
| 00105 | 0x0068 | 1 bit | CH8 DI overflow status Read: 0: normal 1: overflow Write: 0: clear overflow status 1: return illegal data value |
| 00106 | 0x0069 | 1 bit | CH9 DI overflow status Read: 0: normal 1: overflow Write: 0: clear overflow status 1: return illegal data value |
| 00107 | 0x006A | 1 bit | CH10 DI overflow status Read: 0: normal 1: overflow Write: 0: clear overflow status 1: return illegal data value |
| 00108 | 0x006B | 1 bit | CH11 DI overflow status Read: 0: normal 1: overflow Write: 0: clear overflow status 1: return illegal data value |
| 00109 | 0x006C | 1 bit | CH0 DI count trigger |
| 00110 | 0x006D | 1 bit | CH1 DI count trigger |
| 00111 | 0x006E | 1 bit | CH2 DI count trigger |
| 00112 | 0x006F | 1 bit | CH3 DI count trigger |
| 00113 | 0x0070 | 1 bit | CH4 DI count trigger |
| 00114 | 0x0071 | 1 bit | CH5 DI count trigger |
| 00115 | 0x0072 | 1 bit | CH6 DI count trigger |
| 00116 | 0x0073 | 1 bit | CH7 DI count trigger |
| 00117 | 0x0074 | 1 bit | CH8 DI count trigger |
| 00118 | 0x0075 | 1 bit | CH9 DI count trigger |
| 00119 | 0x0076 | 1 bit | CH10 DI count trigger |
| 00120 | 0x0077 | 1 bit | CH11 DI count trigger |
| 00121 | 0x0078 | 1 bit | CH0 DI power-on status 0: off 1: on |
| 00122 | 0x0079 | 1 bit | CH1 DI power-on status 0: off 1: on |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 00123 | 0x007A | 1 bit | CH2 DI power-on status 0: off 1: on |
| 00124 | 0x007B | 1 bit | CH3 DI power-on status 0: off 1: on |
| 00125 | 0x007C | 1 bit | CH4 DI power-on status 0: off 1: on |
| 00126 | 0x007D | 1 bit | CH5 DI power-on status 0: off 1: on |
| 00127 | 0x007E | 1 bit | CH6 DI power-on status 0: off 1: on |
| 00128 | 0x007F | 1 bit | CH7 DI power-on status 0: off 1: on |
| 00129 | 0x0080 | 1 bit | CH8 DI power-on status 0: off 1: on |
| 00130 | 0x0081 | 1 bit | CH9 DI power-on status 0: off 1: on |
| 00131 | 0x0082 | 1 bit | CH10 DI power-on status 0: off 1: on |
| 00132 | 0x0083 | 1 bit | CH11 DI power-on status 0: off 1: on |
| 00133 | 0x0084 | 1 bit | CH0 DI safe operate status 0: off 1: on |
| 00134 | 0x0085 | 1 bit | CH1 DI safe operate status 0: off 1: on |
| 00135 | 0x0086 | 1 bit | CH2 DI safe operate status 0: off 1: on |
| 00136 | 0x0087 | 1 bit | CH3 DI safe operate status 0: off 1: on |
| 00137 | 0x0088 | 1 bit | CH4 DI safe operate status 0: off 1: on |
| 00138 | 0x0089 | 1 bit | CH5 DI safe operate status 0: off 1: on |
| 00139 | 0x008A | 1 bit | CH6 DI safe operate status 0: off 1: on |
| 00140 | 0x008B | 1 bit | CH7 DI safe operate status 0: off 1: on |
| 00141 | 0x008C | 1 bit | CH8 DI safe operate status 0: off 1: on |
| 00142 | 0x008D | 1 bit | CH9 DI safe operate status 0: off 1: on |
| 00143 | 0x008E | 1 bit | CH10 DI safe operate status 0: off 1: on |
| 00144 | 0x008F | 1 bit | CH11 DI safe operate status 0: off 1: on |
| 00145 | 0x0090 | 1 bit | CH0 DI set channel Power-off storage enable on/off 1: on 0: off |
| 00146 | 0x0091 | 1 bit | CH1 DI set channel Power-off storage enable on/off 1: on 0: off |
| 00147 | 0x0092 | 1 bit | CH2 DI set channel Power-off storage enable on/off 1: on 0: off |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 00148 | 0x0093 | 1 bit | CH3 DI set channel Power-off storage enable on/off 1: on 0: off |
| 00149 | 0x0094 | 1 bit | CH4 DI set channel Power-off storage enable on/off 1: on 0: off |
| 00150 | 0x0095 | 1 bit | CH5 DI set channel Power-off storage enable on/off 1: on 0: off |
| 00151 | 0x0096 | 1 bit | CH6 DI set channel Power-off storage enable on/off 1: on 0: off |
| 00152 | 0x0097 | 1 bit | CH7 DI set channel Power-off storage enable on/off 1: on 0: off |
| 00153 | 0x0098 | 1 bit | CH8 DI set channel Power-off storage enable on/off 1: on 0: off |
| 00154 | 0x0099 | 1 bit | CH9 DI set channel Power-off storage enable on/off 1: on 0: off |
| 00155 | 0x009A | 1 bit | CH10 DI set channel Power-off storage enable on/off 1: on 0: off |
| 00156 | 0x009B | 1 bit | CH11 DI set channel Power-off storage enable on/off 1: on 0: off |
| 00157 | 0x009C | 1 bit | DIO 0 1: output DO mode 0: input DI mode |
| 00158 | 0x009D | 1 bit | DIO 1 1: output DO mode 0: input DI mode |
| 00159 | 0x009E | 1 bit | DIO 2 1: output DO mode 0: input DI mode |
| 00160 | 0x009F | 1 bit | DIO 3 1: output DO mode 0: input DI mode |

1xxxx Read Only Coils (Function 2)

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--------------|
| 10001 | 0x0000 | 1 bit | CH0 DI value |
| 10002 | 0x0001 | 1 bit | CH1 DI value |
| 10003 | 0x0002 | 1 bit | CH2 DI value |
| 10004 | 0x0003 | 1 bit | CH3 DI value |
| 10005 | 0x0004 | 1 bit | CH4 DI value |
| 10006 | 0x0005 | 1 bit | CH5 DI value |
| 10007 | 0x0006 | 1 bit | CH6 DI value |
| 10008 | 0x0007 | 1 bit | CH7 DI value |
| 10009 | 0x0008 | 1 bit | CH8 DI value |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---------------|
| 10010 | 0x0009 | 1 bit | CH9 DI value |
| 10011 | 0x000A | 1 bit | CH10 DI value |
| 10012 | 0x000B | 1 bit | CH11 DI value |
| 10013 | 0x000C | 1 bit | Non-active |
| 10014 | 0x000D | 1 bit | Non-active |
| 10015 | 0x000E | 1 bit | Non-active |
| 10016 | 0x000F | 1 bit | Non-active |

3xxxx Read Only Registers (Function 4)

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|-----------------------------|
| 30001 | 0x0000 | 1 word | CH0 DI count value hi-byte |
| 30002 | 0x0001 | 1 word | CH0 DI count value lo-byte |
| 30003 | 0x0002 | 1 word | CH1 DI count value hi-byte |
| 30004 | 0x0003 | 1 word | CH1 DI count value lo-byte |
| 30005 | 0x0004 | 1 word | CH2 DI count value hi-byte |
| 30006 | 0x0005 | 1 word | CH2 DI count value lo-byte |
| 30007 | 0x0006 | 1 word | CH3 DI count value hi-byte |
| 30008 | 0x0007 | 1 word | CH3 DI count value lo-byte |
| 30009 | 0x0008 | 1 word | CH4 DI count value hi-byte |
| 30010 | 0x0009 | 1 word | CH4 DI count value lo-byte |
| 30011 | 0x000A | 1 word | CH5 DI count value hi-byte |
| 30012 | 0x000B | 1 word | CH5 DI count value lo-byte |
| 30013 | 0x000C | 1 word | CH6 DI count value hi-byte |
| 30014 | 0x000D | 1 word | CH6 DI count value lo-byte |
| 30015 | 0x000E | 1 word | CH7 DI count value hi-byte |
| 30016 | 0x000F | 1 word | CH7 DI count value lo-byte |
| 30017 | 0x0010 | 1 word | CH8 DI count value hi-byte |
| 30018 | 0x0011 | 1 word | CH8 DI count value lo-byte |
| 30019 | 0x0012 | 1 word | CH9 DI count value hi-byte |
| 30020 | 0x0013 | 1 word | CH9 DI count value lo-byte |
| 30021 | 0x0014 | 1 word | CH10 DI count value hi-byte |
| 30022 | 0x0015 | 1 word | CH10 DI count value lo-byte |
| 30023 | 0x0016 | 1 word | CH11 DI count value hi-byte |
| 30024 | 0x0017 | 1 word | CH11 DI count value lo-byte |
| 312289 | 0x3000 | 1 word | CH0 DI value |
| 312290 | 0x3001 | 1 word | CH1 DI value |
| 312291 | 0x3002 | 1 word | CH2 DI value |
| 312292 | 0x3003 | 1 word | CH3 DI value |
| 312293 | 0x3004 | 1 word | CH4 DI value |
| 312294 | 0x3005 | 1 word | CH5 DI value |
| 312295 | 0x3006 | 1 word | CH6 DI value |
| 312296 | 0x3007 | 1 word | CH7 DI value |
| 312297 | 0x3008 | 1 word | CH8 DI value |
| 312298 | 0x3009 | 1 word | CH9 DI value |
| 312299 | 0x300A | 1 word | CH10 DI value |
| 312300 | 0x300B | 1 word | CH11 DI value |

4xxxx Read/Write Registers (Functions 3, 6, 16)

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 40001 | 0x0000 | word | CH0 DO pulse output count value hi-word |
| 40002 | 0x0001 | word | CH0 DO pulse output count value lo-word |
| 40003 | 0x0002 | word | CH1 DO pulse output count value hi-word |
| 40004 | 0x0003 | word | CH1 DO pulse output count value lo- word |
| 40005 | 0x0004 | word | CH2 DO pulse output count value hi- word |
| 40006 | 0x0005 | word | CH2 DO pulse output count value lo- word |
| 40007 | 0x0006 | word | CH3 DO pulse output count value hi- word |
| 40008 | 0x0007 | word | CH3 DO pulse output count value lo- word |
| 40009 | 0x0008 | word | CH4 DO pulse output count value hi- word |
| 40010 | 0x0009 | word | CH4 DO pulse output count value lo- word |
| 40011 | 0x000A | word | CH5 DO pulse output count value hi- word |
| 40012 | 0x000B | word | CH5 DO pulse output count value lo- word |
| 40013 | 0x000C | word | CH6 DO pulse output count value hi- word |
| 40014 | 0x000D | word | CH6 DO pulse output count value lo- word |
| 40015 | 0x000E | word | CH7 DO pulse output count value hi- word |
| 40016 | 0x000F | word | CH7 DO pulse output count value lo- word |
| 40017 | 0x0010 | word | CH8 DO pulse output count value hi- word |
| 40018 | 0x0011 | word | CH8 DO pulse output count value lo- word |
| 40019 | 0x0012 | word | CH9 DO pulse output count value hi- word |
| 40020 | 0x0013 | word | CH9 DO pulse output count value lo- word |
| 40021 | 0x0014 | word | CH10 DO pulse output count value hi- word |
| 40022 | 0x0015 | word | CH10 DO pulse output count value lo- word |
| 40023 | 0x0016 | word | CH11 DO pulse output count value hi- word |
| 40024 | 0x0017 | word | CH11 DO pulse output count value lo- word |
| 40025 | 0x0018 | word | CH0 DO pulse low signal width |
| 40026 | 0x0019 | word | CH1 DO pulse low signal width |
| 40027 | 0x001A | word | CH2 DO pulse low signal width |
| 40028 | 0x001B | word | CH3 DO pulse low signal width |
| 40029 | 0x001C | word | CH4 DO pulse low signal width |
| 40030 | 0x001D | word | CH5 DO pulse low signal width |
| 40031 | 0x001E | word | CH6 DO pulse low signal width |
| 40032 | 0x001F | word | CH7 DO pulse low signal width |
| 40033 | 0x0020 | word | CH8 DO pulse low signal width |
| 40034 | 0x0021 | word | CH9 DO pulse low signal width |
| 40035 | 0x0022 | word | CH10 DO pulse low signal width |
| 40036 | 0x0023 | word | CH11 DO pulse low signal width |
| 40037 | 0x0024 | word | CH0 DO pulse high signal width |
| 40038 | 0x0025 | word | CH1 DO pulse high signal width |
| 40039 | 0x0026 | word | CH2 DO pulse high signal width |
| 40040 | 0x0027 | word | CH3 DO pulse high signal width |
| 40041 | 0x0028 | word | CH4 DO pulse high signal width |
| 40042 | 0x0029 | word | CH5 DO pulse high signal width |
| 40043 | 0x002A | word | CH6 DO pulse high signal width |
| 40044 | 0x002B | word | CH7 DO pulse high signal width |
| 40045 | 0x002C | word | CH8 DO pulse high signal width |
| 40046 | 0x002D | word | CH9 DO pulse high signal width |
| 40047 | 0x002E | word | CH10 DO pulse high signal width |
| 40048 | 0x002F | word | CH11 DO pulse high signal width |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 40049 | 0x0030 | word | CH0 DO mode 0: DO 1: pulse |
| 40050 | 0x0031 | word | CH1 DO mode 0: DO 1: pulse |
| 40051 | 0x0032 | word | CH2 DO mode 0: DO 1: pulse |
| 40052 | 0x0033 | word | CH3 DO mode 0: DO 1: pulse |
| 40053 | 0x0034 | word | CH4 DO mode 0: DO 1: pulse |
| 40054 | 0x0035 | word | CH5 DO mode 0: DO 1: pulse |
| 40055 | 0x0036 | word | CH6 DO mode 0: DO 1: pulse |
| 40056 | 0x0037 | word | CH7 DO mode 0: DO 1: pulse |
| 40057 | 0x0038 | word | CH8 DO mode 0: DO 1: pulse |
| 40058 | 0x0039 | word | CH9 DO mode 0: DO 1: pulse |
| 40059 | 0x003A | word | CH10 DO mode 0: DO 1: pulse |
| 40060 | 0x003B | word | CH11 DO mode 0: DO 1: pulse |
| 40061 | 0x003C | word | CH0 DI count filter |
| 40062 | 0x003D | word | CH1 DI count filter |
| 40063 | 0x003E | word | CH2 DI count filter |
| 40064 | 0x003F | word | CH3 DI count filter |
| 40065 | 0x0040 | word | CH4 DI count filter |
| 40066 | 0x0041 | word | CH5 DI count filter |
| 40067 | 0x0042 | word | CH6 DI count filter |
| 40068 | 0x0043 | word | CH7 DI count filter |
| 40069 | 0x0044 | word | CH8 DI count filter |
| 40070 | 0x0045 | word | CH9 DI count filter |
| 40071 | 0x0046 | word | CH10 DI count filter |
| 40072 | 0x0047 | word | CH11 DI count filter |
| 40073 | 0x0048 | word | CH0 DI mode 0: DI 1: count Other: return illegal data value |
| 40074 | 0x0049 | word | CH1 DI mode 0: DI 1: count Other: return illegal data value |
| 40075 | 0x004A | word | CH2 DI mode 0: DI 1: count Other: return illegal data value |
| 40076 | 0x004B | word | CH3 DI mode 0: DI 1: count Other: return illegal data value |

| Reference | Address | Data Type | Description |
|--|---------|-----------|---|
| 40077 | 0x004C | word | CH4 DI mode 0: DI 1: count Other: return illegal data value |
| 40078 | 0x004D | word | CH5 DI mode 0: DI 1: count Other: return illegal data value |
| 40079 | 0x004E | word | CH6 DI mode 0: DI 1: count Other: return illegal data value |
| 40080 | 0x004F | word | CH7 DI mode 0: DI 1: count Other: return illegal data value |
| 40081 | 0x0050 | word | CH8 DI mode 0: DI 1: count Other: return illegal data value |
| 40082 | 0x0051 | word | CH9 DI mode 0: DI 1: count Other: return illegal data value |
| 40083 | 0x0052 | word | CH10 DI mode 0: DI 1: count Other: return illegal data value |
| 40084 | 0x0053 | word | CH11 DI mode 0: DI 1: count Other: return illegal data value |
| For Citect SCADA compatibility, I/O data can be WORD accessed as well | | | |
| 40085 | 0x0054 | 1 word | CH0 DO value 0: off 1: on |
| 40086 | 0x0055 | 1 word | CH1 DO value 0: off 1: on |
| 40087 | 0x0056 | 1 word | CH2 DO value 0: off 1: on |
| 40088 | 0x0057 | 1 word | CH3 DO value 0: off 1: on |
| 40089 | 0x0058 | 1 word | CH4 DO value 0: off 1: on |
| 40090 | 0x0059 | 1 word | CH5 DO value 0: off 1: on |
| 40091 | 0x005A | 1 word | CH6 DO value 0: off 1: on |
| 40092 | 0x005B | 1 word | CH7 DO value 0: off 1: on |
| 40093 | 0x005C | 1 word | CH8 DO value 0: off 1: on |
| 40094 | 0x005D | 1 word | CH9 DO value 0: off 1: on |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 40095 | 0x005E | 1 word | CH10 DO value 0: off 1: on |
| 40096 | 0x005F | 1 word | CH11 DO value 0: off 1: on |
| 40097 | 0x0060 | 1 word | CH0 DO power on value 0: off 1: on |
| 40098 | 0x0061 | 1 word | CH1 DO power on value 0: off 1: on |
| 40099 | 0x0062 | 1 word | CH2 DO power on value 0: off 1: on |
| 40100 | 0x0063 | 1 word | CH3 DO power on value 0: off 1: on |
| 40101 | 0x0064 | 1 word | CH4 DO power on value 0: off 1: on |
| 40102 | 0x0065 | 1 word | CH5 DO power on value 0: off 1: on |
| 40103 | 0x0066 | 1 word | CH6 DO power on value 0: off 1: on |
| 40104 | 0x0067 | 1 word | CH7 DO power on value 0: off 1: on |
| 40105 | 0x0068 | 1 word | CH8 DO power on value 0: off 1: on |
| 40106 | 0x0069 | 1 word | CH9 DO power on value 0: off 1: on |
| 40107 | 0x006A | 1 word | CH10 DO power on value 0: off 1: on |
| 40108 | 0x006B | 1 word | CH11 DO power on value 0: off 1: on |
| 40109 | 0x006C | 1 word | CH0 DO safe mode value 0: off 1: on |
| 40110 | 0x006D | 1 word | CH1 DO safe mode value 0: off 1: on |
| 40111 | 0x006E | 1 word | CH2 DO safe mode value 0: off 1: on |
| 40112 | 0x006F | 1 word | CH3 DO safe mode value 0: off 1: on |
| 40113 | 0x0070 | 1 word | CH4 DO safe mode value 0: off 1: on |
| 40114 | 0x0071 | 1 word | CH5 DO safe mode value 0: off 1: on |
| 40115 | 0x0072 | 1 word | CH6 DO safe mode value 0: off 1: on |
| 40116 | 0x0073 | 1 word | CH7 DO safe mode value 0: off 1: on |
| 40117 | 0x0074 | 1 word | CH8 DO safe mode value 0: off 1: on |
| 40118 | 0x0075 | 1 word | CH9 DO safe mode value 0: off 1: on |
| 40119 | 0x0076 | 1 word | CH10 DO safe mode value 0: off 1: on |
| 40120 | 0x0077 | 1 word | CH11 DO safe mode value 0: off 1: on |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 40121 | 0x0078 | 1 word | CH0 DO pulse operate status 0: stop 1: start |
| 40122 | 0x0079 | 1 word | CH1 DO pulse operate status 0: stop 1: start |
| 40123 | 0x007A | 1 word | CH2 DO pulse operate status 0: stop 1: start |
| 40124 | 0x007B | 1 word | CH3 DO pulse operate status 0: stop 1: start |
| 40125 | 0x007C | 1 word | CH4 DO pulse operate status 0: stop 1: start |
| 40126 | 0x007D | 1 word | CH5 DO pulse operate status 0: stop 1: start |
| 40127 | 0x007E | 1 word | CH6 DO pulse operate status 0: stop 1: start |
| 40128 | 0x007F | 1 word | CH7 DO pulse operate status 0: stop 1: start |
| 40129 | 0x0080 | 1 word | CH8 DO pulse operate status 0: stop 1: start |
| 40130 | 0x0081 | 1 word | CH9 DO pulse operate status 0: stop 1: start |
| 40131 | 0x0082 | 1 word | CH10 DO pulse operate status 0: stop 1: start |
| 40132 | 0x0083 | 1 word | CH11 DO pulse operate status 0: stop 1: start |
| 40133 | 0x0084 | 1 word | CH0 DO power-on pulse operate status 0: stop 1: start |
| 40134 | 0x0085 | 1 word | CH1 DO power-on pulse operate status 0: stop 1: start |
| 40135 | 0x0086 | 1 word | CH2 DO power-on pulse operate status 0: stop 1: start |
| 40136 | 0x0087 | 1 word | CH3 DO power-on pulse operate status 0: stop 1: start |
| 40137 | 0x0088 | 1 word | CH4 DO power-on pulse operate status 0: stop 1: start |
| 40138 | 0x0089 | 1 word | CH5 DO power-on pulse operate status 0: stop 1: start |
| 40139 | 0x008A | 1 word | CH6 DO power-on pulse operate status 0: stop 1: start |
| 40140 | 0x008B | 1 word | CH7 DO power-on pulse operate status 0: stop 1: start |
| 40141 | 0x008C | 1 word | CH8 DO power-on pulse operate status 0: stop 1: start |
| 40142 | 0x008D | 1 word | CH9 DO power-on pulse operate status 0: stop 1: start |
| 40143 | 0x008E | 1 word | CH10 DO power-on pulse operate status 0: stop 1: start |
| 40144 | 0x008F | 1 word | CH11 DO power-on pulse operate status 0: stop 1: start |
| 40145 | 0x0090 | 1 word | CH0 DO safe mode pulse operate status 0: stop 1: start |
| 40146 | 0x0091 | 1 word | CH1 DO safe mode pulse operate status 0: stop 1: start |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 40147 | 0x0092 | 1 word | CH2 DO safe mode pulse operate status 0: stop 1: start |
| 40148 | 0x0093 | 1 word | CH3 DO safe mode pulse operate status 0: stop 1: start |
| 40149 | 0x0094 | 1 word | CH4 DO safe mode pulse operate status 0: stop 1: start |
| 40150 | 0x0095 | 1 word | CH5 DO safe mode pulse operate status 0: stop 1: start |
| 40151 | 0x0096 | 1 word | CH6 DO safe mode pulse operate status 0: stop 1: start |
| 40152 | 0x0097 | 1 word | CH7 DO safe mode pulse operate status 0: stop 1: start |
| 40153 | 0x0098 | 1 word | CH8 DO safe mode pulse operate status 0: stop 1: start |
| 40154 | 0x0099 | 1 word | CH9 DO safe mode pulse operate status 0: stop 1: start |
| 40155 | 0x009A | 1 word | CH10 DO safe mode pulse operate status 0: stop 1: start |
| 40156 | 0x009B | 1 word | CH11 DO safe mode pulse operate status 0: stop 1: start |
| 40157 | 0x009C | 1 word | CH0 DI counter operate status 0: stop 1: start |
| 40158 | 0x009D | 1 word | CH1 DI counter operate status 0: stop 1: start |
| 40159 | 0x009E | 1 word | CH2 DI counter operate status 0: stop 1: start |
| 40160 | 0x009F | 1 word | CH3 DI counter operate status 0: stop 1: start |
| 40161 | 0x00A0 | 1 word | CH4 DI counter operate status 0: stop 1: start |
| 40162 | 0x00A1 | 1 word | CH5 DI counter operate status 0: stop 1: start |
| 40163 | 0x00A2 | 1 word | CH6 DI counter operate status 0: stop 1: start |
| 40164 | 0x00A3 | 1 word | CH7 DI counter operate status 0: stop 1: start |
| 40165 | 0x00A4 | 1 word | CH8 DI counter operate status 0: stop 1: start |
| 40166 | 0x00A5 | 1 word | CH9 DI counter operate status 0: stop 1: start |
| 40167 | 0x00A6 | 1 word | CH10 DI counter operate status 0: stop 1: start |
| 40168 | 0x00A7 | 1 word | CH11 DI counter operate status 0: stop 1: start |
| 40169 | 0x00A8 | 1 word | CH0 DI clear count value Read: 0: no action Write: 1: clear counter value 0: return illegal data value(0x03) |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 40170 | 0x00A9 | 1 word | CH1 DI clear count value Read: 0: no action Write: 1: clear counter value 0: return illegal data value(0x03) |
| 40171 | 0x00AA | 1 word | CH2 DI clear count value Read: 0: no action Write: 1: clear counter value 0: return illegal data value(0x03) |
| 40172 | 0x00AB | 1 word | CH3 DI clear count value Read: 0: no action Write: 1: clear counter value 0: return illegal data value(0x03) |
| 40173 | 0x00AC | 1 word | CH4 DI clear count value Read: 0: no action Write: 1: clear counter value 0: return illegal data value(0x03) |
| 40174 | 0x00AD | 1 word | CH5 DI clear count value Read: 0: no action Write: 1: clear counter value 0: return illegal data value(0x03) |
| 40175 | 0x00AE | 1 word | CH6 DI clear count value Read: 0: no action Write: 1: clear counter value 0: return illegal data value(0x03) |
| 40176 | 0x00AF | 1 word | CH7 DI clear count value Read: 0: no action Write: 1: clear counter value 0: return illegal data value(0x03) |
| 40177 | 0x00B0 | 1 word | CH8 DI clear count value Read: 0: no action Write: 1: clear counter value 0: return illegal data value(0x03) |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 40178 | 0x00B1 | 1 word | CH9 DI clear count value Read: 0: no action Write: 1: clear counter value 0: return illegal data value(0x03) |
| 40179 | 0x00B2 | 1 word | CH10 DI clear count value Read: 0: no action Write: 1: clear counter value 0: return illegal data value (0x03) |
| 40180 | 0x00B3 | 1 word | CH11 DI clear count value Read: 0: no action Write: 1: clear counter value 0: return illegal data value (0x03) |
| 40181 | 0x00B4 | 1 word | CH0 DI overflow status Read: 0: normal 1: overflow Write : 0: clear overflow status 1: return illegal data value (0x03) |
| 40182 | 0x00B5 | 1 word | CH1 DI overflow status Read: 0: normal 1: overflow Write: 0: clear overflow status 1: return illegal data value (0x03) |
| 40183 | 0x00B6 | 1 word | CH2 DI overflow status Read: 0: normal 1: overflow Write: 0: clear overflow status 1: return illegal data value (0x03) |
| 40184 | 0x00B7 | 1 word | CH3 DI overflow status Read: 0: normal 1: overflow Write: 0: clear overflow status 1: return illegal data value (0x03) |
| 40185 | 0x00B8 | 1 word | CH4 DI overflow status Read: 0: normal 1: overflow Write: 0: clear overflow status 1: return illegal data value (0x03) |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 40186 | 0x00B9 | 1 word | CH5 DI overflow status Read: 0: normal 1: overflow Write: 0: clear overflow status 1: return illegal data value (0x03) |
| 40187 | 0x00BA | 1 word | CH6 DI overflow status Read: 0: Normal 1: Overflow Write: 0: clear overflow status 1: return illegal data value (0x03) |
| 40188 | 0x00BB | 1 word | CH7 DI overflow status Read: 0: normal 1: overflow Write: 0: clear overflow status 1: return illegal data value (0x03) |
| 40189 | 0x00BC | 1 word | CH8 DI overflow status Read: 0: normal 1: overflow Write: 0: clear overflow status 1: return illegal data value (0x03) |
| 40190 | 0x00BD | 1 word | CH9 DI overflow status Read: 0: normal 1: overflow Write: 0: clear overflow status 1: return illegal data value (0x03) |
| 40191 | 0x00BE | 1 word | CH10 DI overflow Status Read : 0: normal 1: overflow Write: 0: clear overflow status 1: return illegal data value (0x03) |
| 40192 | 0x00BF | 1 word | CH11 DI overflow status Read: 0: normal 1: overflow Write: 0: clear overflow status 1: return illegal data value (0x03) |
| 40193 | 0x00C0 | 1 word | CH0 DI counter trigger 0=low to high, 1=high to low |
| 40194 | 0x00C1 | 1 word | CH1 DI counter trigger 0=low to high, 1=high to low |
| 40195 | 0x00C2 | 1 word | CH2 DI counter trigger 0=low to high, 1=high to low |
| 40196 | 0x00C3 | 1 word | CH3 DI counter trigger 0=low to high, 1=high to low |
| 40197 | 0x00C4 | 1 word | CH4 DI counter trigger 0=low to high, 1=high to low |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 40198 | 0x00C5 | 1 word | CH5 DI counter trigger 0=low to high, 1=high to low |
| 40199 | 0x00C6 | 1 word | CH6 DI counter trigger 0=low to high, 1=high to low |
| 40200 | 0x00C7 | 1 word | CH7 DI counter trigger 0=low to high, 1=high to low |
| 40201 | 0x00C8 | 1 word | CH8 DI counter trigger 0=low to high, 1=high to low |
| 40202 | 0x00C9 | 1 word | CH9 DI counter trigger 0=low to high, 1=high to low |
| 40203 | 0x00CA | 1 word | CH10 DI counter trigger 0=low to high, 1=high to low |
| 40204 | 0x00CB | 1 word | CH11 DI counter trigger 0=low to high, 1=high to low |
| 40205 | 0x00CC | 1 word | CH0 DI power-on counter operate status 0: stop 1: start |
| 40206 | 0x00CD | 1 word | CH1 DI power-on counter operate status 0: stop 1: start |
| 40207 | 0x00CE | 1 word | CH2 DI power-on counter operate status 0: stop 1: start |
| 40208 | 0x00CF | 1 word | CH3 DI power-on counter operate status 0: stop 1: start |
| 40209 | 0x00D0 | 1 word | CH4 DI power-on counter operate status 0: stop 1: start |
| 40210 | 0x00D1 | 1 word | CH5 DI power-on counter operate status 0: stop 1: start |
| 40211 | 0x00D2 | 1 word | CH6 DI power-on counter operate status 0: stop 1: start |
| 40212 | 0x00D3 | 1 word | CH7 DI power-on counter operate status 0: stop 1: start |
| 40213 | 0x00D4 | 1 word | CH8 DI power-on counter operate status 0: stop 1: start |
| 40214 | 0x00D5 | 1 word | CH9 DI power-on counter operate status 0: stop 1: start |
| 40215 | 0x00D6 | 1 word | CH10 DI power-on counter operate status 0: stop 1: start |
| 40216 | 0x00D7 | 1 word | CH11 DI power-on counter operate status 0: stop 1: start |
| 40217 | 0x00D8 | 1 word | CH0 DI safe mode counter operate status 0: stop 1: start |
| 40218 | 0x00D9 | 1 word | CH1 DI safe mode counter operate status 0: stop 1: start |
| 40219 | 0x00DA | 1 word | CH2 DI safe mode counter operate status 0: stop 1: start |
| 40220 | 0x00DB | 1 word | CH3 DI safe mode counter operate status 0: stop 1: start |
| 40221 | 0x00DC | 1 word | CH4 DI safe mode counter operate status 0: stop 1: start |
| 40222 | 0x00DD | 1 word | CH5 DI safe mode counter operate status 0: stop 1: start |
| 40223 | 0x00DE | 1 word | CH6 DI safe mode counter operate status 0: stop 1: start |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 40224 | 0x00DF | 1 word | CH7 DI safe mode counter operate status 0: stop 1: start |
| 40225 | 0x00E0 | 1 word | CH8 DI safe mode counter operate status 0: stop 1: start |
| 40226 | 0x00E1 | 1 word | CH9 DI safe mode counter operate status 0: stop 1: start |
| 40227 | 0x00E2 | 1 word | CH10 DI safe mode counter operate status 0: stop 1: start |
| 40228 | 0x00E3 | 1 word | CH11 DI safe mode counter operate status 0: stop 1: start |
| 40229 | 0x00E4 | 1 word | CH0 DI set channel Power-off storage enable ON/OFF 1: on 0: off |
| 40230 | 0x00E5 | 1 word | CH1 DI set channel Power-off storage enable ON/OFF 1: on 0: off |
| 40231 | 0x00E6 | 1 word | CH2 DI set channel Power-off storage enable ON/OFF 1: on 0: off |
| 40232 | 0x00E7 | 1 word | CH3 DI set channel Power-off storage enable ON/OFF 1: on 0: off |
| 40233 | 0x00E8 | 1 word | CH4 DI set channel Power-off storage enable ON/OFF 1: on 0: off |
| 40234 | 0x00E9 | 1 word | CH5 DI set channel Power-off storage enable ON/OFF 1: on 0: off |
| 40235 | 0x00EA | 1 word | CH6 DI set channel Power-off storage enable ON/OFF 1: on 0: off |
| 40236 | 0x00EB | 1 word | CH7 DI set channel Power-off storage enable ON/OFF 1: on 0: off |
| 40237 | 0x00EC | 1 word | CH8 DI set channel Power-off storage enable ON/OFF 1: on 0: off |
| 40238 | 0x00ED | 1 word | CH9 DI set channel Power-off storage enable ON/OFF 1: on 0: off |
| 40239 | 0x00EE | 1 word | CH10 DI set channel Power-off storage enable ON/OFF 1: on 0: off |
| 40240 | 0x00EF | 1 word | CH11 DI set channel Power-off storage enable ON/OFF 1: on 0: off |
| 40241 | 0x00F0 | 1 word | DIO 0 1: output DO mode 0: input DI mode |
| 40242 | 0x00F1 | 1 word | DIO 1 1: output DO mode 0: input DI mode |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 40243 | 0x00F2 | 1 word | DIO 2 1: output DO mode 0: input DI mode |
| 40244 | 0x00F3 | 1 word | DIO 3 1: output DO mode 0: input DI mode |
| 40377 | 0x0178 | word | Internal Register 00 Initial Value |
| 40378 | 0x0179 | word | Internal Register 01 Initial Value |
| 40379 | 0x017A | word | Internal Register 02 Initial Value |
| 40380 | 0x017B | word | Internal Register 03 Initial Value |
| 40381 | 0x017C | word | Internal Register 04 Initial Value |
| 40382 | 0x017D | word | Internal Register 05 Initial Value |
| 40383 | 0x017E | word | Internal Register 06 Initial Value |
| 40384 | 0x017F | word | Internal Register 07 Initial Value |
| 40385 | 0x0180 | word | Internal Register 08 Initial Value |
| 40386 | 0x0181 | word | Internal Register 09 Initial Value |
| 40387 | 0x0182 | word | Internal Register 10 Initial Value |
| 40388 | 0x0183 | word | Internal Register 11 Initial Value |
| 40389 | 0x0184 | word | Internal Register 12 Initial Value |
| 40390 | 0x0185 | word | Internal Register 13 Initial Value |
| 40391 | 0x0186 | word | Internal Register 14 Initial Value |
| 40392 | 0x0187 | word | Internal Register 15 Initial Value |
| 40393 | 0x0188 | word | Internal Register 16 Initial Value |
| 40394 | 0x0189 | word | Internal Register 17 Initial Value |
| 40395 | 0x018A | word | Internal Register 18 Initial Value |
| 40396 | 0x018B | word | Internal Register 19 Initial Value |
| 40397 | 0x018C | word | Internal Register 20 Initial Value |
| 40398 | 0x018D | word | Internal Register 21 Initial Value |
| 40399 | 0x018E | word | Internal Register 22 Initial Value |
| 40400 | 0x018F | word | Internal Register 23 Initial Value |
| 42921 | 0x0B68 | word | Internal Register 00 Working Value |
| 42922 | 0x0B69 | word | Internal Register 01 Working Value |
| 42923 | 0x0B6A | word | Internal Register 02 Working Value |
| 42924 | 0x0B6B | word | Internal Register 03 Working Value |
| 42925 | 0x0B6C | word | Internal Register 04 Working Value |
| 42926 | 0x0B6D | word | Internal Register 05 Working Value |
| 42927 | 0x0B6E | word | Internal Register 06 Working Value |
| 42928 | 0x0B6F | word | Internal Register 07 Working Value |
| 42929 | 0x0B70 | word | Internal Register 08 Working Value |
| 42930 | 0x0B71 | word | Internal Register 09 Working Value |
| 42931 | 0x0B72 | word | Internal Register 10 Working Value |
| 42932 | 0x0B73 | word | Internal Register 11 Working Value |
| 42933 | 0x0B74 | word | Internal Register 12 Working Value |
| 42934 | 0x0B75 | word | Internal Register 13 Working Value |
| 42935 | 0x0B76 | word | Internal Register 14 Working Value |
| 42936 | 0x0B77 | word | Internal Register 15 Working Value |
| 42937 | 0x0B78 | word | Internal Register 16 Working Value |
| 42938 | 0x0B79 | word | Internal Register 17 Working Value |
| 42939 | 0x0B7A | word | Internal Register 18 Working Value |
| 42940 | 0x0B7B | word | Internal Register 19 Working Value |
| 42941 | 0x0B7C | word | Internal Register 20 Working Value |
| 42942 | 0x0B7D | word | Internal Register 21 Working Value |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|------------------------------------|
| 42943 | 0x0B7E | word | Internal Register 22 Working Value |
| 42944 | 0x0B7F | word | Internal Register 23 Working Value |
| 43329 | 0x0D00 | 2 word | CH0 DI - Counter mode value |
| 43330 | 0x0D01 | 2 word | CH1 DI - Counter mode value |
| 43331 | 0x0D02 | 2 word | CH2 DI - Counter mode value |
| 43332 | 0x0D03 | 2 word | CH3 DI - Counter mode value |
| 43333 | 0x0D04 | 2 word | CH4 DI - Counter mode value |
| 43334 | 0x0D05 | 2 word | CH5 DI - Counter mode value |
| 43335 | 0x0D06 | 2 word | CH6 DI - Counter mode value |
| 43336 | 0x0D07 | 2 word | CH7 DI - Counter mode value |
| 43337 | 0x0D08 | 2 word | CH8 DI - Counter mode value |
| 43338 | 0x0D09 | 2 word | CH9 DI - Counter mode value |
| 43339 | 0x0D0A | 2 word | CH10 DI - Counter mode value |
| 43340 | 0x0D0B | 2 word | CH11 DI - Counter mode value |

ioLogik E2214 Modbus Mapping

0xxxx Read/Write Coils (Support Functions 1, 5, 15)

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 00001 | 0x0000 | 1 bit | CH0 DO Value 0: Off 1: On |
| 00002 | 0x0001 | 1 bit | CH1 DO Value 0: Off 1: On |
| 00003 | 0x0002 | 1 bit | CH2 DO Value 0: Off 1: On |
| 00004 | 0x0003 | 1 bit | CH3 DO Value 0: Off 1: On |
| 00005 | 0x0004 | 1 bit | CH4 DO Value 0: Off 1: On |
| 00006 | 0x0005 | 1 bit | CH5 DO Value 0: Off 1: On |
| 00007 | 0x0006 | 1 bit | CH0 DO Power On Value 0: Off 1: On |
| 00008 | 0x0007 | 1 bit | CH1 DO Power On Value 0: Off 1: On |
| 00009 | 0x0008 | 1 bit | CH2 DO Power On Value 0: Off 1: On |
| 00010 | 0x0009 | 1 bit | CH3 DO Power On Value 0: Off 1: On |
| 00011 | 0x000A | 1 bit | CH4 DO Power On Value 0: Off 1: On |
| 00012 | 0x000B | 1 bit | CH5 DO Power On Value 0: Off 1: On |
| 00013 | 0x000C | 1 bit | CH0 DO Pulse Operate Status 0: Off 1: On |
| 00014 | 0x000D | 1 bit | CH1 DO Pulse Operate Status 0: Off 1: On |
| 00015 | 0x000E | 1 bit | CH2 DO Pulse Operate Status 0: Off 1: On |
| 00016 | 0x000F | 1 bit | CH3 DO Pulse Operate Status 0: Off 1: On |
| 00017 | 0x0010 | 1 bit | CH4 DO Pulse Operate Status 0: Off 1: On |
| 00018 | 0x0011 | 1 bit | CH5 DO Pulse Operate Status 0: Off 1: On |
| 00019 | 0x0012 | 1 bit | CH0 DO PowerOn Pulse Operate Status 0: Off 1: On |
| 00020 | 0x0013 | 1 bit | CH1 DO PowerOn Pulse Operate Status 0: Off 1: On |
| 00021 | 0x0014 | 1 bit | CH2 DO PowerOn Pulse Operate Status 0: Off 1: On |
| 00022 | 0x0015 | 1 bit | CH3 DO PowerOn Pulse Operate Status 0: Off 1: On |
| 00023 | 0x0016 | 1 bit | CH4 DO PowerOn Pulse Operate Status 0: Off 1: On |
| 00024 | 0x0017 | 1 bit | CH5 DO PowerOn Pulse Operate Status 0: Off 1: On |
| 00025 | 0x0018 | 1 bit | CH0 DO Safe Pulse Operate Status 0: Off 1: On |
| 00026 | 0x0019 | 1 bit | CH1 DO Safe Pulse Operate Status 0: Off 1: On |
| 00027 | 0x001A | 1 bit | CH2 DO Safe Pulse Operate Status 0: Off 1: On |
| 00028 | 0x001B | 1 bit | CH3 DO Safe Pulse Operate Status 0: Off 1: On |
| 00029 | 0x001C | 1 bit | CH4 DO Safe Pulse Operate Status 0: Off 1: On |
| 00030 | 0x001D | 1 bit | CH5 DO Safe Pulse Operate Status 0: Off 1: On |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 00054 | 0x0035 | 1 bit | CH5 DI Count Trigger |
| 00055 | 0x0036 | 1 bit | CH0 DI PowerOn Status 0: Off 1: On |
| 00056 | 0x0037 | 1 bit | CH1 DI PowerOn Status 0: Off 1: On |
| 00057 | 0x0038 | 1 bit | CH2 DI PowerOn Status 0: Off 1: On |
| 00058 | 0x0039 | 1 bit | CH3 DI PowerOn Status 0: Off 1: On |
| 00059 | 0x003A | 1 bit | CH4 DI PowerOn Status 0: Off 1: On |
| 00060 | 0x003B | 1 bit | CH5 DI PowerOn Status 0: Off 1: On |
| 00061 | 0x003C | 1 bit | CH0 DI Safe Pulse Operate Status 0: Off 1: On |
| 00062 | 0x003D | 1 bit | CH1 DI Safe Pulse Operate Status 0: Off 1: On |
| 00063 | 0x003E | 1 bit | CH2 DI Safe Pulse Operate Status 0: Off 1: On |
| 00064 | 0x003F | 1 bit | CH3 DI Safe Pulse Operate Status 0: Off 1: On |
| 00065 | 0x0040 | 1 bit | CH4 DI Safe Pulse Operate Status 0: Off 1: On |
| 00066 | 0x0041 | 1 bit | CH5 DI Safe Pulse Operate Status 0: Off 1: On |
| 00067 | 0x0042 | 1 bit | CH0 DI set channel Power-off storage enable ON/OFF 1:ON 0:OFF |
| 00068 | 0x0043 | 1 bit | CH1 DI set channel Power-off storage enable ON/OFF 1:ON 0:OFF |
| 00069 | 0x0044 | 1 bit | CH2 DI set channel Power-off storage enable ON/OFF 1:ON 0:OFF |
| 00070 | 0x0045 | 1 bit | CH3 DI set channel Power-off storage enable ON/OFF 1:ON 0:OFF |
| 00071 | 0x0046 | 1 bit | CH4 DI set channel Power-off storage enable ON/OFF 1:ON 0:OFF |
| 00072 | 0x0047 | 1 bit | CH5 DI set channel Power-off storage enable ON/OFF 1:ON 0:OFF |

1xxxx Read Only Coils (Function 2)

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--------------|
| 10001 | 0x0000 | 1 bit | CH0 DI Value |
| 10002 | 0x0001 | 1 bit | CH1 DI Value |
| 10003 | 0x0002 | 1 bit | CH2 DI Value |
| 10004 | 0x0003 | 1 bit | CH3 DI Value |
| 10005 | 0x0004 | 1 bit | CH4 DI Value |
| 10006 | 0x0005 | 1 bit | CH5 DI Value |

3xxxx Read Only Registers (Function 4)

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 30001 | 0x0000 | 1 word | CH0 DI Count Value Hi-Byte |
| 30002 | 0x0001 | 1 word | CH0 DI Count Value Lo-Byte |
| 30003 | 0x0002 | 1 word | CH1 DI Count Value Hi-Byte |
| 30004 | 0x0003 | 1 word | CH1 DI Count Value Lo-Byte |
| 30005 | 0x0004 | 1 word | CH2 DI Count Value Hi-Byte |
| 30006 | 0x0005 | 1 word | CH2 DI Count Value Lo-Byte |
| 30007 | 0x0006 | 1 word | CH3 DI Count Value Hi-Byte |
| 30008 | 0x0007 | 1 word | CH3 DI Count Value Lo-Byte |
| 30009 | 0x0008 | 1 word | CH4 DI Count Value Hi-Byte |
| 30010 | 0x0009 | 1 word | CH4 DI Count Value Lo-Byte |
| 30011 | 0x000A | 1 word | CH5 DI Count Value Hi-Byte |
| 30012 | 0x000B | 1 word | CH5 DI Count Value Lo-Byte |
| 30013 | 0x000C | 1 word | CH0 DO Totoal Relay Count Value Hi-Byte |
| 30014 | 0x000D | 1 word | CH0 DO Totoal Relay Count Value Lo-Byte |
| 30015 | 0x000E | 1 word | CH1 DO Totoal Relay Count Value Hi-Byte |
| 30016 | 0x000F | 1 word | CH1 DO Totoal Relay Count Value Lo-Byte |
| 30017 | 0x0010 | 1 word | CH2 DO Totoal Relay Count Value Hi-Byte |
| 30018 | 0x0011 | 1 word | CH2 DO Totoal Relay Count Value Lo-Byte |
| 30019 | 0x0012 | 1 word | CH3 DO Totoal Relay Count Value Hi-Byte |
| 30020 | 0x0013 | 1 word | CH3 DO Totoal Relay Count Value Lo-Byte |
| 30021 | 0x0014 | 1 word | CH4 DO Totoal Relay Count Value Hi-Byte |
| 30022 | 0x0015 | 1 word | CH4 DO Totoal Relay Count Value Lo-Byte |
| 30023 | 0x0016 | 1 word | CH5 DO Totoal Relay Count Value Hi-Byte |
| 30024 | 0x0017 | 1 word | CH5 DO Totoal Relay Count Value Lo-Byte |
| 30025 | 0x0018 | 1 word | CH0 DO Last Reset Time for Current Relay Count Sec Value |
| 30026 | 0x0019 | 1 word | CH0 DO Last Reset Time for Current Relay Count Min Value |
| 30027 | 0x001A | 1 word | CH0 DO Last Reset Time for Current Relay Count Hour Value |
| 30028 | 0x001B | 1 word | CH0 DO Last Reset Time for Current Relay Count Mday Value |
| 30029 | 0x001C | 1 word | CH0 DO Last Reset Time for Current Relay Count Month Value |
| 30030 | 0x001D | 1 word | CH0 DO Last Reset Time for Current Relay Count Year Value |
| 30031 | 0x001E | 1 word | CH1 DO Last Reset Time for Current Relay Count Sec Value |
| 30032 | 0x001F | 1 word | CH1 DO Last Reset Time for Current Relay Count Min Value |
| 30033 | 0x0020 | 1 word | CH1 DO Last Reset Time for Current Relay Count Hour Value |
| 30034 | 0x0021 | 1 word | CH1DO Last Reset Time for Current Relay Count Mday Value |
| 30035 | 0x0022 | 1 word | CH1 DO Last Reset Time for Current Relay Count Month Value |
| 30036 | 0x0023 | 1 word | CH1 DO Last Reset Time for Current Relay Count Year Value |
| 30037 | 0x0024 | 1 word | CH2 DO Last Reset Time for Current Relay Count Sec Value |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 30038 | 0x0025 | 1 word | CH2DO Last Reset Time for Current Relay Count Min Value |
| 30039 | 0x0026 | 1 word | CH2 DO Last Reset Time for Current Relay Count Hour Value |
| 30040 | 0x0027 | 1 word | CH2 DO Last Reset Time for Current Relay Count Mday Value |
| 30041 | 0x0028 | 1 word | CH2 DO Last Reset Time for Current Relay Count Month Value |
| 30042 | 0x0029 | 1 word | CH2 DO Last Reset Time for Current Relay Count Year Value |
| 30043 | 0x002A | 1 word | CH3 DO Last Reset Time for Current Relay Count Sec Value |
| 30044 | 0x002B | 1 word | CH3 DO Last Reset Time for Current Relay Count Min Value |
| 30045 | 0x002C | 1 word | CH3DO Last Reset Time for Current Relay Count Hour Value |
| 30046 | 0x002D | 1 word | CH3 DO Last Reset Time for Current Relay Count Mday Value |
| 30047 | 0x002E | 1 word | CH3DO Last Reset Time for Current Relay Count Month Value |
| 30048 | 0x002F | 1 word | CH3 DO Last Reset Time for Current Relay Count Year Value |
| 30049 | 0x0030 | 1 word | CH4 DO Last Reset Time for Current Relay Count Sec Value |
| 30050 | 0x0031 | 1 word | CH4 DO Last Reset Time for Current Relay Count Min Value |
| 30051 | 0x0032 | 1 word | CH4 DO Last Reset Time for Current Relay Count Hour Value |
| 30052 | 0x0033 | 1 word | CH4 DO Last Reset Time for Current Relay Count Mday Value |
| 30053 | 0x0034 | 1 word | CH4 DO Last Reset Time for Current Relay Count Month Value |
| 30054 | 0x0035 | 1 word | CH4 DO Last Reset Time for Current Relay Count Year Value |
| 30055 | 0x0036 | 1 word | CH5 DO Last Reset Time for Current Relay Count Sec Value |
| 30056 | 0x0037 | 1 word | CH5 DO Last Reset Time for Current Relay Count Min Value |
| 30057 | 0x0038 | 1 word | CH5 DO Last Reset Time for Current Relay Count Hour Value |
| 30058 | 0x0039 | 1 word | CH5 DO Last Reset Time for Current Relay Count Mday Value |
| 30059 | 0x003A | 1 word | CH5 DO Last Reset Time for Current Relay Count Month Value |
| 30060 | 0x003B | 1 word | CH5 DO Last Reset Time for Current Relay Count Year Value |
| 312289 | 0x3000 | 1 word | CH0 DI Value (low byte) |
| 312290 | 0x3001 | 1 word | CH1 DI Value (low byte) |
| 312291 | 0x3002 | 1 word | CH2 DI Value (low byte) |
| 312292 | 0x3003 | 1 word | CH3 DI Value (low byte) |
| 312293 | 0x3004 | 1 word | CH4 DI Value (low byte) |
| 312294 | 0x3005 | 1 word | CH5 DI Value (low byte) |

4xxxx Read/Write Registers (Functions 3, 6, 16)

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 40001 | 0x0000 | word | CH0 DO Pulse Output Count Value Hi-Word |
| 40002 | 0x0001 | word | CH0 DO Pulse Output Count Value Lo-Word |
| 40003 | 0x0002 | word | CH1 DO Pulse Output Count Value Hi-Word |
| 40004 | 0x0003 | word | CH1 DO Pulse Output Count Value Lo- Word |
| 40005 | 0x0004 | word | CH2 DO Pulse Output Count Value Hi- Word |
| 40006 | 0x0005 | word | CH2 DO Pulse Output Count Value Lo- Word |
| 40007 | 0x0006 | word | CH3 DO Pulse Output Count Value Hi- Word |
| 40008 | 0x0007 | word | CH3 DO Pulse Output Count Value Lo- Word |
| 40009 | 0x0008 | word | CH4 DO Pulse Output Count Value Hi- Word |
| 40010 | 0x0009 | word | CH4 DO Pulse Output Count Value Lo- Word |
| 40011 | 0x000A | word | CH5 DO Pulse Output Count Value Hi- Word |
| 40012 | 0x000B | word | CH5 DO Pulse Output Count Value Lo- Word |
| 40013 | 0x000C | word | CH0 DO Pulse Low Signal Width |
| 40014 | 0x000D | word | CH1 DO Pulse Low Signal Width |
| 40015 | 0x000E | word | CH2 DO Pulse Low Signal Width |
| 40016 | 0x000F | word | CH3 DO Pulse Low Signal Width |
| 40017 | 0x0010 | word | CH4 DO Pulse Low Signal Width |
| 40018 | 0x0011 | word | CH5 DO Pulse Low Signal Width |
| 40019 | 0x0012 | word | CH0 DO Pulse High Signal Width |
| 40020 | 0x0013 | word | CH1 DO Pulse High Signal Width |
| 40021 | 0x0014 | word | CH2 DO Pulse High Signal Width |
| 40022 | 0x0015 | word | CH3 DO Pulse High Signal Width |
| 40023 | 0x0016 | word | CH4 DO Pulse High Signal Width |
| 40024 | 0x0017 | word | CH5 DO Pulse High Signal Width |
| 40025 | 0x0018 | word | CH0 DO Mode 0: DO 1: Pulse |
| 40026 | 0x0019 | word | CH1 DO Mode 0: DO 1: Pulse |
| 40027 | 0x001A | word | CH2 DO Mode 0: DO 1: Pulse |
| 40028 | 0x001B | word | CH3 DO Mode 0: DO 1: Pulse |
| 40029 | 0x001C | word | CH4 DO Mode 0: DO 1: Pulse |
| 40030 | 0x001D | word | CH5 DO Mode 0: DO 1: Pulse |
| 40031 | 0x001E | word | CH0 DI Count Filter |
| 40032 | 0x001F | word | CH1 DI Count Filter |
| 40033 | 0x0020 | word | CH2 DI Count Filter |
| 40034 | 0x0021 | word | CH3 DI Count Filter |
| 40035 | 0x0022 | word | CH4 DI Count Filter |
| 40036 | 0x0023 | word | CH5 DI Count Filter |
| 40037 | 0x0024 | word | CH0 DI Mode 0: DI 1: Count Others : return Illegal Data Value |
| 40038 | 0x0025 | word | CH1 DI Mode 0: DI 1: Count Others : return Illegal Data Value |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 40039 | 0x0026 | word | CH2 DI Mode 0: DI 1: Count Others : return Illegal Data Value |
| 40040 | 0x0027 | word | CH3 DI Mode 0: DI 1: Count Others : return Illegal Data Value |
| 40041 | 0x0028 | word | CH4 DI Mode 0: DI 1: Count Others : return Illegal Data Value |
| 40042 | 0x0029 | word | CH5 DI Mode 0: DI 1: Count Others : return Illegal Data Value |
| 40043 | 0x002A | 1 word | CH0 DO Value 0: Off 1: On |
| 40044 | 0x002B | 1 word | CH1 DO Value 0: Off 1: On |
| 40045 | 0x002C | 1 word | CH2 DO Value 0: Off 1: On |
| 40046 | 0x002D | 1 word | CH3 DO Value 0: Off 1: On |
| 40047 | 0x002E | 1 word | CH4 DO Value 0: Off 1: On |
| 40048 | 0x002F | 1 word | CH5 DO Value 0: Off 1: On |
| 40049 | 0x0030 | 1 word | CH0 DO Power On Value 0: Off 1: On |
| 40050 | 0x0031 | 1 word | CH1 DO Power On Value 0: Off 1: On |
| 40051 | 0x0032 | 1 word | CH2 DO Power On Value 0: Off 1: On |
| 40052 | 0x0033 | 1 word | CH3 DO Power On Value 0: Off 1: On |
| 40053 | 0x0034 | 1 word | CH4 DO Power On Value 0: Off 1: On |
| 40054 | 0x0035 | 1 word | CH5 DO Power On Value 0: Off 1: On |
| 40055 | 0x0036 | 1 word | CH0 DO Safe Mode Value 0: Off 1: On 2: Hold Last |
| 40056 | 0x0037 | 1 word | CH1 DO Safe Mode Value 0: Off 1: On 2: Hold Last |
| 40057 | 0x0038 | 1 word | CH2 DO Safe Mode Value 0: Off 1: On 2: Hold Last |
| 40058 | 0x0039 | 1 word | CH3 DO Safe Mode Value 0: Off 1: On 2: Hold Last |
| 40059 | 0x003A | 1 word | CH4 DO Safe Mode Value 0: Off 1: On 2: Hold Last |
| 40060 | 0x003B | 1 word | CH5 DO Safe Mode Value 0: Off 1: On 2: Hold Last |
| 40061 | 0x003C | 1 word | CH0 DO Pulse Operate Status 0: Stop 1: Start |
| 40062 | 0x003D | 1 word | CH1 DO Pulse Operate Status 0: Stop 1: Start |
| 40063 | 0x003E | 1 word | CH2 DO Pulse Operate Status 0: Stop 1: Start |
| 40064 | 0x003F | 1 word | CH3 DO Pulse Operate Status 0: Stop 1: Start |
| 40065 | 0x0040 | 1 word | CH4 DO Pulse Operate Status 0: Stop 1: Start |
| 40066 | 0x0041 | 1 word | CH5 DO Pulse Operate Status 0: Stop 1: Start |
| 40067 | 0x0042 | 1 word | CH0 DO PowerOn Pulse Operate Status 0: Stop 1: Start |
| 40068 | 0x0043 | 1 word | CH1 DO PowerOn Pulse Operate Status 0: Stop 1: Start |
| 40069 | 0x0044 | 1 word | CH2 DO PowerOn Pulse Operate Status 0: Stop 1: Start |
| 40070 | 0x0045 | 1 word | CH3 DO PowerOn Pulse Operate Status 0: Stop 1: Start |
| 40071 | 0x0046 | 1 word | CH4 DO PowerOn Pulse Operate Status 0: Stop 1: Start |
| 40072 | 0x0047 | 1 word | CH5 DO PowerOn Pulse Operate Status 0: Stop 1: Start |
| 40073 | 0x0048 | 1 word | CH0 DO Safe Mode Pulse Operate Status 0: Stop 1: Start |
| 40074 | 0x0049 | 1 word | CH1 DO Safe Mode Pulse Operate Status 0: Stop 1: Start |
| 40075 | 0x004A | 1 word | CH2 DO Safe Mode Pulse Operate Status 0: Stop 1: Start |
| 40076 | 0x004B | 1 word | CH3 DO Safe Mode Pulse Operate Status 0: Stop 1: Start |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 40077 | 0x004C | 1 word | CH4 DO Safe Mode Pulse Operate Status 0: Stop 1: Start |
| 40078 | 0x004D | 1 word | CH5 DO Safe Mode Pulse Operate Status 0: Stop 1: Start |
| 40079 | 0x004E | 1 word | CH0 DI Counter Operate Status 0: Stop 1: Start |
| 40080 | 0x004F | 1 word | CH1 DI Counter Operate Status 0: Stop 1: Start |
| 40081 | 0x0050 | 1 word | CH2 DI Counter Operate Status 0: Stop 1: Start |
| 40082 | 0x0051 | 1 word | CH3 DI Counter Operate Status 0: Stop 1: Start |
| 40083 | 0x0052 | 1 word | CH4 DI Counter Operate Status 0: Stop 1: Start |
| 40084 | 0x0053 | 1 word | CH5 DI Counter Operate Status 0: Stop 1: Start |
| 40085 | 0x0054 | 1 word | CH0 DI Clear Count Value Read: always return: 0 Write: 1 : Clear counter value 0 : Return illegal data value(0x03) |
| 40086 | 0x0055 | 1 word | CH1 DI Clear Count Value Read: always return: 0 Write: 1 : Clear counter value 0 : Return illegal data value(0x03) |
| 40087 | 0x0056 | 1 word | CH2 DI Clear Count Value Read always return: 0 Write: 1 : Clear counter value 0 : Return illegal data value(0x03) |
| 40088 | 0x0057 | 1 word | CH3 DI Clear Count Value Read: always return: 0 Write: 1 : Clear counter value 0 : Return illegal data value(0x03) |
| 40089 | 0x0058 | 1 word | CH4 DI Clear Count Value Read: always return: 0 Write: 1 : Clear counter value 0 : Return illegal data value(0x03) |
| 40090 | 0x0059 | 1 word | CH5 DI Clear Count Value Read: always return: 0 Write: 1 : Clear counter value 0 : Return illegal data value(0x03) |
| 40091 | 0x005A | 1 word | CH0 DI OverFlow Status Read: 0 : Normal 1 : Overflow Write: 0 : Clear overflow status 1 : Return illegal data value (0x03) |
| 40092 | 0x005B | 1 word | CH1 DI OverFlow Status Read: 0 : Normal 1 : Overflow Write: 0 : Clear overflow status 1 : Return illegal data value (0x03) |
| 40093 | 0x005C | 1 word | CH2 DI OverFlow Status Read: 0 : Normal 1 : Overflow Write: 0 : Clear overflow status 1 : Return illegal data value (0x03) |
| 40094 | 0x005D | 1 word | CH3 DI OverFlow Status Read: 0 : Normal 1 : Overflow Write: 0 : Clear overflow status 1 : Return illegal data value (0x03) |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 40095 | 0x005E | 1 word | CH4 DI OverFlow Status Read: 0 : Normal 1 : Overflow Write: 0 : Clear overflow status 1 : Return illegal data value (0x03) |
| 40096 | 0x005F | 1 word | CH5 DI OverFlow Status Read: 0 : Normal 1 : Overflow Write: 0 : Clear overflow status 1 : Return illegal data value (0x03) |
| 40097 | 0x0060 | 1 word | CH0 DI Counter Trigger, 0=Low to High, 1=High to Low |
| 40098 | 0x0061 | 1 word | CH1 DI Counter Trigger, 0=Low to High, 1=High to Low |
| 40099 | 0x0062 | 1 word | CH2 DI Counter Trigger, 0=Low to High, 1=High to Low |
| 40100 | 0x0063 | 1 word | CH3 DI Counter Trigger, 0=Low to High, 1=High to Low |
| 40101 | 0x0064 | 1 word | CH4 DI Counter Trigger, 0=Low to High, 1=High to Low |
| 40102 | 0x0065 | 1 word | CH5 DI Counter Trigger, 0=Low to High, 1=High to Low |
| 40103 | 0x0066 | 1 word | CH0 DI PowerOn Counter Operate Status 0: Stop 1: Start |
| 40104 | 0x0067 | 1 word | CH1 DI PowerOn Counter Operate Status 0: Stop 1: Start |
| 40105 | 0x0068 | 1 word | CH2 DI PowerOn Counter Operate Status 0: Stop 1: Start |
| 40106 | 0x0069 | 1 word | CH3 DI PowerOn Counter Operate Status 0: Stop 1: Start |
| 40107 | 0x006A | 1 word | CH4 DI PowerOn Counter Operate Status 0: Stop 1: Start |
| 40108 | 0x006B | 1 word | CH5 DI PowerOn Counter Operate Status 0: Stop 1: Start |
| 40109 | 0x006C | 1 word | CH0 DI Safe Mode Counter Operate Status 0: Stop 1: Start |
| 40110 | 0x006D | 1 word | CH1 DI Safe Mode Counter Operate Status 0: Stop 1: Start |
| 40111 | 0x006E | 1 word | CH2 DI Safe Mode Counter Operate Status 0: Stop 1: Start |
| 40112 | 0x006F | 1 word | CH3 DI Safe Mode Counter Operate Status 0: Stop 1: Start |
| 40113 | 0x0070 | 1 word | CH4 DI Safe Mode Counter Operate Status 0: Stop 1: Start |
| 40114 | 0x0071 | 1 word | CH5 DI Safe Mode Counter Operate Status 0: Stop 1: Start |
| 40115 | 0x0072 | 1 Word | CH0 DI set channel Power-off storage enable ON/OFF 1:ON 0:OFF |
| 40116 | 0x0073 | 1 Word | CH1 DI set channel Power-off storage enable ON/OFF 1:ON 0:OFF |
| 40117 | 0x0074 | 1 Word | CH2 DI set channel Power-off storage enable ON/OFF 1:ON 0:OFF |
| 40118 | 0x0075 | 1 Word | CH3 DI set channel Power-off storage enable ON/OFF 1:ON 0:OFF |
| 40119 | 0x0076 | 1 Word | CH4 DI set channel Power-off storage enable ON/OFF 1:ON 0:OFF |
| 40120 | 0x0077 | 1 Word | CH5 DI set channel Power-off storage enable ON/OFF 1:ON 0:OFF |
| 40121 | 0x0078 | 1 Word | CH0 DO Current Relay Count Value Hi-Byte |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 40122 | 0x0079 | 1 Word | CH0 DO Current Relay Count Value Lo-Byte |
| 40123 | 0x007A | 1 Word | CH1 DO Current Relay Count Value Hi-Byte |
| 40124 | 0x007B | 1 Word | CH1 DO Current Relay Count Value Lo-Byte |
| 40125 | 0x007C | 1 Word | CH2 DO Current Relay Count Value Hi-Byte |
| 40126 | 0x007D | 1 Word | CH2 DO Current Relay Count Value Lo-Byte |
| 40127 | 0x007E | 1 Word | CH3 DO Current Relay Count Value Hi-Byte |
| 40128 | 0x007F | 1 Word | CH3 DO Current Relay Count Value Lo-Byte |
| 40129 | 0x0080 | 1 Word | CH4 DO Current Relay Count Value Hi-Byte |
| 40130 | 0x0081 | 1 Word | CH4 DO Current Relay Count Value Lo-Byte |
| 40131 | 0x0082 | 1 Word | CH5 DO Current Relay Count Value Hi-Byte |
| 40132 | 0x0083 | 1 Word | CH5 DO Current Relay Count Value Lo-Byte |
| 40133 | 0x0084 | 1 Word | Power On Sequence CH0 DO Delay time (MAX 300 Seconds) |
| 40134 | 0x0085 | 1 Word | Power On Sequence CH1 DO Delay time(MAX 300 Seconds) |
| 40135 | 0x0086 | 1 Word | Power On Sequence CH2 DO Delay time(MAX 300 Seconds) |
| 40136 | 0x0087 | 1 Word | Power On Sequence CH3 DO Delay time(MAX 300 Seconds) |
| 40137 | 0x0088 | 1 Word | Power On Sequence CH4 DO Delay time(MAX 300 Seconds) |
| 40138 | 0x0089 | 1 Word | Power On Sequence CH5 DO Delay time(MAX 300 Seconds) |
| 40377 | 0x0178 | 1 Word | Internal Register 00 Initial Value |
| 40378 | 0x0179 | 1 Word | Internal Register 01 Initial Value |
| 40379 | 0x017A | 1 Word | Internal Register 02 Initial Value |
| 40380 | 0x017B | 1 Word | Internal Register 03 Initial Value |
| 40381 | 0x017C | 1 Word | Internal Register 04 Initial Value |
| 40382 | 0x017D | 1 Word | Internal Register 05 Initial Value |
| 40383 | 0x017E | 1 Word | Internal Register 06 Initial Value |
| 40384 | 0x017F | 1 Word | Internal Register 07 Initial Value |
| 40385 | 0x0180 | 1 Word | Internal Register 08 Initial Value |
| 40386 | 0x0181 | 1 Word | Internal Register 09 Initial Value |
| 40387 | 0x0182 | 1 Word | Internal Register 10 Initial Value |
| 40388 | 0x0183 | 1 Word | Internal Register 11 Initial Value |
| 40389 | 0x0184 | 1 Word | Internal Register 12 Initial Value |
| 40390 | 0x0185 | 1 Word | Internal Register 13 Initial Value |
| 40391 | 0x0186 | 1 Word | Internal Register 14 Initial Value |
| 40392 | 0x0187 | 1 Word | Internal Register 15 Initial Value |
| 40393 | 0x0188 | 1 Word | Internal Register 16 Initial Value |
| 40394 | 0x0189 | 1 Word | Internal Register 17 Initial Value |
| 40395 | 0x018A | 1 Word | Internal Register 18 Initial Value |
| 40396 | 0x018B | 1 Word | Internal Register 19 Initial Value |
| 40397 | 0x018C | 1 Word | Internal Register 20 Initial Value |
| 40398 | 0x018D | 1 Word | Internal Register 21 Initial Value |
| 40399 | 0x018E | 1 Word | Internal Register 22 Initial Value |
| 40400 | 0x018F | 1 Word | Internal Register 23 Initial Value |
| 42921 | 0x0B68 | word | Internal Register 00 Working Value |
| 42922 | 0x0B69 | word | Internal Register 01 Working Value |
| 42923 | 0x0B6A | word | Internal Register 02 Working Value |
| 42924 | 0x0B6B | word | Internal Register 03 Working Value |
| 42925 | 0x0B6C | word | Internal Register 04 Working Value |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|------------------------------------|
| 42926 | 0x0B6D | word | Internal Register 05 Working Value |
| 42927 | 0x0B6E | word | Internal Register 06 Working Value |
| 42928 | 0x0B6F | word | Internal Register 07 Working Value |
| 42929 | 0x0B70 | word | Internal Register 08 Working Value |
| 42930 | 0x0B71 | word | Internal Register 09 Working Value |
| 42931 | 0x0B72 | word | Internal Register 10 Working Value |
| 42932 | 0x0B73 | word | Internal Register 11 Working Value |
| 42933 | 0x0B74 | word | Internal Register 12 Working Value |
| 42934 | 0x0B75 | word | Internal Register 13 Working Value |
| 42935 | 0x0B76 | word | Internal Register 14 Working Value |
| 42936 | 0x0B77 | word | Internal Register 15 Working Value |
| 42937 | 0x0B78 | word | Internal Register 16 Working Value |
| 42938 | 0x0B79 | word | Internal Register 17 Working Value |
| 42939 | 0x0B7A | word | Internal Register 18 Working Value |
| 42940 | 0x0B7B | word | Internal Register 19 Working Value |
| 42941 | 0x0B7C | word | Internal Register 20 Working Value |
| 42942 | 0x0B7D | word | Internal Register 21 Working Value |
| 42943 | 0x0B7E | word | Internal Register 22 Working Value |
| 42944 | 0x0B7F | word | Internal Register 23 Working Value |
| 43329 | 0x0D00 | 2 word | CH0 DI - Counter mode value |
| 43330 | 0x0D01 | 2 word | CH1 DI - Counter mode value |
| 43331 | 0x0D02 | 2 word | CH2 DI - Counter mode value |
| 43332 | 0x0D03 | 2 word | CH3 DI - Counter mode value |
| 43333 | 0x0D04 | 2 word | CH4 DI - Counter mode value |
| 43334 | 0x0D05 | 2 word | CH5 DI - Counter mode value |

ioLogik E2240 Modbus Mapping

0xxxx Read/Write Coils (Functions 1, 5, 15)

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 00001 | 0x0000 | 1 bit | Reset CH0 AI min value Read: 0: no action Write: 1: reset AI min value 0: return illegal data value |
| 00002 | 0x0001 | 1 bit | Reset CH1 AI min value Read: 0: no action Write: 1: reset AI min value 0: return illegal data value |
| 00003 | 0x0002 | 1 bit | Reset CH2 AI min value Read: 0: no action Write: 1: reset AI min value 0: return illegal data value |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 00004 | 0x0003 | 1 bit | Reset CH3 AI min value Read: 0: no action Write: 1: reset AI min value 0: return illegal data value |
| 00005 | 0x0004 | 1 bit | Reset CH4 AI min value Read: 0: no action Write: 1: reset AI min value 0: return illegal data value |
| 00006 | 0x0005 | 1 bit | Reset CH5 AI min value Read: 0: no action Write: 1: reset AI min value 0: return illegal data value |
| 00007 | 0x0006 | 1 bit | Reset CH6 AI min value Read: 0: no action Write: 1: reset AI min value 0: return illegal data value |
| 00008 | 0x0007 | 1 bit | Reset CH7 AI min value Read: 0: no action Write: 1: reset AI min value 0: return illegal data value |
| 00009 | 0x0008 | 1 bit | Reset CH0 AI max value Read: 0: no action Write: 1: reset AI max value 0: return illegal data value |
| 00010 | 0x0009 | 1 bit | Reset CH1 AI max value Read: 0: no action Write: 1: reset AI max value 0: return illegal data value |
| 00011 | 0x000A | 1 bit | Reset CH2 AI max value Read: 0: no action Write: 1: reset AI max value 0: return illegal data value |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 00012 | 0x000B | 1 bit | Reset CH3 AI max value Read: 0: no action Write: 1: reset AI max value 0: return illegal data value |
| 00013 | 0x000C | 1 bit | Reset CH4 AI max value Read: 0: no action Write: 1: reset AI max value 0: return illegal data value |
| 00014 | 0x000D | 1 bit | Reset CH5 AI max value Read: 0: no action Write: 1: reset AI max value 0: return illegal data value |
| 00015 | 0x000E | 1 bit | Reset CH6 AI max value Read: 0: no action Write: 1: reset AI max value 0: return illegal data value |
| 00016 | 0x000F | 1 bit | Reset CH7 AI max value Read: 0: no action Write: 1: reset AI max value 0: return illegal data value |

1xxxx Read Only Coils (Function 2)

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|----------------------------|
| 00001 | 0x0000 | 1 bit | CH0 AI LED 1: On 0: Off |
| 00002 | 0x0001 | 1 bit | CH1 AI LED 1: On 0: Off |
| 00003 | 0x0002 | 1 bit | CH2 AI LED 1: On 0: Off |
| 00004 | 0x0003 | 1 bit | CH3 AI LED 1: On 0: Off |
| 00005 | 0x0004 | 1 bit | CH4 AI LED 1: On 0: Off |
| 00006 | 0x0005 | 1 bit | CH5 AI LED 1: On 0: Off |
| 00007 | 0x0006 | 1 bit | CH6 AI LED 1: On 0: Off |
| 00008 | 0x0007 | 1 bit | CH7 AI LED 1: On 0: Off |

3xxxx Read Only Registers (Function 4)

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|-----------------------|
| 30001 | 0x0000 | 1 word | CH0 read AI value |
| 30002 | 0x0001 | 1 word | CH1 read AI value |
| 30003 | 0x0002 | 1 word | CH2 read AI value |
| 30004 | 0x0003 | 1 word | CH3 read AI value |
| 30005 | 0x0004 | 1 word | CH4 read AI value |
| 30006 | 0x0005 | 1 word | CH5 read AI value |
| 30007 | 0x0006 | 1 word | CH6 read AI value |
| 30008 | 0x0007 | 1 word | CH7 read AI value |
| 30009 | 0x0008 | 1 word | CH0 read AI min value |
| 30010 | 0x0009 | 1 word | CH1 read AI min value |
| 30011 | 0x000A | 1 word | CH2 read AI min value |
| 30012 | 0x000B | 1 word | CH3 read AI min value |
| 30013 | 0x000C | 1 word | CH4 read AI min value |
| 30014 | 0x000D | 1 word | CH5 read AI min value |
| 30015 | 0x000E | 1 word | CH6 read AI min value |
| 30016 | 0x000F | 1 word | CH7 read AI min value |
| 30017 | 0x0010 | 1 word | CH0 read AI max value |
| 30018 | 0x0011 | 1 word | CH1 read AI max value |
| 30019 | 0x0012 | 1 word | CH2 read AI max value |
| 30020 | 0x0013 | 1 word | CH3 read AI max value |
| 30021 | 0x0014 | 1 word | CH4 read AI max value |
| 30022 | 0x0015 | 1 word | CH5 read AI max value |
| 30023 | 0x0016 | 1 word | CH6 read AI max value |
| 30024 | 0x0017 | 1 word | CH7 read AI max value |

4xxxx Read/Write Registers (Functions 3, 6, 16)

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 40001 | 0x0000 | 1 word | CH0 AO value (0 to 4095) |
| 40002 | 0x0001 | 1 word | CH1 AO value (0 to 4095) |
| 40003 | 0x0002 | 1 word | CH0 AO power-on value (0 to 4095) |
| 40004 | 0x0003 | 1 word | CH1 AO power-on value (0 to 4095) |
| 40005 | 0x0004 | 1 word | CH0 AO safe value (0 to 4095) |
| 40006 | 0x0005 | 1 word | CH1 AO safe value (0 to 4095) |
| 40007 | 0x0006 | 1 word | CH0 AO range 0: 0 to 10 VDC 1: 4 to 20 mA Other: return illegal data value |
| 40008 | 0x0007 | 1 word | CH1 AO range 0: 0 to 10 VDC 1: 4 to 20 mA Other: return illegal data value |
| 40009 | 0x0008 | 1 word | CH0 AO power-on range 0: 0 to 10 VDC 1: 4 to 20 mA Other: return illegal data value |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 40010 | 0x0009 | 1 word | CH1 AO power-on range 0: 0 to 10 VDC 1: 4 to 20 mA Other: return illegal data value |
| 40011 | 0x000A | 1 word | CH0 AO safe range 0: 0 to 10 VDC 1: 4 to 20 mA Other: return illegal data value |
| 40012 | 0x000B | 1 word | CH1 AO safe range 0: 0 to 10 VDC 1: 4 to 20 mA Other: return illegal data value |
| 40013 | 0x000C | 1 word | CH0 AI range 00: +/-150 mV 01: +/-500 mV 02: +/-5V 03: +/-10V 04: 0 to 20 mA 05: 4 to 20 mA Other: return illegal data value |
| 40014 | 0x000D | 1 word | CH1 AI range 00: +/-150 mV 01: +/-500 mV 02: +/-5V 03: +/-10V 04: 0 to 20 mA 05: 4 to 20 mA Other: return illegal data value |
| 40015 | 0x000E | 1 word | CH2 AI range 00: +/-150 mV 01: +/-500 mV 02: +/-5V 03: +/-10V 04: 0 to 20 mA 05: 4 to 20 mA Other: return illegal data value |
| 40016 | 0x000F | 1 word | CH3 AI range 00: +/-150 mV 01: +/-500 mV 02: +/-5V 03: +/-10V 04: 0 to 20 mA 05: 4 to 20 mA Other: return illegal data value |
| 40017 | 0x0010 | 1 word | CH4 AI range 00: +/-150 mV 01: +/-500 mV 02: +/-5V 03: +/-10V 04: 0 to 20 mA 05: 4 to 20 mA Other: return illegal data value |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 40018 | 0x0011 | 1 word | CH5 AI range 00: +/-150 mV 01: +/-500 mV 02: +/-5V 03: +/-10V 04: 0 to 20 mA 05: 4 to 20 mA Other: return illegal data value |
| 40019 | 0x0012 | 1 word | CH6 AI range 00: +/-150 mV 01: +/-500 mV 02: +/-5V 03: +/-10V 04: 0 to 20 mA 05: 4 to 20 mA Other: return illegal data value |
| 40020 | 0x0013 | 1 word | CH7 AI range 00: +/-150 mV 01: +/-500 mV 02: +/-5V 03: +/-10V 04: 0 to 20 mA 05: 4 to 20 mA Other: return illegal data value |
| 40021 | 0x0014 | 1 word | CH0 AI power-on range 00: +/-150 mV 01: +/-500 mV 02: +/-5V 03: +/-10V 04: 0 to 20 mA 05: 4 to 20 mA Other: return illegal data value |
| 40022 | 0x0015 | 1 word | CH1 AI power-on range 00: +/-150 mV 01: +/-500 mV 02: +/-5V 03: +/-10V 04: 0 to 20 mA 05: 4 to 20 mA Other: return illegal data value |
| 40023 | 0x0016 | 1 word | CH2 AI power-on range 00: +/-150 mV 01: +/-500 mV 02: +/-5V 03: +/-10V 04: 0 to 20 mA 05: 4 to 20 mA Other: return illegal data value |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 40024 | 0x0017 | 1 word | CH3 AI power-on range 00: +/-150 mV 01: +/-500 mV 02: +/-5V 03: +/-10V 04: 0 to 20 mA 05: 4 to 20 mA Other: return illegal data value |
| 40025 | 0x0018 | 1 word | CH4 AI power-on range 00: +/-150 mV 01: +/-500 mV 02: +/-5V 03: +/-10V 04: 0 to 20 mA 05: 4 to 20 mA Other: return illegal data value |
| 40026 | 0x0019 | 1 word | CH5 AI power-on range 00: +/-150 mV 01: +/-500 mV 02: +/-5V 03: +/-10V 04: 0 to 20 mA 05: 4 to 20 mA Other: return illegal data value |
| 40027 | 0x001A | 1 word | CH6 AI power-on range 00: +/-150 mV 01: +/-500 mV 02: +/-5V 03: +/-10V 04: 0 to 20 mA 05: 4 to 20 mA Other: return illegal data value |
| 40028 | 0x001B | 1 word | CH7 AI power-on range 00: +/-150 mV 01: +/-500 mV 02: +/-5V 03: +/-10V 04: 0 to 20 mA 05: 4 to 20 mA Other: return illegal data value |
| 40029 | 0x001C | 1 word | CH0 AI safe range 00: +/-150 mV 01: +/-500 mV 02: +/-5V 03: +/-10V 04: 0 to 20 mA 05: 4 to 20 mA Other: return illegal data value |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 40030 | 0x001D | 1 word | CH1 AI safe range 00: +/-150 mV 01: +/-500 mV 02: +/-5V 03: +/-10V 04: 0 to 20 mA 05: 4 to 20 mA Other: return illegal data value |
| 40031 | 0x001E | 1 word | CH2 AI safe range 00: +/-150 mV 01: +/-500 mV 02: +/-5V 03: +/-10V 04: 0 to 20 mA 05: 4 to 20 mA Other: return illegal data value |
| 40032 | 0x001F | 1 word | CH3 AI safe range 00: +/-150 mV 01: +/-500 mV 02: +/-5V 03: +/-10V 04: 0 to 20 mA 05: 4 to 20 mA Other: return illegal data value |
| 40033 | 0x0020 | 1 word | CH4 AI safe range 00: +/-150 mV 01: +/-500 mV 02: +/-5V 03: +/-10V 04: 0 to 20 mA 05: 4 to 20 mA Other: return illegal data value |
| 40034 | 0x0021 | 1 word | CH5 AI safe range 00: +/-150 mV 01: +/-500 mV 02: +/-5V 03: +/-10V 04: 0 to 20 mA 05: 4 to 20 mA Other: return illegal data value |
| 40035 | 0x0022 | 1 word | CH6 AI safe range 00: +/-150 mV 01: +/-500 mV 02: +/-5V 03: +/-10V 04: 0 to 20 mA 05: 4 to 20 mA Other: return illegal data value |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 40036 | 0x0023 | 1 word | CH7 AI safe range 00: +/-150 mV 01: +/-500 mV 02: +/-5V 03: +/-10V 04: 0 to 20 mA 05: 4 to 20 mA Other: return illegal data value |
| 40137 | 0x0088 | 1 word | AI Channel 0 Scaling Enable |
| 40138 | 0x0089 | 1 word | AI Channel 1 Scaling Enable |
| 40139 | 0x008A | 1 word | AI Channel 2 Scaling Enable |
| 40140 | 0x008B | 1 word | AI Channel 3 Scaling Enable |
| 40141 | 0x008C | 1 word | AI Channel 4 Scaling Enable |
| 40142 | 0x008D | 1 word | AI Channel 5 Scaling Enable |
| 40143 | 0x008E | 1 word | AI Channel 6 Scaling Enable |
| 40144 | 0x008F | 1 word | AI Channel 7 Scaling Enable |
| 40145 | 0x0090 | 1 word | AI Channel 0 RAW Min Value Hi-Word |
| 40146 | 0x0091 | 1 word | AI Channel 0 RAW Min Value Low-Word |
| 40147 | 0x0092 | 1 word | AI Channel 1 RAW Min Value Hi-Word |
| 40148 | 0x0093 | 1 word | AI Channel 1 RAW Min Value Low-Word |
| 40149 | 0x0094 | 1 word | AI Channel 2 RAW Min Value Hi-Word |
| 40150 | 0x0095 | 1 word | AI Channel 2 RAW Min Value Low-Word |
| 40151 | 0x0096 | 1 word | AI Channel 3 RAW Min Value Hi-Word |
| 40152 | 0x0097 | 1 word | AI Channel 3 RAW Min Value Low-Word |
| 40153 | 0x0098 | 1 word | AI Channel 4 RAW Min Value Hi-Word |
| 40154 | 0x0099 | 1 word | AI Channel 4 RAW Min Value Low-Word |
| 40155 | 0x009A | 1 word | AI Channel 5 RAW Min Value Hi-Word |
| 40156 | 0x009B | 1 word | AI Channel 5 RAW Min Value Low-Word |
| 40157 | 0x009C | 1 word | AI Channel 6 RAW Min Value Hi-Word |
| 40158 | 0x009D | 1 word | AI Channel 6 RAW Min Value Low-Word |
| 40159 | 0x009E | 1 word | AI Channel 7 RAW Min Value Hi-Word |
| 40160 | 0x009F | 1 word | AI Channel 7 RAW Min Value Low-Word |
| 40161 | 0x01A0 | 1 word | AI Channel 0 RAW Max Value Hi-Word |
| 40162 | 0x01A1 | 1 word | AI Channel 0 RAW Max Value Low-Word |
| 40163 | 0x01A2 | 1 word | AI Channel 1 RAW Max Value Hi-Word |
| 40164 | 0x01A3 | 1 word | AI Channel 1 RAW Max Value Low-Word |
| 40165 | 0x01A4 | 1 word | AI Channel 2 RAW Max Value Hi-Word |
| 40166 | 0x01A5 | 1 word | AI Channel 2 RAW Max Value Low-Word |
| 40167 | 0x01A6 | 1 word | AI Channel 3 RAW Max Value Hi-Word |
| 40168 | 0x01A7 | 1 word | AI Channel 3 RAW Max Value Low-Word |
| 40169 | 0x01A8 | 1 word | AI Channel 4 RAW Max Value Hi-Word |
| 40170 | 0x01A9 | 1 word | AI Channel 4 RAW Max Value Low-Word |
| 40171 | 0x01AA | 1 word | AI Channel 5 RAW Max Value Hi-Word |
| 40172 | 0x01AB | 1 word | AI Channel 5 RAW Max Value Low-Word |
| 40173 | 0x01AC | 1 word | AI Channel 6 RAW Max Value Hi-Word |
| 40174 | 0x01AD | 1 word | AI Channel 6 RAW Max Value Low-Word |
| 40175 | 0x01AE | 1 word | AI Channel 7 RAW Max Value Hi-Word |
| 40176 | 0x01AF | 1 word | AI Channel 7 RAW Max Value Low-Word |
| 40177 | 0x01B0 | 1 word | AI Channel 0 Scale Min Value Hi-Word |
| 40178 | 0x01B1 | 1 word | AI Channel 0 Scale Min Value Low-Word |
| 40179 | 0x01B2 | 1 word | AI Channel 1 Scale Min Value Hi-Word |
| 40180 | 0x01B3 | 1 word | AI Channel 1 Scale Min Value Low-Word |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 40181 | 0x01B4 | 1 word | AI Channel 2 Scale Min Value Hi-Word |
| 40182 | 0x01B5 | 1 word | AI Channel 2 Scale Min Value Low-Word |
| 40183 | 0x01B6 | 1 word | AI Channel 3 Scale Min Value Hi-Word |
| 40184 | 0x01B7 | 1 word | AI Channel 3 Scale Min Value Low-Word |
| 40185 | 0x01B8 | 1 word | AI Channel 4 Scale Min Value Hi-Word |
| 40186 | 0x01B9 | 1 word | AI Channel 4 Scale Min Value Low-Word |
| 40187 | 0x01BA | 1 word | AI Channel 5 Scale Min Value Hi-Word |
| 40188 | 0x01BB | 1 word | AI Channel 5 Scale Min Value Low-Word |
| 40189 | 0x01BC | 1 word | AI Channel 6 Scale Min Value Hi-Word |
| 40190 | 0x01BD | 1 word | AI Channel 6 Scale Min Value Low-Word |
| 40191 | 0x01BE | 1 word | AI Channel 7 Scale Min Value Hi-Word |
| 40192 | 0x01BF | 1 word | AI Channel 7 Scale Min Value Low-Word |
| 40193 | 0x01C0 | 1 word | AI Channel 0 Scale Max Value Hi-Word |
| 40194 | 0x01C1 | 1 word | AI Channel 0 Scale Max Value Low-Word |
| 40195 | 0x01C2 | 1 word | AI Channel 1 Scale Max Value Hi-Word |
| 40196 | 0x01C3 | 1 word | AI Channel 1 Scale Max Value Low-Word |
| 40197 | 0x01C4 | 1 word | AI Channel 2 Scale Max Value Hi-Word |
| 40198 | 0x01C5 | 1 word | AI Channel 2 Scale Max Value Low-Word |
| 40199 | 0x01C6 | 1 word | AI Channel 3 Scale Max Value Hi-Word |
| 40200 | 0x01C7 | 1 word | AI Channel 3 Scale Max Value Low-Word |
| 40201 | 0x01C8 | 1 word | AI Channel 4 Scale Max Value Hi-Word |
| 40202 | 0x01C9 | 1 word | AI Channel 4 Scale Max Value Low-Word |
| 40203 | 0x01CA | 1 word | AI Channel 5 Scale Max Value Hi-Word |
| 40204 | 0x01CB | 1 word | AI Channel 5 Scale Max Value Low-Word |
| 40205 | 0x01CC | 1 word | AI Channel 6 Scale Max Value Hi-Word |
| 40206 | 0x01CD | 1 word | AI Channel 6 Scale Max Value Low-Word |
| 40207 | 0x01CE | 1 word | AI Channel 7 Scale Max Value Hi-Word |
| 40208 | 0x01CF | 1 word | AI Channel 7 Scale Max Value Low-Word |
| 40257 | 0x0100 | 1 word | AI Channel 0 Scale Value Hi-Word (float) |
| 40258 | 0x0101 | 1 word | AI Channel 0 Scale Value Lo-Word (float) |
| 40259 | 0x0102 | 1 word | AI Channel 1 Scale Value Hi-Word (float) |
| 40260 | 0x0103 | 1 word | AI Channel 1 Scale Value Lo-Word (float) |
| 40261 | 0x0104 | 1 word | AI Channel 2 Scale Value Hi-Word (float) |
| 40262 | 0x0105 | 1 word | AI Channel 2 Scale Value Lo-Word (float) |
| 40263 | 0x0106 | 1 word | AI Channel 3 Scale Value Hi-Word (float) |
| 40264 | 0x0107 | 1 word | AI Channel 3 Scale Value Lo-Word (float) |
| 40265 | 0x0108 | 1 word | AI Channel 4 Scale Value Hi-Word (float) |
| 40266 | 0x0109 | 1 word | AI Channel 4 Scale Value Lo-Word (float) |
| 40267 | 0x010A | 1 word | AI Channel 5 Scale Value Hi-Word (float) |
| 40268 | 0x010B | 1 word | AI Channel 5 Scale Value Lo-Word (float) |
| 40269 | 0x010C | 1 word | AI Channel 6 Scale Value Hi-Word (float) |
| 40270 | 0x010D | 1 word | AI Channel 6 Scale Value Lo-Word (float) |
| 40271 | 0x010E | 1 word | AI Channel 7 Scale Value Hi-Word (float) |
| 40272 | 0x010F | 1 word | AI Channel 7 Scale Value Lo-Word (float) |
| 40337 | 0x0150 | 1 word | Internal Register 00 Working Value |
| 40338 | 0x0151 | 1 word | Internal Register 01 Working Value |
| 40339 | 0x0152 | 1 word | Internal Register 02 Working Value |
| 40340 | 0x0153 | 1 word | Internal Register 03 Working Value |
| 40341 | 0x0154 | 1 word | Internal Register 04 Working Value |
| 40342 | 0x0155 | 1 word | Internal Register 05 Working Value |
| 40343 | 0x0156 | 1 word | Internal Register 06 Working Value |
| 40344 | 0x0157 | 1 word | Internal Register 07 Working Value |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|------------------------------------|
| 40345 | 0x0158 | 1 word | Internal Register 08 Working Value |
| 40346 | 0x0159 | 1 word | Internal Register 09 Working Value |
| 40347 | 0x015A | 1 word | Internal Register 10 Working Value |
| 40348 | 0x015B | 1 word | Internal Register 11 Working Value |
| 40349 | 0x015C | 1 word | Internal Register 12 Working Value |
| 40350 | 0x015D | 1 word | Internal Register 13 Working Value |
| 40351 | 0x015E | 1 word | Internal Register 14 Working Value |
| 40352 | 0x015F | 1 word | Internal Register 15 Working Value |
| 40353 | 0x0160 | 1 word | Internal Register 16 Working Value |
| 40354 | 0x0161 | 1 word | Internal Register 17 Working Value |
| 40355 | 0x0162 | 1 word | Internal Register 18 Working Value |
| 40356 | 0x0163 | 1 word | Internal Register 19 Working Value |
| 40357 | 0x0164 | 1 word | Internal Register 20 Working Value |
| 40358 | 0x0165 | 1 word | Internal Register 21 Working Value |
| 40359 | 0x0166 | 1 word | Internal Register 22 Working Value |
| 40360 | 0x0167 | 1 word | Internal Register 23 Working Value |

ioLogik E2242 Modbus Mapping

0xxxx Read/Write Coils (Support Functions 1, 5, 15)// DIO Channel

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|-------------------------------------|
| 00001 | 0x0000 | 1 bit | CH0 DO Value 0: Off 1: On |
| 00002 | 0x0001 | 1 bit | CH1 DO Value 0: Off 1: On |
| 00003 | 0x0002 | 1 bit | CH2 DO Value 0: Off 1: On |
| 00004 | 0x0003 | 1 bit | CH3 DO Value 0: Off 1: On |
| 00005 | 0x0004 | 1 bit | CH4 DO Value 0: Off 1: On |
| 00006 | 0x0005 | 1 bit | CH5 DO Value 0: Off 1: On |
| 00007 | 0x0006 | 1 bit | CH6 DO Value 0: Off 1: On |
| 00008 | 0x0007 | 1 bit | CH7 DO Value 0: Off 1: On |
| 00009 | 0x0008 | 1 bit | CH8 DO Value 0: Off 1: On |
| 00010 | 0x0009 | 1 bit | CH9 DO Value 0: Off 1: On |
| 00011 | 0x000A | 1 bit | CH10 DO Value 0: Off 1: On |
| 00012 | 0x000B | 1 bit | CH11 DO Value 0: Off 1: On |
| 00013 | 0x000C | 1 bit | CH0 DO Power On Value 0: Off 1: On |
| 00014 | 0x000D | 1 bit | CH1 DO Power On Value 0: Off 1: On |
| 00015 | 0x000E | 1 bit | CH2 DO Power On Value 0: Off 1: On |
| 00016 | 0x000F | 1 bit | CH3 DO Power On Value 0: Off 1: On |
| 00017 | 0x0010 | 1 bit | CH4 DO Power On Value 0: Off 1: On |
| 00018 | 0x0011 | 1 bit | CH5 DO Power On Value 0: Off 1: On |
| 00019 | 0x0012 | 1 bit | CH6 DO Power On Value 0: Off 1: On |
| 00020 | 0x0013 | 1 bit | CH7 DO Power On Value 0: Off 1: On |
| 00021 | 0x0014 | 1 bit | CH8 DO Power On Value 0: Off 1: On |
| 00022 | 0x0015 | 1 bit | CH9 DO Power On Value 0: Off 1: On |
| 00023 | 0x0016 | 1 bit | CH10 DO Power On Value 0: Off 1: On |
| 00024 | 0x0017 | 1 bit | CH11 DO Power On Value 0: Off 1: On |
| 00025 | 0x0018 | 1 bit | CH0 DO Safe Value 0: Off 1: On |
| 00026 | 0x0019 | 1 bit | CH1 DO Safe Value 0: Off 1: On |
| 00027 | 0x001A | 1 bit | CH2 DO Safe Value 0: Off 1: On |
| 00028 | 0x001B | 1 bit | CH3 DO Safe Value 0: Off 1: On |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 00029 | 0x001C | 1 bit | CH4 DO Safe Value 0: Off 1: On |
| 00030 | 0x001D | 1 bit | CH5 DO Safe Value 0: Off 1: On |
| 00031 | 0x001E | 1 bit | CH6 DO Safe Value 0: Off 1: On |
| 00032 | 0x001F | 1 bit | CH7 DO Safe Value 0: Off 1: On |
| 00033 | 0x0020 | 1 bit | CH8 DO Safe Value 0: Off 1: On |
| 00034 | 0x0021 | 1 bit | CH9 DO Safe Value 0: Off 1: On |
| 00035 | 0x0022 | 1 bit | CH10 DO Safe Value 0: Off 1: On |
| 00036 | 0x0023 | 1 bit | CH11 DO Safe Value 0: Off 1: On |
| 00037 | 0x0024 | 1 bit | CH0 DO Pulse Operate Status 0: Off 1: On |
| 00038 | 0x0025 | 1 bit | CH1 DO Pulse Operate Status 0: Off 1: On |
| 00039 | 0x0026 | 1 bit | CH2 DO Pulse Operate Status 0: Off 1: On |
| 00040 | 0x0027 | 1 bit | CH3 DO Pulse Operate Status 0: Off 1: On |
| 00041 | 0x0028 | 1 bit | CH4 DO Pulse Operate Status 0: Off 1: On |
| 00042 | 0x0029 | 1 bit | CH5 DO Pulse Operate Status 0: Off 1: On |
| 00043 | 0x002A | 1 bit | CH6 DO Pulse Operate Status 0: Off 1: On |
| 00044 | 0x002B | 1 bit | CH7 DO Pulse Operate Status 0: Off 1: On |
| 00045 | 0x002C | 1 bit | CH8 DO Pulse Operate Status 0: Off 1: On |
| 00046 | 0x002D | 1 bit | CH9 DO Pulse Operate Status 0: Off 1: On |
| 00047 | 0x002E | 1 bit | CH10 DO Pulse Operate Status 0: Off 1: On |
| 00048 | 0x002F | 1 bit | CH11 DO Pulse Operate Status 0: Off 1: On |
| 00049 | 0x0030 | 1 bit | CH0 DO PowerOn Pulse Operate Status 0: Off 1: On |
| 00050 | 0x0031 | 1 bit | CH1 DO PowerOn Pulse Operate Status 0: Off 1: On |
| 00051 | 0x0032 | 1 bit | CH2 DO PowerOn Pulse Operate Status 0: Off 1: On |
| 00052 | 0x0033 | 1 bit | CH3 DO PowerOn Pulse Operate Status 0: Off 1: On |
| 00053 | 0x0034 | 1 bit | CH4 DO PowerOn Pulse Operate Status 0: Off 1: On |
| 00054 | 0x0035 | 1 bit | CH5 DO PowerOn Pulse Operate Status 0: Off 1: On |
| 00055 | 0x0036 | 1 bit | CH6 DO PowerOn Pulse Operate Status 0: Off 1: On |
| 00056 | 0x0037 | 1 bit | CH7 DO PowerOn Pulse Operate Status 0: Off 1: On |
| 00057 | 0x0038 | 1 bit | CH8 DO PowerOn Pulse Operate Status 0: Off 1: On |
| 00058 | 0x0039 | 1 bit | CH9 DO PowerOn Pulse Operate Status 0: Off 1: On |
| 00059 | 0x003A | 1 bit | CH10 DO PowerOn Pulse Operate Status 0: Off 1: On |
| 00060 | 0x003B | 1 bit | CH11 DO PowerOn Pulse Operate Status 0: Off 1: On |
| 00061 | 0x003C | 1 bit | CH0 DO Safe Pulse Operate Status 0: Off 1: On |
| 00062 | 0x003D | 1 bit | CH1 DO Safe Pulse Operate Status 0: Off 1: On |
| 00063 | 0x003E | 1 bit | CH2 DO Safe Pulse Operate Status 0: Off 1: On |
| 00064 | 0x003F | 1 bit | CH3 DO Safe Pulse Operate Status 0: Off 1: On |
| 00065 | 0x0040 | 1 bit | CH4 DO Safe Pulse Operate Status 0: Off 1: On |
| 00066 | 0x0041 | 1 bit | CH5 DO Safe Pulse Operate Status 0: Off 1: On |
| 00067 | 0x0042 | 1 bit | CH6 DO Safe Pulse Operate Status 0: Off 1: On |
| 00068 | 0x0043 | 1 bit | CH7 DO Safe Pulse Operate Status 0: Off 1: On |
| 00069 | 0x0044 | 1 bit | CH8 DO Safe Pulse Operate Status 0: Off 1: On |
| 00070 | 0x0045 | 1 bit | CH9 DO Safe Pulse Operate Status 0: Off 1: On |
| 00071 | 0x0046 | 1 bit | CH10 DO Safe Pulse Operate Status 0: Off 1: On |
| 00072 | 0x0047 | 1 bit | CH11 DO Safe Pulse Operate Status 0: Off 1: On |
| 00073 | 0x0048 | 1 bit | CH0 DI Counter Status 0: Off 1: On |
| 00074 | 0x0049 | 1 bit | CH1 DI Counter Status 0: Off 1: On |
| 00075 | 0x004A | 1 bit | CH2 DI Counter Status 0: Off 1: On |
| 00076 | 0x004B | 1 bit | CH3 DI Counter Status 0: Off 1: On |
| 00077 | 0x004C | 1 bit | CH4 DI Counter Status 0: Off 1: On |
| 00078 | 0x004D | 1 bit | CH5 DI Counter Status 0: Off 1: On |
| 00079 | 0x004E | 1 bit | CH6 DI Counter Status 0: Off 1: On |
| 00080 | 0x004F | 1 bit | CH7 DI Counter Status 0: Off 1: On |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 00081 | 0x0050 | 1 bit | CH8 DI Counter Status 0: Off 1: On |
| 00082 | 0x0051 | 1 bit | CH9 DI Counter Status 0: Off 1: On |
| 00083 | 0x0052 | 1 bit | CH10 DI Counter Status 0: Off 1: On |
| 00084 | 0x0053 | 1 bit | CH11 DI Counter Status 0: Off 1: On |
| 00085 | 0x0054 | 1 bit | CH0 DI Clear Count Value read always: 0 Write: 1 : Clear counter value 0 : return Illegal Data Value |
| 00086 | 0x0055 | 1 bit | CH1 DI Clear Count Value read always: 0 Write: 1 : Clear counter value 0 : return Illegal Data Value |
| 00087 | 0x0056 | 1 bit | CH2 DI Clear Count Value read always: 0 Write: 1 : Clear counter value 0 : return Illegal Data Value |
| 00088 | 0x0057 | 1 bit | CH3 DI Clear Count Value read always: 0 Write: 1 : Clear counter value 0 : return Illegal Data Value |
| 00089 | 0x0058 | 1 bit | CH4 DI Clear Count Value read always: 0 Write: 1 : Clear counter value 0 : return Illegal Data Value |
| 00090 | 0x0059 | 1 bit | CH5 DI Clear Count Value read always: 0 Write: 1 : Clear counter value 0 : return Illegal Data Value |
| 00091 | 0x005A | 1 bit | CH6 DI Clear Count Value read always: 0 Write: 1 : Clear counter value 0 : return Illegal Data Value |
| 00092 | 0x005B | 1 bit | CH7 DI Clear Count Value read always: 0 Write: 1 : Clear counter value 0 : return Illegal Data Value |
| 00093 | 0x005C | 1 bit | CH8 DI Clear Count Value read always: 0 Write: 1 : Clear counter value 0 : return Illegal Data Value |
| 00094 | 0x005D | 1 bit | CH9 DI Clear Count Value read always: 0 Write: 1 : Clear counter value 0 : return Illegal Data Value |
| 00095 | 0x005E | 1 bit | CH10 DI Clear Count Value read always: 0 Write: 1 : Clear counter value 0 : return Illegal Data Value |
| 00096 | 0x005F | 1 bit | CH11 DI Clear Count Value read always: 0 Write: 1 : Clear counter value 0 : return Illegal Data Value |
| 00097 | 0x0060 | 1 bit | CH0 DI OverFlow Status Read: 0 : Normal 1 : Overflow Write: 0 : clear overflow status 1 : return Illegal Data Value |
| 00098 | 0x0061 | 1 bit | CH1 DI OverFlow Status Read: 0 : Normal 1 : Overflow Write: 0 : clear overflow status 1 : return Illegal Data Value |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 00099 | 0x0062 | 1 bit | CH2 DI OverFlow Status Read: 0 : Normal 1 : Overflow Write: 0 : clear overflow status 1 : return Illegal Data Value |
| 00100 | 0x0063 | 1 bit | CH3 DI OverFlow Status Read: 0 : Normal 1 : Overflow Write: 0 : clear overflow status 1 : return Illegal Data Value |
| 00101 | 0x0064 | 1 bit | CH4 DI OverFlow Status Read: 0 : Normal 1 : Overflow Write: 0 : clear overflow status 1 : return Illegal Data Value |
| 00102 | 0x0065 | 1 bit | CH5 DI OverFlow Status Read: 0 : Normal 1 : Overflow Write: 0 : clear overflow status 1 : return Illegal Data Value |
| 00103 | 0x0066 | 1 bit | CH6 DI OverFlow Status Read: 0 : Normal 1 : Overflow Write: 0 : clear overflow status 1 : return Illegal Data Value |
| 00104 | 0x0067 | 1 bit | CH7 DI OverFlow Status Read: 0 : Normal 1 : Overflow Write: 0 : clear overflow status 1 : return Illegal Data Value |
| 00105 | 0x0068 | 1 bit | CH8 DI OverFlow Status Read: 0 : Normal 1 : Overflow Write: 0 : clear overflow status 1 : return Illegal Data Value |
| 00106 | 0x0069 | 1 bit | CH9 DI OverFlow Status Read: 0 : Normal 1 : Overflow Write : 0 : clear overflow status 1 : return Illegal Data Value |
| 00107 | 0x006A | 1 bit | CH10 DI OverFlow Status Read: 0 : Normal 1 : Overflow Write: 0 : clear overflow status 1 : return Illegal Data Value |
| 00108 | 0x006B | 1 bit | CH11 DI OverFlow Status Read: 0 : Normal 1 : Overflow Write: 0 : clear overflow status 1 : return Illegal Data Value |
| 00109 | 0x006C | 1 bit | CH0 DI Count Trigger |
| 00110 | 0x006D | 1 bit | CH1 DI Count Trigger |
| 00111 | 0x006E | 1 bit | CH2 DI Count Trigger |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 00112 | 0x006F | 1 bit | CH3 DI Count Trigger |
| 00113 | 0x0070 | 1 bit | CH4 DI Count Trigger |
| 00114 | 0x0071 | 1 bit | CH5 DI Count Trigger |
| 00115 | 0x0072 | 1 bit | CH6 DI Count Trigger |
| 00116 | 0x0073 | 1 bit | CH7 DI Count Trigger |
| 00117 | 0x0074 | 1 bit | CH8 DI Count Trigger |
| 00118 | 0x0075 | 1 bit | CH9 DI Count Trigger |
| 00119 | 0x0076 | 1 bit | CH10 DI Count Trigger |
| 00120 | 0x0077 | 1 bit | CH11 DI Count Trigger |
| 00121 | 0x0078 | 1 bit | CH0 DI Power On Status 0: Off 1: On |
| 00122 | 0x0079 | 1 bit | CH1 DI Power On Status 0: Off 1: On |
| 00123 | 0x007A | 1 bit | CH2 DI Power On Status 0: Off 1: On |
| 00124 | 0x007B | 1 bit | CH3 DI Power On Status 0: Off 1: On |
| 00125 | 0x007C | 1 bit | CH4 DI Power On Status 0: Off 1: On |
| 00126 | 0x007D | 1 bit | CH5 DI Power On Status 0: Off 1: On |
| 00127 | 0x007E | 1 bit | CH6 DI Power On Status 0: Off 1: On |
| 00128 | 0x007F | 1 bit | CH7 DI Power On Status 0: Off 1: On |
| 00129 | 0x0080 | 1 bit | CH8 DI Power On Status 0: Off 1: On |
| 00130 | 0x0081 | 1 bit | CH9 DI Power On Status 0: Off 1: On |
| 00131 | 0x0082 | 1 bit | CH10 DI Power On Status 0: Off 1: On |
| 00132 | 0x0083 | 1 bit | CH11 DI Power On Status 0: Off 1: On |
| 00133 | 0x0084 | 1 bit | CH0 DI Safe Pulse Operate Status 0: Off 1: On |
| 00134 | 0x0085 | 1 bit | CH1 DI Safe Pulse Operate Status 0: Off 1: On |
| 00135 | 0x0086 | 1 bit | CH2 DI Safe Pulse Operate Status 0: Off 1: On |
| 00136 | 0x0087 | 1 bit | CH3 DI Safe Pulse Operate Status 0: Off 1: On |
| 00137 | 0x0088 | 1 bit | CH4 DI Safe Pulse Operate Status 0: Off 1: On |
| 00138 | 0x0089 | 1 bit | CH5 DI Safe Pulse Operate Status 0: Off 1: On |
| 00139 | 0x008A | 1 bit | CH6 DI Safe Pulse Operate Status 0: Off 1: On |
| 00140 | 0x008B | 1 bit | CH7 DI Safe Pulse Operate Status 0: Off 1: On |
| 00141 | 0x008C | 1 bit | CH8 DI Safe Pulse Operate Status 0: Off 1: On |
| 00142 | 0x008D | 1 bit | CH9 DI Safe Pulse Operate Status 0: Off 1: On |
| 00143 | 0x008E | 1 bit | CH10 DI Safe Pulse Operate Status 0: Off 1: On |
| 00144 | 0x008F | 1 bit | CH11 DI Safe Pulse Operate Status 0: Off 1: On |
| 00145 | 0x0090 | 1 bit | CH0 DI set channel Power-off storage enable ON/OFF 1:ON 0:OFF |
| 00146 | 0x0091 | 1 bit | CH1 DI set channel Power-off storage enable ON/OFF 1:ON 0:OFF |
| 00147 | 0x0092 | 1 bit | CH2 DI set channel Power-off storage enable ON/OFF 1:ON 0:OFF |
| 00148 | 0x0093 | 1 bit | CH3 DI set channel Power-off storage enable ON/OFF 1:ON 0:OFF |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 00149 | 0x0094 | 1 bit | CH4 DI set channel Power-off storage enable ON/OFF 1:ON 0:OFF |
| 00150 | 0x0095 | 1 bit | CH5 DI set channel Power-off storage enable ON/OFF 1:ON 0:OFF |
| 00151 | 0x0096 | 1 bit | CH6 DI set channel Power-off storage enable ON/OFF 1:ON 0:OFF |
| 00152 | 0x0097 | 1 bit | CH7 DI set channel Power-off storage enable ON/OFF 1:ON 0:OFF |
| 00153 | 0x0098 | 1 bit | CH8 DI set channel Power-off storage enable ON/OFF 1:ON 0:OFF |
| 00154 | 0x0099 | 1 bit | CH9 DI set channel Power-off storage enable ON/OFF 1:ON 0:OFF |
| 00155 | 0x009A | 1 bit | CH10 DI set channel Power-off storage enable ON/OFF 1:ON 0:OFF |
| 00156 | 0x009B | 1 bit | CH11 DI set channel Power-off storage enable ON/OFF 1:ON 0:OFF |
| 00157 | 0x009C | 1 bit | DIO 00 1: OUTPUT 0: INPUT (Default: INPUT) |
| 00158 | 0x009D | 1 bit | DIO 01 1: OUTPUT 0: INPUT (Default: INPUT) |
| 00159 | 0x009E | 1 bit | DIO 02 1: OUTPUT 0: INPUT (Default: INPUT) |
| 00160 | 0x009F | 1 bit | DIO 03 1: OUTPUT 0: INPUT (Default: INPUT) |
| 00161 | 0x00A0 | 1 bit | DIO 04 1: OUTPUT 0: INPUT (Default: INPUT) |
| 00162 | 0x00A1 | 1 bit | DIO 05 1: OUTPUT 0: INPUT (Default: INPUT) |
| 00163 | 0x00A2 | 1 bit | DIO 06 1: OUTPUT 0: INPUT (Default: OUTPUT) |

| Reference | Address | Data Type | Description |
|----------------------|---------|-----------|---|
| 00164 | 0x00A3 | 1 bit | DIO 07 1: OUTPUT 0: INPUT (Default: OUTPUT) |
| 00165 | 0x00A4 | 1 bit | DIO 08 1: OUTPUT 0: INPUT (Default: OUTPUT) |
| 00166 | 0x00A5 | 1 bit | DIO 09 1: OUTPUT 0: INPUT (Default: OUTPUT) |
| 00167 | 0x00A6 | 1 bit | DIO 10 1: OUTPUT 0: INPUT (Default: OUTPUT) |
| 00168 | 0x00A7 | 1 bit | DIO 11 1: OUTPUT 0: INPUT (Default: OUTPUT) |
| // AI Channel | | | |
| 00257 | 0x0100 | 1bit | Reset CH0 AI Min Value Read: always 0 Write : 1: reset AI Min value 0: return Illegal Data Value |
| 00258 | 0x0101 | 1bit | Reset CH1 AI Min Value Read: always 0 Write : 1: reset AI Min value 0: return Illegal Data Value |
| 00259 | 0x0102 | 1bit | Reset CH2 AI Min Value Read: always 0 Write : 1: reset AI Min value 0: return Illegal Data Value |
| 00260 | 0x0103 | 1bit | Reset CH3 AI Min Value Read: always 0 Write : 1: reset AI Min value 0: return Illegal Data Value |
| 00265 | 0x0104 | 1bit | Reset CH0 AI Max Value Read: always 0 Write : 1: reset AI Max value 0: return Illegal Data Value |
| 00266 | 0x0105 | 1bit | Reset CH1 AI Max Value Read: always 0 Write : 1: reset AI Max value 0: return Illegal Data Value |
| 00267 | 0x0106 | 1bit | Reset CH2 AI Max Value Read: always 0 Write : 1: reset AI Max value 0: return Illegal Data Value |
| 00268 | 0x0107 | 1bit | Reset CH3 AI Max Value Read: always 0 Write : 1: reset AI Max value 0: return Illegal Data Value |

1xxxx Read Only Coils (Function 2)

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|-------------------------|
| 10001 | 0x0000 | 1 bit | CH0 DI Value |
| 10002 | 0x0001 | 1 bit | CH1 DI Value |
| 10003 | 0x0002 | 1 bit | CH2 DI Value |
| 10004 | 0x0003 | 1 bit | CH3 DI Value |
| 10005 | 0x0004 | 1 bit | CH4 DI Value |
| 10006 | 0x0005 | 1 bit | CH5 DI Value |
| 10007 | 0x0006 | 1 bit | CH6 DI Value |
| 10008 | 0x0007 | 1 bit | CH7 DI Value |
| 10009 | 0x0008 | 1 bit | CH8 DI Value |
| 10010 | 0x0009 | 1 bit | CH9 DI Value |
| 10011 | 0x000A | 1 bit | CH10 DI Value |
| 10012 | 0x000B | 1 bit | CH11 DI Value |
| 10013 | 0x000C | 1 bit | CH0 AI LED 1: On 0: Off |
| 10014 | 0x000D | 1 bit | CH1 AI LED 1: On 0: Off |
| 10015 | 0x000E | 1 bit | CH2 AI LED 1: On 0: Off |
| 10016 | 0x000F | 1 bit | CH3 AI LED 1: On 0: Off |

NOTE As for design purposes, the ioLogik E2242 has changed its Modbus/TCP address mapping for DI channel and AI LED status starting from firmware version V3.0. The earlier Modbus address mapping of this part at firmware V1.x starts from 10257(0x0100) to 10272(0x010F).

3xxxx Read Only Registers (Function 4)

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--------------------------------|
| 30001 | 0x0000 | word | CH0 DI Counter Value Hi- Word |
| 30002 | 0x0001 | word | CH0 DI Counter Value Lo- Word |
| 30003 | 0x0002 | word | CH1 DI Counter Value Hi- Word |
| 30004 | 0x0003 | word | CH1 DI Counter Value Lo- Word |
| 30005 | 0x0004 | word | CH2 DI Counter Value Hi- Word |
| 30006 | 0x0005 | word | CH2 DI Counter Value Lo- Word |
| 30007 | 0x0006 | word | CH3 DI Counter Value Hi- Word |
| 30008 | 0x0007 | word | CH3 DI Counter Value Lo- Word |
| 30009 | 0x0008 | word | CH4 DI Counter Value Hi- Word |
| 30010 | 0x0009 | word | CH4 DI Counter Value Lo- Word |
| 30011 | 0x000A | word | CH5 DI Counter Value Hi- Word |
| 30012 | 0x000B | word | CH5 DI Counter Value Lo- Word |
| 30013 | 0x000C | word | CH6 DI Counter Value Hi- Word |
| 30014 | 0x000D | word | CH6 DI Counter Value Lo- Word |
| 30015 | 0x000E | word | CH7 DI Counter Value Hi- Word |
| 30016 | 0x000F | word | CH7 DI Counter Value Lo- Word |
| 30017 | 0x0010 | word | CH8 DI Counter Value Hi- Word |
| 30018 | 0x0011 | word | CH8 DI Counter Value Lo- Word |
| 30019 | 0x0012 | word | CH9 DI Counter Value Hi- Word |
| 30020 | 0x0013 | word | CH9 DI Counter Value Lo- Word |
| 30021 | 0x0014 | word | CH10 DI Counter Value Hi- Word |
| 30022 | 0x0015 | word | CH10 DI Counter Value Lo- Word |
| 30023 | 0x0016 | word | CH11 DI Counter Value Hi- Word |
| 30024 | 0x0017 | word | CH11 DI Counter Value Lo- Word |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--------------------------|
| 30025 | 0x0018 | word | CH0 Read AI Value |
| 30026 | 0x0019 | word | CH1 Read AI Value |
| 30027 | 0x001A | word | CH2 Read AI Value |
| 30028 | 0x001B | word | CH3 Read AI Value |
| 30033 | 0x0020 | word | CH0 Read AI Min Value |
| 30034 | 0x0021 | word | CH1 Read AI Min Value |
| 30035 | 0x0022 | word | CH2 Read AI Min Value |
| 30036 | 0x0023 | word | CH3 Read AI Min Value |
| 30041 | 0x0028 | word | CH0 Read AI Max Value |
| 30042 | 0x0029 | word | CH1 Read AI Max Value |
| 30043 | 0x002A | word | CH2 Read AI Max Value |
| 30044 | 0x002B | word | CH3 Read AI Max Value |
| 312289 | 0x3000 | 1 word | CH0 DI Value (low byte) |
| 312290 | 0x3001 | 1 word | CH1 DI Value (low byte) |
| 312291 | 0x3002 | 1 word | CH2 DI Value (low byte) |
| 312292 | 0x3003 | 1 word | CH3 DI Value (low byte) |
| 312293 | 0x3004 | 1 word | CH4 DI Value (low byte) |
| 312294 | 0x3005 | 1 word | CH5 DI Value (low byte) |
| 312295 | 0x3006 | 1 word | CH6 DI Value (low byte) |
| 312296 | 0x3007 | 1 word | CH7 DI Value (low byte) |
| 312297 | 0x3008 | 1 word | CH8 DI Value (low byte) |
| 312298 | 0x3009 | 1 word | CH9 DI Value (low byte) |
| 312299 | 0x300A | 1 word | CH10 DI Value (low byte) |
| 312300 | 0x300B | 1 word | CH11 DI Value (low byte) |

4xxxx Read/Write Registers (Functions 3, 6, 16)

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 40001 | 0x0000 | 1 word | CH0 DO Pulse Output Count Value Hi-Word |
| 40002 | 0x0001 | 1 word | CH0 DO Pulse Output Count Value Lo-Word |
| 40003 | 0x0002 | 1 word | CH1 DO Pulse Output Count Value Hi-Word |
| 40004 | 0x0003 | 1 word | CH1 DO Pulse Output Count Value Lo- Word |
| 40005 | 0x0004 | 1 word | CH2 DO Pulse Output Count Value Hi- Word |
| 40006 | 0x0005 | 1 word | CH2 DO Pulse Output Count Value Lo- Word |
| 40007 | 0x0006 | 1 word | CH3 DO Pulse Output Count Value Hi- Word |
| 40008 | 0x0007 | 1 word | CH3 DO Pulse Output Count Value Lo- Word |
| 40009 | 0x0008 | 1 word | CH4 DO Pulse Output Count Value Hi- Word |
| 40010 | 0x0009 | 1 word | CH4 DO Pulse Output Count Value Lo- Word |
| 40011 | 0x000A | 1 word | CH5 DO Pulse Output Count Value Hi- Word |
| 40012 | 0x000B | 1 word | CH5 DO Pulse Output Count Value Lo- Word |
| 40013 | 0x000C | 1 word | CH6 DO Pulse Output Count Value Hi- Word |
| 40014 | 0x000D | 1 word | CH6 DO Pulse Output Count Value Lo- Word |
| 40015 | 0x000E | 1 word | CH7 DO Pulse Output Count Value Hi- Word |
| 40016 | 0x000F | 1 word | CH7 DO Pulse Output Count Value Lo- Word |
| 40017 | 0x0010 | 1 word | CH8 DO Pulse Output Count Value Hi- Word |
| 40018 | 0x0011 | 1 word | CH8 DO Pulse Output Count Value Lo- Word |
| 40019 | 0x0012 | 1 word | CH9 DO Pulse Output Count Value Hi- Word |
| 40020 | 0x0013 | 1 word | CH9 DO Pulse Output Count Value Lo- Word |
| 40021 | 0x0014 | 1 word | CH10 DO Pulse Output Count Value Hi- Word |
| 40022 | 0x0015 | 1 word | CH10 DO Pulse Output Count Value Lo- Word |
| 40023 | 0x0016 | 1 word | CH11 DO Pulse Output Count Value Hi- Word |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 40024 | 0x0017 | 1 word | CH11 DO Pulse Output Count Value Lo- Word |
| 40025 | 0x0018 | 1 word | CH0 DO Pulse Low Signal Width Hi- Word |
| 40026 | 0x0019 | 1 word | CH0 DO Pulse Low Signal Width Lo- Word |
| 40027 | 0x001A | 1 word | CH1 DO Pulse Low Signal Width Hi- Word |
| 40028 | 0x001B | 1 word | CH1 DO Pulse Low Signal Width Lo- Word |
| 40029 | 0x001C | 1 word | CH2 DO Pulse Low Signal Width Hi- Word |
| 40030 | 0x001D | 1 word | CH2 DO Pulse Low Signal Width Lo- Word |
| 40031 | 0x001E | 1 word | CH3 DO Pulse Low Signal Width Hi- Word |
| 40032 | 0x001F | 1 word | CH3 DO Pulse Low Signal Width Lo- Word |
| 40033 | 0x0020 | 1 word | CH4 DO Pulse Low Signal Width Hi- Word |
| 40034 | 0x0021 | 1 word | CH4 DO Pulse Low Signal Width Lo- Word |
| 40035 | 0x0022 | 1 word | CH5 DO Pulse Low Signal Width Hi- Word |
| 40036 | 0x0023 | 1 word | CH5 DO Pulse Low Signal Width Lo- Word |
| 40037 | 0x0024 | 1 word | CH6 DO Pulse Low Signal Width Hi- Word |
| 40038 | 0x0025 | 1 word | CH6 DO Pulse Low Signal Width Lo- Word |
| 40039 | 0x0026 | 1 word | CH7 DO Pulse Low Signal Width Hi- Word |
| 40040 | 0x0027 | 1 word | CH7 DO Pulse Low Signal Width Lo- Word |
| 40041 | 0x0028 | 1 word | CH8 DO Pulse Low Signal Width Hi- Word |
| 40042 | 0x0029 | 1 word | CH8 DO Pulse Low Signal Width Lo- Word |
| 40043 | 0x002A | 1 word | CH9 DO Pulse Low Signal Width Hi- Word |
| 40044 | 0x002B | 1 word | CH9 DO Pulse Low Signal Width Lo- Word |
| 40045 | 0x002C | 1 word | CH10 DO Pulse Low Signal Width Hi- Word |
| 40046 | 0x002D | 1 word | CH10 DO Pulse Low Signal Width Lo- Word |
| 40047 | 0x002E | 1 word | CH11 DO Pulse Low Signal Width Hi- Word |
| 40048 | 0x002F | 1 word | CH11 DO Pulse Low Signal Width Lo- Word |
| 40049 | 0x0030 | 1 word | CH0 DO Pulse High Signal Width Hi- Word |
| 40050 | 0x0031 | 1 word | CH0 DO Pulse High Signal Width Lo- Word |
| 40051 | 0x0032 | 1 word | CH1 DO Pulse High Signal Width Hi- Word |
| 40052 | 0x0033 | 1 word | CH1 DO Pulse High Signal Width Lo- Word |
| 40053 | 0x0034 | 1 word | CH2 DO Pulse High Signal Width Hi- Word |
| 40054 | 0x0035 | 1 word | CH2 DO Pulse High Signal Width Lo- Word |
| 40055 | 0x0036 | 1 word | CH3 DO Pulse High Signal Width Hi- Word |
| 40056 | 0x0037 | 1 word | CH3 DO Pulse High Signal Width Lo- Word |
| 40057 | 0x0038 | 1 word | CH4 DO Pulse High Signal Width Hi- Word |
| 40058 | 0x0039 | 1 word | CH4 DO Pulse High Signal Width Lo- Word |
| 40059 | 0x003A | 1 word | CH5 DO Pulse High Signal Width Hi- Word |
| 40060 | 0x003B | 1 word | CH5 DO Pulse High Signal Width Lo- Word |
| 40061 | 0x003C | 1 word | CH6 DO Pulse High Signal Width Hi- Word |
| 40062 | 0x003D | 1 word | CH6 DO Pulse High Signal Width Lo- Word |
| 40063 | 0x003E | 1 word | CH7 DO Pulse High Signal Width Hi- Word |
| 40064 | 0x003F | 1 word | CH7 DO Pulse High Signal Width Lo- Word |
| 40065 | 0x0040 | 1 word | CH8 DO Pulse High Signal Width Hi- Word |
| 40066 | 0x0041 | 1 word | CH8 DO Pulse High Signal Width Lo- Word |
| 40067 | 0x0042 | 1 word | CH9 DO Pulse High Signal Width Hi- Word |
| 40068 | 0x0043 | 1 word | CH9 DO Pulse High Signal Width Lo- Word |
| 40069 | 0x0044 | 1 word | CH10 DO Pulse High Signal Width Hi- Word |
| 40070 | 0x0045 | 1 word | CH10 DO Pulse High Signal Width Lo- Word |
| 40071 | 0x0046 | 1 word | CH11 DO Pulse High Signal Width Hi- Word |
| 40072 | 0x0047 | 1 word | CH11 DO Pulse High Signal Width Lo- Word |
| 40073 | 0x0048 | 1 word | CH0 DO Mode 0: DO 1: Pulse |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 40074 | 0x0049 | 1 word | CH1 DO Mode 0: DO 1: Pulse |
| 40075 | 0x004A | 1 word | CH2 DO Mode 0: DO 1: Pulse |
| 40076 | 0x004B | 1 word | CH3 DO Mode 0: DO 1: Pulse |
| 40077 | 0x004C | 1 word | CH4 DO Mode 0: DO 1: Pulse |
| 40078 | 0x004D | 1 word | CH5 DO Mode 0: DO 1: Pulse |
| 40079 | 0x004E | 1 word | CH6 DO Mode 0: DO 1: Pulse |
| 40080 | 0x004F | 1 word | CH7 DO Mode 0: DO 1: Pulse |
| 40081 | 0x0050 | 1 word | CH8 DO Mode 0: DO 1: Pulse |
| 40082 | 0x0051 | 1 word | CH9 DO Mode 0: DO 1: Pulse |
| 40083 | 0x0052 | 1 word | CH10 DO Mode 0: DO 1: Pulse |
| 40084 | 0x0053 | 1 word | CH11 DO Mode 0: DO 1: Pulse |
| 40085 | 0x0054 | 1 word | CH0 DI Count Filter |
| 40086 | 0x0055 | 1 word | CH1 DI Count Filter |
| 40087 | 0x0056 | 1 word | CH2 DI Count Filter |
| 40088 | 0x0057 | 1 word | CH3 DI Count Filter |
| 40089 | 0x0058 | 1 word | CH4 DI Count Filter |
| 40090 | 0x0059 | 1 word | CH5 DI Count Filter |
| 40091 | 0x005A | 1 word | CH6 DI Count Filter |
| 40092 | 0x005B | 1 word | CH7 DI Count Filter |
| 40093 | 0x005C | 1 word | CH8 DI Count Filter |
| 40094 | 0x005D | 1 word | CH9 DI Count Filter |
| 40095 | 0x005E | 1 word | CH10 DI Count Filter |
| 40096 | 0x005F | 1 word | CH11 DI Count Filter |
| 40097 | 0x0060 | 1 word | CH0 DI Mode 0: DI 1: Count Others : return Illegal Data Value |
| 40098 | 0x0061 | 1 word | CH1 DI Mode 0: DI 1: Count Others : return Illegal Data Value |
| 40099 | 0x0062 | 1 word | CH2 DI Mode 0: DI 1: Count Others : return Illegal Data Value |
| 40100 | 0x0063 | 1 word | CH3 DI Mode 0: DI 1: Count Others : return Illegal Data Value |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 40101 | 0x0064 | 1 word | CH4 DI Mode 0: DI 1: Count Others : return Illegal Data Value |
| 40102 | 0x0065 | 1 word | CH5 DI Mode 0: DI 1: Count Others : return Illegal Data Value |
| 40103 | 0x0066 | 1 word | CH6 DI Mode 0: DI 1: Count Others : return Illegal Data Value |
| 40104 | 0x0067 | 1 word | CH7 DI Mode 0: DI 1: Count Others : return Illegal Data Value |
| 40105 | 0x0068 | 1 word | CH8 DI Mode 0: DI 1: Count Others : return Illegal Data Value |
| 40106 | 0x0069 | 1 word | CH9 DI Mode 0: DI 1: Count Others : return Illegal Data Value |
| 40107 | 0x006A | 1 word | CH10 DI Mode 0: DI 1: Count Others : return Illegal Data Value |
| 40108 | 0x006B | 1 word | CH11 DI Mode 0: DI 1: Count Others : return Illegal Data Value |
| 40109 | 0x006C | 1 word | CH0 AI set/get Enable 1:Enable , 0: Disable |
| 40110 | 0x006D | 1 word | CH1 AI set/get Enable 1:Enable , 0: Disable |
| 40111 | 0x006E | 1 word | CH2 AI set/get Enable 1:Enable , 0: Disable |
| 40112 | 0x006F | 1 word | CH3 AI set/get Enable 1:Enable , 0: Disable |
| 40129 | 0x0080 | 1 word | CH0 DO set/get wordvalue ; 0: Off 1:On |
| 40130 | 0x0081 | 1 word | CH1 DO set/get wordvalue ; 0: Off 1:On |
| 40131 | 0x0082 | 1 word | CH2 DO set/get wordvalue ; 0: Off 1:On |
| 40132 | 0x0083 | 1 word | CH3 DO set/get wordvalue ; 0: Off 1:On |
| 40133 | 0x0084 | 1 word | CH4 DO set/get wordvalue ; 0: Off 1:On |
| 40134 | 0x0085 | 1 word | CH5 DO set/get wordvalue ; 0: Off 1:On |
| 40135 | 0x0086 | 1 word | CH6 DO set/get wordvalue ; 0: Off 1:On |
| 40136 | 0x0087 | 1 word | CH7 DO set/get wordvalue ; 0: Off 1:On |
| 40137 | 0x0088 | 1 word | CH8 DO set/get wordvalue ; 0: Off 1:On |
| 40138 | 0x0089 | 1 word | CH9 DO set/get wordvalue ; 0: Off 1:On |
| 40139 | 0x008A | 1 word | CH10 DO set/get wordvalue ; 0: Off 1:On |
| 40140 | 0x008B | 1 word | CH11 DO set/get wordvalue ; 0: Off 1:On |
| 40141 | 0x008C | 1 word | CH0 DO set/get poweron wordvalue |
| 40142 | 0x008D | 1 word | CH1 DO set/get poweron wordvalue |
| 40143 | 0x008E | 1 word | CH2 DO set/get poweron wordvalue |
| 40144 | 0x008F | 1 word | CH3 DO set/get poweron wordvalue |
| 40145 | 0x0090 | 1 word | CH4 DO set/get poweron wordvalue |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 40146 | 0x0091 | 1 word | CH5 DO set/get poweron wordvalue |
| 40147 | 0x0092 | 1 word | CH6 DO set/get poweron wordvalue |
| 40148 | 0x0093 | 1 word | CH7 DO set/get poweron wordvalue |
| 40149 | 0x0094 | 1 word | CH8 DO set/get poweron wordvalue |
| 40150 | 0x0095 | 1 word | CH9 DO set/get poweron wordvalue |
| 40151 | 0x0096 | 1 word | CH10 DO set/get poweron wordvalue |
| 40152 | 0x0097 | 1 word | CH11 DO set/get poweron wordvalue |
| 40153 | 0x0098 | 1 word | CH0 DO set/get safe mode wordvalue |
| 40154 | 0x0099 | 1 word | CH1 DO set/get safe mode wordvalue |
| 40155 | 0x009A | 1 word | CH2 DO set/get safe mode wordvalue |
| 40156 | 0x009B | 1 word | CH3 DO set/get safe mode wordvalue |
| 40157 | 0x009C | 1 word | CH4 DO set/get safe mode wordvalue |
| 40158 | 0x009D | 1 word | CH5 DO set/get safe mode wordvalue |
| 40159 | 0x009E | 1 word | CH6 DO set/get safe mode wordvalue |
| 40160 | 0x009F | 1 word | CH7 DO set/get safe mode wordvalue |
| 40161 | 0x00A0 | 1 word | CH8 DO set/get safe mode wordvalue |
| 40162 | 0x00A1 | 1 word | CH9 DO set/get safe mode wordvalue |
| 40163 | 0x00A2 | 1 word | CH10 DO set/get safe mode wordvalue |
| 40164 | 0x00A3 | 1 word | CH11 DO set/get safe mode wordvalue |
| 40165 | 0x00A4 | 1 word | CH0 DO set/get pwm start wordvalue |
| 40166 | 0x00A5 | 1 word | CH1 DO set/get pwm start wordvalue |
| 40167 | 0x00A6 | 1 word | CH2 DO set/get pwm start wordvalue |
| 40168 | 0x00A7 | 1 word | CH3 DO set/get pwm start wordvalue |
| 40169 | 0x00A8 | 1 word | CH4 DO set/get pwm start wordvalue |
| 40170 | 0x00A9 | 1 word | CH5 DO set/get pwm start wordvalue |
| 40171 | 0x00AA | 1 word | CH6 DO set/get pwm start wordvalue |
| 40172 | 0x00AB | 1 word | CH7 DO set/get pwm start wordvalue |
| 40173 | 0x00AC | 1 word | CH8 DO set/get pwm start wordvalue |
| 40174 | 0x00AD | 1 word | CH9 DO set/get pwm start wordvalue |
| 40175 | 0x00AE | 1 word | CH10 DO set/get pwm start wordvalue |
| 40176 | 0x00AF | 1 word | CH11 DO set/get pwm start wordvalue |
| 40177 | 0x00B0 | 1 word | CH0 DO set/get pwm poweron wordvalue |
| 40178 | 0x00B1 | 1 word | CH1 DO set/get pwm poweron wordvalue |
| 40179 | 0x00B2 | 1 word | CH2 DO set/get pwm poweron wordvalue |
| 40180 | 0x00B3 | 1 word | CH3 DO set/get pwm poweron wordvalue |
| 40181 | 0x00B4 | 1 word | CH4 DO set/get pwm poweron wordvalue |
| 40182 | 0x00B5 | 1 word | CH5 DO set/get pwm poweron wordvalue |
| 40183 | 0x00B6 | 1 word | CH6 DO set/get pwm poweron wordvalue |
| 40184 | 0x00B7 | 1 word | CH7 DO set/get pwm poweron wordvalue |
| 40185 | 0x00B8 | 1 word | CH8 DO set/get pwm poweron wordvalue |
| 40186 | 0x00B9 | 1 word | CH9 DO set/get pwm poweron wordvalue |
| 40187 | 0x00BA | 1 word | CH10 DO set/get pwm poweron wordvalue |
| 40188 | 0x00BB | 1 word | CH11 DO set/get pwm poweron wordvalue |
| 40189 | 0x00BC | 1 word | CH0 DO set/get pwm safe mode wordvalue |
| 40190 | 0x00BD | 1 word | CH1 DO set/get pwm safe mode wordvalue |
| 40191 | 0x00BE | 1 word | CH2 DO set/get pwm safe mode wordvalue |
| 40192 | 0x00BF | 1 word | CH3 DO set/get pwm safe mode wordvalue |
| 40193 | 0x00C0 | 1 word | CH4 DO set/get pwm safe mode wordvalue |
| 40194 | 0x00C1 | 1 word | CH5 DO set/get pwm safe mode wordvalue |
| 40195 | 0x00C2 | 1 word | CH6 DO set/get pwm safe mode wordvalue |
| 40196 | 0x00C3 | 1 word | CH7 DO set/get pwm safe mode wordvalue |
| 40197 | 0x00C4 | 1 word | CH8 DO set/get pwm safe mode wordvalue |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 40198 | 0x00C5 | 1 word | CH9 DO set/get pwm safe mode wordvalue |
| 40199 | 0x00C6 | 1 word | CH10 DO set/get pwm safe mode wordvalue |
| 40200 | 0x00C7 | 1 word | CH11 DO set/get pwm safe mode wordvalue |
| 40201 | 0x00C8 | 1 word | CH0 DI set/get counter start word |
| 40202 | 0x00C9 | 1 word | CH1 DI set/get counter start word |
| 40203 | 0x00CA | 1 word | CH2 DI set/get counter start word |
| 40204 | 0x00CB | 1 word | CH3 DI set/get counter start word |
| 40205 | 0x00CC | 1 word | CH4 DI set/get counter start word |
| 40206 | 0x00CD | 1 word | CH5 DI set/get counter start word |
| 40207 | 0x00CE | 1 word | CH6 DI set/get counter start word |
| 40208 | 0x00CF | 1 word | CH7 DI set/get counter start word |
| 40209 | 0x00D0 | 1 word | CH8 DI set/get counter start word |
| 40210 | 0x00D1 | 1 word | CH9 DI set/get counter start word |
| 40211 | 0x00D2 | 1 word | CH10 DI set/get counter start word |
| 40212 | 0x00D3 | 1 word | CH11 DI set/get counter start word |
| 40213 | 0x00D4 | 1 word | CH0 DI set/get counter clear word |
| 40214 | 0x00D5 | 1 word | CH1 DI set/get counter clear word |
| 40215 | 0x00D6 | 1 word | CH2 DI set/get counter clear word |
| 40216 | 0x00D7 | 1 word | CH3 DI set/get counter clear word |
| 40217 | 0x00D8 | 1 word | CH4 DI set/get counter clear word |
| 40218 | 0x00D9 | 1 word | CH5 DI set/get counter clear word |
| 40219 | 0x00DA | 1 word | CH6 DI set/get counter clear word |
| 40220 | 0x00DB | 1 word | CH7 DI set/get counter clear word |
| 40221 | 0x00DC | 1 word | CH8 DI set/get counter clear word |
| 40222 | 0x00DD | 1 word | CH9 DI set/get counter clear word |
| 40223 | 0x00DE | 1 word | CH10 DI set/get counter clear word |
| 40224 | 0x00DF | 1 word | CH11 DI set/get counter clear word |
| 40225 | 0x00E0 | 1 word | CH0 DI clear/get overflow word |
| 40226 | 0x00E1 | 1 word | CH1 DI clear/get overflow word |
| 40227 | 0x00E2 | 1 word | CH2 DI clear/get overflow word |
| 40228 | 0x00E3 | 1 word | CH3 DI clear/get overflow word |
| 40229 | 0x00E4 | 1 word | CH4 DI clear/get overflow word |
| 40230 | 0x00E5 | 1 word | CH5 DI clear/get overflow word |
| 40231 | 0x00E6 | 1 word | CH6 DI clear/get overflow word |
| 40232 | 0x00E7 | 1 word | CH7 DI clear/get overflow word |
| 40233 | 0x00E8 | 1 word | CH8 DI clear/get overflow word |
| 40234 | 0x00E9 | 1 word | CH9 DI clear/get overflow word |
| 40235 | 0x00EA | 1 word | CH10 DI clear/get overflow word |
| 40236 | 0x00EB | 1 word | CH11 DI clear/get overflow word |
| 40237 | 0x00EC | 1 word | CH0 DI set/get trigger word |
| 40238 | 0x00ED | 1 word | CH1 DI set/get trigger word |
| 40239 | 0x00EE | 1 word | CH2 DI set/get trigger word |
| 40240 | 0x00EF | 1 word | CH3 DI set/get trigger word |
| 40241 | 0x00F0 | 1 word | CH4 DI set/get trigger word |
| 40242 | 0x00F1 | 1 word | CH5 DI set/get trigger word |
| 40243 | 0x00F2 | 1 word | CH6 DI set/get trigger word |
| 40244 | 0x00F3 | 1 word | CH7 DI set/get trigger word |
| 40245 | 0x00F4 | 1 word | CH8 DI set/get trigger word |
| 40246 | 0x00F5 | 1 word | CH9 DI set/get trigger word |
| 40247 | 0x00F6 | 1 word | CH10 DI set/get trigger word |
| 40248 | 0x00F7 | 1 word | CH11 DI set/get trigger word |
| 40249 | 0x00F8 | 1 word | CH0 DI set/get power on start word |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|-------------------------------------|
| 40250 | 0x00F9 | 1 word | CH1 DI set/get power on start word |
| 40251 | 0x00FA | 1 word | CH2 DI set/get power on start word |
| 40252 | 0x00FB | 1 word | CH3 DI set/get power on start word |
| 40253 | 0x00FC | 1 word | CH4 DI set/get power on start word |
| 40254 | 0x00FD | 1 word | CH5 DI set/get power on start word |
| 40255 | 0x00FE | 1 word | CH6 DI set/get power on start word |
| 40256 | 0x00FF | 1 word | CH7 DI set/get power on start word |
| 40257 | 0x0100 | 1 word | CH8 DI set/get power on start word |
| 40258 | 0x0101 | 1 word | CH9 DI set/get power on start word |
| 40259 | 0x0102 | 1 word | CH10 DI set/get power on start word |
| 40260 | 0x0103 | 1 word | CH11 DI set/get power on start word |
| 40261 | 0x0104 | 1 word | CH0 DI set/get safe start word |
| 40262 | 0x0105 | 1 word | CH1 DI set/get safe start word |
| 40263 | 0x0106 | 1 word | CH2 DI set/get safe start word |
| 40264 | 0x0107 | 1 word | CH3 DI set/get safe start word |
| 40265 | 0x0108 | 1 word | CH4 DI set/get safe start word |
| 40266 | 0x0109 | 1 word | CH5 DI set/get safe start word |
| 40267 | 0x010A | 1 word | CH6 DI set/get safe start word |
| 40268 | 0x010B | 1 word | CH7 DI set/get safe start word |
| 40269 | 0x010C | 1 word | CH8 DI set/get safe start word |
| 40270 | 0x010D | 1 word | CH9 DI set/get safe start word |
| 40271 | 0x010E | 1 word | CH10 DI set/get safe start word |
| 40272 | 0x010F | 1 word | CH11 DI set/get safe start word |
| 40273 | 0x0110 | 1 word | CH0 Power-off storage enable |
| 40274 | 0x0111 | 1 word | CH1 Power-off storage enable |
| 40275 | 0x0112 | 1 word | CH2 Power-off storage enable |
| 40276 | 0x0113 | 1 word | CH3 Power-off storage enable |
| 40277 | 0x0114 | 1 word | CH4 Power-off storage enable |
| 40278 | 0x0115 | 1 word | CH5 Power-off storage enable |
| 40279 | 0x0116 | 1 word | CH6 Power-off storage enable |
| 40280 | 0x0117 | 1 word | CH7 Power-off storage enable |
| 40281 | 0x0118 | 1 word | CH8 Power-off storage enable |
| 40282 | 0x0119 | 1 word | CH9 Power-off storage enable |
| 40283 | 0x011A | 1 word | CH10 Power-off storage enable |
| 40284 | 0x011B | 1 word | CH11 Power-off storage enable |
| 40285 | 0x011C | 1 word | AI Channel 0 Scaling Enable |
| 40286 | 0x011D | 1 word | AI Channel 1 Scaling Enable |
| 40287 | 0x011E | 1 word | AI Channel 2 Scaling Enable |
| 40288 | 0x011F | 1 word | AI Channel 3 Scaling Enable |
| 40289 | 0x0120 | 1 word | AI Channel 0 RAW Min Value |
| 40290 | 0x0121 | 1 word | AI Channel 1 RAW Min Value |
| 40291 | 0x0122 | 1 word | AI Channel 2 RAW Min Value |
| 40292 | 0x0123 | 1 word | AI Channel 3 RAW Min Value |
| 40293 | 0x0124 | 1 word | AI Channel 0 RAW Max Value |
| 40294 | 0x0125 | 1 word | AI Channel 1 RAW Max Value |
| 40295 | 0x0126 | 1 word | AI Channel 2 RAW Max Value |
| 40296 | 0x0127 | 1 word | AI Channel 3 RAW Max Value |
| 40297 | 0x0128 | 1 word | AI Channel 0 Scale Min Value |
| 40298 | 0x0129 | 1 word | AI Channel 1 Scale Min Value |
| 40299 | 0x012A | 1 word | AI Channel 2 Scale Min Value |
| 40300 | 0x012B | 1 word | AI Channel 3 Scale Min Value |
| 40301 | 0x012C | 1 word | AI Channel 0 Scale Max Value |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 40302 | 0x012D | 1 word | AI Channel 1 Scale Max Value |
| 40303 | 0x012E | 1 word | AI Channel 2 Scale Max Value |
| 40304 | 0x012F | 1 word | AI Channel 3 Scale Max Value |
| 40305 | 0x0130 | 1 word | AI Channel 0 Scale Value Lo-Word (float) |
| 40306 | 0x0131 | 1 word | AI Channel 0 Scale Value Hi-Word (float) |
| 40307 | 0x0132 | 1 word | AI Channel 1 Scale Value Lo-Word (float) |
| 40308 | 0x0133 | 1 word | AI Channel 1 Scale Value Hi-Word (float) |
| 40309 | 0x0134 | 1 word | AI Channel 2 Scale Value Lo-Word (float) |
| 40310 | 0x0135 | 1 word | AI Channel 2 Scale Value Hi-Word (float) |
| 40311 | 0x0136 | 1 word | AI Channel 3 Scale Value Lo-Word (float) |
| 40312 | 0x0137 | 1 word | AI Channel 3 Scale Value Hi-Word (float) |
| 40337 | 0x0150 | 1 word | Internal Register 00 Working Value |
| 40338 | 0x0151 | 1 word | Internal Register 01 Working Value |
| 40339 | 0x0152 | 1 word | Internal Register 02 Working Value |
| 40340 | 0x0153 | 1 word | Internal Register 03 Working Value |
| 40341 | 0x0154 | 1 word | Internal Register 04 Working Value |
| 40342 | 0x0155 | 1 word | Internal Register 05 Working Value |
| 40343 | 0x0156 | 1 word | Internal Register 06 Working Value |
| 40344 | 0x0157 | 1 word | Internal Register 07 Working Value |
| 40345 | 0x0158 | 1 word | Internal Register 08 Working Value |
| 40346 | 0x0159 | 1 word | Internal Register 09 Working Value |
| 40347 | 0x015A | 1 word | Internal Register 10 Working Value |
| 40348 | 0x015B | 1 word | Internal Register 11 Working Value |
| 40349 | 0x015C | 1 word | Internal Register 12 Working Value |
| 40350 | 0x015D | 1 word | Internal Register 13 Working Value |
| 40351 | 0x015E | 1 word | Internal Register 14 Working Value |
| 40352 | 0x015F | 1 word | Internal Register 15 Working Value |
| 40353 | 0x0160 | 1 word | Internal Register 16 Working Value |
| 40354 | 0x0161 | 1 word | Internal Register 17 Working Value |
| 40355 | 0x0162 | 1 word | Internal Register 18 Working Value |
| 40356 | 0x0163 | 1 word | Internal Register 19 Working Value |
| 40357 | 0x0164 | 1 word | Internal Register 20 Working Value |
| 40358 | 0x0165 | 1 word | Internal Register 21 Working Value |
| 40359 | 0x0166 | 1 word | Internal Register 22 Working Value |
| 40360 | 0x0167 | 1 word | Internal Register 23 Working Value |
| 40513 | 0x0200 | 1 word | CH0 AI Range 00 : +/-150mV 01: +/-500mV 02: +/-5V 03: +/-10V 04: 0-20mA 05: 4-20mA 06 : 0 -150mV 07 : 0 - 500mV 08: 0 - 5V 09: 0 -10V Others: return Illegal Data Value |

| Reference | Address | Data Type | Description |
|---------------------------------|------------------|-----------|--|
| 40514 | 0x0201 | 1 word | CH1 AI Range 00 : +/-150mV 01: +/-500mV 02: +/-5V 03: +/-10V 04: 0-20mA 05: 4-20mA 06 : 0 -150mV 07 : 0 - 500mV 08: 0 - 5V 09: 0 -10V Others: return Illegal Data Value |
| 40515 | 0x0202 | 1 word | CH2 AI Range 00: +/-150mV 01: +/-500mV 02: +/-5V 03: +/-10V 04: 0-20mA 05: 4-20mA 06 : 0 -150mV 07 : 0 - 500mV 08: 0 - 5V 09: 0 -10V Others: return Illegal Data Value |
| 40516 | 0x0203 | 1 word | CH3 AI Range 00 : +/-150mV 01: +/-500mV 02: +/-5V 03: +/-10V 04: 0-20mA 05: 4-20mA 06 : 0 -150mV 07 : 0 - 500mV 08: 0 - 5V 09: 0 -10V Others: return Illegal Data Value |
| System information (R/W) | | | |
| 41000 | 0x03E8 (1000) | 1 word | Load default setting, data=0x0078 |
| 44097 | 0x1000 | 2 word | IP address (need reboot) Word 0 Hi byte = 192 (0xC0) Word 0 Lo byte = 168 (0xA8) Word 1 Hi byte = 15 (0x0F) Word 1 Lo byte = 1 (0x01) IP address is "192.168.15.1" |
| 44098 | 0x1001 | 2 word | Subnet mask (need reboot) Word 0 Hi byte = 255 Word 0 Lo byte = 255 Word 1 Hi byte = 255 Word 1 Lo byte = 0 Subnet mask is "255.255.255.0" |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 44099 | 0x1002 | 2 word | Gateway (need reboot) Word 0 Hi byte = 192 Word 0 Lo byte = 168 Word 1 Hi byte = 15 Word 1 Lo byte = 1 Gateway is "192.168.15.1" |
| 44100 | 0x1003 | 1 word | Timeout for idle TCP/IP connection In sec |
| 44101 | 0x1004 | 6 word | System Local Time: Word 0= Sec: 00-59 Word 1= Min: 00-59 Word 2= Hour: 00-23 Word 3= Day: 01-31 Word 4= Month: 01-12 Word 5= Year: 2000-2099 |
| 44102 | 0x1005 | 1 word | System Local Time zone (1 ~ 63), refer to appendix time zone code. |
| 44103 | 0x1006 | 20 word | System Time Server Address Word 0 Hi byte = 192 Word 0 Lo byte = 168 Word 1 Hi byte = 15 Word 1 Lo byte = 1 Time Server Address is "192.168.15.1" |
| 44104 | 0x1007 | 2 word | DNS Server 1 IP Address Word 0 Hi byte = 192 Word 0 Lo byte = 168 Word 1 Hi byte = 15 Word 1 Lo byte = 1 DNS Server 1 IP="192.168.15.1" |
| 44105 | 0x1008 | 2 word | DNS Server 2 IP Address Word 0 Hi byte = 192 Word 0 Lo byte = 168 Word 1 Hi byte = 15 Word 1 Lo byte = 1 DNS Server 2 IP="192.168.15.1" |
| 44106 | 0x1009 | 1 word | Allow Web Access 1=Enable, 0=Disable |
| 44107 | 0x100A | 30 word | Module Location String (Terminated by '\0') |
| 44108 | 0x100B | 30 word | Module Description String (Terminated by '\0') |
| 44109 | 0x100C | 5 word | Module Password String (Terminated by '\0') |
| 44110 | 0x100D | 1 word | External Uart Packet RW Timeout Interval (in ms) |
| 44111 | 0x100E | 1 word | Lost Host Connection Timeout Interval (Will enter safe mode if timeout once occurred) |
| 44112 | 0x100F | 1 word | Lost Host Connection Timeout Flag 1=Set, 0=Clear |
| 44113 | 0x1010 | 1 word | SNMP Enable |
| 44114 | 0x1011 | 10 word | SNMP Read Community Name String |
| 44115 | 0x1012 | 10 word | SNMP Contact String |
| 44116 | 0x1013 | 10 word | SNMP Location String |
| 44117 | 0x1014 | 10 word | SNMP RW Community Name String |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 44118 | 0x1015 | 20 word | SNMP Manager IP0 (Server Name or IP String) |
| 44119 | 0x1016 | 20 word | SNMP Manager IP1 (Server Name or IP String) |
| 44120 | 0x1017 | 20 word | SNMP Manager IP2 (Server Name or IP String) |
| 44121 | 0x1018 | 20 word | SNMP Manager IP3 (Server Name or IP String) |
| 44122 | 0x1019 | 20 word | SNMP Manager IP4 (Server Name or IP String) |
| 44123 | 0x101A | 20 word | SNMP Manager IP5 (Server Name or IP String) |
| 44124 | 0x101B | 20 word | SNMP Manager IP6 (Server Name or IP String) |
| 44125 | 0x101C | 20 word | SNMP Manager IP7 (Server Name or IP String) |
| 44126 | 0x101D | 20 word | SNMP Manager IP8 (Server Name or IP String) |
| 44127 | 0x101E | 20 word | SNMP Manager IP9 (Server Name or IP String) |
| 44128 | 0x101F | 1 word | IP Configuration Type |
| 44129 | 0x1020 | 1 word | IP Filter Global Enable Flag |
| 44130 | 0x1021 | 10 word | IP Filter Enable (all entries) |
| 44131 | 0x1022 | 20 word | IP Filter Address (all entries) |
| 44132 | 0x1023 | 20 word | IP Filter Mask (all entries) |
| 43329 | 0x0D00 | 2 word | CH0 DI - Counter mode value |
| 43330 | 0x0D01 | 2 word | CH1 DI - Counter mode value |
| 43331 | 0x0D02 | 2 word | CH2 DI - Counter mode value |
| 43332 | 0x0D03 | 2 word | CH3 DI - Counter mode value |
| 43333 | 0x0D04 | 2 word | CH4 DI - Counter mode value |
| 43334 | 0x0D05 | 2 word | CH5 DI - Counter mode value |
| 43335 | 0x0D06 | 2 word | CH6 DI - Counter mode value |
| 43336 | 0x0D07 | 2 word | CH7 DI - Counter mode value |
| 43337 | 0x0D08 | 2 word | CH8 DI - Counter mode value |
| 43338 | 0x0D09 | 2 word | CH9 DI - Counter mode value |
| 43339 | 0x0D0A | 2 word | CH10 DI - Counter mode value |
| 43340 | 0x0D0B | 2 word | CH11 DI - Counter mode value |

5xxxx Write Registers (Function 8)

| Sub-function | Data Field (Request) | Data Field (Response) | Description |
|--------------|----------------------|-----------------------|----------------------------|
| 0x0001 | 0xFF00 | Echo Request Data | Reboot |
| 0x0001 | 0x55AA | Echo Request Data | Reset with Factory default |

ioLogik E2260 Modbus Mapping

0xxxx Read/Write Coils (Functions 1, 5, 15)

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 00001 | 0x0000 | 1bit | CH0 RTD Reset Minimum Value <R> Always 0 <W> 1=Reset to current value, 0=return illegal data value |
| 00002 | 0x0001 | 1 bit | CH1 RTD Reset Minimum Value |
| 00003 | 0x0002 | 1 bit | CH2 RTD Reset Minimum Value |
| 00004 | 0x0003 | 1 bit | CH3 RTD Reset Minimum Value |
| 00005 | 0x0004 | 1 bit | CH4 RTD Reset Minimum Value |
| 00006 | 0x0005 | 1 bit | CH5 RTD Reset Minimum Value |
| 00007 | 0x0006 | 1 bit | Virtual CH6 RTD Reset Maximum Value |
| 00008 | 0x0007 | 1 bit | Virtual CH7 RTD Reset Minimum Value |
| 00009 | 0x0008 | 1 bit | Virtual CH8 RTD Reset Minimum Value |
| 00010 | 0x0009 | 1 bit | Virtual CH9 RTD Reset Minimum Value |
| 00011 | 0x000A | 1 bit | Virtual CH10 RTD Reset Minimum Value |
| 00012 | 0x000B | 1 bit | Virtual CH11 RTD Reset Minimum Value |
| 00013 | 0x000C | 1 bit | CH0 RTD Reset Maximum Value |
| 00014 | 0x000D | 1 bit | CH1 RTD Reset Maximum Value |
| 00015 | 0x000E | 1 bit | CH2 RTD Reset Maximum Value |
| 00016 | 0x000F | 1 bit | CH3 RTD Reset Maximum Value |
| 00017 | 0x0010 | 1 bit | CH4 RTD Reset Maximum Value |
| 00018 | 0x0011 | 1 bit | CH5 RTD Reset Maximum Value |
| 00019 | 0x0012 | 1 bit | Virtual CH6 RTD Reset Maximum Value |
| 00020 | 0x0013 | 1 bit | Virtual CH7 RTD Reset Maximum Value |
| 00021 | 0x0014 | 1 bit | Virtual CH8 RTD Reset Maximum Value |
| 00022 | 0x0015 | 1 bit | Virtual CH9 RTD Reset Maximum Value |
| 00023 | 0x0016 | 1 bit | Virtual CH10 RTD Reset Maximum Value |
| 00024 | 0x0017 | 1 bit | Virtual CH11 RTD Reset Maximum Value |
| 00025 | 0x0018 | 1 bit | CH0 RTD Enable <RW> 0=Disable, 1=Enable |
| 00026 | 0x0019 | 1 bit | CH1 RTD Enable |
| 00027 | 0x001A | 1 bit | CH2 RTD Enable |
| 00028 | 0x001B | 1 bit | CH3 RTD Enable |
| 00029 | 0x001C | 1 bit | CH4 RTD Enable |
| 00030 | 0x001D | 1 bit | CH5 RTD Enable |
| 00031 | 0x001E | 1 bit | CH0 DO Status <RW> 0=OFF, 1=ON |
| 00032 | 0x001F | 1 bit | CH1 DO Status |
| 00033 | 0x0020 | 1 bit | CH2 DO Status |
| 00034 | 0x0021 | 1 bit | CH3 DO Status |
| 00035 | 0x0022 | 1 bit | CH0 DO Power-On Status <RW> 0=OFF, 1=ON |
| 00036 | 0x0023 | 1 bit | CH1 DO Power-On Status |
| 00037 | 0x0024 | 1 bit | CH2 DO Power-On Status |
| 00038 | 0x0025 | 1 bit | CH3 DO Power-On Status |
| 00039 | 0x0026 | 1 bit | CH0 DO Safe Status <RW> 0=OFF, 1=ON |
| 00040 | 0x0027 | 1 bit | CH1 DO Safe Status |
| 00041 | 0x0028 | 1 bit | CH2 DO Safe Status |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 00042 | 0x0029 | 1 bit | CH3 DO Safe Status |
| 00043 | 0x002A | 1 bit | CH0 DO Pulse Output Status <RW> 0=Stop, 1=Start |
| 00044 | 0x002B | 1 bit | CH1 DO Pulse Output Status |
| 00045 | 0x002C | 1 bit | CH2 DO Pulse Output Status |
| 00046 | 0x002D | 1 bit | CH3 DO Pulse Output Status |
| 00047 | 0x002E | 1 bit | CH0 DO Power-On Pulse Output Status <RW> 0=Stop, 1=Start |
| 00048 | 0x002F | 1 bit | CH1 DO Power-On Pulse Output Status |
| 00049 | 0x0030 | 1 bit | CH2 DO Power-On Pulse Output Status |
| 00050 | 0x0031 | 1 bit | CH3 DO Power-On Pulse Output Status |
| 00051 | 0x0032 | 1 bit | CH0 DO Safe Mode Pulse Output Status <RW> 0=Stop, 1=Start |
| 00052 | 0x0033 | 1 bit | CH1 DO Safe Mode Pulse Output Status |
| 00053 | 0x0034 | 1 bit | CH2 DO Safe Mode Pulse Output Status |
| 00054 | 0x0035 | 1 bit | CH3 DO Safe Mode Pulse Output Status |

3xxxx Read Only Registers (Function 4)

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 30001 | 0x0000 | 1 word | CH0 RTD Value <R> 0~65535, Unit:0.1 (Ohm, Celsius, Fahrenheit) |
| 30002 | 0x0001 | 1 word | CH1 RTD Value |
| 30003 | 0x0002 | 1 word | CH2 RTD Value |
| 30004 | 0x0003 | 1 word | CH3 RTD Value |
| 30005 | 0x0004 | 1 word | CH4 RTD Value |
| 30006 | 0x0005 | 1 word | CH5 RTD Value |
| 30007 | 0x0006 | 1 word | Virtual CH6 RTD Value <R> 0~65535, Unit:0.1 (Celsius, Fahrenheit) |
| 30008 | 0x0007 | 1 word | Virtual CH7 RTD Value |
| 30009 | 0x0008 | 1 word | Virtual CH8 RTD Value |
| 30010 | 0x0009 | 1 word | Virtual CH9 RTD Value |
| 30011 | 0x000A | 1 word | Virtual CH10 RTD Value |
| 30012 | 0x000B | 1 word | Virtual CH11 RTD Value |
| 30013 | 0x000C | 1 word | CH0 RTD Minimum Value <R> 0~65535, Unit:0.1 (Ohm, Celsius, Fahrenheit) |
| 30014 | 0x000D | 1 word | CH1 RTD Minimum Value |
| 30015 | 0x000E | 1 word | CH2 RTD Minimum Value |
| 30016 | 0x000F | 1 word | CH3 RTD Minimum Value |
| 30017 | 0x0010 | 1 word | CH4 RTD Minimum Value |
| 30018 | 0x0011 | 1 word | CH5 RTD Minimum Value |
| 30019 | 0x0012 | 1 word | Virtual CH6 RTD Minimum Value |
| 30020 | 0x0013 | 1 word | Virtual CH7 RTD Minimum Value |
| 30021 | 0x0014 | 1 word | Virtual CH8 RTD Minimum Value |
| 30022 | 0x0015 | 1 word | Virtual CH9 RTD Minimum Value |
| 30023 | 0x0016 | 1 word | Virtual CH10 RTD Minimum Value |
| 30024 | 0x0017 | 1 word | Virtual CH11 RTD Minimum Value |
| 30025 | 0x0018 | 1 word | CH0 RTD Maximum Value <R> 0~65535, Unit:0.1 (Ohm, Celsius, Fahrenheit) |
| 30026 | 0x0019 | 1 word | CH1 RTD Maximum Value |
| 30027 | 0x001A | 1 word | CH2 RTD Maximum Value |
| 30028 | 0x001B | 1 word | CH3 RTD Maximum Value |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|-----------------------|
| 30029 | 0x001C | 1 word | CH4 RTD Maximum Value |
| 30030 | 0x001D | 1 word | CH5 RTD Maximum Value |
| 30031 | 0x001E | 1 word | CH1 RTD Maximum Value |
| 30032 | 0x001F | 1 word | CH2 RTD Maximum Value |
| 30033 | 0x0020 | 1 word | CH2 RTD Maximum Value |
| 30034 | 0x0021 | 1 word | CH3 RTD Maximum Value |
| 30035 | 0x0022 | 1 word | CH4 RTD Maximum Value |
| 30036 | 0x0023 | 1 word | CH5 RTD Maximum Value |

4xxxx Read/Write Registers (Functions 3, 6, 16)

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 40001 | 0x0000 | 1 word | CH0 DO Pulse Output Count Value Hi Word <RW> 0~4294967295 |
| 40002 | 0x0001 | 1 word | CH0 DO Pulse Output Count Value Lo Word <RW> 0~4294967295 |
| 40003 | 0x0002 | 1 word | CH1 DO Pulse Output Count Value Hi Word |
| 40004 | 0x0003 | 1 word | CH1 DO Pulse Output Count Value Lo Word |
| 40005 | 0x0004 | 1 word | CH2 DO Pulse Output Count Value Hi Word |
| 40006 | 0x0005 | 1 word | CH2 DO Pulse Output Count Value Lo Word |
| 40007 | 0x0006 | 1 word | CH3 DO Pulse Output Count Value Hi Word |
| 40008 | 0x0007 | 1 word | CH3 DO Pulse Output Count Value Lo Word |
| 40009 | 0x0008 | 1 word | CH0 DO Pulse Output Low Signal Width – Hi Word <RW> 0~4294967295 |
| 40010 | 0x0009 | 1 word | CH0 DO Pulse Output Low Signal Width – Lo Word <RW> 0~4294967295 |
| 40011 | 0x000A | 1 word | CH1 DO Pulse Output Low Signal Width – Hi Word |
| 40012 | 0x000B | 1 word | CH1 DO Pulse Output Low Signal Width – Lo Word |
| 40013 | 0x000C | 1 word | CH2 DO Pulse Output Low Signal Width – Hi Word |
| 40014 | 0x000D | 1 word | CH2 DO Pulse Output Low Signal Width – Lo Word |
| 40015 | 0x000E | 1 word | CH3 DO Pulse Output Low Signal Width – Hi Word |
| 40016 | 0x000F | 1 word | CH3 DO Pulse Output Low Signal Width – Lo Word |
| 40017 | 0x0010 | 1 word | CH0 DO Pulse Output High Signal Width – Hi Word <RW> 0~4294967295 |
| 40018 | 0x0011 | 1 word | CH0 DO Pulse Output High Signal Width – Lo Word <RW> 0~4294967295 |
| 40019 | 0x0012 | 1 word | CH1 DO Pulse Output High Signal Width – Hi Word |
| 40020 | 0x0013 | 1 word | CH1 DO Pulse Output High Signal Width – Lo Word |
| 40021 | 0x0014 | 1 word | CH2 DO Pulse Output High Signal Width – Hi Word |
| 40022 | 0x0015 | 1 word | CH2 DO Pulse Output High Signal Width – Lo Word |
| 40023 | 0x0016 | 1 word | CH3 DO Pulse Output High Signal Width – Hi Word |
| 40024 | 0x0017 | 1 word | CH3 DO Pulse Output High Signal Width – Lo Word |
| 40025 | 0x0018 | 1 word | CH0 DO Operation Mode <RW> 0=DO Mode, 1=Pulse Output Mode |
| 40026 | 0x0019 | 1 word | CH1 DO Operation Mode |
| 40027 | 0x001A | 1 word | CH2 DO Operation Mode |
| 40028 | 0x001B | 1 word | CH3 DO Operation Mode |
| 40029 | 0x001C | 1 word | CH0 RTD Engineering Unit 0=Ohm, 1=Celsius, 2=Fahrenheit |
| 40030 | 0x001D | 1 word | CH1 RTD Engineering Unit |
| 40031 | 0x001E | 1 word | CH2 RTD Engineering Unit |
| 40032 | 0x001F | 1 word | CH3 RTD Engineering Unit |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 40033 | 0x0020 | 1 word | CH4 RTD Engineering Unit |
| 40034 | 0x0021 | 1 word | CH5 RTD Engineering Unit |
| 40035 | 0x0022 | 1 word | Virtual CH6 RTD Engineering Unit 1=Celsius, 2=Fahrenheit |
| 40036 | 0x0023 | 1 word | Virtual CH7 RTD Engineering Unit |
| 40037 | 0x0024 | 1 word | Virtual CH8 RTD Engineering Unit |
| 40038 | 0x0025 | 1 word | Virtual CH9 RTD Engineering Unit |
| 40039 | 0x0026 | 1 word | Virtual CH10 RTD Engineering Unit |
| 40040 | 0x0027 | 1 word | Virtual CH11 RTD Engineering Unit |
| 40041 | 0x0028 | 1 word | CH0 RTD Sensor Type 0=PT50 1=PT100 2=PT200 3=PT500 4=PT1000 5=JPT100 6=JPT200 7=JPT500 8=JPT1000 9=NI100 10=NI200 11=NI500 12=NI1000 13=NI120 14=310 Ohm 15=620 Ohm 16=1250 Ohm 17=2500 Ohm |
| 40042 | 0x0029 | 1 word | CH1 RTD Sensor Type |
| 40043 | 0x002A | 1 word | CH2 RTD Sensor Type |
| 40044 | 0x002B | 1 word | CH3 RTD Sensor Type |
| 40045 | 0x002C | 1 word | CH4 RTD Sensor Type |
| 40046 | 0x002D | 1 word | CH5 RTD Sensor Type |
| 40047 | 0x002E | 1 word | CH6 RTD Sensor Type 20=AVG 21=DIV |
| 40048 | 0x002F | 1 word | Virtual CH7 RTD Sensor Type |
| 40049 | 0x0030 | 1 word | Virtual CH8 RTD Sensor Type |
| 40050 | 0x0031 | 1 word | Virtual CH9 RTD Sensor Type |
| 40051 | 0x0032 | 1 word | Virtual CH10 RTD Sensor Type |
| 40052 | 0x0033 | 1 word | Virtual CH11 RTD Sensor Type |
| 40053 | 0x0034 | 1 word | CH0 RTD Reset Minimum Value <R> Always 0 <W> 1=Reset, 0=return illegal data value |
| 40054 | 0x0035 | 1 word | CH1 RTD Reset Minimum Value |
| 40055 | 0x0036 | 1 word | CH2 RTD Reset Minimum Value |
| 40056 | 0x0037 | 1 word | CH3 RTD Reset Minimum Value |
| 40057 | 0x0038 | 1 word | CH4 RTD Reset Minimum Value |
| 40058 | 0x0039 | 1 word | CH5 RTD Reset Minimum Value |
| 40059 | 0x003A | 1 word | Virtual CH6 RTD Reset Minimum Value |
| 40060 | 0x003B | 1 word | Virtual CH7 RTD Reset Minimum Value |
| 40061 | 0x003C | 1 word | Virtual CH8 RTD Reset Minimum Value |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 40062 | 0x003D | 1 word | Virtual CH9 RTD Reset Minimum Value |
| 40063 | 0x003E | 1 word | Virtual CH10 RTD Reset Minimum Value |
| 40064 | 0x003F | 1 word | Virtual CH11 RTD Reset Minimum Value |
| 40065 | 0x0040 | 1 word | CH0 RTD Reset Maximum Value <R> Always 0 <W> 1=Reset, 0=return illegal data value |
| 40066 | 0x0041 | 1 word | CH1 RTD Reset Maximum Value |
| 40067 | 0x0042 | 1 word | CH2 RTD Reset Maximum Value |
| 40068 | 0x0043 | 1 word | CH3 RTD Reset Maximum Value |
| 40069 | 0x0044 | 1 word | CH4 RTD Reset Maximum Value |
| 40070 | 0x0045 | 1 word | CH5 RTD Reset Maximum Value |
| 40071 | 0x0046 | 1 word | Virtual CH6 RTD Reset Maximum Value |
| 40072 | 0x0047 | 1 word | Virtual CH7 RTD Reset Maximum Value |
| 40073 | 0x0048 | 1 word | Virtual CH8 RTD Reset Maximum Value |
| 40074 | 0x0049 | 1 word | Virtual CH9 RTD Reset Maximum Value |
| 40075 | 0x004A | 1 word | Virtual CH10 RTD Reset Maximum Value |
| 40076 | 0x004B | 1 word | Virtual CH11 RTD Reset Maximum Value |
| 40077 | 0x004C | 1 word | CH0 DO Status <RW> 0=OFF, 1=ON |
| 40078 | 0x004D | 1 word | CH1 DO Status |
| 40079 | 0x004E | 1 word | CH2 DO Status |
| 40080 | 0x004F | 1 word | CH3 DO Status |
| 40081 | 0x0050 | 1 word | CH0 DO Power On Status <RW> 0=OFF, 1=ON |
| 40082 | 0x0051 | 1 word | CH1 DO Status |
| 40083 | 0x0052 | 1 word | CH2 DO Status |
| 40084 | 0x0053 | 1 word | CH3 DO Status |
| 40085 | 0x0054 | 1 word | CH0 DO Safe Status <RW> 0=OFF, 1=ON |
| 40086 | 0x0055 | 1 word | CH1 DO Status |
| 40087 | 0x0056 | 1 word | CH2 DO Status |
| 40088 | 0x0057 | 1 word | CH3 DO Status |
| 40089 | 0x0058 | 1 word | CH0 DO Pulse Output Status <RW> 0=Stop, 1=Start |
| 40090 | 0x0059 | 1 word | CH1 DO Pulse Output Status |
| 40091 | 0x005A | 1 word | CH2 DO Pulse Output Status |
| 40092 | 0x005B | 1 word | CH3 DO Pulse Output Status |
| 40093 | 0x005C | 1 word | CH0 DO Power On Pulse Output Status <RW> 0=Stop, 1=Start |
| 40094 | 0x005D | 1 word | CH1 DO Pulse Output Status |
| 40095 | 0x005E | 1 word | CH2 DO Pulse Output Status |
| 40096 | 0x005F | 1 word | CH3 DO Pulse Output Status |
| 40097 | 0x0060 | 1 word | CH0 DO Safe Pulse Output Status <RW> 0=Stop, 1=Start |
| 40098 | 0x0061 | 1 word | CH1 DO Pulse Output Status |
| 40099 | 0x0062 | 1 word | CH2 DO Pulse Output Status |
| 40100 | 0x0063 | 1 word | CH3 DO Pulse Output Status |
| 40101 | 0x0064 | 1 word | CH0 RTD Enable <RW> 0 =Disable, 1=Enable |
| 40102 | 0x0065 | 1 word | CH1 RTD Enable |
| 40103 | 0x0066 | 1 word | CH2 RTD Enable |
| 40104 | 0x0067 | 1 word | CH3 RTD Enable |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|------------------------------------|
| 40105 | 0x0068 | 1 word | CH4 RTD Enable |
| 40106 | 0x0069 | 1 word | CH5 RTD Enable |
| 40337 | 0x0150 | 1 word | Internal Register 00 Working Value |
| 40338 | 0x0151 | 1 word | Internal Register 01 Working Value |
| 40339 | 0x0152 | 1 word | Internal Register 02 Working Value |
| 40340 | 0x0153 | 1 word | Internal Register 03 Working Value |
| 40341 | 0x0154 | 1 word | Internal Register 04 Working Value |
| 40342 | 0x0155 | 1 word | Internal Register 05 Working Value |
| 40343 | 0x0156 | 1 word | Internal Register 06 Working Value |
| 40344 | 0x0157 | 1 word | Internal Register 07 Working Value |
| 40345 | 0x0158 | 1 word | Internal Register 08 Working Value |
| 40346 | 0x0159 | 1 word | Internal Register 09 Working Value |
| 40347 | 0x015A | 1 word | Internal Register 10 Working Value |
| 40348 | 0x015B | 1 word | Internal Register 11 Working Value |
| 40349 | 0x015C | 1 word | Internal Register 12 Working Value |
| 40350 | 0x015D | 1 word | Internal Register 13 Working Value |
| 40351 | 0x015E | 1 word | Internal Register 14 Working Value |
| 40352 | 0x015F | 1 word | Internal Register 15 Working Value |
| 40353 | 0x0160 | 1 word | Internal Register 16 Working Value |
| 40354 | 0x0161 | 1 word | Internal Register 17 Working Value |
| 40355 | 0x0162 | 1 word | Internal Register 18 Working Value |
| 40356 | 0x0163 | 1 word | Internal Register 19 Working Value |
| 40357 | 0x0164 | 1 word | Internal Register 20 Working Value |
| 40358 | 0x0165 | 1 word | Internal Register 21 Working Value |
| 40359 | 0x0166 | 1 word | Internal Register 22 Working Value |
| 40360 | 0x0167 | 1 word | Internal Register 23 Working Value |

ioLogik E2262 Modbus Mapping

0xxxx Read/Write Coils (Functions 1, 5, 15)

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 00001 | 0x0000 | 1 bit | CH0 TC Reset Minimum Value <R> Always 0 <W> 1=Reset to current value, |
| 00002 | 0x0001 | 1 bit | CH1 TC Reset Minimum Value |
| 00003 | 0x0002 | 1 bit | CH2 TC Reset Minimum Value |
| 00004 | 0x0003 | 1 bit | CH3 TC Reset Minimum Value |
| 00005 | 0x0004 | 1 bit | CH4 TC Reset Minimum Value |
| 00006 | 0x0005 | 1 bit | CH5 TC Reset Minimum Value |
| 00007 | 0x0006 | 1 bit | CH6 TC Reset Minimum Value |
| 00008 | 0x0007 | 1 bit | CH7 TC Reset Minimum Value |
| 00009 | 0x0008 | 1 bit | Virtual CH8 TC Reset Maximum Value |
| 00010 | 0x0009 | 1 bit | Virtual CH9 TC Reset Minimum Value |
| 00011 | 0x000A | 1 bit | Virtual CH10 TC Reset Minimum Value |
| 00012 | 0x000B | 1 bit | Virtual CH11 TC Reset Minimum Value |
| 00013 | 0x000C | 1 bit | Virtual CH12 TC Reset Minimum Value |
| 00014 | 0x000D | 1 bit | Virtual CH13 TC Reset Minimum Value |
| 00015 | 0x000E | 1 bit | Virtual CH14 TC Reset Minimum Value |
| 00016 | 0x000F | 1 bit | Virtual CH15 TC Reset Minimum Value |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 00017 | 0x0010 | 1 bit | CH0 TC Reset Maximum Value |
| 00018 | 0x0011 | 1 bit | CH1 TC Reset Maximum Value |
| 00019 | 0x0012 | 1 bit | CH2 TC Reset Maximum Value |
| 00020 | 0x0013 | 1 bit | CH3 TC Reset Maximum Value |
| 00021 | 0x0014 | 1 bit | CH4 TC Reset Maximum Value |
| 00022 | 0x0015 | 1 bit | CH5 TC Reset Maximum Value |
| 00023 | 0x0016 | 1 bit | CH6 TC Reset Maximum Value |
| 00024 | 0x0017 | 1 bit | CH7 TC Reset Maximum Value |
| 00025 | 0x0018 | 1 bit | Virtual CH8 TC Reset Maximum Value |
| 00026 | 0x0019 | 1 bit | Virtual CH9 TC Reset Maximum Value |
| 00027 | 0x001A | 1 bit | Virtual CH10 TC Reset Maximum Value |
| 00028 | 0x001B | 1 bit | Virtual CH11 TC Reset Maximum Value |
| 00029 | 0x001C | 1 bit | Virtual CH12 TC Reset Maximum Value |
| 00030 | 0x001D | 1 bit | Virtual CH13 TC Reset Maximum Value |
| 00031 | 0x001E | 1 bit | Virtual CH14 TC Reset Maximum Value |
| 00032 | 0x001F | 1 bit | Virtual CH15 TC Reset Maximum Value |
| 00033 | 0x0020 | 1 bit | CH0 TC Enable <RW> 0=Disable, 1=Enable |
| 00034 | 0x0021 | 1 bit | CH1 TC Enable |
| 00035 | 0x0022 | 1 bit | CH2 TC Enable |
| 00036 | 0x0023 | 1 bit | CH3 TC Enable |
| 00037 | 0x0024 | 1 bit | CH4 TC Enable |
| 00038 | 0x0025 | 1 bit | CH5 TC Enable |
| 00039 | 0x0026 | 1 bit | CH6 TC Enable |
| 00040 | 0x0027 | 1 bit | CH7 TC Enable |
| 00041 | 0x0028 | 1 bit | CH0 DO Status <RW> 0=OFF, 1=ON |
| 00042 | 0x0029 | 1 bit | CH1 DO Status |
| 00043 | 0x002A | 1 bit | CH2 DO Status |
| 00044 | 0x002B | 1 bit | CH3 DO Status |
| 00045 | 0x002C | 1 bit | CH0 DO Power-On Status <RW> 0=OFF, 1=ON |
| 00046 | 0x002D | 1 bit | CH1 DO Power-On Status |
| 00047 | 0x002E | 1 bit | CH2 DO Power-On Status |
| 00048 | 0x002F | 1 bit | CH3 DO Power-On Status |
| 00049 | 0x0030 | 1 bit | CH0 DO Safe Status <RW> 0=OFF, 1=ON |
| 00050 | 0x0031 | 1 bit | CH1 DO Safe Status |
| 00051 | 0x0032 | 1 bit | CH2 DO Safe Status |
| 00052 | 0x0033 | 1 bit | CH3 DO Safe Status |
| 00053 | 0x0034 | 1 bit | CH0 DO Pulse Output Status <RW> 0=Stop, 1=Start |
| 00054 | 0x0035 | 1 bit | CH1 DO Pulse Output Status |
| 00055 | 0x0036 | 1 bit | CH2 DO Pulse Output Status |
| 00056 | 0x0037 | 1 bit | CH3 DO Pulse Output Status |
| 00057 | 0x0038 | 1 bit | CH0 DO Power-On Pulse Output Status <RW> 0=Stop, 1=Start |
| 00058 | 0x0039 | 1 bit | CH1 DO Power-On Pulse Output Status |
| 00059 | 0x003A | 1 bit | CH2 DO Power-On Pulse Output Status |
| 00060 | 0x003B | 1 bit | CH3 DO Power-On Pulse Output Status |
| 00061 | 0x003C | 1 bit | CH0 DO Safe Mode Pulse Output Status <RW> 0=Stop, 1=Start |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--------------------------------------|
| 00062 | 0x003D | 1 bit | CH1 DO Safe Mode Pulse Output Status |
| 00063 | 0x003E | 1 bit | CH2 DO Safe Mode Pulse Output Status |
| 00064 | 0x003F | 1 bit | CH3 DO Safe Mode Pulse Output Status |

3xxxx Read Only Registers (Function 4)

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 30001 | 0x0000 | 1 word | CH0 TC Value Hi Word <R> 0~4294967295, Unit:0.1 (Celsius, Fahrenheit) 0.0001(mV) |
| 30002 | 0x0001 | 1 word | CH0 TC Value Lo Word <R> 0~4294967295, Unit:0.1 (Celsius, Fahrenheit) 0.0001(mV) |
| 30003 | 0x0002 | 1 word | CH1 TC Value Hi Word |
| 30004 | 0x0003 | 1 word | CH1 TC Value Lo Word |
| 30005 | 0x0004 | 1 word | CH2 TC Value Hi Word |
| 30006 | 0x0005 | 1 word | CH2 TC Value Lo Word |
| 30007 | 0x0006 | 1 word | CH3 TC Value Hi Word |
| 30008 | 0x0007 | 1 word | CH3 TC Value Lo Word |
| 30009 | 0x0008 | 1 word | CH4 TC Value Hi Word |
| 30010 | 0x0009 | 1 word | CH4 TC Value Lo Word |
| 30011 | 0x000A | 1 word | CH5 TC Value Hi Word |
| 30012 | 0x000B | 1 word | CH5 TC Value Lo Word |
| 30013 | 0x000C | 1 word | CH6 TC Value Hi Word |
| 30014 | 0x000D | 1 word | CH6 TC Value Lo Word |
| 30015 | 0x000E | 1 word | CH7 TC Value Hi Word |
| 30016 | 0x000F | 1 word | CH7 TC Value Lo Word |
| 30017 | 0x0010 | 1 word | Virtual CH8 TC Value Hi Word <R> 0~4294967295, Unit:0.1 (Celsius, Fahrenheit) 0.0001(mV) |
| 30018 | 0x0011 | 1 word | Virtual CH8 TC Value Lo Word <R> 0~4294967295, Unit:0.1 (Celsius, Fahrenheit) 0.0001(mV) |
| 30019 | 0x0012 | 1 word | Virtual CH9 TC Value Hi Word |
| 30020 | 0x0013 | 1 word | Virtual CH9 TC Value Lo Word |
| 30021 | 0x0014 | 1 word | Virtual CH10 TC Value Hi Word |
| 30022 | 0x0015 | 1 word | Virtual CH10 TC Value Lo Word |
| 30023 | 0x0016 | 1 word | Virtual CH11 TC Value Hi Word |
| 30024 | 0x0017 | 1 word | Virtual CH11 TC Value Lo Word |
| 30025 | 0x0018 | 1 word | Virtual CH12 TC Value Hi Word |
| 30026 | 0x0019 | 1 word | Virtual CH12 TC Value Lo Word |
| 30027 | 0x001A | 1 word | Virtual CH13 TC Value Hi Word |
| 30028 | 0x001B | 1 word | Virtual CH13 TC Value Lo Word |
| 30029 | 0x001C | 1 word | Virtual CH14 TC Value Hi Word |
| 30030 | 0x001D | 1 word | Virtual CH14 TC Value Lo Word |
| 30031 | 0x001E | 1 word | Virtual CH15 TC Value Hi Word |
| 30032 | 0x001F | 1 word | Virtual CH15 TC Value Lo Word |
| 30033 | 0x0020 | 1 word | CH0 TC Minimum Value Hi Word <R> 0~4294967295, Unit:0.1 (Celsius, Fahrenheit) 0.0001(mV) |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 30034 | 0x0021 | 1 word | CH0 TC Minimum Value Lo Word <R> 0~4294967295, Unit:0.1 (Celsius, Fahrenheit) 0.0001(mV) |
| 30035 | 0x0022 | 1 word | CH1 TC Minimum Value Hi Word |
| 30036 | 0x0023 | 1 word | CH1 TC Minimum Value Lo Word |
| 30037 | 0x0024 | 1 word | CH2 TC Minimum Value Hi Word |
| 30038 | 0x0025 | 1 word | CH2 TC Minimum Value Lo Word |
| 30039 | 0x0026 | 1 word | CH3 TC Minimum Value Hi Word |
| 30040 | 0x0027 | 1 word | CH3 TC Minimum Value Lo Word |
| 30041 | 0x0028 | 1 word | CH4 TC Minimum Value Hi Word |
| 30042 | 0x0029 | 1 word | CH4 TC Minimum Value Lo Word |
| 30043 | 0x002A | 1 word | CH5 TC Minimum Value Hi Word |
| 30044 | 0x002B | 1 word | CH5 TC Minimum Value Lo Word |
| 30045 | 0x002C | 1 word | CH6 TC Minimum Value Hi Word |
| 30046 | 0x002D | 1 word | CH6 TC Minimum Value Lo Word |
| 30047 | 0x002E | 1 word | CH7 TC Minimum Value Hi Word |
| 30048 | 0x002F | 1 word | CH7 TC Minimum Value Lo Word |
| 30049 | 0x0030 | 1 word | Virtual CH8 TC Minimum Value Hi Word <R> 0~4294967295, Unit:0.1 (Celsius, Fahrenheit) 0.0001(mV) |
| 30050 | 0x0031 | 1 word | Virtual CH8 TC Minimum Value Lo Word <R> 0~4294967295, Unit:0.1 (Celsius, Fahrenheit) 0.0001(mV) |
| 30051 | 0x0032 | 1 word | Virtual CH9 TC Minimum Value Hi Word |
| 30052 | 0x0033 | 1 word | Virtual CH9 TC Minimum Value Lo Word |
| 30053 | 0x0034 | 1 word | Virtual CH10 TC Minimum Value Hi Word |
| 30054 | 0x0035 | 1 word | Virtual CH10 TC Minimum Value Lo Word |
| 30055 | 0x0036 | 1 word | Virtual CH11 TC Minimum Value Hi Word |
| 30056 | 0x0037 | 1 word | Virtual CH11 TC Minimum Value Lo Word |
| 30057 | 0x0038 | 1 word | Virtual CH12 TC Minimum Value Hi Word |
| 30058 | 0x0039 | 1 word | Virtual CH12 TC Minimum Value Lo Word |
| 30059 | 0x003A | 1 word | Virtual CH13 TC Minimum Value Hi Word |
| 30060 | 0x003B | 1 word | Virtual CH13 TC Minimum Value Lo Word |
| 30061 | 0x003C | 1 word | Virtual CH14 TC Minimum Value Hi Word |
| 30062 | 0x003D | 1 word | Virtual CH14 TC Minimum Value Lo Word |
| 30063 | 0x003E | 1 word | Virtual CH15 TC Minimum Value Hi Word |
| 30064 | 0x003F | 1 word | Virtual CH15 TC Minimum Value Lo Word |
| 30065 | 0x0040 | 1 word | CH0 TC Maximum Value Hi Word <R> 0~4294967295, Unit:0.1 (Celsius, Fahrenheit) 0.0001(mV) |
| 30066 | 0x0041 | 1 word | CH0 TC Maximum Value Lo Word <R> 0~4294967295, Unit:0.1 (Celsius, Fahrenheit) 0.0001(mV) |
| 30067 | 0x0042 | 1 word | CH1 TC Maximum Value Hi Word |
| 30068 | 0x0043 | 1 word | CH1 TC Maximum Value Lo Word |
| 30069 | 0x0044 | 1 word | CH2 TC Maximum Value Hi Word |
| 30070 | 0x0045 | 1 word | CH2 TC Maximum Value Lo Word |
| 30071 | 0x0046 | 1 word | CH3 TC Maximum Value Hi Word |
| 30072 | 0x0047 | 1 word | CH3 TC Maximum Value Lo Word |
| 30073 | 0x0048 | 1 word | CH4 TC Maximum Value Hi Word |
| 30074 | 0x0049 | 1 word | CH4 TC Maximum Value Lo Word |
| 30075 | 0x004A | 1 word | CH5 TC Maximum Value Hi Word |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 30076 | 0x004B | 1 word | CH5 TC Maximum Value Lo Word |
| 30077 | 0x004C | 1 word | CH6 TC Maximum Value Hi Word |
| 30078 | 0x004D | 1 word | CH6 TC Maximum Value Lo Word |
| 30079 | 0x004E | 1 word | CH7 TC Maximum Value Hi Word |
| 30080 | 0x004F | 1 word | CH7 TC Maximum Value Lo Word |
| 30081 | 0x0050 | 1 word | Virtual CH8 TC Maximum Value Hi Word <R> 0~4294967295, Unit:0.1 (Celsius, Fahrenheit) 0.0001(mV) |
| 30082 | 0x0051 | 1 word | Virtual CH8 TC Maximum Value Lo Word <R> 0~4294967295, Unit:0.1 (Celsius, Fahrenheit) 0.0001(mV) |
| 30083 | 0x0052 | 1 word | Virtual CH9 TC Maximum Value Hi Word |
| 30084 | 0x0053 | 1 word | Virtual CH9 TC Maximum Value Lo Word |
| 30085 | 0x0054 | 1 word | Virtual CH10 TC Maximum Value Hi Word |
| 30086 | 0x0055 | 1 word | Virtual CH10 TC Maximum Value Lo Word |
| 30087 | 0x0056 | 1 word | Virtual CH11 TC Maximum Value Hi Word |
| 30088 | 0x0057 | 1 word | Virtual CH11 TC Maximum Value Lo Word |
| 30089 | 0x0058 | 1 word | Virtual CH12 TC Maximum Value Hi Word |
| 30090 | 0x0059 | 1 word | Virtual CH12 TC Maximum Value Lo Word |
| 30091 | 0x005A | 1 word | Virtual CH13 TC Maximum Value Hi Word |
| 30092 | 0x005B | 1 word | Virtual CH13 TC Maximum Value Lo Word |
| 30093 | 0x005C | 1 word | Virtual CH14 TC Maximum Value Hi Word |
| 30094 | 0x005D | 1 word | Virtual CH14 TC Maximum Value Lo Word |
| 30095 | 0x005E | 1 word | Virtual CH15 TC Maximum Value Hi Word |
| 30096 | 0x005F | 1 word | Virtual CH15 TC Maximum Value Lo Word |

4xxxx Read/Write Registers (Functions 3, 6, 16)

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 40001 | 0x0000 | 1 word | CH0 DO Pulse Output Count Value Hi Word <RW> 0~4294967295 |
| 40002 | 0x0001 | 1 word | CH0 DO Pulse Output Count Value Lo Word <RW> 0~4294967295 |
| 40003 | 0x0002 | 1 word | CH1 DO Pulse Output Count Value Hi Word |
| 40004 | 0x0003 | 1 word | CH1 DO Pulse Output Count Value Lo Word |
| 40005 | 0x0004 | 1 word | CH2 DO Pulse Output Count Value Hi Word |
| 40006 | 0x0005 | 1 word | CH2 DO Pulse Output Count Value Lo Word |
| 40007 | 0x0006 | 1 word | CH3 DO Pulse Output Count Value Hi Word |
| 40008 | 0x0007 | 1 word | CH3 DO Pulse Output Count Value Lo Word |
| 40009 | 0x0008 | 1 word | CH0 DO Pulse Output Low Signal Width – Hi Word <RW> 0~4294967295 |
| 40010 | 0x0009 | 1 word | CH0 DO Pulse Output Low Signal Width – Lo Word <RW> 0~4294967295 |
| 40011 | 0x000A | 1 word | CH1 DO Pulse Output Low Signal Width – Hi Word |
| 40012 | 0x000B | 1 word | CH1 DO Pulse Output Low Signal Width – Lo Word |
| 40013 | 0x000C | 1 word | CH2 DO Pulse Output Low Signal Width – Hi Word |
| 40014 | 0x000D | 1 word | CH2 DO Pulse Output Low Signal Width – Lo Word |
| 40015 | 0x000E | 1 word | CH3 DO Pulse Output Low Signal Width – Hi Word |
| 40016 | 0x000F | 1 word | CH3 DO Pulse Output Low Signal Width – Lo Word |
| 40017 | 0x0010 | 1 word | CH0 DO Pulse Output High Signal Width – Hi Word <RW> 0~4294967295 |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 40018 | 0x0011 | 1 word | CH0 DO Pulse Output High Signal Width – Lo Word <RW> 0~4294967295 |
| 40019 | 0x0012 | 1 word | CH1 DO Pulse Output High Signal Width – Hi Word |
| 40020 | 0x0013 | 1 word | CH1 DO Pulse Output High Signal Width – Lo Word |
| 40021 | 0x0014 | 1 word | CH2 DO Pulse Output High Signal Width – Hi Word |
| 40022 | 0x0015 | 1 word | CH2 DO Pulse Output High Signal Width – Lo Word |
| 40023 | 0x0016 | 1 word | CH3 DO Pulse Output High Signal Width – Hi Word |
| 40024 | 0x0017 | 1 word | CH3 DO Pulse Output High Signal Width – Lo Word |
| 40025 | 0x0018 | 1 word | CH0 DO Operation Mode <RW> 0=DO Mode, 1=Pulse Output Mode |
| 40026 | 0x0019 | 1 word | CH1 DO Operation Mode |
| 40027 | 0x001A | 1 word | CH2 DO Operation Mode |
| 40028 | 0x001B | 1 word | CH3 DO Operation Mode |
| 40029 | 0x001C | 1 word | CH0 TC Engineering Unit 0=Celsius, 1=Fahrenheit, 2=millivolt |
| 40030 | 0x001D | 1 word | CH1 TC Engineering Unit |
| 40031 | 0x001E | 1 word | CH2 TC Engineering Unit |
| 40032 | 0x001F | 1 word | CH3 TC Engineering Unit |
| 40033 | 0x0020 | 1 word | CH4 TC Engineering Unit |
| 40034 | 0x0021 | 1 word | CH5 TC Engineering Unit |
| 40035 | 0x0022 | 1 word | CH6 TC Engineering Unit |
| 40036 | 0x0023 | 1 word | CH7 TC Engineering Unit |
| 40037 | 0x0024 | 1 word | Virtual CH8 TC Engineering Unit 0=Celsius, 1=Fahrenheit, 2= millivolt |
| 40038 | 0x0025 | 1 word | Virtual CH9 TC Engineering Unit |
| 40039 | 0x0026 | 1 word | Virtual CH10 TC Engineering Unit |
| 40040 | 0x0027 | 1 word | Virtual CH11 TC Engineering Unit |
| 40041 | 0x0028 | 1 word | Virtual CH12 TC Engineering Unit |
| 40042 | 0x0029 | 1 word | Virtual CH13 TC Engineering Unit |
| 40043 | 0x002A | 1 word | Virtual CH14 TC Engineering Unit |
| 40044 | 0x002B | 1 word | Virtual CH15 TC Engineering Unit |
| 40045 | 0x002C | 1 word | CH0 TC Sensor Type 0=J Type 1=K Type 2=T Type 3=E Type 4=R Type 5=S Type 6=B Type 7=N Type 8=Voltage: 78.126mV 9=Voltage: 39.062mV 10=Voltage: 19.532mV |
| 40046 | 0x002D | 1 word | CH1 TC Sensor Type |
| 40047 | 0x002E | 1 word | CH2 TC Sensor Type |
| 40048 | 0x002F | 1 word | CH3 TC Sensor Type |
| 40049 | 0x0030 | 1 word | CH4 TC Sensor Type |
| 40050 | 0x0031 | 1 word | CH5 TC Sensor Type |
| 40051 | 0x0032 | 1 word | CH6 TC Sensor Type |
| 40052 | 0x0033 | 1 word | CH7 TC Sensor Type |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|--|
| 40053 | 0x0034 | 1 word | CH8 TC Sensor Type 20=AVG 21=DIF |
| 40054 | 0x0035 | 1 word | Virtual CH9 TC Sensor Type |
| 40055 | 0x0036 | 1 word | Virtual CH10 TC Sensor Type |
| 40056 | 0x0037 | 1 word | Virtual CH11 TC Sensor Type |
| 40057 | 0x0038 | 1 word | Virtual CH12 TC Sensor Type |
| 40058 | 0x0039 | 1 word | Virtual CH13 TC Sensor Type |
| 40059 | 0x003A | 1 word | Virtual CH14 TC Sensor Type |
| 40060 | 0x003B | 1 word | Virtual CH15 TC Sensor Type |
| 40061 | 0x003C | 1 word | CH0 TC Reset Minimum Value <R> Always 0 <W> 1=Reset, 0=return illegal data value |
| 40062 | 0x003D | 1 word | CH1 TC Reset Minimum Value |
| 40063 | 0x003E | 1 word | CH2 TC Reset Minimum Value |
| 40064 | 0x003F | 1 word | CH3 TC Reset Minimum Value |
| 40065 | 0x0040 | 1 word | CH4 TC Reset Minimum Value |
| 40066 | 0x0041 | 1 word | CH5 TC Reset Minimum Value |
| 40067 | 0x0042 | 1 word | CH6 TC Reset Minimum Value |
| 40068 | 0x0043 | 1 word | CH7 TC Reset Minimum Value |
| 40069 | 0x0044 | 1 word | Virtual CH8 TC Reset Minimum Value |
| 40070 | 0x0045 | 1 word | Virtual CH9 TC Reset Minimum Value |
| 40071 | 0x0046 | 1 word | Virtual CH10 TC Reset Minimum Value |
| 40072 | 0x0047 | 1 word | Virtual CH11 TC Reset Minimum Value |
| 40073 | 0x0048 | 1 word | Virtual CH12 TC Reset Minimum Value |
| 40074 | 0x0049 | 1 word | Virtual CH13 TC Reset Minimum Value |
| 40075 | 0x004A | 1 word | Virtual CH14 TC Reset Minimum Value |
| 40076 | 0x004B | 1 word | Virtual CH15 TC Reset Minimum Value |
| 40077 | 0x004C | 1 word | CH0 TC Reset Maximum Value <R> Always 0 <W> 1=Reset, 0=return illegal data value |
| 40078 | 0x004D | 1 word | CH1 TC Reset Maximum Value |
| 40079 | 0x004E | 1 word | CH2 TC Reset Maximum Value |
| 40080 | 0x004F | 1 word | CH3 TC Reset Maximum Value |
| 40081 | 0x0050 | 1 word | CH4 TC Reset Maximum Value |
| 40082 | 0x0051 | 1 word | CH5 TC Reset Maximum Value |
| 40083 | 0x0052 | 1 word | CH6 TC Reset Maximum Value |
| 40084 | 0x0053 | 1 word | CH7 TC Reset Maximum Value |
| 40085 | 0x0054 | 1 word | Virtual CH8 TC Reset Maximum Value |
| 40086 | 0x0055 | 1 word | Virtual CH9 TC Reset Maximum Value |
| 40087 | 0x0056 | 1 word | Virtual CH10 TC Reset Maximum Value |
| 40088 | 0x0057 | 1 word | Virtual CH11 TC Reset Maximum Value |
| 40089 | 0x0058 | 1 word | Virtual CH12 TC Reset Maximum Value |
| 40090 | 0x0059 | 1 word | Virtual CH13 TC Reset Maximum Value |
| 40091 | 0x005A | 1 word | Virtual CH14 TC Reset Maximum Value |
| 40092 | 0x005B | 1 word | Virtual CH15 TC Reset Maximum Value |
| 40093 | 0x005C | 1 word | CH0 DO Status <RW> 0=OFF, 1=ON |
| 40094 | 0x005D | 1 word | CH1 DO Status |
| 40095 | 0x005E | 1 word | CH2 DO Status |
| 40096 | 0x005F | 1 word | CH3 DO Status |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|---|
| 40097 | 0x0060 | 1 word | CH0 DO Power On Status <RW> 0=OFF, 1=ON |
| 40098 | 0x0061 | 1 word | CH1 DO Status |
| 40099 | 0x0062 | 1 word | CH2 DO Status |
| 40100 | 0x0063 | 1 word | CH3 DO Status |
| 40101 | 0x0064 | 1 word | CH0 DO Safe Status <RW> 0=OFF, 1=ON |
| 40102 | 0x0065 | 1 word | CH1 DO Status |
| 40103 | 0x0066 | 1 word | CH2 DO Status |
| 40104 | 0x0067 | 1 word | CH3 DO Status |
| 40105 | 0x0068 | 1 word | CH0 DO Pulse Output Status <RW> 0=Stop, 1=Start |
| 40106 | 0x0069 | 1 word | CH1 DO Pulse Output Status |
| 40107 | 0x006A | 1 word | CH2 DO Pulse Output Status |
| 40108 | 0x006B | 1 word | CH3 DO Pulse Output Status |
| 40109 | 0x006C | 1 word | CH0 DO Power On Pulse Output Status <RW> 0=Stop, 1=Start |
| 40110 | 0x006D | 1 word | CH1 DO Pulse Output Status |
| 40111 | 0x006E | 1 word | CH2 DO Pulse Output Status |
| 40112 | 0x006F | 1 word | CH3 DO Pulse Output Status |
| 40113 | 0x0070 | 1 word | CH0 DO Safe Pulse Output Status <RW> 0=Stop, 1=Start |
| 40114 | 0x0071 | 1 word | CH1 DO Pulse Output Status |
| 40115 | 0x0072 | 1 word | CH2 DO Pulse Output Status |
| 40116 | 0x0073 | 1 word | CH3 DO Pulse Output Status |
| 40117 | 0x0074 | 1 word | CH0 TC Enable <RW> 0 =Disable, 1=Enable |
| 40118 | 0x0075 | 1 word | CH1 TC Enable |
| 40119 | 0x0076 | 1 word | CH2 TC Enable |
| 40120 | 0x0077 | 1 word | CH3 TC Enable |
| 40121 | 0x0078 | 1 word | CH4 TC Enable |
| 40122 | 0x0079 | 1 word | CH5 TC Enable |
| 40123 | 0x007A | 1 word | CH6 TC Enable |
| 40124 | 0x007B | 1 word | CH7 TC Enable |
| 40337 | 0x0150 | 1 word | Internal Register 00 Working Value |
| 40338 | 0x0151 | 1 word | Internal Register 01 Working Value |
| 40339 | 0x0152 | 1 word | Internal Register 02 Working Value |
| 40340 | 0x0153 | 1 word | Internal Register 03 Working Value |
| 40341 | 0x0154 | 1 word | Internal Register 04 Working Value |
| 40342 | 0x0155 | 1 word | Internal Register 05 Working Value |
| 40343 | 0x0156 | 1 word | Internal Register 06 Working Value |
| 40344 | 0x0157 | 1 word | Internal Register 07 Working Value |
| 40345 | 0x0158 | 1 word | Internal Register 08 Working Value |
| 40346 | 0x0159 | 1 word | Internal Register 09 Working Value |
| 40347 | 0x015A | 1 word | Internal Register 10 Working Value |
| 40348 | 0x015B | 1 word | Internal Register 11 Working Value |
| 40349 | 0x015C | 1 word | Internal Register 12 Working Value |
| 40350 | 0x015D | 1 word | Internal Register 13 Working Value |
| 40351 | 0x015E | 1 word | Internal Register 14 Working Value |
| 40352 | 0x015F | 1 word | Internal Register 15 Working Value |
| 40353 | 0x0160 | 1 word | Internal Register 16 Working Value |
| 40354 | 0x0161 | 1 word | Internal Register 17 Working Value |

| Reference | Address | Data Type | Description |
|-----------|---------|-----------|------------------------------------|
| 40355 | 0x0162 | 1 word | Internal Register 18 Working Value |
| 40356 | 0x0163 | 1 word | Internal Register 19 Working Value |
| 40357 | 0x0164 | 1 word | Internal Register 20 Working Value |
| 40358 | 0x0165 | 1 word | Internal Register 21 Working Value |
| 40359 | 0x0166 | 1 word | Internal Register 22 Working Value |
| 40360 | 0x0167 | 1 word | Internal Register 23 Working Value |

5xxxx Write Registers (Function 8)

| Sub-function | Data Field (Request) | Data Field (Response) | Description |
|--------------|----------------------|-----------------------|----------------------------|
| 0x0000 | Any Data | Echo Request Data | Echo |
| 0x0001 | 0xFF00 | Echo Request Data | Reboot |
| 0x0001 | 0x55AA | Echo Request Data | Reset with Factory default |